Surface EMG Signal Segmentation and Classification for Parkinson's Disease Based on HMM Modelling

Hichem Bengacemi^{1,3}[®]^a, Abdenour Hacine Gharbi², Philippe Ravier³[®]^b, Karim Abed-Meraim³ and Olivier Buttelli³

¹Signal Processing Lab, École Militaire Polytechnique, Algiers, Algeria

²LMSE laboratory, University Mohamed El Bachir El Ibrahimi of Bordj Bou Arreridj, El-Anasser, Bordj Bou Arréridj, 34030, Algeria

³PRISME Lab, Université d'Orléans, INSA-CVL, 12 Rue de Blois, 45067, Orléans, France

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Abstract: To increase the diagnostic accuracy, the techniques of artificial intelligence can be used as a medical support. The Electromyography (EMG) signals are used in the neuromuscular dysfunction evaluation. This paper proposes a new frame work for segmenting and classifying the surface EMG (sEMG)signals by segmenting the EMG signal in regions of muscle activity (ACN) and non activity (NAN) for control group (healthy) and the muscle activity (ACP) and non activity (NAP) for Parkinsonian group. This paper proposes an automatic system of the neuromuscular dysfunction identification for Parkinson disease diagnosis based on HMM modeling by using on sEMG signals. Discrete Wavelet Transform (DWT), LP coefficients and FLP coefficients have been used for feature extraction. The results have been evaluated on ECOTECH project database using the signal classification rate (*CRS*) and the Accuracy (Acc) criterion. The obtained results show highest performance by using HMM models of 2 states associated with GMM of 6 Gaussians, combined with Log Wavelet decomposition based Energy(LWE) descriptor based on Coiffet wavelet mother with decomposition level of 4. The proposed methodology leads to a classification accuracy of leads to an *Acc* of 99.37 % and a *CRS* of 100 %.

1 INTRODUCTION

Parkinson's disease (PD) is a neurodegenerative disease caused by dopaminergic degeneration. This disease is defined clinically by movement disturbances, motor disturbances, and loss of postural control. It is characterized by several symptoms: freezing, postural instability and gait disturbance, resting tremor, rigidity, Akinesia and Bradykinesia.

The diagnosis of PD is not always easy to make. The latter is generally based on the symptoms described by the patient and neurological examination made by the doctor. Several research works are carried out for the analysis, evaluation and identification of PD using several approaches such as: Hand writing (Rosenblum et al., 2013), analysis and gait evaluation by recording stride intervals (Wendling, 2008; Bhoi,

^a https://orcid.org/0000-0002-4141-5275

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2017; Abdulhay et al., 2018; Kugler et al., 2013), voice analysis (Manwatkar et al.,), medical imaging (Xu and Zhang, 2019; Porter et al., 2020), the analysis of electrovestibulography (EVestG) signals which are in fact the vestibular response modulated by cortical cerebral signals (Dastgheib et al., 2012) and finally the analysis of gait using surface EMG signals which are the subject of this work (Elamvazuthi et al., 2015; Raut and Gurjar, 2015; Nazmi et al., 2016).

The problem of classification and diagnosis of neurodegenerative diseases including PD, is strongly lied to the techniques of features extraction and those of classification (Sugavaneswaran et al., 2012; Carletti et al., 2006; Henmi et al., 2009; Hausdorff et al., 1998; Okamoto et al., 2009; Surangsrirat et al., 2016; Bhoi, 2017). In (Hausdorff et al., 1997), the authors presented that the fluctuations of stride interval are increased in PD and correlate with the disease severity degree. In (Miller et al., 1996), the authors showed that the variability of the EMG signal

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^b https://orcid.org/0000-0002-0925-6905

recorded from the astrocnemius muscle is higher in Parkinson's patients. In (Oung et al., 2018), the authors proposed a multi-class classification, to indicate the severity level of PD (mild, moderate, severe) using the empirical wavelet transformation (EWT) and empirical packet-to-wavelet transformation (EWPT) based on the motion signals and audio signals. In (Putri et al., 2018), the authors proposed the classification of PD by combining voice recordings and EMG signals using an Adaptive Neuro-Fuzzy Inference System (ANFIS) and artificial neural networks (ANN). In (Yuvaraj et al., 2018), the authors used the EEG signal by combining higher order spectra (HOS) with some fuzzy k-nearest neighbor classification techniques (fuzzy K-nearest neighbor: FKNN), k more near neighbors (K-nearest neighbor: KNN) and the naive bayes approach (NB). In (Elamvazuthi et al., 2015), ANN is combined with linear prediction coefficients (LPCs) to classify neuromuscular disorders (myopathic and neuropathic).In (Bengacemi et al., 2021a), the authors have proposed the modelling of muscle activity (AC) and non activity (NA) using HMM models combined with wavelet analysis for sEMG signal segmentation in in regions of AC and non NA applied in PD. In the present work, we propose to extend the previous work using four HMM models with adding a decision step for simultaneously sEMG segmentation and PD diagnosis.

The HMMs have been widely employed and investigated in the automatic speech recognition. Recently, it has been successfully used for both medical monitoring and diagnosis system applications such as ECG classification (Patil et al., 2017), EEG classification (Jiang et al., 2019), electrical appliances identification (Nait-Meziane et al., 2016). Especially, this method is also used for the PD classification using the raw gait data (Khorasani and Daliri, 2014). The HMM has been also combined with support vector machine (SVM) classifier for natural gesture recognition using EMG signals for upper limb prostheses control (Rossi et al., 2015). In (Kwon et al., 2007), the authors have combined the multilayer perceptrons (MLP's) and the HMM for classifying six motions based on EMG signals. A HMM based classifier is used for speech recognition using myoelectric signals from the muscles of vocal articulation (Chan et al., 2002). In (Liu et al., 2015), the authors have used the HMM on EMG signals to measure the EMG burst presence probability (EBPP). The study was limited to simulated signals and to one experimental signal just for illustration purpose. In (Bengacemi et al., 2021a), the authors have showed the effectiveness of HMM for PD modelling where the authors have classified the EMG activity (AC) versus the no EMG activity (NAC). In this paper, we use HMM to classify EMG activity versus no EMG activity, in which we have defined four classes ACN, NAN, ACP and NAP (P: Parkinson and N: Normal). The proposed system segments the signals on sequence of ACN and NAN or on sequence of ACP and NAP, then makes a decision about the class of the EMG signal by verifying the class type of the sequence P or N.

The proposed system uses the extracted features from the EMGs signals recorded within the framework of the ECOTECH project (Buttelli, 2012). The extraction techniques used in this work are the linear prediction (LP) coefficients, the fractional prediction coefficients (FLP) and the Discrete Wavelet decomposition based calculus Energy (DWE), Log Wavelet decomposition based Energy (LWE) and Wavelet Cepstral Coefficients (WCC)(Bengacemi et al., 2021a). The main task consists of looking for optimal parameters of HMM and wavelets descriptors to achieve the best surface EMG signals segmentation and classification. The proposed system is carried out in two phases, namely: the learning phase and the evaluation and test phase. The first phase is reserved to model the different classes, while the test phase is used to evaluate the performance of the diagnostic system.

The main contributions of our work are: firstly, this work exploits the principal advantage of wavelet decomposition that is better adapted for extracting the impulsive information of the action potentials (AP) of the motor units (MU), especially in PD case. Secondly, this work adapts the HMM to automatic sEMG signal segmentation and classification. Note that HMM is one of the best tools to model signal state transitions which is considered as the supervised PD diagnostic task (Bengacemi et al., 2021a). Finally, based on the real ECOTECH data base, we provide a high performance analysis using two evaluation criterion. This proposed approach is carried out in a learning and a test phases. The learning phase consists in modeling the four classes ACN, NAN, ACP and NAP, while the test phase aims to evaluate the performance of the classification systems using the HMM. These two phases require a step of extracting discriminating parameters from the four classes.

The rest of the paper is organized as follows: section 2 describes the problem formulation and the proposed methodology. Section 3 is dedicated to the performance analysis and discussions while section 4 is reserved for the concluding remarks.

2 MATERIAL AND METHOD

In this section, we present in details the methodology of our proposed work. More precisely, after defining thoroughly the problem formulation, we introduce gradually the proposed method starting by the performance evaluation Tools. Then, the description of the used database of sEMG signal has been presented. Then, we present the used features extraction techniques for EMG signal modeling.

2.1 **Problem Formulation**

In this paper, we present the PD diagnostic system based on the HMM models. These have already been used and tested as an sEMG signal segmentation technique, in (Bengacemi et al., 2021a). However, in this work, we use this method for a task of diagnosing and classifying PD. In this system, we used the HMMs for the both segmentation and classification of the sEMG signal for the PD diagnostic task. The proposed approach involves transcribing the sEMG signal of a control and parkinsonian subjects into a sequence of activity zone followed by a non-activity zone. Four classes are considered in this work such as ACP and NAP for Parkinsonian subject and ACN and NAN for a control subject.

- (1) ACN: EMG activity class for a control subject;
- (2) NAN: non-activity class (noise region) for a control subject;
- (3) ACP: EMG activity class for a Parkinson's patient;
- (4) NAP: non-activity class (noise region) for a Parkinson's patient.

We consider *K* observations $(samples) \{x[n]\}_{n=1:K}$ of sEMG signal. Given a chosen analysis frame length, these measurements are divided into overlapping¹ frames. For each signal's frame, we are interested in determining whether it contains a signal s[n] embedded in a random background noise w[n] (EMG activity) or, on the contrary, it is just the confusing manifestation of the noise (no EMG activity). Hence, we have a decision problem expressed as:

$$\Gamma: \begin{cases} H_0: & \text{no EMG activity for control subject} \\ H_1: & \text{EMG activity for control subject} \\ H_3: & \text{no EMG activity for Parkinsonian subject} \\ H_4: & \text{EMG activity for Parkinsonian subject} \end{cases}$$
(1)

This task is known as sEMG signal segmentation and classification based on the HMM approach which allows us to classify a signal either in class P (parkinsonian) or in class N (control) according to the type of the sequence of the areas ACP, NAP or ACN, NAN. Thus, this system makes it possible to segment the signal into activity zones and non-activity zones, and also to perform the task of diagnosing Parkinson's disease. In the following, we will present the methodology of diagnosis and classification of PD adopted in this present system.



Figure 1: Segmentation and classification of EMG signal based on HMM models.

In the learning phase, each class (ACN, NAN or ACP, NAP) of region is modeled by an HMM model of N_{states} states, each state being represented by a GMM model of N_{GMM} Gaussian with a diagonal covariance matrix. The parameters of the HMM and GMM models are estimated using the HEREST command of the HTK tool, applied to the sequence of feature vectors extracted from the EMG signals from the database of the ECOTECH project (Buttelli, 2012). In addition, this estimation requires the transcription of the reference text which contains the class sequence of each signal. The feature vector sequences are extracted using the LPC, FLP, DWE, LWE and WCC descriptors, applied to each surface EMG signal.

In the segmentation and classification phase, the HVITE command of the HTK tool uses the trained HMM models and the constraint model (language model) to transcribe each input sequence of features vectors into a sequence of classes (ACN, NAN) or a sequence of classes (ACP,NAP) and detect the boundaries of their segments (Young et al., 2006; Chibelushi et al., 2002). The constraint problem is to accept only the sequence of classes in which each ACN tag (class) is followed by the NAN tag for the control subject's surface EMG signal and each ACP tag (class) is followed by the NAP tag for the surface EMG signal for the Parkinson's patient. Then, a decision is made for SEMG signal classification by verifying the class of obtained sequence, either P (Parkinsonian subjects) or N (Control subjects).

¹In this work, we used 50% overlapping windows.

2.2 Performance Evaluation Tools

The performance evaluation can be performed using the HRESULTS command of the HTK tool which compares each test transcript of an EMG signal to its corresponding reference transcript (Young et al., 2006). The result of identifying and classifying segments is evaluated using the precision *Acc* defined in the equation (2).

The precision *Acc* is used to evaluate the number of bursts of EMG activity correctly detected, taking into account the constraints already described previously.

$$Acc = \frac{N - D - S - I}{N} \tag{2}$$

N represents the total number of segment labels in the reference transcriptions of EMG signals, D is the number of removed labels, S is the number of substituted labels and I is the number of the inserted labels. The classification system is composed of the following three steps.

For the performance test and evaluation stage, we adopt the following performance indicators: the classification precision (*Acc*) and the signal classification rate (*CRS*), defined in the equation (2) and the equation (3) respectively.

The precision allows us to have an overall measurement calculated from the classification of all the zones of the test base (ACN-NAN or ACP-NAP) independently of the signals. However, the diagnostic task consists in classifying the signals, this diagnostic task uses the segmentation results which makes it possible to classify the signal in Parkinson's class (P) or in control class (N) according to the type of the sequence of zones (ACN-NAN or ACP-NAP). The classification rate is calculated using the equation 3 which allows us to get the perfomance analysis of the proposed diagnostic system.

$$CRS = NsC/NsT \tag{3}$$

where *CRS* is signal classification rate, *NsC* is the classified signals correctly and *NsT* is the total number of signals.

2.3 Surface EMG Signal Database

For this study, nine healthy subjects and eight Parkinsonian patients were recruited in the frame of the French national research project ECOTECH (Buttelli, 2012). This work was approved by the local ethics committee and subjects provided written consent prior to commencement.

A specific lower limb muscles of gait activity have been measured. Patients were prepared for electrodes placement by shaving the skin and cleaning it with alcohol wipes. EMG sensors were placed on the muscle belly parallel to the main direction of muscle fibres in accordance with study on the innervation zone (Barbero et al., 2012). Data were collected using an on board system of wearable sensors (20-450 Hz bandwidth, 16 bits per sample, 1926 Hz sampling rate). Data collection provides several burst activities from each right *soleus* muscle corresponding to several gait cycles. The data base description is reported in tables 1 and 2.

| Table 1: Descrip | ion of sEMG signals for | healthy subjects. |
|------------------|-------------------------|-------------------|
| | | |

| Subjects | | Number of EMG bursts | Signal duration (second) | | |
|------------------------------|----------------------|----------------------|--------------------------|--|--|
| | $Control_1$ | 22 | 26.0685 | | |
| Data base for training phase | $Control_2$ | 10 | 11.2128 | | |
| Data base for training phase | $Control_3$ | 11 | 14.3998 | | |
| | $Control_4$ | 11 | 14.7441 | | |
| | $Control_5$ | 11 | 11.1635 | | |
| | $Control_6$ | 6 | 7.7121 | | |
| Data base for testing phase | Control ₇ | 6 | 6.5298 | | |
| | $Control_8$ | 12 | 14.3458 | | |
| | Control ₉ | 26 | 28.5702 | | |

Table 2: Description of sEMG signals for Parkinsonian subjects.

| Subjects | | Number of EMG bursts | Signal duration (second) |
|------------------------------|-------------------|----------------------|--------------------------|
| / | $Park_1$ | 10 | 28.5702 |
| Data base for training phase | Park ₂ | 10 | 9.1317 |
| Data base for training phase | Park ₃ | 5 | 4.8657 |
| | Park ₄ | 37 | 39.6152 |
| | Park ₅ | 10 | 11.2876 |
| Data hasa far tasting phase | Park ₆ | 9 | 8.9152 |
| Data base for testing phase | Park ₇ | 5 | 4.4742 |
| | Park ₈ | 5 | 4.6487 |

2.4 Features Extraction and EMG Signal Modeling

The feature extraction plays a critical role to get a robust diagnosis system. This process transforms the raw sEMG signal into a feature vector. Generally, the used features in EMG signals analysis can be divided into three categories: time domain, frequency domain and time-frequency domain features (Hogan and Mann, 1980; Tsai et al., 2014; Englehart et al., 1999). As a particular class within the time-frequency methods, the time-scale methods have gained high interest because the scale parameter provides a natural analysis of biological phenomena, that is to say a high time precision for rapid events (low scales) and conversely a poor time precision with high frequency precision for slow events (high scales). Moreover, they show a high tuning flexibility in their design useful for performance seeking. In our work, we are interested in the use of Discrete Wavelet transform, particularly the Wavelet Cepstral Coefficient (WCC) coefficients. In this study, we have also analysed the Discrete Wavelet Energy (DWE) normalized on total energy of win-

dow analysis, the logarithm of wavelet energy (LWE) and the Wavelet Cepstral Coefficient (WCC) computed from the discrete cosine transform (DCT) of LWE (Hacine-Gharbi and Ravier, 2018) (see Fig.2). All the features were calculated using the discrete wavelet transform (DWT) which mother wavelet is characterized by two digital low-pass and high-pass filters. The DWT provides coefficients by an iterative down sampling-filtering procedure achieved at successive scales beginning on the N-length original signal x[n] up to a desired decomposition level L_{decomp} (that should be lower than the maximum decomposition level $L_{max} = log_2[n]$ provided N is a power of 2 or rounded to its nearest high value). The iterative procedure extracts the set of wavelet coefficients $d_i[n]$ at each scale i from 1 up to L_{decomp} value plus the $a_{L_{decomp}}[n]$ at the last scale. Then the DWE features $E(d_i)$ and $E(a_{L_{decomp}})$ are composed of the energy values calculated as the squared absolute magnitude sum of the wavelet coefficients at each scale i. The LWE are the log of the DWE coefficients previously normalized by the number of samples per scale. Finally, the WCC coefficients are obtained by applying the inverse DCT on the previous LWE coefficients for decorrelation. In this work, we investigated the impact of these descriptors on the performance results of PD classification. Hence different experiences have been carried out to search for the optimal configuration. These features are widely used in: speech recognition (Lei and Kun, 2016; Adam et al., 2013), Electrical Appliances Identification (Hacine-Gharbi and Ravier, 2018; Bengacemi et al., 2021a; Bengacemi et al., 2021b) and Recognition of Heart Sound (Xiong et al., 2019).

In this work, we have also integrated the dynamic features which are the first order differential coefficients (also called delta Δ) and second order (called delta-delta $\Delta \Delta$), resulting from the initially calculated coefficients DWE, LWE and WCC, considered as static features. The static's features contain only information on a given frame. In order to improve the representation of the frame's information, it is often proposed to introduce new features in the vector of features. (Furui, 1981; Furui, 1986) proposed the use of dynamic features which present the spectral transition information in the signal. The dynamic features are calculed using *HCopy* command of the HTK tools library (Hidden Markov Model Toolkit).

Let $C_k(t)$ is the extracted feature k of frame t, then the corresponding differential coefficient ΔC_k is calculated on $2\eta_{\Delta}$ analysis frames by estimating the slope of the linear regression of the coefficient C_k at time t (Young et al., 2006):

$$\Delta C_k(t) = \frac{\sum_{i=-\eta_{\Delta}}^{i=+\eta_{\Delta}} i.C_k(t+i)}{2.\sum_{i=-\eta_{\Delta}}^{i=+\eta_{\Delta}} i^2}$$
(4)

The second order differential coefficients $\Delta\Delta$ (deltadelta or acceleration) are calculated in the same way from the first order coefficients.

The proposed system can be seen as pattern recognition system which requires a training and recognition phases. The first one is used for modelling the temporal pattern classes and the second one is used for Parkinson's diseases classification. Hence, both phases require feature extraction step to convert each signal in sequence of features vectors obtained by dividing the signal into overlapping windows and computing from each window a set of features that constitutes the feature vector (see Fig.2). This sequence of vectors can be considered as input sequence of observations in modelling or classification steps.



Figure 2: Features extraction steps (Bengacemi et al., 2021b).

3 RESULTS AND DISCUSSION

In this paragraph, we evaluate the performance of the proposed HMM approach with the different feature extraction techniques. Like any classification system, we have two phases, the first is the learning phase and the second is the testing phase. The first phase is performed with a set of nine real EMG signals, made up of four signals from Parkinson's subjects and five signals from control subjects. In the second phase, we take four signals from Parkinson's subjects and four signals from control subjects, as shown in the tables 1 and 2.

Several experiments are carried out to find the optimal configuration which gives the best performance by studying: (i) The parameters of the HMM models (number of states and the number of Gaussians), (ii) The study of different types of descriptors for feature extraction (iii) The optimal combination of the mother wavelet with the level of decomposition. The three experiments are processed in this order: Table 4: Comparison of performances in Acc % and CRS % for the LWE descriptor using 'Coif5' for different analysis frame's duration.

| The analysis frame duration (ms) | 16.61 | 20 | 30 | 33.22 | 40 | 50 | 60 | 66.45 | 70 | 80 | 90 | 100 | 110 | 120 | 130 | 132.91 | 140 | 150 |
|----------------------------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|--------|-------|-------|
| Acc % | 61,01 | 53,46 | 51,57 | 67,92 | 72,96 | 79,25 | 69,18 | 44,03 | 68,55 | 99,37 | 68,55 | 83,02 | 72,33 | 84,91 | 46,54 | 47,80 | 69,18 | 32,08 |
| CRS % | 75.00 | 62.50 | 75.00 | 75.00 | 75.00 | 87.50 | 75.00 | 62.50 | 75.00 | 100 | 75.00 | 87.50 | 75.00 | 87.50 | 62.50 | 62.50 | 75.00 | 50.00 |

- (1) Comparison of the performance of the LPC, FLP, DWE, DWE and WCC descriptors;
- (2) Finds the optimal duration of the analysis frame;
- (3) Finding the best combination between the mother wavelet and the level of decomposition.
- (4) Analyse the performance of the obtained results.

For the first experiment, we have varied the number of states HMM N_{states} , the number of Gaussians N_{GMM} and the level of wavelet decomposition L_{decomp} for wavelet analysis ², The order *P* for the *LPC* descriptor and the order *L* for the FLP descriptor. The best descriptor with the optimal parameters found are used for the second experiment to study the duration of the analysis frame. Next, we look for the optimal configuration for the mother wavelet.

3.1 Performances Comparison of Different Descriptors

This part presents the performance evaluation results of five descriptors namely LPC, FLP, DWE, LWE and WCC for the diagnosis of PD. In this experiment, we are looking for the optimal configuration that gives the best performance in terms of *Acc* and *CRS*. For each descriptor, we vary the number of states for each experiment $N_{states} = (2,3,4,5,6,7,8,9,10)$, the number of components of Gaussians in GMM modeling $N_{GMM} = (1,2,3,6,12,24,48)$, the order P = (2,3,4,5,6,7,8,9,10) of the LPC descriptor and the order *L* of the FLP descriptor.

The obtained results are presented in the table 3 which show the optimal configurations in terms of number of Gaussians N_{GMM} and number of states N_{states} for each wavelet analysis descriptor DWE, LWE and WCC with the optimal order *P* for the descriptor *LPC* and the optimal order *L* for the FLP descriptor. These results demonstrate the gain in performance of the wavelet analysis descriptors which show an *Acc* greater than 88 % and a *CRS* greater than 87 % compared to the LPC and FLP descriptors. In particular, the descriptor *LWE* with *Acc* = 98.11% and *CRS* = 100% for $N_{GMM} = 6$ and $N_{states} = 2$.

Table 3: Comparison of performance in *Acc* % and *CRS* % for DWE, LPC, LWE and WCC descriptors using '*Coif5*' and $L_{decomp} = 4$ with a the analysis frame equal to 66.45 *ms*.

| Descriptors | LPC | FLP | DWE | LWE | WCC |
|--------------------|------------------------------|------------------------------|------------------|------------------|------------------|
| Optimal parameters | $N_{GMM} = 24$ | $N_{GMM} = 6$ | $N_{GMM} = 3$ | $N_{GMM} = 6$ | $N_{GMM} = 12$ |
| | $N_{states} = 3$ and $P = 3$ | $N_{states} = 3$ and $L = 5$ | $N_{states} = 3$ | $N_{states} = 2$ | $N_{states} = 3$ |
| Acc % | 66.97 | 83.65 | 88.05 | 98.11 | 91.82 |
| CRS % | 75 | 75 | 87.5 | 100 | 87.5 |

3.2 Influence of the Duration of the Analysis Window

After having chosen the descriptor LWE, we study in this paragraph the duration of the appropriate analysis frame taking into account the advantages of the wavelet analysis, which is appropriate for the nonstationarity of EMG signals. We vary the analysis frame duration for the mother wavelet 'Coif5', the number of GMMs $N_{GMM} = 6$, the number of states $N_{states} = 2$ and the level of decomposition equal to $L_{decomp} = 4$ for the descriptor LWE. The table 4 shows the values of Acc for each value of the duration of the analysis frame. The best performance is obtained for an analysis frame duration equal to 80 ms, which corresponds to the values of Acc equal to 99.37 % and CRS equal to 100 %. This analysis frame duration is used in the performance analysis for the optimal choice of the mother wavelet.

3.3 Choice of the Mother Wavelet and Decomposition Level

Several studies on surface EMG analysis have concluded that the Daubechies wavelet family (Db) is the most suitable wavelet for the analysis of the EMGs signal (Hussain et al., 2009; Mahaphonchaikul et al., 2010; Phinyomark et al., 2009). In (Too et al., 2018), the authors concluded that the 'Sym4' is the most suitable for EMG pattern recognition. In (Bengacemi et al., 2021b), we found that Coif5 is the most suitable for the segmentation of the surface EMG signal. This part of the study aims to select the optimal order of the mother wavelets within its family for a duration of the analysis frame equal to 80 ms, a number of GMM $N_{GMM} = 6$, a number of states $N_{states} = 2$ with a decomposition level varying between 1 to log2(N) (N is the number of samples in the analysis window $(\max \text{ level} = 7)$). In this study, we consider the following wavelet families:

²The mother wavelet '*Coif*5' was chosen with an analysis frame duration equal to 66.45 *ms* and a wavelet decomposition level $L_{decomp} = 4$, found as optimal parameters in the segmentation by HMM modelling (Bengacemi et al., 2021a).

- The Daubechies family with orders 1 to 8: Db1, Db2, ..., Db10;
- The Symlets family with orders 1 to 8: Sym1, Sym2, ..., Sym8;
- The Coiflets family with orders 1 to 5: Coif1, Coif2,..., Coif5.

The obtained results of Acc and L_{decomp} are reported in the tables 5, 6 and 7 for each of the three wavelet family, respectively from which we can note that the best results:

- For the wavelet family **Daubechies** (see the table 5), we notice that the average of the classification precision *Acc* is greater than 87 % and the average of the classification rate *CRS* is greater than 87%. We also notice that for *Db7*, *Db8* and *Db9* with $L_{decomp} = 4$, we have a *Acc* = 99.37 and a *CRS* = 100%.
- For the wavelet family **Symlets** (see the table 6), we notice that the average of the classification rates *Acc* is greater than 87 % and the average of the classification rate *CRS* is greater than 89%. We also notice that for *Sym4* and $L_{decomp} = 2$ we have a *Acc* = 97.48 and a *CRS* = 100%.
- For the wavelet family **Coiflets** (see the table 7), we notice that the average of the classification rates *Acc* is greater than 96 % and the average of the classification rate *CRS* is greater than 97%. We also notice that for *Coif5* and $L_{decomp} = 4$ leads to an *Acc* = 99.37 and a *CRS* = 100%.

The obtained results demonstrate the robustness of the performance of the proposed approach in terms of the value of Acc and of CRS where we notice that all the mean values of Acc and CRS are greater than 87 %. In particular, we notice that the wavelet family 'Coiflets' gives an average Acc greater than 96 % and an average CRS 97 %. The mother wavelets Db7, Db8, Db9 and Coif5 with Ldecomp = 4 give the same values of Acc = 99.37 and of CRS = 100%. This improvement of the results is obtained through the various experiments described previously without any exhaustive empirical calculation.

Table 5: The performance in terms of Acc %, *CRS* % and L_{decomp} optimal for LWE using the **Daubechies** wavelet family.

| Daub | echies | Db1 | Db2 | Db3 | Db4 | Db5 | Db6 | Db7 | Db8 | Db9 | Db10 | moyenne |
|-------|---------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|---------|
| | Ldecomp | 2 | 5 | 3 | 2 | 5 | 2 | 4 | 4 | 4 | 2 | // |
| 80 ms | Acc % | 80.50 | 86.16 | 82.39 | 74.21 | 79.87 | 91.82 | 99.37 | 99.37 | 99.37 | 83.02 | 87.60 |
| | CRS % | 87.5 | 75 | 87.5 | 75 | 75 | 87.5 | 100 | 100 | 100 | 87.5 | 87.5 |

Table 6: The performance in terms of $Acc \ \%$, *CRS* % and L_{decomp} optimal for LWE using the **Symlets** wavelet family.

| Syn | nlets | Sym1 | Sym2 | Sym3 | Sym4 | Sym5 | Sym6 | Sym7 | Sym8 | moyenne |
|-------|---------|-------|-------|-------|-------|-------|-------|-------|-------|---------|
| | Ldecomp | 2 | 5 | 3 | 2 | 4 | 4 | 4 | 2 | // |
| 80 ms | Acc % | 80.50 | 86.16 | 82.39 | 97.48 | 86.16 | 83.65 | 83.65 | 96.23 | 87.02 |
| | CRS % | 87.5 | 75 | 87.5 | 100 | 87.5 | 87.5 | 87.5 | 100 | 89.06 |

| Table 7: The performance in | terms of Acc | %, CRS % an | d |
|------------------------------|-----------------|----------------|----|
| Ldecomp optimal for LWE usin | ng the Coiflets | wavelet family | y. |

| Coi | flets | Coif1 | Coif2 | Coif3 | Coif4 | Coif5 | moyenne |
|-------|---------|-------|-------|-------|-------|-------|---------|
| | Ldecomp | 1 | 4 | 2 | 2 | 4 | // |
| 80 ms | Acc % | 91.19 | 97.48 | 97.48 | 97.48 | 99.37 | 96.60 |
| | CRS % | 87.5 | 100 | 100 | 100 | 100 | 97.50 |

4 CONCLUSION

The classification and diagnosis of diseases has important clinical application. This paper describes the new diagnostic systems for dealing with the classification problem of Parkinson's disease. The proposed system is based on HMM modeling and wavelet analysis which is most suitable for non-stationary signals, especially surface EMG signals. The results show the HMM system achieved good classification accuracy of ACN, NAN, ACP, NAP (segmentation) and signal classification rate (diagnostic) suitable for clinical applications. The evaluation of diagnostic performance is performed by performing various experiments on surface EMG signals. The proposed system gives better results which lead to an Acc of 99.37 % and a CRS of 100 %. Consequently, this proposed approach represents an appropriate solution for the analysis of EMGs signals and its use for both EMG signal segmentation and diagnostic purposes, in particular Parkinson's disease. We have also seen the effectiveness of the HMM method for PD.

DLOGY PUBLICATIONS

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