





Efficient Computation of Base-pairing Probabilities in Multi-strand RNA Folding

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Abstract: RNA folding algorithms, including McCaskill's partition function algorithm for computing base pairing probabilities, can be extended to $N \geq 2$ interacting strands by considering all permutations π of the N strands. For each π , the inside dynamic programming recursion for connected structures needs to be extended by only a single extra case corresponding to a base pair connecting exactly two connected substructures. This leaves the cubic running time unchanged. A straightforward implementation of the corresponding outside recursion, however results in a quartic algorithm. We show here how cubic running time asymptotically equal to McCaskill's partition function algorithm can be achieved by introducing linear-size auxiliary arrays. The algorithm is implemented within the framework of the ViennaRNA package and conforms to the theoretical performance bounds.


1 INTRODUCTION


RNA molecules not only form intramolecular base pairs but also interact with other RNAs according to the same rules to form hetero-polymeric complexes. RNA-RNA interactions play an important role in eukaryotic gene regulation, see (Guil and Esteller, 2015) for a recent review: The best known example is the binding of microRNAs (miRNAs) to their mRNA targets in post-transcriptional gene silencing. Recently, a plethora of different modes of action have been reported. Both small interfering RNAs (siRNAs) and long non-coding RNAs (lncRNAs) can regulate splicing. The lncRNA *TINCR* binds several mRNAs to control translation. MiRNAs as well as other ncRNAs are involved in the regulation of miRNA biogenesis from their primary precursors. LncRNAs may act as


“sponges” to bind and sequester miRNAs. A zoo of small RNAs (sRNAs) has also been described in prokaryotes, many of which act as regulators of translation by directly binding to their mRNA targets, reviewed e.g. in (Dutta and Srivastava, 2018). Hetero-duplexes between spliceosomal RNAs are crucial for the assembly of the spliceosome, and many of the chemical modifications of ribosomal RNAs require the base pairing between small nucleolar RNAs (snoRNAs) and rRNAs. Recent advances in transcriptome-wide experimental approaches have revealed an unexpected extent of RNA-RNA interactions (Gong et al., 2018), suggesting that – similar to the protein case – complexes composed of more than two RNAs may also play important roles. Such higher order complexes have already been considered extensively in synthetic biology (Isaacs et al., 2006; Chappell et al., 2015).

RNA structures are efficiently modeled by their secondary structures, i.e., at the level of discrete base pairs. Together with a set of empirically well-supported energy parameters for the stacking

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of base pairs and the destabilizing effects of unpaired “loops” (Turner and Mathews, 2010), efficient dynamic programming algorithms are available to compute ground state structures (Zuker and Stiegler, 1981) as well as the partition function of the equilibrium ensemble of secondary structures (McCaskill, 1990). Most routine applications consider only pseudoknot-free structures, i.e., structures without crossing base pairs (i, j) and (k, l) with $i < k < j < l$, see (Reidys, 2011). The same physical principles govern the interaction of two or more RNA molecules, and thus similar combinatorial models are applicable. The interaction of two or more RNA strands naturally leads to a class of structures that includes pseudoknot-like structures and thus is difficult to handle computationally. An example is the RIP model of Alkan et al. (2006), for which the computation of base-pairing probabilities is still feasible for pairs of RNAs (Chitsaz et al., 2009; Huang et al., 2009). A combinatorial model that captures the multi-strand case was introduced by Mneimneh and Ahmed (2015). A greedy, helix-based approach that allows essentially unrestricted matchings is described by Bindewald et al. (2011). The combination of local structures and interactions can be formalized also as a constrained maximum weight clique problem (Legendre et al., 2019). An alternative class of approaches restricts the interaction of a pair of RNAs to a single sequence region in each partner, making it possible to decompose the energy of interaction in contributions for unfolding the interaction sites and their hybridization (Busch et al., 2008; Mückstein et al., 2008; Bernhart et al., 2011).

Here we are concerned with a simplified model that excludes such pseudoknot-like features (and thus also some important types of interactions including kissing-hairpins). We stipulate that the heteropolymeric complex can be understood as secondary structure formed by a conceptual concatenation of the interacting strands. The corresponding folding problems thus remains equivalent to the case of a single RNA molecule (Zuker and Stiegler, 1981; McCaskill, 1990). For two strands, this model has been analyzed in detail by Dimitrov and Zuker (2004), Andronescu et al. (2005), and Bernhart et al. (2006). Even for multiple ($N > 2$) strands, the folding problem remains very similar to the single strand folding problem in this setting. It suffices to assign different energy contributions to substructures (“loops”) that contain one or more breakpoints between strands (Dirks et al., 2007). An implementation for the general case is available in NUPACK (Zadeh et al., 2011). Kinetic simulations of multi-strand cofolding have been studied by Schaeffer et al. (2015).

It is important to note that binding energies between strands in heteropolymeric structures are intrinsically concentration dependent because the number of particles changes when polymeric structures are formed (Dimitrov and Zuker, 2004). In partition function computations it is therefore important to treat complexes separately that are composed of different compositions of strands. RNACoFold (Bernhart et al., 2006) handles this issue as a post-processing step: first a partition function Z_{AB} over all conformation of two strands is computed, from which the contribution $Z_A Z_B$ of the separated monomers is subtracted. This approach quickly becomes tedious for higher-order interactions, however. In NUPACK, Dirks et al. (2007) therefore introduced a different strategy in which partition functions are computed that sum only over conformations that are connected. This does not significantly change the recursions of McCaskill’s algorithm for a single RNA molecule (McCaskill, 1990). This approach reduced the complications arising from disconnected structures but in return complicated the outside recursion, i.e., the computations of base pairing probabilities.

The computation of base-pairing probabilities for multiple interacting RNAs conceptually follows McCaskill’s outside recursions (McCaskill, 1990). The key issue is that in order to compute the probability of a base pair (k, l) one needs to explicitly handle the case that the focal base pair (k, l) is located in a loop \mathcal{L} with closing pair (i, j) that contains *exactly* one concatenation point (“nick”) between strands *in the loop* \mathcal{L} . As a consequence, the structure on the sequence interval $[i, j]$ becomes disconnected upon removal of the pair (i, j) . While conceptually simple, the practical difficulties arise from the fact that all partition function variables computed in the inside recursions only cover connected substructures, and hence the cases with a nick in the exterior loop need to be handled separately. It is the purpose of this contribution to show how this can be achieved efficiently.

2 INSIDE RECURSION

Consider $N \geq 1$ RNA strands with a total length n . We are interested here in the ensemble of connected structures that are *crossing free* in at least one permutation of the strands, that is, if (i, j) is a base pair, then (k, l) with $i < k < j$ is a base-pair only if $i < l < j$. As shown in (Dirks et al., 2007), the sets of crossing free structures are invariant under *circular permutations* of the strands, while the sets of connected structures generated from other permutations of strands π are disjoint. As an immediate consequence, it is pos-

sible, therefore, to compute the base pairing probabilities $p_{k,l}$ in a given complex of N RNA strands as (weighted) sums of the base pairing probabilities $p_{k,l}[\pi]$ of all permutations π that fix the first strand (Dirks et al., 2007). Each permutation π contributes with a weight proportional to its partition function $Q[\pi]$, i.e., $p_{k,l} = \sum_{\pi} w(\pi) p_{k,l}[\pi]$ with $w(\pi) = Q[\pi]/Q$, where $Q := \sum_{\pi} Q[\pi]$ is the total partition function of the complex. It thus suffices to investigate the inside and outside recursions for a fixed permutation π . We can therefore assume that the strands are indexed by $s = 1, \dots, N$ and the nucleotides are numbered consecutively by $i = 1, \dots, n$.

The standard energy model for RNA folding distinguishes three types of “loops”: *hairpin loops*, which contain no further interior base pairs, *interior loops*, which contain exactly one interior base pair, and *multi-branch loops* (multi-loops for short), containing two more consecutive pairs. Stacked base pairs, the main stabilizing contribution of RNA structures, are treated as special case of interior loops. While energy contributions for hairpin and interior loops are tabulated as function of sequence and length of the unpaired stretches, a linear approximation is used for multiloops. This both reduced the number of parameters to a manageable size and ensures that the recursions require $O(n^3)$ time and $O(n^2)$ space.

As discussed in detail in (Dirks et al., 2007), the main difference between McCaskill’s original approach (McCaskill, 1990) to computing partition functions and the generalization to multi-strand problems is the interpretation of the variables: instead of computing partitions over *all* structures, the computations are restricted to *connected* structures. Interestingly, this introduces only a small modification to the standard recursions.

Denote by Q_{ij} the partition function over all crossing-free connected structures on the interval $[i, j]$. Analogously, Q_{ij}^B denotes the partition function over all crossing-free connected structures on the interval $[i, j]$ that are enclosed by the base-pair (i, j) . For hairpin loops, which contain no interior base pairs, i and j thus must be located on the same or consecutive strands. Interior loops have a single enclosed base pair (p, q) with $i < p < q < j$. Multi-branch loops are handled in the standard RNA folding model based on a linear approximation of the folding energy that makes it possible to decompose every multi-loop into its closing base pairs (i, j) , a part $Q_{i+1, u}^M$ containing at least one stem, and a part $Q_{u+1, j-1}^I$ comprising exactly one stem, see (McCaskill, 1990) for details. If the structure on $[i, j]$ to which the closing pair is added is already connected, the recursions are the same as in McCaskill’s original algorithm. In the

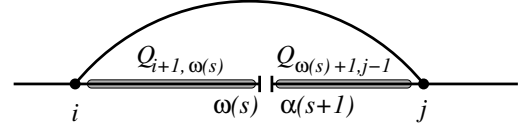


Figure 1: **Nicked loop case in the inside recursion.** The base pair (i, j) , as usual represented by an arc, connects two connected components separated by a single nick between $\omega(s)$ and $\alpha(s+1) = \omega(s) + 1$. Since nicked loops are exterior, connected secondary structures on the intervals $[i+1, \omega(s)]$ and $[\alpha(s+1), j-1]$ contribute independently. Note that the nick can also be adjacent to i or j , in which case one of the two intervals is empty, and thus formally contributes as factor of 1 to the partition function.

multi-strand case, however, connected structures also arise by combining exactly two disjoint connected components by means of the closing pair (i, j) . This gives rise to an additional term in the decomposition of Q_{ij}^B (Dirks et al., 2007).

From an energetic point of view, the loop closed by (i, j) is an external loop. Using $\omega(s)$ to denote 3’-most nucleotide position of strand s , the contribution of “nicked loops” is

$$Q_{ij}^N = \sum_{s: i \leq \omega(s) \leq j} e^{-\varepsilon_{ij}/RT} Q_{i+1, \omega(s)} Q_{\omega(s)+1, j-1} \quad (1)$$

with the additional constraint that either i and $i+1$ as well as $j-1$ and j must be on the same strand, or the nick is adjacent to the base pair, in which case either $i = \omega(s)$ and $j-1$ and j are on the same strand, or $j-1 = \omega(s)$ and i and $i+1$ are on the same strand. The energy term ε_{ij} contains only the so-called dangling end terms (Turner and Mathews, 2010). A graphical representation is given in Fig. 1.

3 OUTSIDE RECURSION

Complementary to the structures on $[k, l]$ enclosed by a pair (k, l) , McCaskill’s approach considers the ensemble of partial secondary structure on $[1, k] \cup [l, n]$ that contain the base pair (k, l) . Such “outside ensembles” can always be constructed as complements of “inside ensembles” (Höner zu Siederdisen et al., 2015). For fixed π , we consider here the partition function $\widehat{Q}_{k,l}[\pi]$ over all connected partial secondary structures outside of the base pair (k, l) . Clearly a secondary structure containing (k, l) is connected if and only if both the substructures inside and outside of (k, l) are connected. Thus $\widehat{Q}_{k,l}[\pi] Q_{k,l}^B[\pi]$ is the partition function over all connected structures that contain the pair (k, l) and the base pairing probabilities for fixed π can be computed as $p_{k,l}[\pi] = \widehat{Q}_{k,l}[\pi] Q_{k,l}^B[\pi] / Q[\pi]$, where $Q[\pi] = Q_{1,n}[\pi]$ is the partition function over all connected secondary structures.

The base pairing probability $p_{k,l}$ in a given complex of RNAs is therefore given by

$$p_{k,l} = \sum_{\pi} w(\pi) p_{k,l}[\pi] = \frac{1}{Q} \sum_{\pi} \widehat{Q}_{k,l}[\pi] Q_{k,l}^B[\pi]. \quad (2)$$

As outlined in (Dirks et al., 2007), these values can then be used to obtain further derived quantities such as expected number of base pairs connecting any two strands. Equ.(2) implies that it suffices to compute the $p_{k,l}[\pi]$ separately for all π . From here on, we therefore suppress the reference to the fixed permutation π .

Following McCaskill (1990), $\widehat{Q}_{k,l}$ can be computed from three mutually exclusive subsets of structures: (1) the contribution $\widehat{Q}_{k,l}$ of structures in which (k,l) is not enclosed by any other base pair and (2) the contribution of structures in which (k,l) is enclosed by another base pairs (i,j) . The second case can further be subdivided into two disjoint contribution $\check{Q}_{k,l} + \check{Q}_{k,l}$ depending on whether the loop enclosed by (i,j) contains (2a) no nick or (2b) exactly one nick. If there were two or more nicks, the structure would not be connected. The recursions for $\widehat{Q}_{k,l}$ and $\check{Q}_{k,l}$ are identical to the ones developed by McCaskill (1990). They have been presented repeatedly in the literature, we therefore do not recall them here. The naïve implementation of the recursions for $\widehat{Q}_{k,l}$ and $\check{Q}_{k,l}$ requires $O(n^4)$ time. With the help of auxiliary arrays of size $O(n)$, however, they can be modified to allow evaluation in cubic time (McCaskill, 1990; Lorenz et al., 2011).

Here, we study the additional multi-strand case $\check{Q}_{k,l}$ in detail. The notation below is consistent with implementation in the ViennaRNA package. Following Lorenz et al. (2011) we also allow terms of the form $Q_{i,i-1} = 1$, denoting empty intervals. This considerably simplifies the notation since boundary cases do not need to be treated explicitly. For each strand s we define $\alpha(s)$ and $\omega(s)$ to denote its 5'-most and 3'-most nucleotide position with respect to the fixed order to the strands. To this end, we write $\sigma(i)$ for the strand that contains position i , i.e., $\sigma(i) = s$ iff $\alpha(s) \leq i \leq \omega(s)$. The *same-strand indicator function* is given by $\xi_i = 1$ if $\sigma(i) = \sigma(i+1)$ and $\xi_i = 0$ otherwise. We write $\bar{\xi}_i := 1 - \xi_i$.

In order to compute $\check{Q}_{k,l}$ we separately consider the case that the single nick in the loop containing (k,l) is located 5' (left) of (k,l) , i.e., between i and k , and the case that the nick is found 3' (right) of (k,l) , i.e., between l and j . Clearly, these cases are mutually exclusive.

Hence we can write

$$\check{Q}_{k,l} = \check{Q}_{k,l}^{5'} + \check{Q}_{k,l}^{3'} \quad (3)$$

with

$$\check{Q}_{k,l}^{5'} = \sum_{\substack{1 \leq i < k \\ l < j \leq n}} \widehat{Q}_{i,j} Q_{l+1,j-1} \times \sum_{s | i \leq \omega(s) < k} Q_{i+1,\omega(s)} Q_{\omega(s)+1,k-1} \quad (4)$$

$$\check{Q}_{k,l}^{3'} = \sum_{\substack{1 \leq i < k \\ l < j \leq n}} \widehat{Q}_{i,j} Q_{i+1,k-1} \times \sum_{s | l < \alpha(s) \leq j} Q_{l+1,\alpha(s)-1} Q_{\alpha(s),j-1} \quad (5)$$

In this form, the computation of a single entry $\check{Q}_{k,l}$ requires $O(n^2N)$ operations for N strands with a total length n , leading to an overall running time of $O(n^4N)$. This time complexity is much worse than cubic running time of all other components of the partition function algorithm. Since the pairing probabilities need to be computed for all $(N-1)!$ non-cyclic permutations of the strands, the additional factor nN is a serious practical burden. Our goal is therefore to reduce the time complexity by rearranging the recursions for $\check{Q}_{k,l}^{5'}$ and $\check{Q}_{k,l}^{3'}$ at the expense of introducing additional arrays to store intermediate results.

4 COMPUTING $\check{Q}_{k,l}$ IN CUBIC TIME

Let us assume that position l is fixed and we compute the values of $\check{Q}_{k,l}$ consecutively for all k . The basic idea is then to pre-compute and store contributions that depend only on l and are required for all k . Let us first consider $\check{Q}_{k,l}^{5'}$, i.e., Equ.(4). Fixing the second index k only affects the number of choices for i and s . Moreover, a particular strand s already determines the number of choices for i , since $i \leq \omega(s)$. We may, therefore, pre-compute parts of the outside contribution for each s with $\omega(s) < l$ and all possible i , and j . We store these values in auxiliary array

$$Y_s^{5'} = \xi_l \sum_{j>l} \xi_{j-1} Q_{l+1,j-1} \times \left(\widehat{Q}_{\omega(s),j} + \sum_{i<\omega(s)} \xi_i \cdot \widehat{Q}_{i,j} \cdot Q_{i+1,\omega(s)} \right). \quad (6)$$

This array has size $O(N)$ and each entry is computed on $O(n^2)$ time, hence the total effort is $O(n^2N)$. Figure 2 gives a graphical representation of the contri-

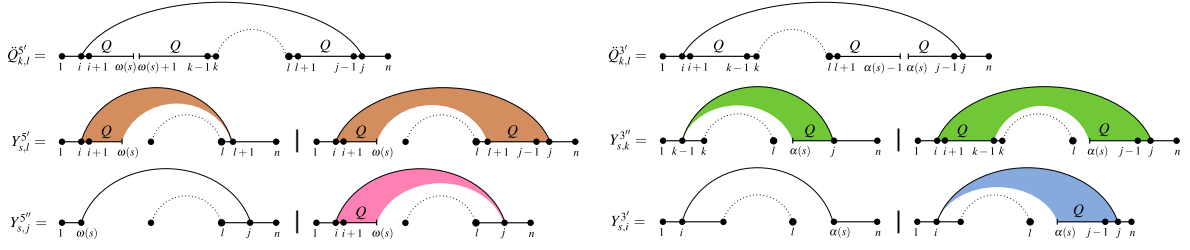


Figure 2: **Auxiliary arrays for RNA multi-fold base pair probabilities.** The first line consists of a schematic representation of all contributions that need to be considered when a base pair (k, l) is enclosed by another pair (i, j) and effectively forms a loop with a strand-change (nicked loop). We explicitly distinguish the two cases $\tilde{Q}_{k,l}^{5'}$ and $\tilde{Q}_{k,l}^{3'}$, where the nick appears to the left ($5'$) and to the right ($3'$) of the pair (k, l) , respectively. To efficiently compute both contributions, we introduce the two auxiliary arrays $Y_{s,l}^{5'}$ and $Y_{s,k}^{3'}$ (2nd line) to store and re-use pre-computed contributions that are independent of the choice of i and j . This reduces the effort to compute $\tilde{Q}_{k,l}^{5'}$ and $\tilde{Q}_{k,l}^{3'}$ to a sum over the strands s . Still, for different l and k , parts of the contributions stored in these two auxiliary arrays are computed repeatedly. Hence, to keep the computational effort as small as possible, we add two further arrays $Y_{s,j}^{5''}$ and $Y_{s,i}^{3''}$ (3rd line) to store these parts for reuse. Finally, both multi-strand cases can be evaluated for all possible pairs (k, l) in $O(n^2N)$ total time.

Contributions captured by $Y_s^{5'}$. We can now re-write Equation (4) as

$$\tilde{Q}_{k,l}^{5'} = \bar{\xi}_{k-1} Y_{\sigma(k-1)}^{5'} + \bar{\xi}_{k-1} \sum_{s|\omega(s)<k} Q_{\omega(s)+1,k-1} Y_s^{5'}. \quad (7)$$

Each of the $O(n^2)$ is now computed in $O(nN)$ time, hence we have already reduced the complexity by a factor of n . A further reduction is obtained by observing that parts required to compute $Y_s^{5'}$ for l can be re-used when $Y_s^{5'}$ is computed for $l-1$. This is due to the fact that the major difference between consecutive entries is only a single extra value of j . On the expense of an additional $O(nN)$ memory and explicitly denoting k , we re-write (6) as

$$Y_{s,l}^{5'} = \xi_l \left(Y_{s,l+1}^{5''} + \sum_{j>l+1} Q_{l+1,j-1} \cdot Y_{s,j}^{5''} \right) \quad (8)$$

$$Y_{s,j}^{5''} = \xi_{j-1} \left(\hat{Q}_{\omega(s),j} + \sum_{i<\omega(s)} \xi_i \hat{Q}_{i,j} \cdot Q_{i+1,\omega(s)} \right) \quad (9)$$

Since $Y_{s,j}^{5''}$ is independent of l and k , we can even re-use the corresponding stored contributions throughout all computations for any pair (k, l) . However, care has to be taken to properly interleave the computations of $Y_{s,j}^{5''}$ into the part that loops over variable l . More precisely, the required contributions $\hat{Q}_{i,j}$ only become available for $l < j$. Still, the time complexity to pre-fill all $Y_{s,j}^{5''}$ is $O(n^2N)$. Hence, the time complexity for (8) reduces to $O(n)$, and the overall time complexity to compute (7) becomes $O(n^2N)$.

Let us now focus on the second case and assume that the single nick is located $3'$ of base pair (k, l) . Here, we can apply the same re-arrangement and pre-computation as above. First, we observe that fixing a

value of k only affects the possible choices of i . But this time, the contributions to the left of the nick do not contain a re-usable factor independent of k . This is due to the fact that (i) we always require the full contribution of $Q_{i+1,k-1}$ and (ii) the strand-changes we need to consider only depend on the current value of l . There are contributions on the right, however, that can be pre-computed. Consider the $O(nN)$ terms

$$Y_{s,i}^{3'} = \xi_i \left(\hat{Q}_{i,\alpha(s)} + \sum_{j>\alpha(s)} \xi_{j-1} \hat{Q}_{i,j} Q_{\alpha(s),j-1} \right) \quad (10)$$

These terms are independent of both k and l . Hence they need to be computed only once and can then be re-used for any pair (k, l) . Using equ.(10), equ.(5) can be rewritten as

$$\tilde{Q}_{k,l}^{3'} = \xi_{k-1} \sum_{i<k} \xi_i Q_{i+1,k-1} \times \left(\bar{\xi}_j Y_{\sigma(l+1),i}^{3'} + \xi_l \sum_{s|\alpha(s)>l} Q_{l+1,\alpha(s)-1} Y_{s,i}^{3'} \right), \quad (11)$$

which can be evaluated in total time $O(n^3N)$ for all k and l at the expense of storing the nN auxiliary values $Y_{s,i}^{3'}$. Still, the effort asymptotically exceeds McCaskill's cubic-time algorithm by a factor $O(N)$. To further reduce the computational time, we observe that the order of summation in equ.(11) can be changed in such a way that the inner sum becomes independent of l . We can therefore pre-compute

$$Y_{s,k}^{3''} = \xi_{k-1} \sum_{i<k} \xi_i Q_{i+1,k-1} Y_{s,i}^{3'} \quad (12)$$

for all possible k and any strand s in total time $O(n^2N)$ and store it with additional memory requirements of $O(nN)$. Taken together, we have now removed the

dependence of k from l , and can, therefore, re-use (12) for all pairs (k, l) . Similar to equ. (7), equ. (5) can now be rewritten as

$$\tilde{Q}_{k,l}^{3'} = \bar{\xi}_l Y_{\sigma(l+1),k}^{3''} + \xi_l \sum_{s|\alpha(s)>l+1} Q_{l+1,\alpha(s)-1} Y_{s,k}^{3''}. \quad (13)$$

and be evaluated in $O(n^2N)$ time provided that the $O(nN)$ values of $Y_{s,k}^{3''}$ are stored. Again, due to the dependence of $Y_{s,i}^{3'}$ on $\hat{Q}_{i,j}$, proper interleaving into the recursion is necessary. But this can be easily achieved by filling $Y_{\sigma(l+1),i}^{3''}$ for all i if $\xi_l = 1$ and subsequently re-compute $Y_{s,k}^{3''}$. Figure 2 gives a graphical representation of the class of structures contributing to $Y_{s,k}^{3''}$.

The additional effort to compute the auxiliary arrays thus matches the added effort for the inside recursion of the multi-strand problem, namely $O(n^2N)$ time, though with extra $O(nN)$ space. In any reasonable application scenario, the number of strands is much smaller than their total length, i.e., $N \ll n$. Under this assumption, the additional resources required for the multi-strand version of McCaskill's partition function algorithms therefore are asymptotically negligible compared to the cubic running time and quadratic memory consumption of the single-strand problem.

5 IMPLEMENTATION AND BENCHMARKING

The inside and outside recursions for a fixed permutation π of strands has been implemented as part of ViennaRNA package (Hofacker et al., 1994; Lorenz et al., 2011). This initial version of RNAmultifold, which is available as part of release 2.5.0alpha, is primarily intended for testing and benchmarking. Although functional, it does not yet provide all features of partition function algorithms. For instance, no corresponding minimum energy folding algorithm is available at this point. Future versions of RNAmultifold will feature further optimizations making use of the fact that for $N > 2$ strands some parts of the arrays for different permutations are the same and thus need not be recomputed.

A generic difficulty in practical implementations of partition function algorithms are overflow and underflow errors due to the exponential terms. The ViennaRNA package therefore does not directly compute the partition functions as outlined above. Instead, scaled partition functions of the form $z_{ij} := Z_{ij}/\zeta^{j-i+1}$ are computed. The scaling constant ζ is an *a priori* estimate of $\sqrt[n]{Z}$, i.e., the average contribution

of a single nucleotide to the overall partition function (Hofacker et al., 1994). It can be estimated by $\zeta = \exp(-E^*/nRT)$, where E^* is the expected ground state energy. As described by Hofacker et al. (1994), ζ can be estimated for connected structures with a simple regression model. This scaling keeps the values of Z_{ij} and its restricted versions sufficiently close to unity to avoid overflow and underflow errors for sequence lengths of at least $n \leq 10^4$. Since the effect of the nicks on the ground state energy is bounded above by the sum of the energies of the loops that contain the nicks, ζ can be estimated with sufficient accuracy to ensure numerical stability from the ground state energy of the concatenation of the strands, i.e., by ignoring the nicks.

In order to benchmark the performance of our implementation we compare running time and memory consumption of the preliminary version of RNAmultifold with RNAfold (Lorenz et al., 2011), RNAcofold (Bernhart et al., 2006), and NUPACK (Zadeh et al., 2011). As input we generated 10 random sequences for each length and subdivided these into a different number of strands. This choice of benchmark data is designed to minimize sequence-specific variations between instances with different numbers of strands. The performance measurements for RNAmultifold and NUPACK are summarized in Fig. ???. We also compared RNAmultifold with the previously available components of the ViennaRNA package.

RNAfold, and RNAcofold use identical energy parameters. As expected, for $N = 1$ the results of RNAmultifold and RNAfold coincide within the expected numerical inaccuracies; for $N = 2$ we obtained the same output for RNAmultifold and RNAcofold. We observed no significant differences in memory consumption. RNAfold is 10-15% faster than RNAmultifold. In contrast, we found that the outside recursion of RNAmultifold is approximately twice as fast as the version implemented in RNAcofold. Because of the small differences between RNAmultifold and RNAfold or RNAcofold, resp., the latter are not shown separately in Fig. ??.

As expected from the theoretical considerations above, we find that both memory consumption and running time of RNAmultifold becomes independent of N for large n . The number of strands plays a noticeable role only when the average length of individual strands is smaller than about 20 nt. We found, furthermore, that RNAmultifold consistently outperforms NUPACK 3.2.2. For large sequences, the inside recursion of RNAmultifold is about 35× and the outside recursion is about 50-65× faster. The memory consumption is about 7× lower.

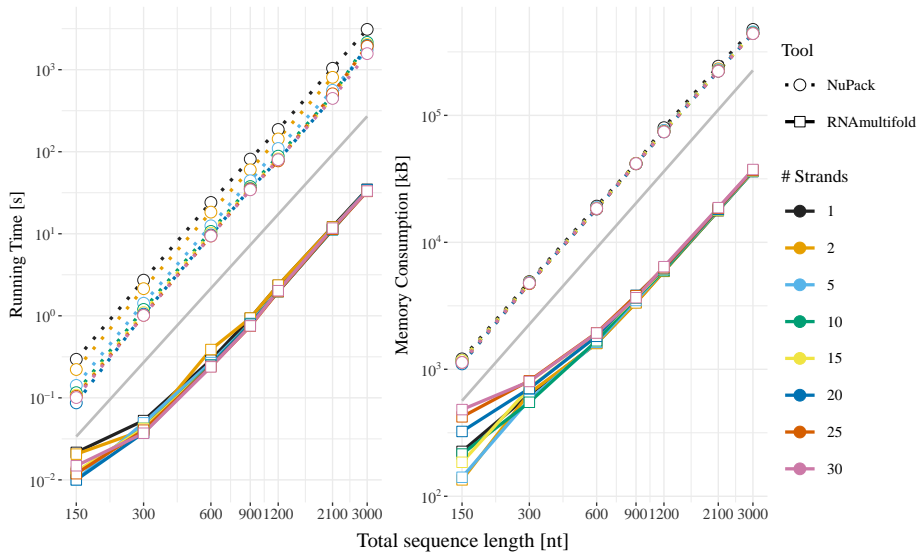


Figure 3: **Comparison of the performance measures** for NUPACK (version 3.2.2) and RNAmultifold for different total sequence length n and different number N of strands. Each data point is the average over 10 random instances. The thin lines indicate $O(n^3)$ and $O(n^2)$ for running time and memory consumption, respectively.

RNAmultifold uses the full framework for handling constraints in the ViennaRNA package and thus supports user-defined hard and soft constraints (Lorenz et al., 2016), such as experimental probing data or forbidden base pairs. It also handles intra-strand G-quadruplexes in the same way as in case of a single strand (Lorenz et al., 2013).

6 FUTURE WORK

We have shown here that the base pairing probabilities in the multi-strand RNA folding problem can be computed in $O(n^3)$ time and $O(n^2)$ space for a fixed permutation π of the strands. We provide an implementation within the framework of the ViennaRNA package that has negligible overhead compared to RNAfold and RNAcifold. The performance gain compared to NUPACK, at present the only competing software, is nearly an order of magnitude in memory and about a factor of 50 in running time.

A full-fledged implementation of multi-strand folding will also include a minimum free energy routine as well as a facility to enumerate suboptimal structures (Wuchty et al., 1999). Here, one has to take special care to properly treat the energy penalties associated with structures with symmetries that appear in particular in homo-dimers and -multimers (Hofacker et al., 2012). Stochastic backtracing makes it possible to sample individual structures with Boltzmann probabilities (Tacker et al., 1996; Ding et al.,

2004). As a straightforward extension of the partition function algorithms, this feature will also become available with the next release of RNAmultifold. We also plan to implement the extension of RNA folding grammar necessary to handle multiple ligand binding sites (Forties and Bundschuh, 2010) again making use of the constraints framework of Lorenz et al. (2016). A closer inspection of the folding recursions for different permutations π and π' shows that parts of the arrays are identical. In a forthcoming version of RNAmultifold we will utilize this fact to further reduce the computational efforts.

The concentration dependence of the different multi-strand complexes under equilibrium conditions are of practical importance in particular for design tasks. Since the partition functions computed here refer to connected structures, i.e., complexes with a given composition, it is easy to compute the equilibrium constants for the association/dissociation of complexes: For reactions of the form $A_1A_2\dots A_k + B_1B_2\dots B_l \rightleftharpoons A_1A_2\dots A_kB_1B_2\dots B_l$ we have equilibrium constants $K = Z_{A_1A_2\dots A_kB_1B_2\dots B_l} / Z_{A_1A_2\dots A_k} Z_{B_1B_2\dots B_l}$. As described previously in the literature (Dimitrov and Zuker, 2004; Bernhart et al., 2006; Dirks et al., 2007), the law of mass action together with mass conservation leads to a system of non-linear equations for the concentrations that, by detailed balance, is guaranteed to have a unique positive solution. This makes it possible to compute the equilibrium concentrations given only the total concentrations of the RNA strands as input.

For the complete analysis, *RNAmultifold* will be extended to automatically enumerate all permutations π and all complexes consisting of subsets of the input strands up to a maximum interaction order. It will then compute equilibrium constants and solve the resulting non-linear system of equations to obtain concentrations for each complex. To reduce the combinatorial explosion of permutations and compositions, users will be able to supply a list of complexes that are of interest. An automatic selection of the maximal interaction order may be achieved by starting with the smallest complexes, increasing the maximum interaction order step by step, until the computed equilibrium concentrations do not change significantly anymore.

AVAILABILITY

RNAmultifold can be downloaded as part of ViennaRNA Package 2.5.0a1 from www.tbi.univie.ac.at/RNA.

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