

End-user Development for Smart Spaces: A Comparison of Block and Data-flow Programming

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Abstract: Block and data-flow programming are well-known concepts for enabling end users to visually create their own customized solutions. They both offer comprehensive visual interfaces and are becoming popular within the smart spaces domain. However, there is currently no systematic, comparative evaluation of the two concepts in the domain. In this user study, we implemented two prototypes for block and data-flow programming and compared their performance on typical usage scenarios in common smart spaces. We used a mixed methods approach of quantitative and qualitative analysis to gain an in-depth understanding of the user experience. Our results show that data-flow programming is overall better received by users than block programming and is considered being state-of-the art and visually more appealing. For block programming, our results reveal that participants appreciate the playful character and the feedback provided. Our study contributes to the improvement of block and data-flow solutions in place and discusses aspects relevant to the future advancement of end-user development in smart spaces.

1 INTRODUCTION AND RELATED WORK

Smart spaces that support people in their daily lives are more and more becoming a reality (Mennicken et al., 2014). The availability of affordable hardware fosters the introduction of smart devices in different areas and tailored services are connecting these devices in a useful manner (Jensen et al., 2018). However, the smart spaces that surround our modern lives are inherently complex and make it difficult to design one-size-fits-all solutions (Mennicken et al., 2014). Not all services that the inhabitants of smart spaces (e.g., smart homes, smart cities, etc.) desire are known a priori. End users have the best knowledge of their requirements, can build the functions they desire, and invent novel services that were not intended by system designers (Coutaz et al., 2010; Jensen et al., 2018; Mennicken et al., 2014).

At the same time, users of smart spaces want to be in control and have the ability to regulate all aspects of their lives with cyber-physical technologies surrounding them (Davidoff et al., 2006). However, existing solutions for configuring smart spaces are often considered as being too complicated or not offering sufficient functionalities (Reisinger et al., 2017;

Altendeitering and Schimmler, 2020).

To address these problems, low code visual programming languages have become wide-spread methods for interacting with smart spaces as they enable end-users without coding knowledge to create customized solutions (Reisinger et al., 2017; Altendeitering and Schimmler, 2020). To provide adequate usability and accessibility, it is important to utilize a visual language that is suitable for a specific user group. Otherwise, inexperienced users could face barriers that hinder them from fully exploiting the possibilities offered by smart spaces (Davidoff et al., 2006).

In literature and practice, form-filling (e.g., (IFTTT, 2021)), data-flow (e.g., (Node-RED, 2021)), and block programming (e.g., (Blockly, 2021; Scratch, 2021)) are well-established visual programming concepts. These approaches have in common that they try to reduce the semantic, syntactic, and pragmatic barriers to programming inexperienced users are facing. They are different in their expressiveness, visual representation and cognitive style (Ur et al., 2014; Reisinger et al., 2017). Block and data-flow programming tools come with a more comprehensive visual interface as compared to form-filling solutions and are becoming increasingly popular within the smart spaces domain (Altendeitering

and Schimmler, 2020; Reisinger et al., 2017).

Several studies examined the differences between programming paradigms in different scenarios. Most of them focus on the differences between graphical and textual approaches (e.g., (Stein and Hanenberg, 2011; Weintrop and Wilensky, 2015)). The two studies that come closest to the idea of our paper are (Reisinger et al., 2017) and (Mason and Dave, 2017).

In the paper of (Reisinger et al., 2017), the authors compared form-filling and data-flow programming concepts using exemplary usage scenarios. They found that data-flow excels form-filling through a better comprehensiveness and usability. In the short paper of (Mason and Dave, 2017), the authors investigated the differences between block and data-flow programming, similar to our study. However, only preliminary results were presented and no in-depth investigation of the two concepts was provided.

With our study we want to contribute such an in-depth analysis and help researchers and practitioners to distinguish the concepts and determine which one is preferable. We, therefore, conducted a comparative evaluation and implemented a visual language in two exemplary prototypes for block and data-flow programming that enable the creation of typical usage scenarios in smart spaces. Specifically, we formulated the following research question:

- **Research Question:** *What are the differences in user perception between block and data-flow programming within smart spaces? Can known differences be replicated?*

The remainder of this article is structured as follows. In Section 2, we start by describing our research methodology including the prototypes we realized and the experimental setting. In Section 3, we present the results of our study. We conclude with a discussion of the results in Section 4.

2 RESEARCH METHODOLOGY

To answer the proposed research questions, we conducted a mixed methods user study on two prototypes for the visual programming paradigms under investigation. We decided to apply a mixed methods approach of (1) quantitative and (2) qualitative analysis to increase the robustness of our results by triangulating different methods for the same phenomenon (Graziano and Raulin, 1993; Zhao et al., 2019). Specifically, we followed the example of (Reisinger et al., 2017) and conducted a laboratory user study with twelve participants, a sufficient number for finding most usability issues (Nielsen and

Landauer, 1993). Hereby, the participants were confronted with three tasks based on typical usage scenarios in smart spaces and asked to solve these tasks using both prototypes (Zhao et al., 2019).

2.1 Participants

Of the twelve participants five were female and seven were male. Potential candidates were recruited from the scope of a German smart spaces research project and approached by email. The participants' mean age was 26.67 with a standard deviation (SD) of 3.61. The group of participants had an average computer literacy with a mean of 2.92 on a scale from 1 to 5. The programming knowledge was slightly below average with a mean of 2. Only one participant reported to have high programming skills. All other participants reported low to medium programming skills. Both, the computer literacy and programming knowledge, were self-reported by the participants.

Everyone was familiar with the concept of smart spaces or smart homes. Two persons had heard of Node-RED before, but did not use it on a regular basis. The other participants had not heard of either Node-RED or Blockly before. Overall, our user group is not representative for the general population, but matches a typical smart spaces user group, which consists of young adults with an interest in digital technologies and limited programming skills (Reisinger et al., 2017; Altendeitering and Schimmler, 2020).

2.2 Experimental Setting

To evaluate the participants' performance, we defined three common usage scenarios for programming smart spaces. We based these usage scenarios on use cases that were presented in related studies (Altendeitering and Schimmler, 2020; Reisinger et al., 2017; Mason and Dave, 2017). We decided to use generic usage scenarios instead of concrete task descriptions to gain a better understanding of the ease of use of the two prototypes for inexperienced users. The three scenarios vary in their difficulty, which we specified as the amount of block or data-flow items that are required to realize the respective scenario (see Table 1).

For enabling the participants to realize the described usage scenarios we created a visual language and two prototypes for block and data-flow programming. For this, we extended the standard vocabulary of established solutions with custom blocks (for block programming) and nodes (for data-flow programming). Specifically, we created artifacts for accessing the relevant data sources from the smart spaces (i.e., Smart Parking, Smart Home, Smart Me-

Table 1: Usage scenarios for smart spaces.

Scenario	Elements [Flow/Block]	Difficulty	Description	Custom Artifacts
Smart Parking (a)	6/7	easy	After work, I want to spend as little time as possible looking for a parking lot. Notify me on the way home if there are free parking lots available.	Energy consumption sensor for TV, fridge, and oven; Warning and Information engine
Smart Home (b)	7/9	medium	I want the air quality in my apartment to be good. Open a window when the air quality inside is poor and good outside.	Air Quality sensor inside and outside; Open Window function; method for determining whether Air Quality is good
Smart Meter (c)	13/13	hard	The power consumption of my three appliances (TV, fridge, oven) is very high. Warn me if I consume more than 10 kWh and inform me which device consumes the most.	Energy consumption sensor for TV, fridge, and oven; Warning and Information engine

ter) and organized these in categories that are named after the respective smart space. We implemented a demo back-end to provide the data sources with exemplary sensor streams. Additionally, we included a separate category that contains useful artifacts (e.g., for determining whether the air quality is sufficient) to simplify the usage of the two prototypes. Overall, we included twelve new custom artifacts to enable the creation of the usage scenarios (see Table 1).

To create a realistic experience, we used existing solutions (e.g., (Xiaomi, 2021; Homee, 2021; Loxone, 2021)) as an example for the styling and naming of our custom artifacts. All other required artifacts remained in the standard categorization of the block and data-flow programming solutions we used. Both prototypes offered an open canvas and allowed participants to freely combine blocks or nodes in their own way. There was no pre-defined structure and all tasks offered multiple ways to achieve the desired outcome.

We implemented the block-programming prototype on Google Blockly (Blockly, 2021). We decided to extend Blockly as it is a well-established and easily extensible block programming language. Figure 1 shows an implementation of the smart home task.

For the data-flow programming prototype we used Node-RED (Node-RED, 2021) as a basis. We chose to use Node-RED as it has a broad community that offers many extensions and custom developments and is well documented. In addition to creating new nodes, Node-RED offers the possibility to create sub-flows, which are made up of existing Node-RED blocks. We used this possibility instead of creating new nodes wherever possible. Figure 2 displays a realization of

the smart home task using the Node-RED based data-flow prototype.

2.3 Measures & Data Analysis

Following the described mixed methods approach, our data analysis has two separate parts: **quantitative** and **qualitative** analysis.

2.3.1 Quantitative

With our quantitative analysis we followed the example of (Reisinger et al., 2017), who conducted a similar study. It consists of six measures based on the usability factors (UFs) proposed by (Nielsen, 1994) (see Table 2).

For the *Task Completion Time* (measure 1) we manually tracked the time the participants spent on the prototype trying to solve the tasks at hand. To determine the *Task Completion Rate* (measure 2), we analyzed the participants' final programs after completion. We defined this measure as the number of elements used in the optimal solution minus the number of corrective steps needed. For measures 3 and 4 the participants rated their *Perceived Success* and the *Perceived Difficulty* of the respective prototype on a 7-item Likert scale. For analysis, we used a MANOVA with these measures as dependent variables and the respective prototype as independent variable (Graziano and Raulin, 1993).

We investigated measure 5 with a standardized *User Experience Questionnaire (UEQ)* as introduced by (Laugwitz et al., 2008). For an analysis of the UEQ

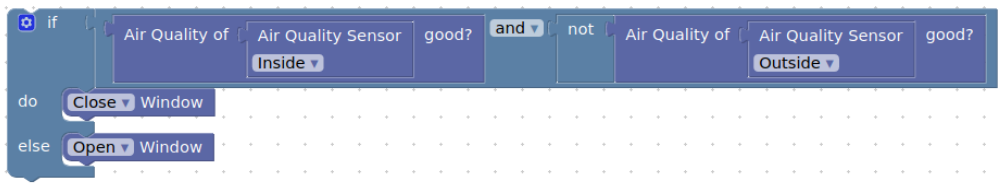


Figure 1: Block programming prototype showing the smart home task (b).

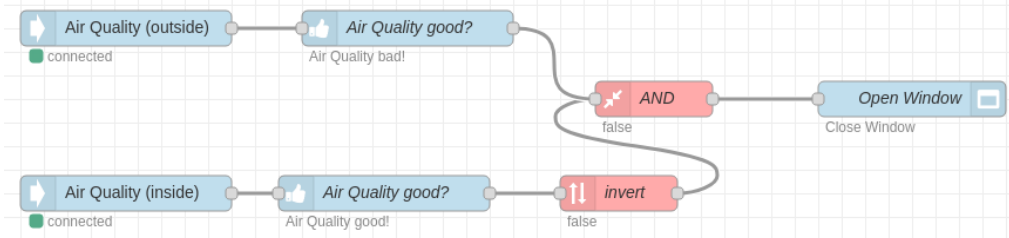


Figure 2: Data-flow programming prototype showing the smart home task (b).

Table 2: Six measures for performance and usability analysis (based on (Nielsen, 1994)).

#	Measure	Usability (UF)	Factor
1	Task Completion Time	Efficiency	
2	Task Completion Rate	Errors	
3	Perceived Success	Satisfaction, Learnability	
4	Perceived Difficulty	Satisfaction, Learnability	
5	UEQ	Satisfaction, Learnability	
6	Self-Assessment	Memorability, Learnability	

we used descriptive statistical measures. These contain the calculation of mean, standard deviation (SD), and effect sizes (Graziano and Raulin, 1993). Effect sizes were calculated with Cohen’s d (Cohen, 1992).

For the *Self-Assessment* (measure 6) we asked the participants to draw two of their solutions, one for each prototype, from memory and asked how confident they felt about the correctness of their drawing on a 7-item Likert scale. A high recollection rate and self-assessment is an important factor for visual programming in smart spaces as it supports the cooperative work with friends and families (Reisinger et al., 2017; Davidoff et al., 2006).

2.3.2 Qualitative

The qualitative part of our data analysis adds an in-depth analysis to the quantitative measures. For this

purpose, we added open questions on the positive and negative experiences made while using the prototypes to the questionnaires. This allowed us to gain an in-depth understanding of the phenomena the participants experienced while using the prototypes (Zhao et al., 2019). To systematically analyze these questions, we used content analysis as a common approach for analyzing unstructured data like written text. By repeatedly chunking different sentences into fewer related categories and sub-categories, it delivers a dense description of the phenomenon under investigation (Elo and Kyngäs, 2008; Vaismoradi et al., 2013). Following (Vaismoradi et al., 2013), content analysis has a low level of interpretation and is useful for gaining insights in usability issues experienced by users of a product or software.

For the content analysis two researchers independently coded the answers for positive and negative aspects. Afterwards, they iterative grouped related codes that describe the same phenomenon into abstract themes. Potential differences in the derived codes and themes were clarified in subsequent discussions between the two researchers.

2.4 Procedure

The participants had a one-hour time frame to complete all tasks and questionnaires. They worked on the tasks alone with one of the authors in the same room for tracking the time needed and handing out the tasks. Unnecessary or distracting items were removed from the room to allow for a neutral setting (Bordens and Abbott, 2002). We initiated the user study with a short explanation of smart spaces and visual programming to ensure a common understanding. Afterwards, the participants started working on the three tasks in

ascending difficulty. Hereby, six people started with one prototype, while the remaining six started with the other one.

Once they finished their tasks, the present author noted quantitative measures, the participants rated the perceived success and difficulty, and filled out the UEQ. Moreover, they answered open questions on both prototypes for qualitative analysis. After this first iteration the participants repeated the same procedure for the other prototype. Once they finished their tasks and questionnaires, we started the measurement of the self-assessment. At last, we requested the participants to fill out a short demographic questionnaire to enable the differentiation of the responses by gender, age, and other factors. Overall, they worked on scenarios a, b, and c twice, answered two questionnaires, and drew two solutions on paper.

3 RESULTS

With regard to the study’s procedure we found that, overall, it was a good fit and helped us to be in accordance with our research goal. We were able to gain insights in the usability of the two prototypes and an answer to our research question. However, in future studies we would allow the users more time in using the applications to investigate the learning effect and select a more diverse user group. In the following two sections we present our quantitative and qualitative results in detail.

3.1 Quantitative Results

We summarized the results of measures 1-4 in Table 3. An analysis of the *Task Completion Time* shows that users needed almost a minute longer with Blockly (7.52) as compared to Node-RED (6.67) to realize all scenarios. The most important difference between both prototypes is the *Task Completion Rate*, which shows that users were significantly more successful with the data-flow prototype. For *Perceived Success*, *Perceived Difficulty*, and *Self-Assessment* we did not observe significant differences between both programming paradigms.

The results of measure 5 (UEQ) are shown in Figure 3. The UEQ included questions in six dimensions. Only in the dimension *Perspicuity* ($p = .69, |d| = .09$) the block approach (0.64) excels data-flow (0.42). In all other dimensions, data-flow scored higher or similar. In case of *Attractiveness* ($p = .03, |d| = .5$) and *Novelty* ($p = .01, |d| = .8$) with a significant difference and medium effect size.

Finally, for the *Self-Assessment* (measure 6) we

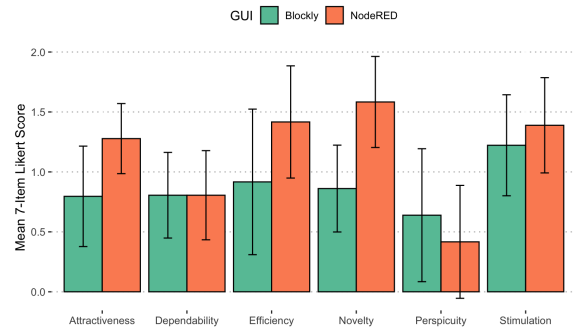


Figure 3: Results for the UEQ (measure 5). Scores are balanced (-3 to +3) and grouped by GUI with 75% confidence interval.

observed that Node-RED scored (2.22) considerably higher than Blockly (0.78), having a big gap between the means ($p = .09, |d| = .9$). Scores were balanced from -3 to 3. Although not statistically significant the result shows an advantage for Node-RED over Blockly that should be further investigated.

3.2 Qualitative Results

To visualize the results of our qualitative analysis, we organized the themes, which we derived from the open questions, as two word clouds. We chose to use word clouds for visualization as they offer the reader an easy and intuitive way for identifying the essential feedback for both programming paradigms. They, furthermore, allow us to compare the balance between positive and negative remarks for the data-flow and block programming prototypes. Green themes have a positive sentiment, while red represents a negative theme. The size of the labels relates to the number of occurrences of the respective theme.

The strongest positive theme for data-flow programming (see Figure 4) was *simple representation*, which was mentioned nine times (+9). People liked the concept of the *flow model* (+4) in general and that the connections were clear. It was easy to understand that the data “flows like a river” and is transformed by nodes in sequence. On the contrary, people criticized that the interaction with the nodes was not dynamic. There was *no feedback* (-6) if the connection of two nodes made any sense or if they are incompatible. This left error handling and debugging entirely up to the user.

Block-programming’s (see Figure 5) strongest positive themes included the intuitive *puzzle mechanic* (+3) together with *connection feedback* (+3) as elements would “jump away” when incompatible. Additionally, people find the *simple representation* (+2) and the interactive *limitation* (+2) appealing.

Table 3: Descriptive measures and MANOVA using task observations as dependent variables and the respective prototype as independent variable.

	Mean (\pm sd)		MANOVA
	Blockly	Node-RED	
Task Completion Time in minutes	7.52 (\pm 3.12)	6.67 (\pm 4.40)	F=1.65 p=.22
Task Completion Rate as ratio %	83 (\pm 14)	94 (\pm 9)	F=6.72 p=.02
Perceived Success 7-item Likert Scale	5.52 (\pm 1.78)	5.33 (\pm 1.90)	F=0.86 p=.37
Perceived Difficulty 7-item Likert Scale	4.59 (\pm 1.65)	4.78 (\pm 1.55)	F=1.67 p=.21

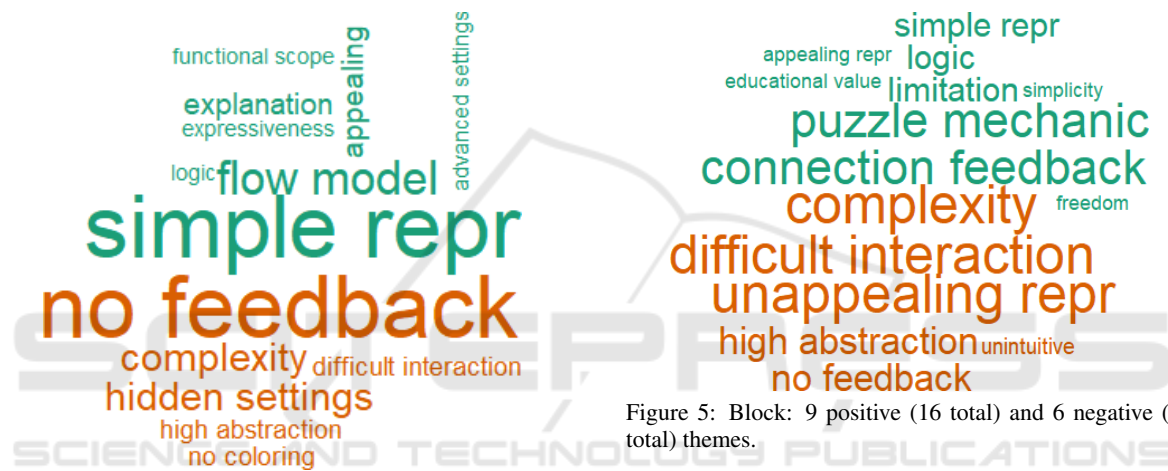


Figure 4: Data-flow: 8 positive (21 total) and 6 negative (13 total) themes.

However, the puzzle mechanic also comes with some downsides including a high *complexity*, *difficult interaction*, and *unappealing representation* (all -3). Overall, data-flow has a larger share of positive themes (21 positive / 13 negative) as compared to block programming (16 positive / 14 negative).

4 DISCUSSION, LIMITATIONS AND FUTURE WORK

By comparing the two prototypes for block and data-flow programming, we can summarize that the data-flow (Node-RED) excels the block prototype (Blockly) in several dimensions. Most importantly, we observed that the users were significantly more successful in completing the tasks with the Node-RED prototype. They also felt more confident in using the data-flow application and preferred the user interface. In this sense, our results are tallied with

Figure 5: Block: 9 positive (16 total) and 6 negative (14 total) themes.

previous studies (Reisinger et al., 2017; Leitner et al., 2013; Mason and Dave, 2017) and indicate that the data-flow visual programming paradigm might be preferable in smart spaces. However, since most of our measures were not statistically significant further studies are necessary to deepen the analysis of the two concepts.

With regard to the data-flow prototype, users found the solution visually more appealing as compared to the block prototype and considered it as being state-of-the-art. They also felt more secure in using the prototype and liked the freedom offered by the flow-based interaction model. These results are interesting as people also noted that they sometimes feel overwhelmed by the possibilities and criticized the lack of feedback. Intelligent hints or limitations in node connections could help make the tool more useful and improve on Hick’s law (Rosati, 2013).

Looking at the block prototype, the participants liked the heightened perspicuity they received from the puzzle mechanic, which offers a more playful character. The puzzle mechanic also provides users with immediate feedback on their programs, which

was well received. On the other hand, the interaction model and the visual representation were seen as complex and unappealing. A more modern user interface and full-grown IDE could help overcome these issues and increase the usability of the prototype (Inayama and Hosobe, 2018).

For both tools we observed downsides in their interaction model, which led participants to perceive the tools as complex and rather difficult. Future developments should combine the strengths of both concepts, especially a simple and modern user interface with feedback mechanisms. Additionally, new formats of human-computer interaction, such as conversational AI (e.g., chatbots or voice interaction) could support inexperienced users by indicating potential pitfalls (Jung et al., 2019; Inayama and Hosobe, 2018).

Although our study uncovered some interesting details it is subject to several limitations. A study with a larger and more-diverse group of participants could shed additional light on the subject. Furthermore, our study could be biased by the choice of the underlying technology (i.e., Blockly and Node-RED) and the interaction model of the particular tools. Other solutions might offer different forms of interaction and user feedback and achieve different results. It would, moreover, be interesting to include the learning effect as an additional metric in further studies and investigate how well participants remember the user interface after some time.

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