Survival Status Prediction for Non-small Cell Lung Cancer Patients using Machine Learning

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Abstract: Lung cancer is the leading cause among cancer-related deaths worldwide. Clinically, it could be divided into several groups: 1) the non-small cell lung cancer (NSCLC, 83.4%), 2) the small cell lung cancer (SCLC,13.3%), 3) not otherwise specified lung cancer (NOS,3.1%), 4) aarcoma lung carcinoma (0.2%), and 5) other specified carcinoma (0.1%). According to SEER Cancer Statistics Review, 5-year survival rate of patients with advanced non-small cell lung cancer (NSCLC) who received chemotherapy was less than 5%. Our ability to provide survival status at any time in future is important from at least two standpoints: a) from the clinical standpoint it enables clinicians to provide optimal delivery of healthcare and b) from a personal standpoint, by providing patient's family with opportunities to plan their life ahead and potentially cope with emotional aspect of loss of life. In this paper we propose to utilize machine learning techniques to achieve this goal and evaluate several techniques in order to determine their prediction performance using publicly available dataset.

1 INTRODUCTION

According to American Cancer Society, lung cancer is the leading cause of cancer death among men and women, for almost 25% of all cancer deaths. Since the mortality rate of lung cancer is high, it belongs to a group that has the worst survival prognosis (Matuzzi, 2019). Generally, after diagnosis the patient's family expects to know the patient's chances of survival from a clinician. An ability to predict life expectancy can be beneficial from both emotional standpoint and clinical standpoint, as it reduces stress on patient's family and enables them to cope with situation. It can also allow clinicians to evaluate patients' risk, likelihood of survival and postoperative treatment procedures. Due to the very nature of the disease, lung cancer datasets are generally imbalanced where majority of patient population has low chances of survival. As a result, predictive modelling on imbalanced datasets where the majority of patients have low chances of survival (Liang, 2017) makes it more challenging to accurately predict survival status of patients with higher chances of survival. Thus, for clinicians to accurately evaluate patients' risk and further design appropriate post treatment procedures it is equally important to accurately predict both true negatives and true positives.

Increasing the number diagnostic lab tests indi-

cates a potential of vast biomedical data assuming there are plenty of electronic health records of patients. As a result, rapid increase in volume and complexity of biomedical data can be utilized to draw patterns and inferences. One of the promising techniques that can be helpful in finding patterns from a large patient cohort data is predictive modelling which utilizes biomedical data to investigate relationships between the factors and the dependencies that further help us predict survival. Ultimately, this can help patients with personalized medication and risk assessment. Developing algorithms and mathematical models that can generate reliable predictions on an imbalanced dataset is a daunting task because of the underlying dependencies and bias which can be complex. As a result, number of factors influencing the predictions are huge. To implement this technique in medical practice we need rigorous training procedures for complexities. Even in this case, the underlying assumption of these techniques is that certain statistical/probabilistic models can describe these dependencies which may not be true in certain cases (i.e., there may exist certain number of outliers in every dataset). In addition, we need to design vigorous testing, validation, and verification procedures because of overwhelming intricacies such as variability from patientto -patient that needs to be evaluated.

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Unequal distribution of data between majority class i.e. patients that are less likely to survive and minority class i.e. patients that are likely to survive can induce bias towards majority class, leaving minority class samples to be often misclassified. Misclassification of minority class can lead to hectic postoperative treatment procedures, high dosage of recommended drugs and accelerated health follow-ups and diagnostic tests which can cause stress both physically and psychologically. An ability to predict survival status of patient at a given time by clinician can alleviate this stress. Hence, to use machine learning models in clinical practice they should be designed in such a way that they are robust towards bias induced by majority class. These models can also be used as a risk assessment tool to help us determine which patients should be offered imaging. However, all these tools suffer from aforementioned common challenge of bias towards majority class. Furthermore, they are also dynamic in nature and need to be updated continuously as the environment changes. Hence, model should be constructed and designed in such a way that it can adjust if there are changes in the subset of the population.

In this paper, we investigate different approaches for predicting survival status of patients suffering from non-small cell lung cancer. In Section 2 we present signal model, i.e. different classifiers on which our analysis will be performed and later in the paper we list evaluation metrics for measuring performance. In addition we define a fusion algorithm that can be used to combine decisions of different machine learning algorithms. In Section 3, related dataset and results from different tests performed on training data will be discussed. In Section 4 we conclude our findings for this study and present suggestions for future work.

2 SIGNAL MODELS

2.1 Data Set

The dataset used for evaluation of the proposed model is from MAASTRO Clinic, (Maastricht, The Netherlands). This dataset is open source and can be found at TCIA (The cancer imaging archive) under NSCLC (Aerts, 2019). Four hundred and twenty-two consecutive patients were included (132 women and 290 men), with inoperable, histologic or cytologic conferred NSCLC, UICC stages I-IIIb, treated with radical radiotherapy alone (n = 196) or with chemoradiation (n = 226). Mean age was 67.5 years (range: 33–91 years). The study has been approved by the institutional review board. All research was carried out in accordance with Dutch law. The Institutional Review Board of the Maastricht University Medical Centre (MUMC+) waved review due to the retrospective nature of this study. Out of 422 records, we have only 365 patients with all the information. The survival time (in days) in the dataset is from the start of the treatment and there is a possibility that the status of patient recorded may not be accurate i.e. the clinicians may not have received the information right when the event outcome occurred.

2.2 Machine Learning Models

Training a model that predicts the survival status at a given time, means forecasting the odds of outcome instead of forecasting the point estimate of the occurrence. In our case there are two disease outcomes i.e. alive and dead, defined so that if the result of odds are greater than 50% then the predicted class is assigned value 1 (alive) otherwise it is 0 (dead). We investigate applicability of several models: gradient boosting, XGboost and random forrest. The main difficulty in this particular application are the unbalanced data sets since the number of patients surviving the lung cancer after certain period of time is relatively small. To this purpose we propose to fuse the the proposed machine learning algorithms using our information fusion algorithm proposed in (Liu et al., 2007).

2.3 Gradient Boosting

Boosting is defined as a strategy that involves combination of multiple simple models resulting in an overall stronger model. The simple models are called as weak learners. For example, the flow chart in Figure 1 below explains the gradient boosting method for N trees. Tree 1 is trained using a feature matrix X and target variable y. The predictions labelled \hat{y}_1 are used to determine the training set loss function r_1 . Tree2 is then trained using the feature matrix X and the loss function r_1 of Tree1 as labels. The predicted results *hat* r_1 are then used to determine the loss function r_2 . The process is repeated until all the N trees forming the ensemble are trained.

In other words, instead of fitting a model on the data at each iteration, it fits a new model to the residual errors made by the previous model. The details of gradient boosting method are outlined in (Ke et al., 2017).



Figure 1: Gradient Boosting algorithm scheme.

2.4 XGBoost

XGBoost stands for extreme gradient boosting as it uses second-order Taylor expansion of the loss function to iterate and calculate weights at leaf nodes of the new tree K (Zhao, 2020). Additionally, a regularization term is added to the loss function to control the complexity of the model and prevent it from overfitting. Therefore, XGBoost performs better in training efficiency, massive parallelism, and quadratic convergence (Zhao, 2020).

It can perform well on imbalanced datasets as it calculates the second order gradients i.e., second partial derivatives of loss function ultimately giving more information about the direction of gradients and minimizes loss function.

2.5 Random Forrest

In addition to the aforementioned models, we investigate applicability of the ensemble methods that utilize machine learning methods using different learning algorithms. To this purpose we select decision tree approach and utilize commonly used Random Forrest (Dai et al., 2018) technique which uses bagging and feature randomness when building each tree creating an uncorrelated forest of trees which makes decision by aggregating the votes from different trees. To illustrate the performance of this algorithm in Fig. 2-4 we illustrate the tree growth for our dataset. Due to random feature selection, the trees are more independent of each other as compared to regular bagging, which often results in better predictive performance.

2.6 Fusion Algorithm

Each of the aforementioned classifiers can be treated as a single channel detector making a decision in a binary classification problem. In order to improve their overall performance we propose to combine their classifications using the distributed system illustrated in Figure 5.



Figure 2: First decision tree.



Figure 3: Fourth decision tree.

The global decision in the fusion centre is then made by minimizing the overall probability of error/misclassification.

$$P_e = P(H_0)P(u_0 = 1|H_0) + P(H_1)P(u_0 = 0|H_1)$$

The optimality criterion for N is given by (Varshney, 1986).

$$u_{0} = \begin{cases} 1, & \text{if } w_{0} + \sum_{n=1}^{3} w_{n} > 0\\ 0, & \text{otherwise} \end{cases}$$
(1)

where,
$$w_0 = \log\left(\frac{P_1}{P_0}\right)$$

and
$$w_n = \begin{cases} \log((1 - P_n^m)/P_n^f), & \text{if } u_n = 1\\ \log(P_n^m/(1 - P_n^f)), & \text{if } u_n = 0 \end{cases}$$
 (3)

The probabilities of false alarm and missed detection of the *n*th local detector are denoted as P_n^f and P_n^m , respectively. Note that in (Mirjalily, 2003) the authors presented analytical solution for the above problem in the case of binary classification. Note that in a particular setting if the data size is limited



Figure 4: Fourth Decision Tree.

(2)



Figure 5: Classification Fusion System.

and/or the number of events needed for accurate calculation of anomalies is not sufficient we developed a maximum likelihood based algorithm that exploits the multinomial probability mass function describing the decision vector and utilized in order to estimate the anomalies as well as prior probabilities (seizure and no-seizure). We presented the details of these algorithms in (Liu et al., 2014).

3 RESULTS

To evaluate the performance of the proposed algorithm we plan to use several commonly used performance metrics F1-score and recall as most of the lung cancer datasets are imbalanced due to the nature of the disease. Recall is defined as a ratio of true positives and summation of true positives and false negatives and F1-score is defined as a harmonic mean of the precision and recall.. In Table 1 we illustrate the performance results for 50-50 split in which only 50% of the data was used for training. The results include both average value and variance since the performance of machine learning algorithms is heavily dependent on the training dataset. In Table 2 we illustrate similar results but for training ratio split 90-10.

Table 1.

	av. R.	av. F1	var R	var F1
GB	79%	77%	0.7%	3%
XGB	73%	67%	0.6%	2.1%
RF	82%	63%	0.9%	0.8%
Fus,	86%	82%	0.8%.	0.6%

Table 2.

	av. R.	av. F1	var R	var F1
GB	80%	83%	0.9%	1.9%
XGB	79%	80%	1.1%	3.1%
RF	88%	84%	1.2%	0.9%
Fus,	92%	89%	1.1%.	0.6%

4 CONCLUSIONS

In this paper we demonstrated applicability of several machine learning models in order to determine the life status of lung cancer patients after certain period of time. Due to the limited nature of the dataset available fully temporal model was not developed as it would require larger data set in order to evaluate performance dependence on the time passed. Our preliminary results indicate that significant accuracy can be achieved assuming that all the relevant parameters are measured/monitored and available which further emphasizes the need for standardized data management. Due to the fact that the performance of machine learning models is heavily dependent on data set, an effort should be made in order to investigate performance of the proposed techniques, especially fusion, on larger data sets. Given a sufficiently large data set, we would be able to compare the performance of our fusion model to an unsupervised model in which the prediction results would be fused using another layer of machine learning models.

Furthermore, the proposed techniques can be extended to create soft decision algorithms in which outcomes would be given with certain probabilistic confidence. However to achieve this goal, which would include temporal dependence, an effort should be made to obtain a database in which sufficient status information exists for variety of patients and sufficiently large temporal points. The main advantage of this approach would be to provide life expectancy estimate in addition to survival probability at a particular time.

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