

# Study on Laminar Flow Field Characteristics in Stirred Tank with Different Combinations of Dual Impellers

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**Abstract.** The numerical simulation of the flow field generated by dual impellers in glycerol was carried out by using CFD method and laminar flow model. The flow field structure of four combinations of impellers under different spacing and constant rotation speed of 200 rpm in the stirred tank is obtained, and axial and radial velocity vectors and velocity distribution curves are compared and analyzed. The results show that when the distance between layers is greater than or equal to  $T/2$ , the flow pattern of the flow field is parallel flow, and the distribution of the two straight blades is the best. When the distance between layers is less than  $T/3$ , the flow pattern is connected flow, at this time, the combination of the run-off impeller under the axial propeller is the best.

## 1. Introduction

With the development of technology and the expansion of production scale, the volume of industrial agitator reactor tends to be large, and most of the high-diameter ratio is usually greater than 1. The distribution range of the materials involved is also very wide, which includes the low viscosity fluid with the fast settlement of solid particles and the non-newtonian fluid with high viscosity and shear thinning properties. This requires the use of double-layer and multi-layer impellers and effective combination to ensure the mixing effect of the reactor. At present, the research on the single layer paddle stirred tank in the flow characteristics [1-6], mixing time [7-10], energy dissipation [11-12], wake vortex structure [13-15] and the impact of blade height from the bottom [16-17] is quite in-depth and systematic. Lightnin company in USA has developed a new type of axial flow impeller by using experiment and CFD simulation technology, such as efficient A310, A315 and A340 series [18-19] that the pitch and width of the blade vary with its radial position, which can effectively improve the efficiency of mixing, and the D&R work of wing-shaped impeller is gradually being carrying out in china. The mixing characteristics of two layers and multi-layer impeller [20-29] have also been studied. Hao Zhigang et al. [30] studied the dispersion of gas in a stirred tank with different mixing impellers, and considered that the combination of the run-off impeller under the axial propeller the radial paddle was the most suitable for gas-liquid dispersion. Liang Yingna et al. [31] used the CFD laminar flow model to simulate the double-layer straight-skewed impeller blade combination and analyzed the structural characteristics of different forms of flow field.

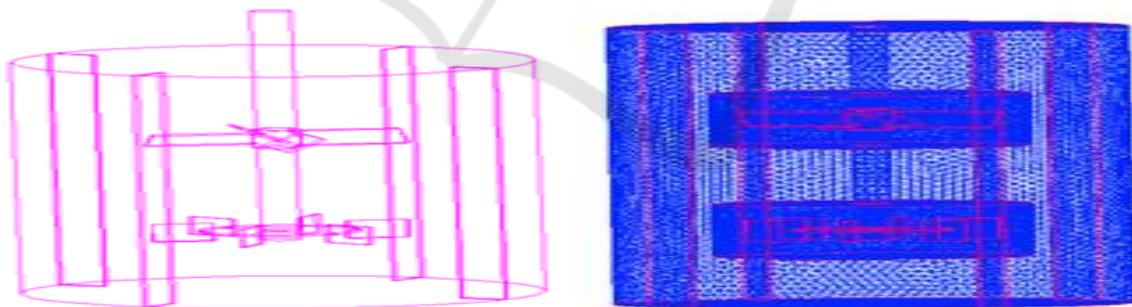
Up to now, the research on the flow of stirred tanks with two-layer and multi-layer impellers mainly focuses on turbulent flow conditions. However, the research on the flow field characteristics of laminar flow in high viscosity system is relatively few, and the effect of layer spacing on flow is

not considered. For the double-layer impellers reactor, the flow structure is mainly determined by the geometric combination of the two layers of paddles and the interaction between the two layers of paddles. Most of the interlayer spacing reported in the literature is relatively large. The vast majority of interlamellar spacing reported in the literature is relatively large. The flow in a stirred tank can be thought of as a superposition of two impellers, and the two impellers produce their own flow patterns with little or no interaction. However, when the distance between layers is small, the interaction between impeller jets is very obvious and the flow field becomes very complicated. Due to the unpredictability of such complicated flow field, the design and analysis of multi-layer paddle stirred tank in industrial production have been affected to a certain extent.

Therefore, in this paper, four different two-layer combination impellers consisting of 6-bladed radial disc turbines (6DT) and pitch 4-bladed turbines (4PBT) are used to simulate the flow generated by the propeller in glycerin. Using CFD software FLUENT, numerical simulation is performed to analyze the flow field characteristics of the combined impellers with two-runoff paddle, two-inclined impeller and multi-impeller of runoff impeller and inclined impeller at different layer spacings, and the suitable layer spacing and suitable combination for laminar flow are given impeller form, provide a useful reference for the design of industrial multi-layer paddle stirred reactor.

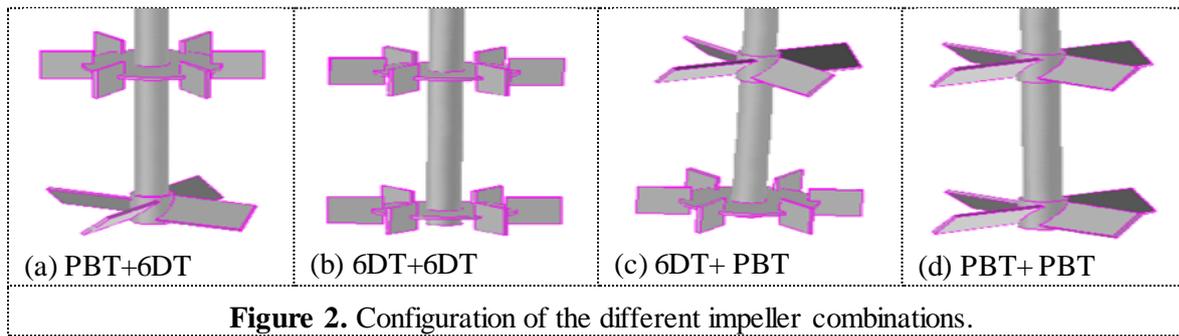
## 2. Stirred tank structure and meshing

Flat-bottomed cylindrical tank diameter  $T = 210\text{mm}$ , around the four uniform full baffle, baffle width  $w = T / 10$ , tank level of glycerol  $H = 1.25T$ , density  $\rho = 1259.9\text{kg} / \text{m}^3$ , viscosity  $\mu = 0.799\text{Pa}\cdot\text{s}$ ; shaft diameter  $d = 16\text{mm}$ , impeller diameter  $D = T/2$ , width  $h = D/5$ , blade thickness  $\delta = 2\text{mm}$ . Bottom paddle center height from the bottom of the tank  $C_1 = T/3$ , the distance between the center of the upper and lower impeller is  $C_2$ , the origin is located in the center of the bottom impeller, impeller around the z-axis rotation. For six-straight turbine blades, blade length  $a = D/4$ , disk diameter  $d = 3D/4$ , for diagonal quad-blade, hub diameter  $d_j = 20\text{mm}$  height. Stirrer  $b = 22\text{mm}$  speed are  $N = 200\text{rpm}$ , corresponding to the leaf tip linear velocity  $U_{ip} = 1.15\text{m/s}$ , Reynolds number  $R_e = 57.95$ , the flow within the tank is in the laminar flow state.



**Figure 1.** Model configuration and mesh of the stirred tank.

The whole calculation domain is divided into two sub-regions of stator and rotor. The rotor region adopts the rotating coordinate system, and the static coordinate system is adopted in the static subregion. Using unstructured tetrahedron grid for discrete, as shown in Figure 1, the rotor area uses a more detailed grid whose cell number is about 346000, and the number of the stator area cell grid is about 358000, which is sparse.



**Figure 2.** Configuration of the different impeller combinations.

In this paper, the lower impeller is pitch 4-bladed turbine and the upper paddle is 6-bladed radial disc turbine, which is represented by PBT + 6DT. The other paddle combinations are expressed in the same way. There are four kinds of impellers in combination: PBT + 6DT, 6DT + 6DT, 6DT + PBT, PBT + PBT, as shown in Figure 2.

### 3. Fluid mechanics model and simulation method

Assumptions: (1) The time-averaged movement of the fluid is a steady flow, ignoring the effect of the periodic motion of the impeller on the macroscopic movement of the fluid. (2) The fluid is a continuous incompressible fluid.

In the numerical analysis, the fluid control equation can be written as the following conservation form:

$$\frac{\partial(\rho\phi)}{\partial t} + \text{div}(\rho\mathbf{u}\phi) = \text{div}(\Gamma \cdot \text{grad}\phi) + S \quad (1)$$

Where:  $\rho$  is the fluid density,  $t$  is time,  $\Gamma$  is the generalized diffusion coefficient,  $S$  is a generalized source term,  $\phi$  is a field variable that varies with time,  $\mathbf{u}$  is the velocity vector whose component is represented by  $u_r, u_\theta, u_z$  in the cylindrical coordinate system.

The mixing tank used for the simulation is a flat-bottomed cylindrical structure. In order to facilitate the analysis and the characteristics of the mixing tank, the governing equation can adopt the following cylindrical coordinates:

$$\begin{aligned} & \frac{\partial}{\partial t}(\rho\phi) + \frac{\partial}{\partial z}(\rho u_z \phi) + \frac{1}{r} \frac{\partial}{\partial r}(r \rho u_r \phi) + \frac{1}{r} \frac{\partial}{\partial \theta}(\rho u_\theta \phi) \\ & = \frac{\partial}{\partial z} \left( \Gamma \frac{\partial \phi}{\partial z} \right) + \frac{1}{r} \frac{\partial}{\partial r} \left( \Gamma r \frac{\partial \phi}{\partial r} \right) + \frac{1}{r} \frac{\partial}{\partial \theta} \left( \frac{\Gamma}{r} \frac{\partial \phi}{\partial \theta} \right) + S \end{aligned} \quad (2)$$

The model boundary conditions are set as follows: the symmetry boundary condition are used at the free surface and the interface between the rotor and the stator is set to interface condition. Using Multiple Reference Frames (MRF) method, the fluid in the rotor region is set to rotate at the same speed as the impeller while the fluid in the stator region is stationary. The inner wall of the tank is defined as a stationary wall condition, and the stirring shaft and the paddle are set as moving wall. The stirring shaft rotates relative to the stator and the impellers do not rotate with the rotor.

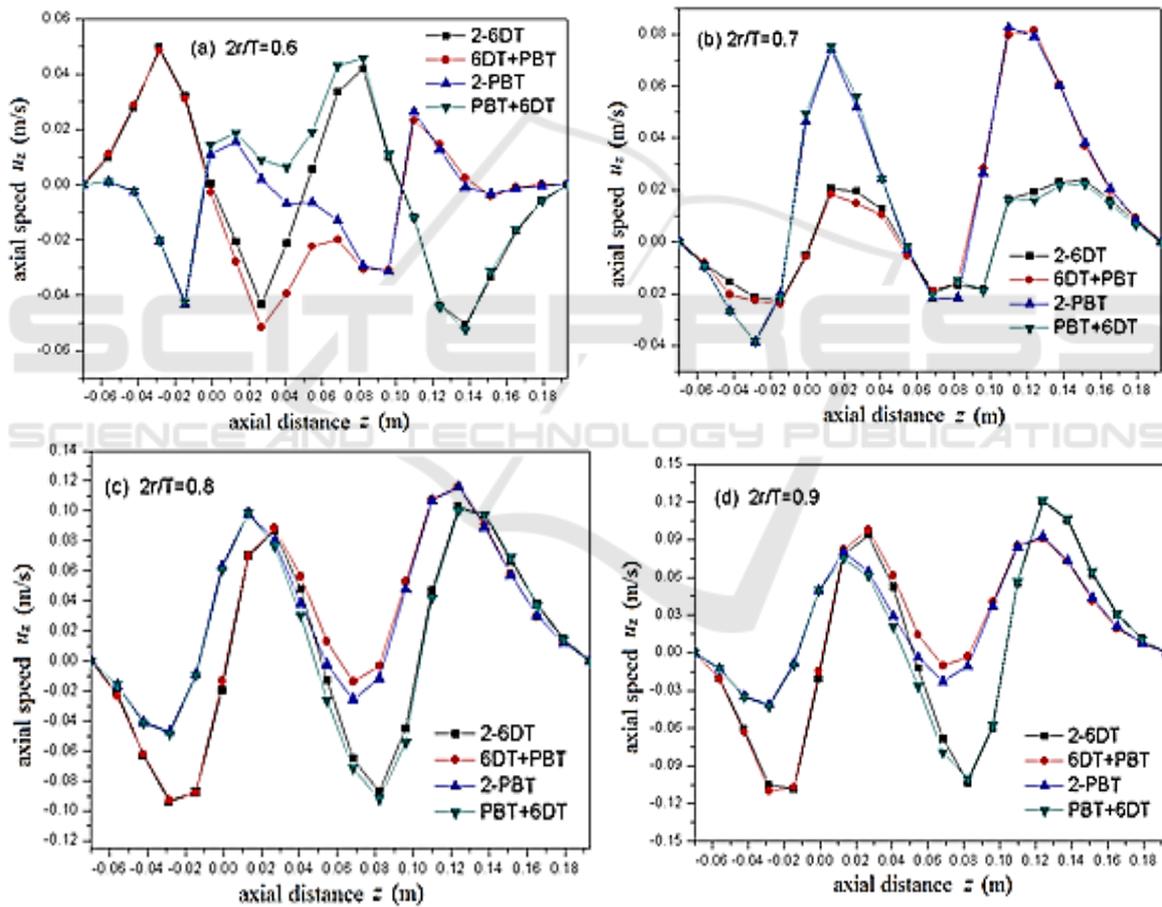
The steady-state implicit separation algorithm was used and the Laminar viscosity model was chosen. The momentum was discretized by the first-order upwind scheme, and the SIMPLEC algorithm was used for the coupling of pressure and velocity. The convergence residuals of all the variables were all less than  $1 \times 10^{-4}$ . And the initial conditions is zero.

#### 4. Calculation results and discussion

The velocity field is the basis for optimizing the stirring reactor, and the distribution of shearing rate can be obtained, also the distribution of displacement can be obtained by differentiating the velocity field. On the basis of obtaining the velocity field, the distribution of temperature field and concentration field can be obtained with the proper model equation. Besides, the problems of the power dimensionless number, the cycle time distribution and the mixing time can be solved. Therefore, the following is mainly for the analysis of the velocity field distribution, taking the axial longitudinal section of stirred tank as the object of the study.

Figure 3~ 6 shows distribution curves of the axial velocity and radial velocity of four combined paddle agitators in different radial positions and  $y=0$ ,  $z$  from  $-70\text{mm}$  to  $193\text{mm}$ . In the paper, when the axial velocity is the same as the positive direction of  $z$  axis, the axial velocity is positive, and vice versa. The radial velocity is positive when the stirred slurry is pointing to the direction of the cell wall, and vice versa.

1) Layer spacing  $C_2=T/2$ :



**Figure 3.** Axial profiles distribution of axial speed at different radial positions.

Figure 3 shows the the variation of axial velocity along the axial profiles at different radial positions, and at the bottom and top of the trough, the axial velocity is zero. As shown in Figure 3 (a), at  $2r/T=0.6$  radial position, the axial velocity distribution of the combined impeller agitators with two-layers six straight blades (2-6DT) is superior to the other impeller, embodying in: under the lower impeller  $z = -28\text{ mm}$ , the first upward (positive) velocity perturbation appeared with a value of

0.05 m/s; After the first wave, axial velocity curve downwards rapidly (positive is becoming negative). Above the lower impeller  $z = 27$  mm, the first downward (negative) velocity trough appeared with the value of 0.044 m/s, slightly inferior to the 0.05 m/s trough wave value of 6DT+PBT combined impeller agitators; Then the velocity curve changes the direction again, and at  $z = 82$  mm (below the upper propeller), the second velocity wave appeared with the value of 0.043 m/s. Afterwards, the axial velocity changes from the positive to the negative again. At  $z = 138$  mm (above the upper blade), the second velocity trough is obtained with the value of 0.05 m/s. In the distance from the second trough to the liquid level, the axial velocity decreases gradually and becomes zero at the liquid level. From Figure 3 (b), we can see that the positive and negative of the axial velocity of 6DT change, which reveals that between the radial position of the  $2r/T = 0.6$  and  $2r/T = 0.7$ , there exists a whirlpool. While axial velocity direction of PBT at different radial position has remained the same, indicating that the whirlpool radius formed by PBT is less than 6DT. From Figure 3 (c) (d) we can see, with the enlargement of the radial position, a variety of combinations are showing a curve of two peaks and troughs, and the axial distribution of 2-6DT gets obvious advantages, the maximum axial velocity reaches 0.11 m/s. The above analysis shows that the axial velocity distribution of the 2-6DT is the best at the layer spacing of  $0.5T$ , which is better for the axial mixing of the fluid than the other impellers.

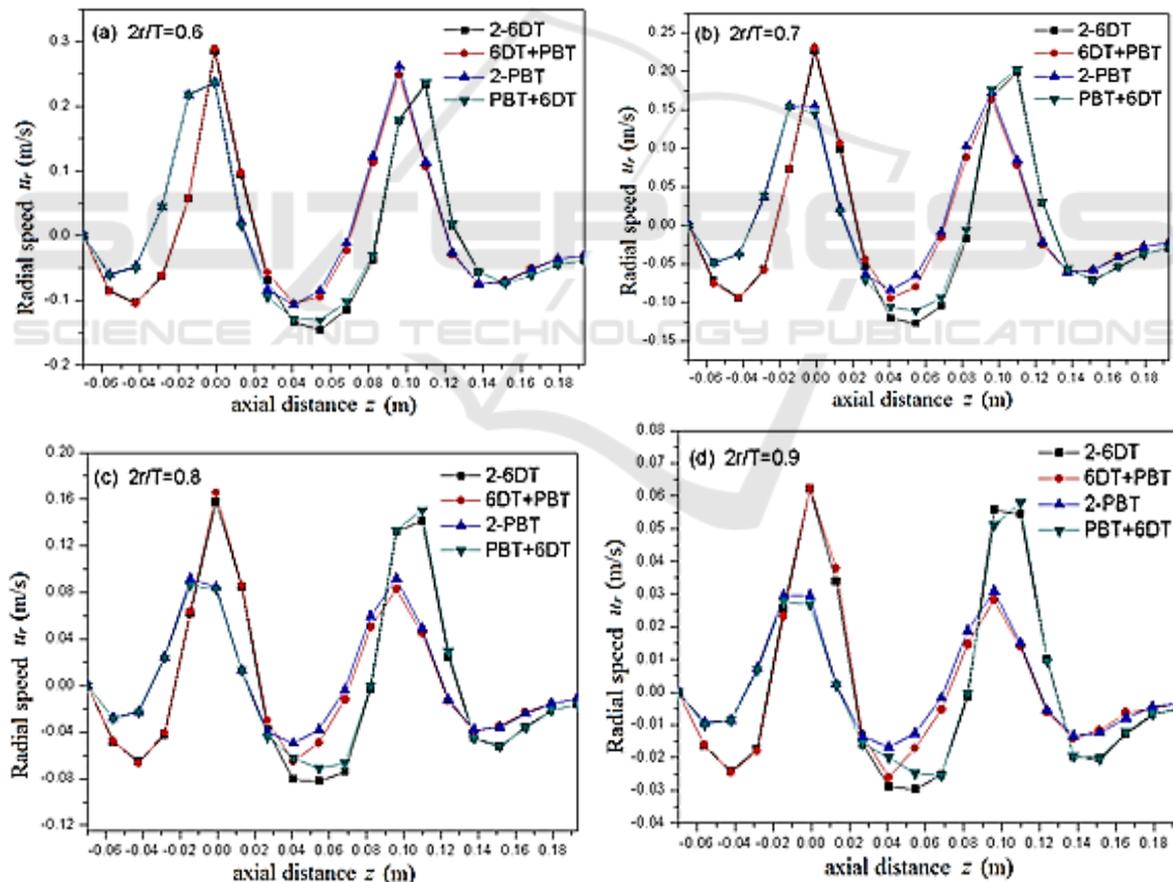


Figure 4. Axial profiles of radial speed at radial positions.

Figure 4 is the variation of radial velocity along the axial height at different radial positions. Combined with Figure 3, we can see that the flow field is superimposed by two single impellers

under the layer spacing, and there is a parallel flow between the layers, which consists with the previous analysis of the flow field structure. Further observation shows that the radial velocity at the bottom and top of the groove is also zero. The radial velocity changes of different oar types show the same wave pattern, and the radial velocity distribution of the 2-6DT is the best, as shown in Figure 4 (a) for the 2-6DT.

The radial velocity is negative in the range of  $z=-20\text{mm}$  from the tank bottom to the lower impeller, which is one of the vortex ring regions. The maximum magnitude of negative radial velocity appears at  $z=-43\text{mm}$  and its value is  $-0.11\text{ m/s}$ . In the range of  $z=-20 \sim 20\text{mm}$ , the radial velocity is positive, which is exactly near the upper and lower level of the lower impeller. Because of the effect of the paddle, the fluid flows to the cell wall and reaches the maximum at  $z=0$ , which is  $0.29\text{ m/s}$ . In the middle of the upper and lower impellers, the negative radial velocity is the maximum and the maximum value is  $-0.15\text{ m/s}$  due to the joint action of the two vortex rings. The second maximum value of the positive velocity appears near the upper impeller, and its value is similar to the first positive maximum magnitude of radial velocity, which is  $0.24\text{ m/s}$ . Above the upper impeller, the third peak of the negative radial velocity, which is the upper vortex ring area. From the vortex ring area to the liquid level, the radial velocity becomes zero gradually.

From the above analysis we come to the conclusion that the two larger positive radial velocities occur on the near edge of the upper and lower impeller, and the three smaller negative radial velocities appear below the lower impeller, between the dual impellers, and above the upper impeller. The positive velocity is greater than the negative velocity, while the negative velocity between dual impellers is greater than below the lower impeller and above the upper impeller. This indicates that the energy loss of the radial flow colliding tank wall is caused by the paddle tip and the backflow velocity decreases. However, the backflow of double - layer vortex ring is combined to make its radial velocity greater.

Through the comparative analysis, when the spacing between the layers is greater than or equal to  $0.5T$ , the flow field is the superposition of two single impellers. In the four combined impellers, the 2-6DT combination is the best.

1) Layer spacing  $C_2=T/3$ :

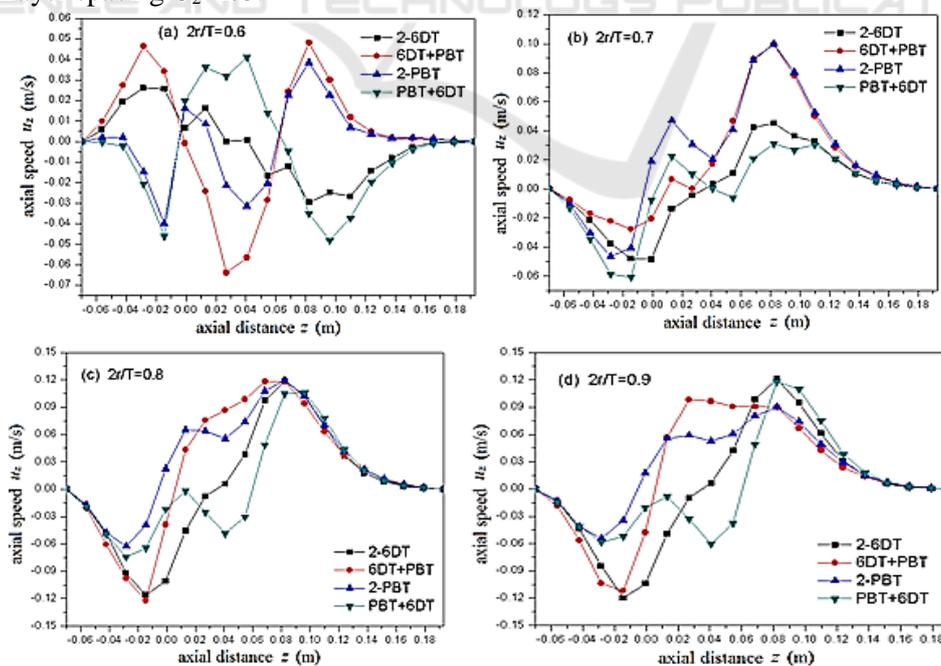
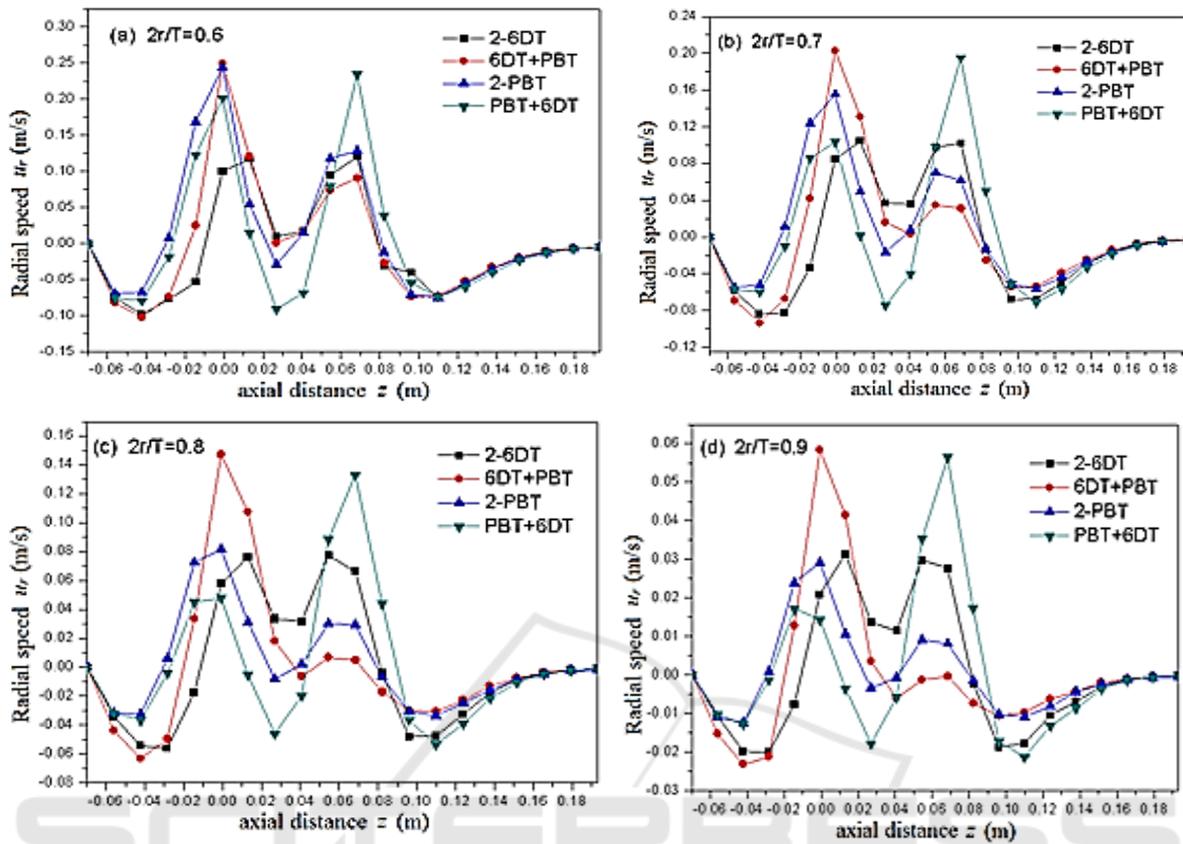


Figure 5. Axial profiles of Axial speed at radial positions.



**Figure 6.** Axial profiles of radial speed at radial positions.

As can be seen from Figure 5 (a), the combination form of 6DT+ PBT is the best when the layer spacing is  $C_2=T/3$ , namely the bottom is the radial flow impeller, and the upper part is the axial flow impeller combination. Take the combination of 6DT+ PBT as an example: the axial velocity at the bottom of the groove is zero, and then the velocity of upward (positive) along the  $z$ -axis increases gradually. At  $z=-28\text{mm}$ , the first upward axial velocity peak is obtained, which is  $0.047\text{m/s}$ . Above the lower oar,  $z=27\text{mm}$ , the maximum magnitude of axial velocity of downward (negative) is reached, which is  $-0.064\text{ m/s}$ . With the increase of axial height, above the upper impeller  $z=85\text{mm}$ , the second upward axial velocity peak is obtained, which is  $0.048\text{m/s}$ . Then the axial velocity decreases gradually, and the axial velocity becomes zero at the liquid level. When in  $2r/T = 0.7$  radial position, as shown in Figure 5(b), axial velocity of 6 DT oar steers, so between the two radial position there exist vortex. While the Figure 5(b) is closer to the vortex, making 6 DT oar axial velocity decrease; With the increase of the radius, the axial velocity distribution of 6 DT + PBT combination is generally better than other one, especially areas between the two oars get obvious advantages, as shown in Figure 5(c), (d), it is highly advantageous for the axial mixing of fluid.

From Figure 6 we can see that, when layer spacing is  $T / 3$ , there is the tendency of "continuous flow" between two impellers. The lower impeller sucks almost all of the fluid that is discharged by the upper impeller, forming the whole kettle large cycle. Axial flow between layers is greatly enhanced, but the radial velocity decreases accordingly, from the point of velocity curve, 6 DT + PBT is the best combination.

When layer spacing  $C_2 = T / 4$ , layers are completely "continuous flow" (due to the page limitation, this paper does not show its axial and radial velocity distribution), and the axial velocity gradient between the layers is enhanced obviously, the upper and lower two impellers combining 2 to 1, like a paddle. 6 DT + PBT combination advantage is more obvious, the fluid that is discharged by

the upper PBT was almost sucked by the lower impeller vertically. The simulation results are similar to the literature [31], which verifies the correctness of the simulation results in this paper.

Based on the above analysis, when the layer spacing is less than or equal to  $T/3$ , flow features with the continuum between the layers and layer partition gradually disappears. The axial flow will no doubt greatly enhance the fluid mixing. According to the velocity distribution curve of different radial positions, the 6DT+ PBT combination has the advantage.

## 5. Conclusions

- 1) When layer spacing is greater than or equal to  $T/2$ , the flow field is for the superposition of two single impellers, and there exists the partition phenomenon between layers. Its flow is parallel. The flow field structure of the four combinations is four vortex ring pattern, in which axial and radial velocity distribution of the 2-6DT combination is relatively good.
- 2) When layer spacing is less than or equal to  $T/3$ , the flow in the kettle is the connection flow; When the spacing of the layers is less than or equal to  $T/4$ , the two upper and lower impellers merge into one, like a single impeller. The flow field structure is two upper and lower vortex rings model, and the axial flow is significantly enhanced. Therefore, the combination of 6DT+ PBT is more conducive to fluid mixing under smaller layer spacing.
- 3) In the four agitators, the flow field structure at the bottom of the lower tank is almost impervious to the spacing of the layers.

## Nomenclature

$\rho$ fluid density (kg/m <sup>3</sup> )	$t$ time (s)
$\Gamma$ generalized diffusion system	$s$ generalized source item.
$\phi$ field variable	$\mathbf{u}$ velocity vector (m/s)
$u_r$ radial velocity component (m/s)	$u_z$ axial velocity component (m/s)
$T$ tank diameter (m)	$N$ stirring speed (RPM)

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