OPTIMIZATION OF NEURAL NETWORK'S TRAINING SETS VIA CLUSTERING: APPLICATION IN SOLAR COLLECTOR REPRESENTATION

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Keywords: Artificial Intelligence, Artificial Neural Networks, Solar Energy, Clustering, Thermosiphon.

Abstract: Due to the necessity of new ways of energy producing, solar collector systems have been widely used around the world. There are mathematical models that calculate the efficiency of those systems; however these models involve several parameters that may lead to nonlinear equations of the process. Artificial Neural Networks have been proposed in this work as an alternative of those models. However, a better modeling of the process by means of ANN depends on a representative training set; thus, in order to better define the training set, the clustering technique called k-means has been used in this work.

1 INTRODUCTION

In a reality where natural resources are becoming scarce, associated with the population increasing, the traditional ways of energy producing (hydroelectric power plants) may not be sufficient. Therefore some alternative ways of energy producing are proposed; and among them, there are solar energy systems.

Solar energy systems, specifically water heaters, have considerable importance in the substitution of traditional electrical systems. The most widely used solar energy systems are known as thermosiphon systems; which are cost competitive with those conventional energy systems available everywhere.

In Figure 1, a schematic diagram of thermosiphon system is represented; its main component is the collector plate. Numerous researchers (Morrison & Ranatunga 1980; Huang 1984; Kudish, Santaura & Beaufort 1985) investigate the performance those systems, both experimentally and analytically. The efficiency of thermosiphon systems can be obtained by means of the equation

$$\eta = \frac{\dot{m}c_p (T_{out} - T_{in})}{GA_{extern}} \tag{1}$$

where η is efficiency, *m*, the flow rate, c_p , the heat capacity of water, T_{out} , the output water temperature, T_{in} , the input water temperature, *G*, solar irradiance and A_{extern} is the area of the collector.



Figure 1: Schematic diagram of thermosiphon system.

The solar collector efficiency depends on some structural aspects like its position, the material of its components and thermal insulation. Efficiency is obtained by means of experiments that use some process parameters like output water temperature, ambient temperature, input water temperature, solar irradiance and flow rate. Thus, for new operational conditions, new experiments must be made in order to recalculate the efficiency. There are mathematical models that avoid those experiments (Kudish, Santaura & Beaufort 1985), but they have the discouraging aspect of involving several parameters that may lead to non-linearity.

Linear regression has been proposed as alternative to those complex mathematical models. However that technique may introduce estimative errors in actual and future values due to its limitation in better working with linearly correlated values.

In the last years, Artificial Neural Networks (ANN) have been proposed as powerful computational tools due to their facility in solving non-linear problems, generalizing what they have learnt, besides the low time of processing that can be reached when the nets are in operation. Some researches discuss the use of ANN to represent termosiphon systems (Kalogirou 2000; Kalogirou, Panteliou & Dentsoras 1999; Zárate et al. 2003a; Zárate et al. 2003b). In Zárate et al. 2003a, a net trained with 603 data has been presented, however the time spent to train this net is not satisfactory. In Zárate et al. 2003b, statistical analysis is adopted with the objective of building a reduced but better defined training set. In Moreira and Roisenberg 2003, an alternative solution, based in genetic algorithm, is presented as an alternative of reducing the training set; but the needed time to obtain the optimal training set makes this technique not satisfactory.

The usage of ANN to model solar collectors has several advantages over other techniques, like not needing linearly correlated data and their capacity of generalization in order to deal of new data values. ANN are presented here, besides the clustering technique known as k-means, used to reduce and better define the training set.

This paper is organized in six sections. In the second one, solar collectors are physically described. In the third section, the process of collecting data from the solar collector is presented. In the fourth one, clustering technique is presented. In the fifth section, modeling by means of ANN is discussed. And finally, conclusions are presented.

2 PHYSICAL DESCRIPTION OF THE SOLAR COLLECTOR

The working principles of thermosiphon systems are based on thermodynamic laws (Duffie & Beckman 1999). In those systems water circulates through the solar collector due to the natural density difference between cooler water in the storage tank and warmer water in the collector. Although they demand larger cares in their installation, thermosiphon systems are of extreme reliability and lower maintenance. Their application is restricted to residential installations and to small commercial and industrial installations. Thermosiphon system structure is presented in Figure 1.

Solar irradiance reaches the collectors, which heat up water inside them, decreasing the density of heated up water. Thus cooler and denser water forces warm water to the storage tank. Since this is a constant process, the water flow happens between the storage tank and the collector, resulting in a natural circulation called "thermosiphon effect".

3 COLLECTING DATA FROM THE SOLAR COLLECTOR

Collected data refer to a typical solar collector and have been obtained by means of experiments in different ambient situations, under ASHRAE standards (ASHRAE 93-86 RA 91). During three days of a characteristic period of the year for those experiments, measurements have been realized several times per day. Figure 2 shows a graphic where the relation between output temperature of water (T_{out}) and the hours during the day (*hours*) can be observed. Notice that the collected data are representative for different operating points and output temperatures.



Figure 2: Collected output water temperatures.

In order to verify the non-linearity of the collected data, some graphics have been built, like the one presented in Figure 3, however linearity in those data has been noticed. Despite that linearity, ANN are presented here as an alternative to model solar collectors with more precision than other techniques like linear regression.



Figure 3: Solar irradiance X output water temperature.

The total number of collected data equal 631; those data include values of solar irradiance (*G*), ambient (T_{amb}), input (T_{in}) and output (T_{out}) temperatures. Table I.1 (in the append) shows a sample composed by 15 of those collected data. A subset composed by 30 data has been extracted from the original set in order to be used as validation set which is used later. Thus the new training set contains 601 data.

A reduced and better-defined training set must continue representing the problem, maintaining the capacity of generalization of the net, tolerable errors and permitting the reduction of time spent in the training process. In Zárate et al. 2003b, statistical analysis has been used to reduce the training set, resulting in 84 data. The clustering technique called k-means has been used in this work to reduce the training set, maintaining its capacity of represent the problem.

4 CLUSTERING WITH K-MEANS

The k-means algorithm is one of the several techniques of clustering. It divides n data into k clusters, where k is a constant not defined by the algorithm. The result of this algorithm is a frame where all the objects present in a cluster have considerable similarity among them and a great dissimilarity to objects present in other clusters. Each cluster has a center point, which has the principal characteristics of the group. In the center point, the sum of distances of all objects in that cluster is minimized.

4.1 Selecting data for the training

In order to build a representative training set, the kmeans algorithm, described above, has been used in the set composed by 601 data. The technique has been applied identifying clusters in which data have similar characteristics. As the number k of clusters must be explicitly given to the algorithm, k value has been varied from 10 to 100. For each test with a different number of clusters, the distance between each point in data set to each cluster center point has been calculated. Figure 4 shows average distances between all points of each cluster and the center points of neighbor clusters, for all the tested quantities of clusters.



Figure 4: Average distances between the points of each cluster and the neighbor clusters.

Higher average distances between the points of each cluster and the center points of neighbor clusters characterize better-defined clusters. Considering this, the set divided in 20 clusters has been chosen. After determining the optimal number k of clusters, a technique to select data present in the clusters has been applied. Although most representative characteristics are present in the center point of each cluster, this center point may not correspond to a real point in the data set. Thus, for each cluster, the point closest to the center point has been chosen resulting in 20 sets. Figure 5 shows, graphically, the data set divided in 20 clusters.



Figure 5: Clusters centers points (•) and data values (+).

5 NEURAL REPRESENTATION OF SOLAR COLLECTOR

Multi-layer ANN have been used in this work. The values of entries are presented to the hidden layer and satisfactory answers are expected to be obtained from the output layer. The most suitable number of neurons in the hidden layer is still a non-solved problem, although researches discuss some approaches. In Kovács 1996, the suggested number of hidden neurons is 2n+1, where *n* is the number of entries. In the other hand, the number of output neurons equals the number of expected answers from the net.

Input water temperature (T_{in}) , solar irradiance (G) and ambient temperature (T_{amb}) are variables used as entries to the ANN. The output water temperature (T_{out}) is the wanted output from the net. In this work, ANN represent the thermosiphon system according to the following formula

$$f(T_{in}, T_{amb}, G) \xrightarrow{ANN} T_{out}$$
 (2)

The structure of the ANN in this work is schematically represented as shown in the Figure 6. The net contains seven hidden neurons (i.e. 2n+1) and one neuron in the output layer, from which the output water temperature is obtained.



Supervised learning has been adopted to train the net, specifically, the widely used algorithm known as backpropagation. Nonlinear sigmoid function has been chosen, in this work, as the axon transfer function

$$f = \frac{1}{1 + \exp^{-\sum Entries \ x \ Weights}} \tag{3}$$

5.1 Preparing data for training

The largest effort to get a trained net generally lies on collecting and pre-processing the input data. The pre-processing stage consists in data normalization in such way that inputs and outputs values are within 0 to 1 range. The following procedure has been adopted to normalize the data before using them in the net structure:

1) The normalization interval [0, 1] has been reduced to [0.2, 0.8].

2) Data have been normalized by means of the following formulas

$$f^{a}(Lo) = Ln = (Lo - Lmin) / (Lmax - Lmin)$$
(4a)
$$f^{b}(Ln) = Lo = Ln * Lmax + (1 - Ln) * Lmin$$
(4b)

The formulas above must be applied to each variable of the training set (e.g. T_{amb} , T_{in} , G), normalizing all their values.

3) L_{min} and L_{max} have been computed as follows:

$$L_{\rm min} = L_{\rm sup} - (N_s / (N_i - N_s))^* (L_{\rm inf} - L_{\rm sup})$$
(5a)
$$L_{\rm max} = ((L_{\rm inf} - L_{\rm sup}) / (N_i - N_s)) + L_{\rm min}$$
(5b)

where L_{sup} is the maximum value of that variable, L_{inf} is its minimum value, N_i and N_s are the limits for the normalization (in this case, $N_i = 0.2$; $N_s = 0.8$).

5.2 The training process

For the training process, random values (between -1 and 1) have been attributed to connections weights. As explained in section (4.1), 20 data have been chosen for the training process. After approximately 80800 iterations, with learning rate equivalent to 0.08, the obtained error value reached 0.0016. The final weights of hidden and output layers with polarization weight (bias) are:

$$W_{bias}^{h} = \begin{bmatrix} 0.7190721 \\ 0.4899998 \\ 0.065922424 \\ 1.0196898 \\ -1.1757647 \\ -1.6151366 \\ 0.97916955 \end{bmatrix} W^{h} = \begin{bmatrix} 0.36259624 & -0.55641556 & 0.4545914\overline{8} \\ 0.22867158 & 0.881328 & 0.00832278 \\ 0.01728606 & 0.20641379 & 0.97605497 \\ 1.0179754 & 0.5750891 & 0.76203126 \\ 0.53837997 & 2.0769408 & 0.624686 \\ -0.18253215 & 3.4406793 & 0.15900967 \\ 0.13926853 & -0.0701353\overline{3} & 0.7837078 \end{bmatrix}$$
$$W_{bias}^{out} = \begin{bmatrix} -0.90068215 \\ 0.2919098 \\ 0.023139533 \\ -0.4214473 \\ 2.231161 \\ 3.764176 \\ -0.6316091 \end{bmatrix}$$

In W_{bias}^{h} and W^{h} lines refer to hidden neurons and columns refer to their input connections. In W_{bias}^{out} and W^{out} lines refer to connections between hidden and output layers while columns refer to output neurons. Table 1 shows errors values obtained in the training process.

	Table 1: Training results.				
Min. error (°C)		Max. error (°C) Error average (
	0.017174	0.92959	0.33199015		



Figure 7 graphically shows the result of training.

Figure 7: Real (°) and ANN (+) output temperatures.

5.3 Validation of the Neural Network

Table I.2 (append) shows the data set used to validate the ANN, previously extracted from the collected data. Table I.2 also shows the output of the ANN and the errors obtained, compared to the real output temperature.

Table 2 shows the errors values obtained in the validation process.

Table 2: Errors from validation process				
Min. error (°C) Max. error (°C) Error avera				
0.030246	1.359952	0.458544167		

Figure 8 graphically shows the results obtained from the trained and validated net, when operated with the validation set.



Figure 8: Real (+) and ANN (°) output temperatures.

5.4 Verification of Results

For the analysis by means of linear regression, Equation (6) has been used:

$$\eta = F_{R}(\tau \alpha)_{e} - F_{R}U_{L}\frac{(T_{in} - T_{amb})}{G}$$
(6)

 $F_R(\tau \alpha)_e$ equals 66.662 and $F_R U_L$, 809.89. F_R corresponds to collector heat removal factor, $(\tau \alpha)_e$, to transmittance absorptance product and U_L , to collector overall loss coefficient. T_{in} is the input water temperature, T_{amb} , the ambient temperature and *G*, the solar irradiance. Equation (6) calculates efficiency when linear regression is used.

With the values of the output temperature of the water, the efficiency of the solar collector can be calculated. Table 3 shows the comparison between linear regression and ANN errors in calculating the efficiency of the solar collector.

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Table 3: Comparison between errors.				
	Eff – Eff ANN (%)	Eff - Eff LR(%)		
Average	3.124178769	1.864363541		
Minimum	0.14650623	0.08587937		
Maximum	8.110471201	7.215990429		
Std. deviation	2.672893417	1.816157438		

6 CONCLUSIONS

In this work, a possible use of ANN to model a solar collector has been presented. It has been also presented a technique to build a more representative training set – the widely used k-means clustering method. With k-means, a training set composed by 20 data could be used, as shown in Figure 5.

Table 1 shows the results of the training process; the average error in the output water temperature equals 0.33199 and maximum and minimum errors are, respectively, 0.92959 and 0.017174. Those results show the optimal approach of ANN, since the error recommended by INMETRO (National Institute of Metrology and Industrial Quality - Brazil) is 1°C.

Efficiency errors, calculated via ANN and linear regression, are presented in Table 3. Although the errors obtained via linear regression are lower, ANN present some advantages on linear regression (e.g. For new situations with unusual values of entries, the equation of linear regression may increase the actual errors values unless it is reformulated, while a trained net may use its capacity of generalization in order to maintain the errors values).

Comparing the results of training and validation processes of a net trained with 631 data (Zárate et al. 2003a), with a training set selected by means of statistical analysis (Zárate et al. 2003b) and with the training set of this work, it can be observed that a better-defined training set may decrease the time spent in training and may also maintain the capacity of generalization of the net (Tables 4 and 5).

		<u> </u>	
	None	Statistical	k-means
	technique	analysis	clustering
Min. error (°C)	0.000035	0.000039	0.017174
Max. error (°C)	1.19	1.021237	0.92959
Error average (°C)	0.15	0.244534	0.33199
N° of iterations spent in training	7700000	412800	80800

Table 4: Comparing training results.

Table 5: Comparing validation results.

	<u> </u>		
	None	Statistical	k-means
	technique	analysis	clustering
Min. error (°C)	0.02185	0.043265	0.030246
Max. error (°C)	0.70706	1.475292	1.359952
Error average (°C)	0.27365	0.625548	0.458544

ACKNOWLEDGEMENTS

This work has been financially supported by CEMIG (Energy Company of Minas Gerais - Brazil).

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APPEND

Tamb	Tin	Solar Irradiance	Tout
25.05	27.17	908.42	33.97
25.91	34.7	1005.68	41.61
23.51	43.42	967.31	49.43
26.26	39.98	761.83	44.73
22.61	25.31	905.41	32.02
23.12	32.82	922.13	39.23
23.75	57.89	958.19	62.21
24.71	38.32	833.93	43.76
25.66	31.65	958.24	38.58
24.49	22.65	872.67	29.46
24.22	23.01	933.09	30.4
23.53	22.83	958.29	30.41
23.96	20.76	768.96	27.28
23.36	39.89	962.33	45.79
25.99	38.11	794.92	43.15

Table I.2: Validation data sets.

T	amb	Tin	G	Tout	Tout (ANN)	Error	
2	3.83	20.66	755.1	27.17	27.630451	0.460451	
2	4.43	20.97	819.75	27.74	28.14392	0.40392	
2	4.61	21.47	850.02	28.07	28.63377	0.56377	
2	4.44	22.5	860.06	29.27	29.388565	0.118565	
2	4.87	23.72	869.47	30.55	30.365038	0.184962	
2	4.81	25.96	912.59	32.85	32.46125	0.38875	
2	5.31	30.81	932.79	37.52	37.219883	0.300117	
2	5.66	31.65	958.24	38.58	38.304413	0.275587	
2	5.82	33.75	993.54	40.78	40.810246	0.030246	
2	5.85	33.81	996.78	40.86	40.902008	0.042008	
2	5.96	34.65	993.69	41.6	41.772133	0.172133	
2	6.03	34.79	1024.01	41.88	42.176178	0.296178	
2	6.45	37.9	1022.66	44.63	45.445923	0.815923	
2	6.66	38.04	1022.82	45.12	45.592113	0.472113	
2	6.98	38.16	1041	45.27	45.85676	0.58676	
2	6.02	38.18	794.81	43.3	43.93853	0.63853	
2	6.08	39.96	765.05	44.65	45.60505	0.95505	
2	3.77	22.96	924.79	30.32	30.066198	0.253802	
2	24.1	22.98	924.84	30.28	30.099792	0.180208	
2	4.04	23.05	931.81	30.42	30.191616	0.228384	
2	2.76	23.03	907.4	29.93	29.971178	0.041178	
2	3.33	39.98	966.37	46.05	47.142525	1.092525	
2	3.27	40.09	967.81	46.09	47.26527	1.17527	
2	3.74	53.4	983.64	58.6	57.840714	0.759286	
2	25.1	27.13	911.55	33.95	33.501625	0.448375	
2	5.09	27.12	910.06	33.95	33.481182	0.468818	
2	4.65	38.42	849.35	43.85	44.61326	0.76326	
2	4.69	47.01	809.17	51.31	52.669952	1.359952	
2	4.86	23.72	785.5	30.12	29.872047	0.247953	
2	4.96	23.73	770.1	29.83	29.797749	0.032251	

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