On Function of the Cortical Column and Its Significance for Machine Learning

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Abstract: Columnar organization of the neocortex is widely adopted to explain the cortical processing of information (Mountcastle, V., 1957, Mountcastle, V., 1997, DeFelipe, J., 2012). Neurons within a minicolumn (feature column) simultaneously respond to a specific feature, whereas neurons within a macrocolumn respond to all values of receptive field parameters (Horton, J., Adams, D., 2005). Hypotheses for a cortical column function envisage a massively repeated "canonical" circuit or a spatiotemporal filter (Bastos, A. et al., 2012). However, nearly a century after the neuroanatomical organization of the cortex was first defined, there is still no consensus about what a function of the cortical column is (Marcus, G., Marblestone, A., Dean, T., 2014). That is, why are cortical pyramidal neurons arranged into columns? Here we propose what the function of the column's function helped find a way of evaluating the memory capacity of a cortical region in terms of patterns as a solution to a suggested connectivity equation. Also, it allowed introducing a connectivity-based machine learning model that accounted for pattern recognition accuracy, noise tolerance and showed how to build practically instant learning pattern recognition systems.

1 INTRODUCTION

The paper elucidates the function of the neocortical column in the context of pattern recognition capabilities of neocortical areas, - the capabilities that emerge as a result of multiplying connections that grow both within and between regions. This goal seems to be justified as it is still necessary to achieve a better fundamental understanding "about whether such a canonical circuit exists, either in terms of its anatomical basis or its function." (Marcus, G., Marblestone, A., Dean, T., 2014). Another question is as follows. It is known that patterns are represented in cortical regions by combinations of feature columns (Tsunoda, K. et al., 2001). How many patterns a cortical region can memorize? Given, for instance, an average pattern size of 100 features per pattern and 1000 feature columns in a cortical area, all possible feature column combinations would produce an intractable number of patterns

 $C(1000, 100) = 1000!/100!900! = 63 \times 10^{295}$

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as all the atoms in the Universe would not suffice to develop this amount of synapses. In fact, there are many more columns in an average cortical region. A realistic amount of patterns should be just a tiny fraction of all possible combinations. Also, does the cortex recognize patterns by computations? If so, how can neurons operating at 1 - 400 Hz outperform computers running at GHz frequencies? The paper shows that signal propagation along convergent / divergent paths, rather than computations, can support practically instant learning in a connectivitybased pattern recognition model. Cortical pattern recognition resembles a split-ticket vote, where each pattern feature casts its vote through its feature column not just for one, but for many candidate patterns. Besides, it is a multilevel voting, where chosen candidates elect next level candidates and so on. Each feature of a trained cortical area is associated with a subset of patterns through a connection list, which is established by axon terminals of a neuron excited by the feature. In this process, the cortical feature column (a bundle of about 100 neurons)

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serves as a multiplier of feature connections or a feature connection list expander. Such multipliers increase association capabilities of a cortical area. Importantly, a length of a connection list should not grow excessively. Otherwise, the information value of the feature column declines: a vote cast for all candidates does not make much sense.

Inverted indexing structures were invented long before emergence of machine learning. Indeed, it is not known who invented a back-of-the-book index, where rows or columns of page numbers instantly point to a location of keywords. The inverted index was re-invented in (Harris, D., 1954) and christened as Bag-of-Words. Computer science text-books describe a use of inverted (and fully inverted) files. In computer vision, the bag-of-visual-words model, where image features are treated as words was reinvented in (Csurska, G., et al., 2004), though it was first discussed in (Bledsoe, W., Browning, I., 1959). Partly borrowing ideas from text search engines (Brin, S., Page, L. 1998), the numerical data indexing was discussed in (Sivic, J., Zisserman, A., 2009). In the latter paper, image local features are first converted into words and later processed using inverted text index.

However, this paper's method does not convert noisy numeric features into words, but directly treats features using a numeric inverted index. Whereas artificial neural networks make use of iterative training, which results into slow learning, the numeric index leads to practically an instant learning. For instance (Mikhailov, A. et al., 2023), the training with dataset that involves 800 patients, each represented by 20531 gene profiles, took only 0.075 seconds. Also, learning of half of 581012 patterns, 52 features each, from famous CoverType dataset took only 0.00046 seconds. Both training sessions were followed by pattern recognition sessions that produced 99.75% and 90% accuracy, respectively.

However, the novelty of this paper comes from applying inverted index technique to elucidating the function of the neocortical column in the context of pattern recognition. For that, a pattern recognition model was built, whose performance is discussed in Section 5, whereas its mathematics is presented in Section 6.

2 INTRODUCTORY EXAMPLE

A seemingly chaotic network can be mathematically represented by perfectly ordered columns. In Figure 1, all connections depicted with thin lines between feature nodes (denoted by blank squares) and target nodes (depicted as black dots) were chosen randomly. Upon arrival of the feature pattern $\{b, c, e, g, i\}$, connections depicted with bold lines become active, where the feature "b" talks to nodes (1,2,3,4), feature "g" talks to nodes (5,3,6). If a combination of features were to spawn connections that never intersect, such a network would be a waste of efforts because no node would receive a sufficiently strong input. Hence, a subset of connections must converge to a few nodes. Here, nodes 3 and 8 become most excited as it can be seen from 1st level node histogram, which is obtained from network's columnar representation. On 2nd level, the winner is the node alpha.

The results of the paper are based on the neurobiological evidence presented in the next session.

3 NEUROBIOLOGICAL EVIDENCE

(a) Patterns are represented by combinations of feature columns or sensory neurons (Tsunoda, K. et al., 2001, Wilson, D., 2008).

(b) Branching of neuronal axons allows for simultaneous transmission of messages to a number of target neurons (Horton, J., Adams, D., 2005, LeDoux, J., 2002, Squire, L., 2013) (excluding internal connections within each minicolumn).

(c) Neurons in a minicolumn have the same receptive field and respond to the same stimulus (Buxhoeveden, D., Casanova, M., 2002).

(d) There exist hypercolumns in the neocortex. The term hypercolumn "denotes a unit containing a full set of values for any given set of receptive field parameters" (Mountcastle, V., 1997, Horton, J., Adams, D., 2005).

What is a feasible number of feature patterns a cortical area can memorize? Firstly, "Complex objects are represented in macaque inferotemporal cortex by the combination of feature columns" (Tsunoda, K. et al., 2001). Secondly, "Any given sensory neuron will respond to many different odors as long as they share a common feature. The brain's olfactory cortex then looks at the combination of sensory neurons activated at any given time and interprets that pattern" (Wilson, D., 2008). Secondly, let us suppose that active feature columns transmit their messages through axon terminals to distinct destinations that never intersect. Then such a network would be a waste of efforts, energy and money like sprinkling water on the sand. There would be no beneficiaries as no target neuron would ever receive more than one input.



Figure 1: Network and its representation in terms of columns. **a**, nodes 3 and 8 connect to the node α in the next level region, - the region that is delineated by a "fine" curve, thus, producing a single peak in the connectivity histogram (**b**). **b**, single peak in the histogram is the reason that only the node α becomes active, given the pattern $\{b, c, e, g, i\}$ is available as an input. **c**, columnar representation of the first / second levels connections. **d**, first level histogram. **e**, columnar representation of the first / second levels connections.

Let *D* be the average number of connections (density) in terms of outgoing axons' terminals in minicolumns (feature columns), *C* be the total number of minicolumns in a cortical area, \overline{F} be the average pattern size in terms of active feature columns and *N* be the number of lower level patterns.

Each incoming pattern being a combination of, on average, \overline{F} features activates \overline{F} feature columns, so that at least \overline{F} axon terminals simultaneously project to a **single** destination in order to elicit a sufficiently strong activation of this target that is supposed to respond to the pattern. Besides, it implies that *N* distinct lower level patterns would activate higher level neurons at *N* **distinct** destinations and the total number of axon terminals that send information to various destinations cannot be greater that *CD*.

An assumption that a process of memorizing N distinct patterns establishes on average \overline{FN} connections justifies the connectivity equation:

$$CD = \overline{FN}$$

A grossly simplified diagram (Figure 2) exemplifies this equation.

The connectivity equation comprises four variables. Three of them, which are C, D, \overline{F} can be measured physically. For example, each minicolumn



Figure 2: Connectivity equation diagram. Here, density D = (4/6)2 = 4/3 at $\overline{F} = 4$ (average pattern size), C = 6 (number of features), N = 2 (number of patterns).

contains about 100 pyramidal neurons (Buxhoeveden, D., Casanova, M., 2002) and each such neuron can develop around thousand (at most a few thousands) axon terminals. Then the number of outgoing axon terminals in a minicolumn is about $D = 10^5$. Supposing that the feature pattern size is $\overline{F} = 0.1C$, which sounds reasonable as it means that 10% of region minicolumns fire simultaneously, then, at C = 1000, the number of patterns the region can remember is

$$N = \frac{C}{\overline{F}} D = \frac{1000}{100} 10^5 = 10^6$$

4 **RESULTS**

1) Conjecture. The cortical minicolumn (feature column) serves as a multiplier of connections, that is, a device that increases the number of patterns a feature can be associated with.

2) The number of distinct patterns N a cortical area can memorize and thereafter recognize is proportional to the average number of axon terminals projecting from minicolumns, so that the following connectivity equation holds (Figure 2).

$N = CD / \overline{F}$

3) A connectivity-based pattern recognition model was developed that learns by establishing connections rather than by calculating parameters. This model, unlike artificial neural networks, is featured by practically an **instant learning** at the accuracy equaling that of traditional artificial neural networks. The learning is practically instant because it amounts only to saving feature patterns in their inverse form without any calculations (Section 6). Pattern recognition accuracy in the context of the connectivitybased model was evaluated as a function of:

- Average **density** of connections (Figure 3, Section 5). Both too low and too high densities have a tendency to reduce a cortical region ability to accurately distinguish patterns;

- Macrocolumn radius R. (Macrocolumns are unions of neighboring minicolumns) (Figure 4, Section 5)). With macrocolumns, temporal inhibition (Section 6.4) of inputs is needed, which enhances the recognition accuracy of patterns represented by feature sets, i.e., not by feature vectors.

5 SIMULATIONS

Computational experiments show that accuracy of a connectivity-based pattern recognition model depends on a macrocolumn's radius, density of connections and features' inhibition policy. The accuracy was evaluated by training the model with N random patterns and testing it with the same collection of patterns, whose features were distorted by a random noise (ξ). The patterns were represented by either variable length feature sets or *F*-dimensional feature vectors. As described in Sections 2 and 6, connectivity-based model uses a destination or a class histogram, whose samples represent destination activities elicited by input features. For a given input

pattern, positions of the histogram's maxima indicate a system's response in terms of target nodes or pattern classes. The variable-length input pattern size was accounted for by Jaccard set similarity measure and its modification (Section 6.4).

In the 1st experiment, pattern recognition accuracy was calculated as a percentage of correctly identified patterns. Figure 3 shows the accuracy as a function of density D (connections per column) in the presence of noise.

Specifications of computational experiments are provided in Appendix. Figure 3a shows that pattern recognition accuracy decreases with growing density of connections. However, the density should not be set up too low. Figure 3b shows that in absence of macrocolumns and inhibition, a feature measurement noise completely compromises the accuracy on testing.

In the 2^{nd} experiment, pattern recognition accuracy of the model was tested as a function of a macrocolumn radius and inhibition (Figure 4). Figure 4 shows that the absence of inhibition drastically reduces accuracy in the case of patterns represented by feature sets.

Patterns that comprise ordered features or time series can be mathematically represented by vectors. Such representation greatly enhances accuracy and robustness. In the 3rd experiment, accuracy function was calculated as a number of correctly recognized vectors versus macrocolumn radius. The accuracy fast approaches 100% with the growing radius at 50% noise level (Figure 5).

Note that in case of patterns represented by feature vectors no inhibition is needed, which is a consequence of properties of the numeric inverted index transform (Section 6.1).

6 METHODS

Inverted indexes are known to be central to extremely fast text search engines' algorithms. Another major application is bioinformatics, where inverted indexes support genome sequence assembly from short DNA fragments. However, this paper considers mathematics of **numeric** inverted indexes, which can handle noisy numeric data and, as such, can be used for pattern recognition.

Given variables with subscripts, for instance, elements of sequences, vectors, matrices etc., subsets of their subscripts can be considered. For instance, in a sequence $x_1, ..., x_N$, variables' indexes are just consecutive subscripts. On the other hand, S&P,



Figure 3: Influence of connection density on pattern recognition accuracy. **a**, accuracy function at 5%-feature noise on testing with macrocolumns (R = 3%) and inhibition. **b**, accuracy function at 5%-feature noise on testing without macrocolumns and inhibition.



Figure 4: Set recognition accuracy as a function of macrocolumn radius *R* with and without inhibition of inputs. **a**, with inhibition, noise at validation = 5%, best accuracy = 95% at R = 3%. **b**, no inhibition, noise at testing = 5%, best accuracy = 54% at R = 1%.



Figure 5: Vector recognition accuracy as a function of macrocolumn radius *R*. **a**, noise at testing = 50%, accuracy = 100% at R = 2.3% - 80% of a 256-feature range. **b**, noise at testing = 100%, accuracy = 100% at R = 10.9% - 59.4% of a 256-feature range.

Dow-Jones etc., are value indexes. If multiple values are used as indexes, it becomes possible, for example, to quickly find a useful pattern in millions of noisy patterns, instantaneously predict coming failures of jet engines (Mikhailov, A., Karavay, M. and Farkhadov, M., 2017), accurately diagnose diseases with gene expression profiles (Mikhailov, A. et al., 2023), recognize trademarks images (Mikhailov, A., Karavay, M., 2023) and so on. Such numeric inverse indexing can be achieved by swapping subscripts and values.

6.1 Numeric Inverted Index

Values and their subscript subsets can be flipped as easily as sides of a coin. Such swap transforms are a one-to-one correspondence in a sense that values can be uniquely reconstructed from the subsets of subscripts and vice versa. These transforms do not involve any arithmetic operations but just rearranging of data. This is a reason numeric inverse indexing can often deliver practically instant machine learning, because all it takes to train a connectivity-based system (Figure 1) is to rearrange data. Note that all variables in the following expressions are integers.

Example 1. Given a sequence of values

$$x_n, n = 1, .., N, x \in X$$

where X is a set of all distinct values of x_n , the following subsets of subscripts can be constructed:

$$\{n\}_x = \{n \colon x = x_n\}, \quad \forall x \in X$$

In mathematics, such subsets are called inverse images or pre-images, which are referred to in this paper as inverse patterns. Here, the numeric inverted index transform is

$$x_n, n = 1, ..., N \iff \{n\}_x, \forall x \in X$$

Clearly, each side of the above expression can be uniquely reconstructed from the other side. The numeric inverted index algorithm is as follows:

$$m = 1, ..., N, \{n\}_{x_m} = \{n\}_{x_m} \bigcup m$$

with initial conditions: $\{n\}_x = \emptyset$, $\forall x \in X$. Obviously, after executing the algorithm, we have $\{n\}_{x_k} = \{n\}_{x_m}$, if $x_k = x_m$, even though $k \neq m$.

The histogram $h_x = |\{n\}_x|, \forall x \in X$, represents sizes of subsets indexed by values

Example 2. Given a matrix of *N* distinct rows

$$(x_{n,f})_{N \times F} = \begin{pmatrix} x_{1,1} & \dots & x_{1,F} \\ \vdots & \ddots & \vdots \\ x_{N,1} & \dots & x_{N,F} \end{pmatrix}$$
(1)

where $x \in X$, the numeric inverted index transform

$$(x_{n,f})_{N \times F} \leftrightarrow (\{n\}_{x,f})_{|X| \times F}$$

produces an array of sets of row subscripts

$$(\{n\}_{x,f})_{|X| \ltimes F} = \begin{pmatrix} \{n\}_{1,1} & \dots & \{n\}_{1,F} \\ \vdots & \ddots & \vdots \\ \{n\}_{N,1} & \cdots & \{n\}_{N,F} \end{pmatrix}$$

Here, the numeric inverted index algorithm is given as

 $f = 1, ..., F, \ m = 1, ..., N, \ \{n\}_{x_{m,f}, f} = \{n\}_{x_{m,f}, f} \bigcup m$ with initial conditions: $\{n\}_{x_{m,f}, f} = \emptyset, \ \forall \ m, f$

6.2 Pattern Recognition Task

Given an input pattern $\mathbf{x} = (x_f, f = 1, ..., F)$ and

collection of patterns (1) represented by N distinct rows of features, it is required to find a row that shares a maximum number of similar features with the input pattern, that is

$$m: H_R(\mathbf{x}, \mathbf{x}_m) = \max_{n=1}^N H_R(\mathbf{x}, \mathbf{x}_n)$$
(2)

A full search would take about FN operations needed to compare the input pattern **x** to *N* template patterns. However, a use of inverse data representations, that is, numeric inverted indexed allows reducing the computational complexity on recognition to O(FN/X).

6.3 Solution to Pattern Recognition Task

The numeric inverted index transform produces a matrix of inverse patterns, which allows calculating Hamming vector similarities $H_R(\mathbf{x}, \mathbf{x}_m)$ (number of dimensions with close features) between an input vector $\mathbf{x} = (x_1, ..., x_F)$ and all template vectors $\mathbf{x}_m = (x_{m,1}, ..., x_{m,F})$, m = 1, ..., N, as samples of the following index histogram:

$$H_{R}(\mathbf{x},\mathbf{x}_{m}) = |\{f: m \in \bigcup_{x > x_{f} - R}^{x < x_{f} + R} \{n\}_{x, f}\}|, m = 1, ..., N$$

Indeed, the numeric inverse indexing ensures that

$$m \in \bigcup_{x > x_f - R}^{x < x_f + R} \{n\}_{x, f} \iff |x_f - x_{m, f}| < R$$

Finally, the solution to the pattern recognition task is a feature vector \mathbf{x}_m that satisfies (2).

6.4 Set Case

There exist certain differences in processing of feature vectors and feature sets because the latter once are unordered, variable size patterns. This is

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the reason the Hamming vector similarity was replaced with Jaccard similarity measure

$$S(Y, X_n) = |Y \cap X_n| / |Y \bigcup X_n|, n = 1, ..., N$$

Here, $X_n = \{x\}_n$, n = 1, ..., N, is a sequence of enumerated sets and $Y = \{y\}$ is an input set. The inverse sets can be produced by the numeric inverted index algorithm

 $\{n\}_{x} = \{n\}_{x} \bigcup m, \ \forall x \in X_{m}, \ m = 1, ..., N$ with initial conditions: $\{n\}_{x} = \emptyset, \ \forall x \in \bigcup X_{m}$

The Jaccard similarity should be re-written as

$$S_{R}(Y, X_{n}) = \frac{|Y \bigcap_{R} X_{n}|}{|Y| + |Y_{n}| - |Y \bigcap_{R} X_{n}|}, \ n = 1, ..., N$$
(3)

Here, $|Y \bigcap_R X_n|$ is the random quasi intersection (Mikhailov, A., Karavay, M., 2023). Finally, the solution to the feature set recognition task is the pattern X_n that maximizes (3).

7 CONCLUSIONS

1) Cortical column can be mathematically described as an inverse pattern.

2) A set of cortical columns serves as an inverted index.

4) Inverted index supports practically instant learning capabilities even in noisy environments.

3) Increased number of cortical columns enhances pattern recognition accuracy.

4) Suggested model shows a way of implementing pattern learning systems that do not use any arithmetic operations.

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APPENDIX

This section provides details of computer experiments described in Section 5.

Experiment 1: The collection of 1280 random patterns, where each pattern was represented by a variable length feature set, was created T times. Each time, the system's memory was reset and the system re-trained with the next 1280-pattern collection by using the numeric inverted index transform (Section 6.1). The number of columns in the region was C = 256. In accordance with the connectivity equation, $D = \overline{F}N/C$, the connection density kept on increasing at each training session by incrementing the average pattern size: $\overline{F} = 1\%$, 2%,...,100%. The random feature values of each pattern were uniformly distributed in the interval [0, *C*-1]. The random lengths of patterns were normally distributed in the interval $[\overline{F} - 0.05C, \overline{F} + 0.05C]$. On each testing run, each feature x from the current pattern collection was distorted by $\xi = 5\%$ random noise, that is, $\tilde{x} = (1 \pm \xi)x$. The experiment was conducted twice. For the first training/testing batch, the radius was set to R = 3% of the value of C, leading up to almost a 100% accuracy. For the second batch, the radius was set to 0, resulting in a poor performance.

Experiment 2: The collection of 1280 random patterns, where each pattern was represented by a variable length feature set, was created only one time. The average pattern size was set to 64 features. As in experiment 1, the random feature values of each pattern were uniformly distributed in the interval [0, C-1]. The random lengths of each pattern were normally distributed in the interval $[\bar{F}-0.05C, \bar{F}+0.05C]$.

For a testing, each feature *x* from the training pattern collection was distorted by $\xi = 5\%$ random noise. Unlike experiment 1, the macrocolumn radius kept on increasing at each testing run as R = 1%, 2%, ..., 32% of *C*. Although training was conducted only once, the 32 testing runs were conducted twice. Whereas the first testing batch involved a use of inhibition, the second testing batch was inhibition free, resulting in a poor performance.

Experiment 3: In this experiment, 1280 vectors in F - dimensional space (F = 128) were employed to train the system using the numeric inverted index algorithm (Section 6.1). The uniformly distributed random components of vectors ranged from 0 to 255. The test set contained the same vectors that were engineered from training set by way of distorting original vectors' components x by $\xi = 50\%$ noise of the value of the corresponding

component. The pattern size was fixed at F = 128. All 1280 test vectors were submitted for recognition. The resulting accuracy function achieves a 100%-level for a wide range of *R*. Note that in the vector case, inhibition policy is not needed.