

FLOW AND PARTICLE DEPOSITION IN THE TURBUHALER DPI

A CFD Simulation

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Abstract: In this work the steady-state flow in a commercial dry powder inhaler device (i.e., Turbuhaler) is described. The DPI geometry is constructed in a CAD/CAM environment (i.e., CATIA v5) and then imported into GAMBIT where the geometry is discretized into a computational grid. The Navier-Stokes equations are solved using FLUENT (v6.3) and particle motion and deposition are described using an Eulerian-fluid/Lagrangian-particle approach. Flow and particle deposition for a range of mouthpiece pressure drops (i.e., 800-8800Pa), as well as particle sizes corresponding to single particles and aggregates (i.e., 0.5-20 μ m) are examined. The total volumetric outflow rate, the overall particle deposition as well as the particle deposition sites in the DPI are determined. The simulation results are found to agree well with available experimental data for volumetric flow and overall particle deposition.

1 INTRODUCTION

Dry Powder Inhalers, DPIs, are one of the principle means of delivering pharmaceuticals due to their ease of use and cost-effectiveness. The main function of a DPI device is the adequate dispersion and delivery of particles. Initially the particles are in the form of a loose powder which, under the action of airflow is broken up and dispersed as particle aggregates which are then further broken up into fine particles (Ashurst et al. 2000; Newman and Busse, 2002; Toby et al., 2004; Islam et al., 2008; Alagusundaram et al., 2010). Powder properties, e.g., cohesion, charge, size, and size distribution, influence powder dispersion and the breakage of particle agglomerates (French et al., 1996; Zeng et al., 2000; Finlay, 2001; Newman and Busse, 2002; Chan, 2006).

One of the common problems with DPIs is the loss of powder/drug due to deposition within the device. In order to provide the maximum drug dose per inhalation and to ensure minimal dose-to-dose variation it is necessary to minimize the drug losses due to internal deposition. It is also desired to have good control over the dispersibility of the powder, release of drug (when attached to powder particles),

and breakup of agglomerates in order to achieve the desired particle/agglomerate size distributions at the DPI mouthpiece outflow (Alagusundaram et al., 2010). Consequently, if the underlying processes are better understood one can achieve the desired outflow particle distribution which will conceivably minimize oropharyngeal losses and also permit better targeting for drug delivery in the respiratory tract.

Due to the complex and transient flow structures observed in most commercial DPIs as well as the dynamic powder breakup and dispersion processes only a small number of computational fluid dynamics, CFD, investigations have been conducted (Schuler et al., 1999; Ligothke, 2002). Systematic computational studies have led to a better understanding of the function of DPI devices. For example, Coates et al. (2004, 2005, 2006) studied the Aerolizer DPI in detail including the effects of air-intake, mouthpiece, and internal grid which led to improvements in the design and function of the DPI. Recently, the discrete element method, DEM, coupled to continuous phase-models has been implemented to describe the powder dispersion process within the inhaler (Tong et al., 2010; Calvert et al., 2011). From the current state-of-the-art it is

clear that the proper description of the agglomerate strength as well as the particle/agglomerate interaction with the inhaler walls are key processes that determine the final dispersion and size distribution of pharmaceutical powders (Adi et al., 2011).

The Turbuhaler (AstraZeneca) is a multidose dry powder inhaler that is widely used to deliver a number of drugs (typically for asthma), e.g., terbutaline sulphate, (as Bricanyl), or budesonide (as Pulmicort), to the upper respiratory tract (Wetterlin, 1988). Each dose is initially in the form of loosely packed particle agglomerates, $\sim 10\text{-}20\mu\text{m}$ in size, which are released into a mixing/dispersion chamber, where they are broken up into particles, $\sim 1\mu\text{m}$ in size, which are then directed to the inhalation channel of the device (Tsimia et al., 1994; Wetterlin, 1988). The proper function of the Turbuhaler is dependent on the dynamic volumetric flow as well as the peak inspiratory flow rate attained during inhalation, the amount of particles lost due to deposition within the device, and the adequate dispersion and breakup of the powder agglomerates in the airflow exiting the mouthpiece. Recent experimental investigations have provided detailed information on particle capture as well as the percent and size distribution of escaped particles in the outlet flow (de Koning et al., 2001; Hoe et al., 2009; Abdelrahim, 2010).

In this work the steady airflow in a Turbuhaler DPI is determined by CFD simulations and particle motion as well as deposition is determined by Eulerian-fluid/Lagrangian-particle simulations. In what follows the DPI geometry, the discretization procedure, and the CFD simulations are described in detail. Next the results for steady-state airflow are presented followed by the results for particle deposition. Finally, the computational results are compared to available experimental data.

2 RESULTS

The Turbuhaler DPI geometry was constructed in a CAD/CAM environment (i.e., CATIA v5 R19) and then imported into GAMBIT (v2.1) where a series of computational grids were constructed consisting of $2 \cdot 10^5 - 2 \cdot 10^6$ tetrahedral cells with a maximum skewness of 0.85 (Figures 1 and 2). The computational grids were originally refined in regions where large gradients of flow were expected. Further refinement was conducted within FLUENT based on actual velocity gradients observed in initial solutions.

The Navier-Stokes equations for airflow were solved using the commercial CFD software (i.e., FLUENT v6.3). The SIMPLEC scheme was employed to describe pressure-velocity coupling. Second order discretization was used for pressure and third order MUSCL for momentum and turbulent variables. Convergence of CFD simulations was assumed when the residuals were $< 10^{-4}$. Zero gauge pressure boundary conditions were employed at all the inlets, i.e., two powder loaded cylinders (see bottom of Figure 2b) and four extra air inlets in the DPI dispersion chamber (see Figure 1). Different steady state airflows were simulated by imposing a wide range of pressure drops at the mouthpiece outflow ranging from 800 to 8800Pa which corresponded to volumetric flow rates of 20 to 70 l/min. Steady-state airflow can be considered an approximation to dynamic inhalations where the flow rate has approached the peak inspiratory value.

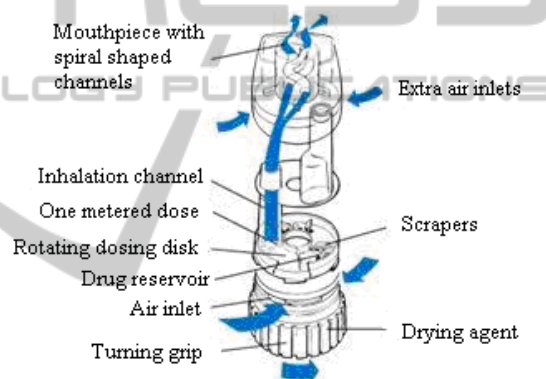


Figure 1: Turbuhaler Dry Powder Inhaler.

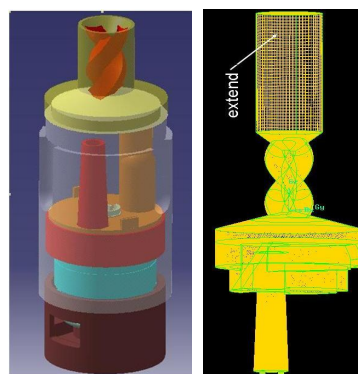


Figure 2: Turbuhaler Dry Powder Inhaler Geometry and Grid ($1 \cdot 10^6$ tetrahedral cells).

Eulerian-fluid/Lagrangian-particle simulations of particle motion and deposition were conducted for particles between $0.5\text{-}20\mu\text{m}$ in size encompassing the single particle and particle agglomerate size

ranges of typical pharmaceutical powders employed in the Turbuhaler. Particles were assumed to be released instantaneously at $t = 0$ and uniformly from a surface located immediately upstream from the powder storage site. Powder dispersion was assumed to occur instantaneously after which no further breakage occurred. Consequently, particles in motion were taken to be constant in size. Upon collision with the inhaler walls particles either deposited or reflected. No collision-induced breakage was examined in this work. The capture efficiency of particles with the inhaler walls was assumed to be either equal to one or a function of the velocity magnitude.

2.1 Simulations of Airflow in the Turbuhaler DPI

According to the range of volumetric airflows examined in this work, e.g. $Q = 20 - 70\text{l/min}$, the local Reynolds numbers, $Re = Q \rho / \mu A^{1/2}$, where ρ and μ are the density and the viscosity of air and A is the cross-sectional area, ranged from 130-16,000. Consequently the transitional SST $k-\omega$ model was employed to describe the transitional turbulent flows encountered in the DPI.

Computational grids varying between $2 \cdot 10^5$ and $2 \cdot 10^6$ tetrahedral elements were employed to test for convergence. The $1 \cdot 10^6$ grid was found to provide essentially identical results as the $2 \cdot 10^6$ grid and was used for the results presented in this paper. It should be noted that the computational grid was extended from the mouthpiece by 20mm in order to minimize recirculation effects at the outflow surface and to improve convergence behaviour.

In Figures 3-5 the velocity magnitudes as well as the tangential and radial velocities are displayed along an axial (i.e., zx) plane and several planes normal to the z -axis (i.e., xy sections). As can be observed, the airflow in the DPI device is found to be laminar in the inhalation channel with two jet flows emanating from the powder storage cylinders. In the dispersion chamber the flow is characterized by large eddies and secondary flows. In the spiral region significant tangential flows develop and persist about halfway up the mouthpiece extension. The tangential motion induced by the spiral airway in the mouthpiece is significant reaching 83% of the maximum velocity magnitude. It should be noted that the velocity profiles observed for larger flow rates, e.g., 60 l/min, are qualitatively similar.

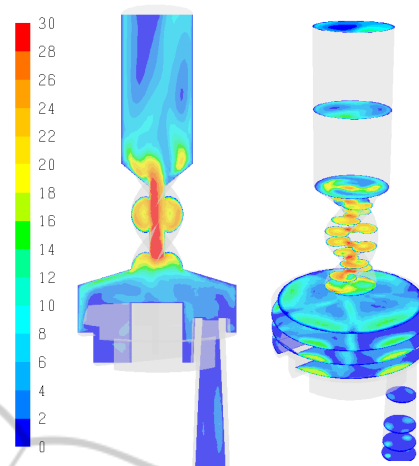


Figure 3: Velocity magnitude in the Turbuhaler DPI (mouthpiece pressure drop $\Delta P = 800\text{Pa}$).

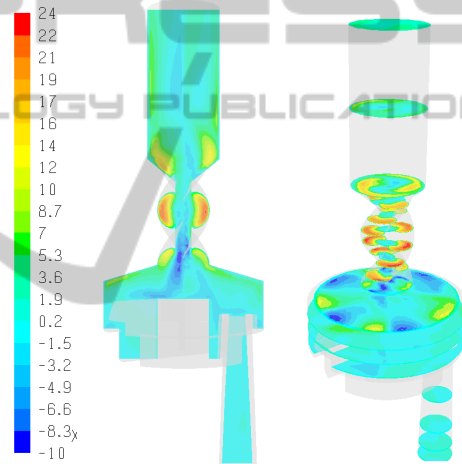


Figure 4: Tangential velocity in the Turbuhaler DPI ($\Delta P = 800\text{Pa}$).

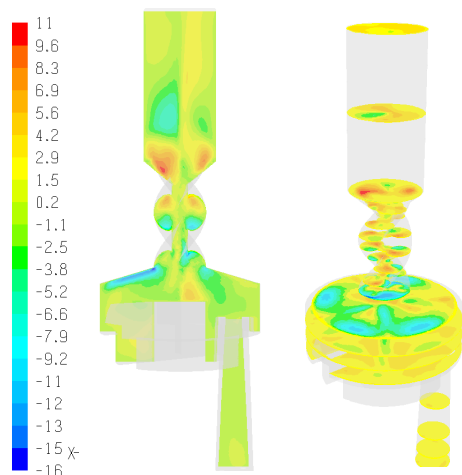


Figure 5: Radial velocity in the Turbuhaler DPI ($\Delta P = 800\text{Pa}$).

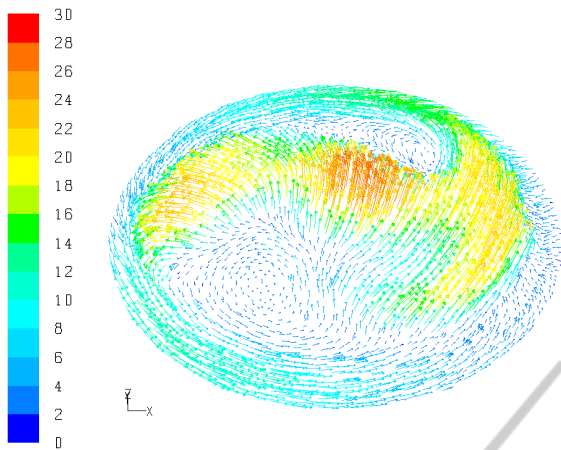


Figure 6: Velocity vectors at the mouthpiece ($\Delta P = 800\text{Pa}$).

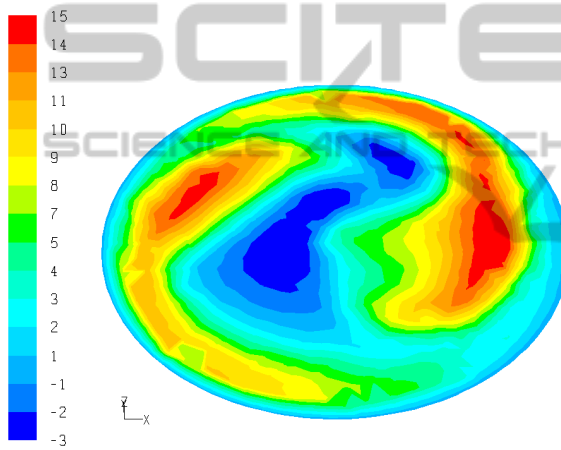


Figure 7: Tangential velocity at the mouthpiece ($\Delta P = 800\text{Pa}$).

The mouthpiece outflow of a DPI is very important as it determines the dispersion and flow behaviour of the particles in the oral cavity and the upper respiratory tract and consequently influences particle losses in the oral cavity and throat regions. In Figures 6 and 7 the mouthpiece outflow for a pressure drop of $\Delta P = 800\text{Pa}$ is shown in terms of velocity magnitude and tangential velocity. It is clear that the flow is strongly influenced from the preceding spiral region and that the axial and tangential components of the velocity are nonuniform. Moreover, the strongly localized tangential and axial airflows at the mouthpiece cause recirculation flows in both the tangential and axial directions, further complicating the flow. Wall-stresses can also be determined based on the CFD solution. In Figure 8 the wall stresses for $\Delta P = 800\text{Pa}$ are shown. It is clear that most of the wall stresses correspond to the high flowing regions

adjacent to the dispersion chamber air inlets and attain their maximum value at the entry and exit regions of the spiral region.

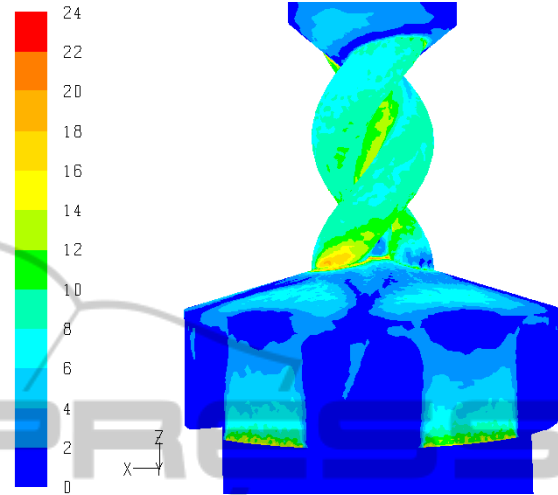


Figure 8: Turbuhaler wall stresses.

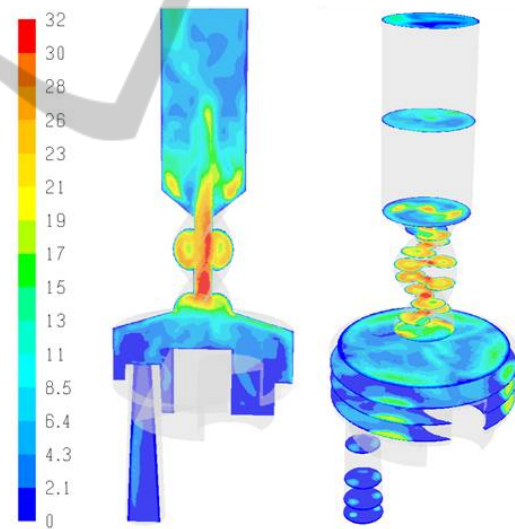


Figure 9: Velocity magnitude in the Turbuhaler DPI – LES results ($\Delta P = 800\text{Pa}$).

Large Eddy Simulations, LES, fully resolve the large scale motion of turbulent flows thus providing more information and accurate results compared to Reynolds Averaged Navier-Stokes approaches, RANS, e.g., $k-\epsilon$, $k-\omega$. The computational burden of LES is significant (e.g., at least an order of magnitude more than with RANS models). Consequently, only a single case (i.e., $\Delta P = 800\text{Pa}$) of steady-state flow of the Turbuhaler DPI was simulated with LES using FLUENT.

In Figure 9 the results for the mean velocity magnitude obtained with LES is shown. The main flow structures are similar with the $k-\omega$ SST results in Figure 3 but, as expected, differences can be observed in the flow details as well as in secondary flows.

The enhanced resolution of eddies and secondary flows with the LES is demonstrated in Figures 10 and 11 depicting the tangential and radial flow, respectively. Compared to the radial and tangential flows predicted with the $k-\omega$ SST model (Figures 4 and 5) there are many differences, e.g., in the large eddies of the mouthpiece extension.

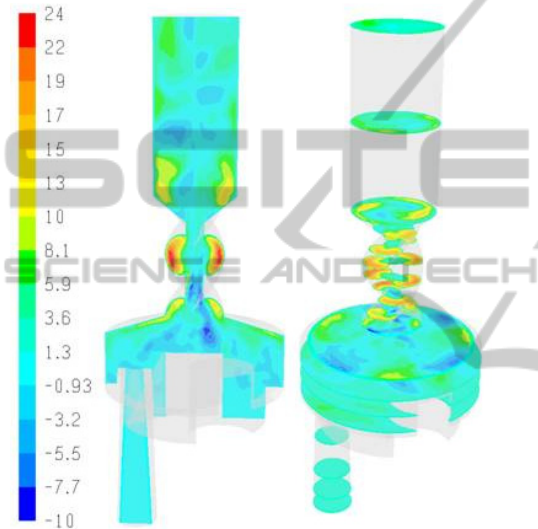


Figure 10: Tangential velocity component in the Turbuhaler DPI – LES results ($\Delta P = 800\text{Pa}$).

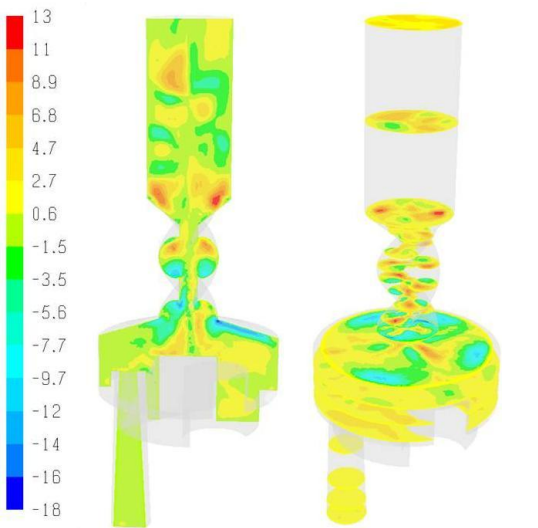


Figure 11: Radial velocity component in the Turbuhaler DPI – LES results ($\Delta P = 800\text{Pa}$).

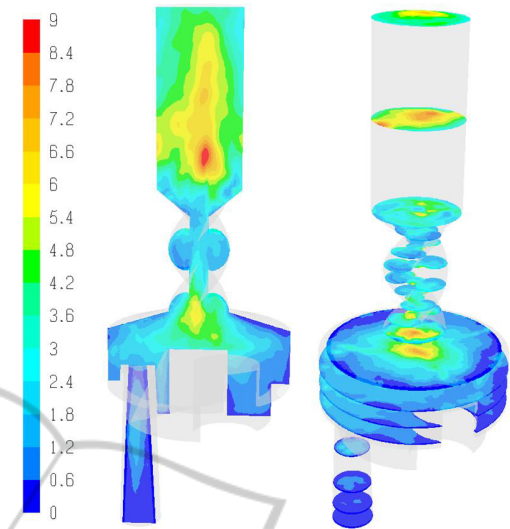


Figure 12: RMS velocity magnitude in the Turbuhaler DPI ($\Delta P = 800\text{Pa}$).

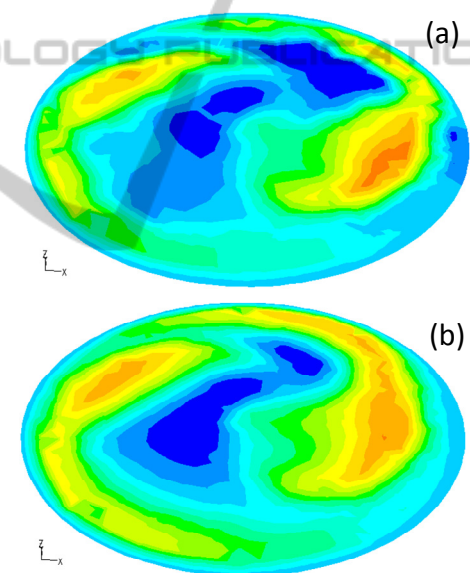


Figure 13: Tangential velocity component at the mouthpiece exit ($\Delta P = 1400\text{Pa}$). (a) LES (b) $k-\omega$ SST.

In Figure 12 the magnitude of the RMS velocity fluctuations is shown. Significant velocity fluctuations are observed at the top of the dispersion chamber ($\sim 6\text{m/s}$) and in the mouthpiece extension ($\sim 9\text{m/s}$). The intensity of fluctuations (e.g., RMS velocity / velocity magnitude) varies within the device up to a value of $\sim 50\%$ indicating significant local fluctuations around the mean for the length scales of flow resolved within the LES.

The RMS fluctuations of the individual velocity components range from 1-8m/s for the axial velocity component and 1-4m/s for the other components

with different spatial variations within the device. These results demonstrate that the fundamental assumption of local turbulence isotropy of the RANS models is incorrect.

In Figure 13 the tangential velocities at the outlet surface for $\Delta P=1400\text{Pa}$ are shown. It is clear that the tangential velocities predicted by the $k-\omega$ SST and LES turbulence models are very similar. In fact the $k-\omega$ SST turbulence model provided the most similar to the LES results compared to the other RANS turbulence models (e.g., standard $k-\epsilon$, RNG $k-\epsilon$). Consequently, despite the observed differences in secondary flows (Figures 9-11) the $k-\omega$ SST model was employed for all the simulations of this work.

2.2 Simulation of Particle Motion and Deposition in the Turbuhaler DPI

Eulerian-fluid/Lagrangian-particle simulations were performed for all the flows examined in section 2.1. These simulations are generally valid for particle volume fractions $<10\%$. For effective powder dispersion the solids volume ratio in the DPI device is approximately 10^{-2} - 10^{-4} depending on the location and the flow rate. Consequently, the particle phase was assumed to not influence the airflow.

The total particle deposition in the DPI device was determined assuming either a 100% capture efficiency or a capture efficiency based on a critical velocity magnitude. The later case was implemented within FLUENT using a user-defined function for the capture efficiency.

Single-sized simulations were performed with particle sizes ranging from 0.5 - $20\mu\text{m}$. Particle sizes 0.5 - $1.5\mu\text{m}$ correspond to individual particle constituents of the agglomerates. Agglomerate breakage and redispersion effects were not considered. Instead, the agglomerates in the powder storage cylinders were assumed to break-up rapidly into their constituent particles. Clearly, agglomerate breakage and flow occur simultaneously and this is an area which requires further investigation.

The total particle deposition in the DPI was found to be strongly dependent on particle size. For micron sized particles inertial forces dominate the deposition process and for particles $<100\mu\text{m}$ gravity can be ignored during the time-scale of a single inhalation. In Figure 14 the total depositions for single-sized particles ranging from 0.5 - $10\mu\text{m}$, for a 100% capture efficiency, and for two pressure drops, e.g., 800 and 1400Pa , are shown. Simulations indicate that for a pressure drop of 800Pa the deposition of 0.5 - $1\mu\text{m}$ particles is 19 - 24% but that of agglomerates 5 - $10\mu\text{m}$ is 90 - 100% . The predicted

total particle deposition in the DPI increases with volumetric flow to large, and unrealistic, values (Figure 14). Smaller deposition values can be obtained by considering less than 100% particle capture efficiency. Other mechanisms such as agglomerate breakage dynamics and/or redispersion of deposited agglomerates could also result in smaller values of particle deposition.

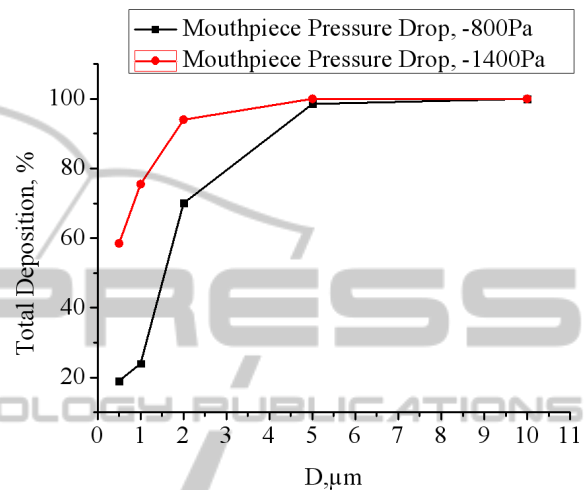


Figure 14: Overall particle deposition in the Turbuhaler.

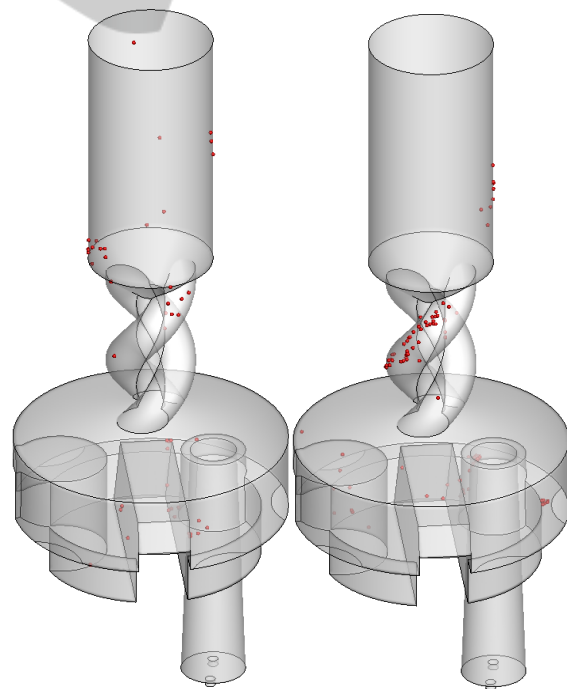


Figure 15: Particle Deposition – Effect of Pressure drop. (a) $\Delta P = 800\text{Pa}$, (b) $\Delta P = 5400\text{Pa}$. $D = 1\mu\text{m}$.

The spatial distribution of particles deposited on the DPI walls was visualized using Tecplot. In Figure 15 particle depositions for two pressure drops, i.e., 800 and 5400Pa, are shown. Thus, the larger pressure drop results increased velocities and total particle deposition but also significantly different particle deposition patterns. The increased deposition for large pressure drops in the spiral region is caused by the increased tangential flow in this region.

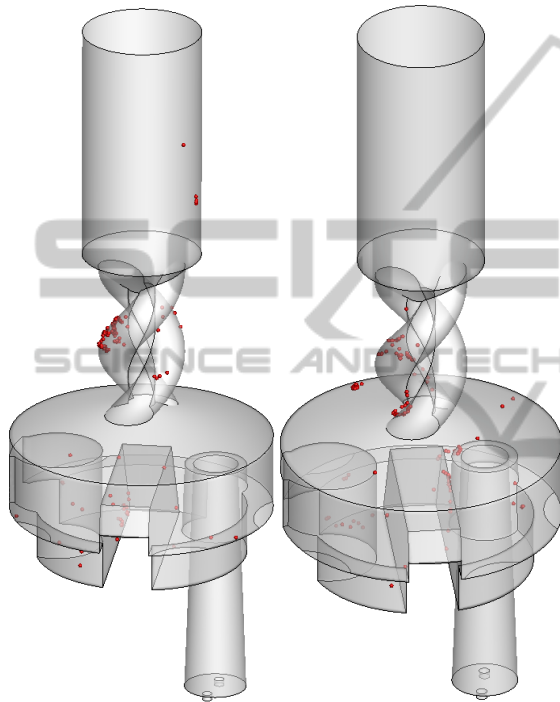


Figure 16: Particle Deposition – Effect of Particle Size. (a) $D = 2 \mu\text{m}$, (b) $D = 5 \mu\text{m}$. $\Delta P = 800\text{Pa}$.

In Figure 16 the effect of particle size on the distribution of deposited particles in the DPI device is shown. Comparing particle sizes of 1 (see Figure 15a), 2 and $5 \mu\text{m}$ (Figure 16) significant differences in the total deposition as well as the deposition distribution are observed. The significant particle deposition that occurs in the mouthpiece region (which includes the spiral region) is actually a common problem in many commercial DPI devices where about half the internal deposition occurs (de Koning et al., 2001).

The results of Figures 15 and 16 can be used to optimize the design of the DPI. For example, the spiral region of the Turbuhaler could be redesigned so that smaller radial and tangential velocities develop leading to decreased particle collisions in this region.

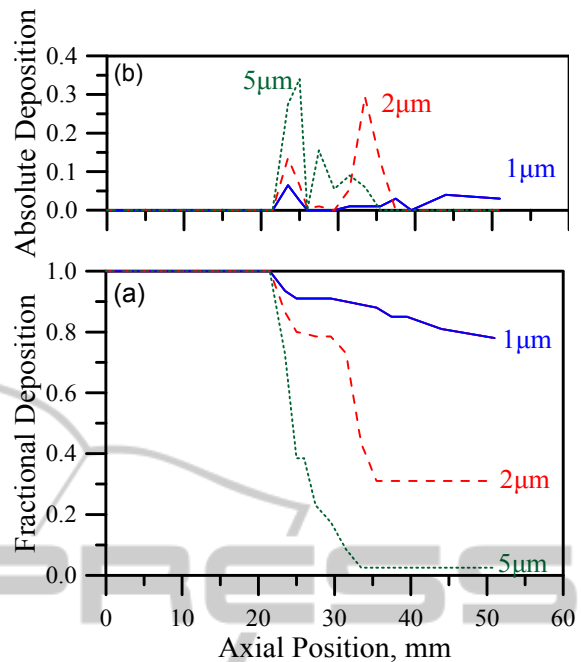


Figure 17: Particle Deposition. (a) Fractional Cumulative Deposition, (b) Local Deposition ($\Delta P = 800\text{Pa}$).

In Figure 17 the axial fractional cumulative deposition distribution and the local fractional deposition for $\Delta P = 800\text{Pa}$ are shown. The results indicate significant differences in the deposition patterns with particle size with most deposition occurring in the dispersion chamber and the spiral region.

2.3 Comparison to Experimental Data

The computational results of this work were compared to the experimental results of de Koning et al (2001) and Abdelrahim (2010) for the Turbuhaler in terms of flow and particle deposition. In Figure 18 the predicted steady-state volumetric flows are plotted against the outlet pressure drop applied at the mouthpiece. Both laminar and $k-\omega$ SST models for flow are examined. It is clear that both models agree very well with the experimental data for all flow rates with the $k-\omega$ SST model being slightly more accurate.

In Figure 19 the total, dispersion chamber, and mouthpiece particle depositions for 1400Pa (or 30 l/min) are compared to the experimental data of de Koning et al. (2001). A 100% capture efficiency leads to very large total deposition values, i.e., 75%, for this flow rate (see Figure 14) and even larger for larger flow rates, e.g., $Q > 30 \text{ l/min}$. Consequently, in this work the capture efficiency is related to a

critical velocity, V_c , above which particles reflect (without deposition or momentum dissipation). Assuming a critical velocity magnitude for deposition, $V_c = 22\text{m/s}$, which results in an overall capture efficiency of $\sim 42.5\%$, the mouthpiece, dispersion chamber, and total particle deposition results for $Q = 30\text{ l/min}$ are in good agreement to the experimental data.

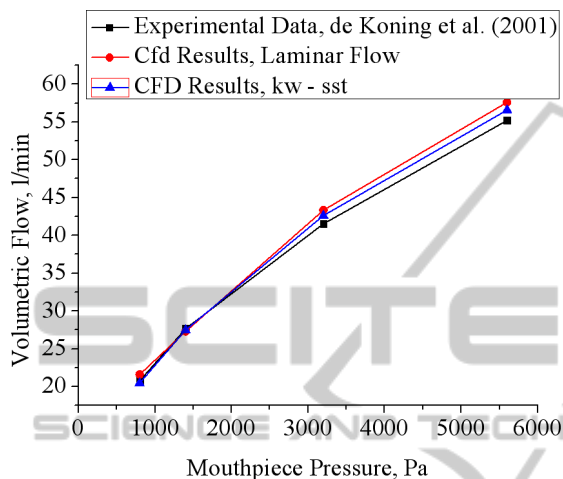


Figure 18: Volumetric flow in the Turbuhaler.

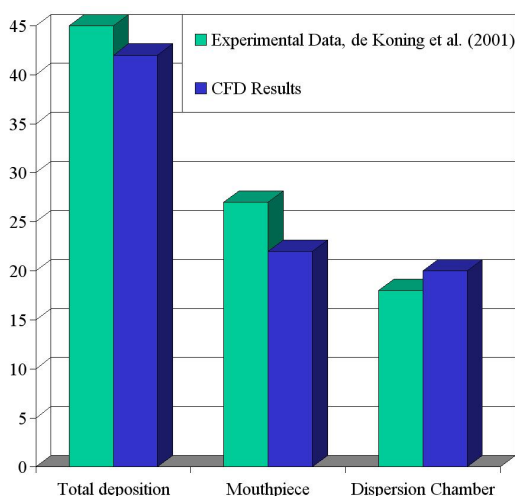


Figure 19: Regional particle deposition in the Turbuhaler. $Q = 30\text{ l/min}$. $V_c = 5\text{ m/s}$.

In Figure 20 the predicted total particle deposition are compared to the experimental data of de Koning et al (2001) and Abdelrahim (2010) for flowrates $Q = 30, 40, 50, 60$ and 70 l/min and for two different inspired volumes, i.e., 2 and 4l (Abdelrahim, 2010). For a critical velocity of $V_c = 22\text{ m/s}$ and a particle diameter of $D = 2\mu\text{m}$ the agreement with the experimental data is good considering the different experimental conditions

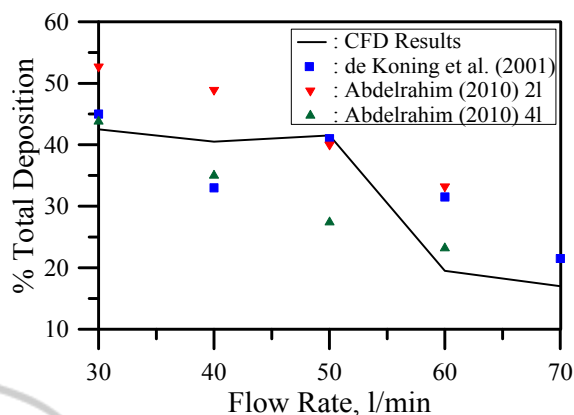


Figure 20: Total particle deposition in the Turbuhaler. $D = 2\mu\text{m}$. $V_c = 22\text{ m/s}$. Comparison between experimental results of de Koning et al. (2001), Abdelrahim (2010) and computational CFD results.

(e.g., dynamic inhalation vs. steady state simulations) and the simplicity of the particle deposition model (e.g., velocity cut-off capture efficiency and single-size size distribution).

3 CONCLUSIONS

This work has demonstrated the use of CFD to determine the complicated airflow as well as particle motion and deposition in the Turbuhaler DPI. As the flow was either locally laminar or transitionally turbulent the transitional SST $k-\omega$ model for turbulence was employed. LES results revealed some differences in the large eddies and secondary flows but were otherwise closest to the $k-\omega$ SST results. The simulations revealed complicated flows with intense recirculation patterns in the dispersion chamber and strong tangential flows in the spiral region of the mouthpiece.

Particle deposition was found to depend on size and flow rate and occurred predominantly in the dispersion chamber and the mouthpiece. The computational solutions were compared to experimental data for volumetric flow and regional deposition of de Koning et al. (2001) and good agreement was observed for volumetric flow. Particle deposition data were in agreement to experimental data only for capture efficiencies less than 100%. A simple capture efficiency model assuming a critical velocity limit for particle capture was found to produce total particle depositions similar to the experimental values of de Koning et al (2001) and Abdelrahim (2010).

Future work will involve dynamic inhalations and will elaborate on the particle capture efficiency

model. The capture efficiency can be determined more accurately based on collision angle, velocity magnitude, particle properties (e.g., size, shape, and charge), surface properties (e.g., roughness, charge), as well as particle/surface cohesion forces.

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