Contactless Camera-Based Detection of Oxygen Desaturation Events and ODI Estimation During Sleep in SAS Patients

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- Keywords: Contactless, Camera-Based, Oxygen Desaturation Detection, ODI, Sleep Apnea, SAS, Feature Extraction, rPPG, Near-Infrared, Far-Infrared.
- Abstract: Recurrent nocturnal breathing cessation leads to the reduction of the blood oxygen level and eventually to oxygen desaturation. Oxygen desaturation events are traditionally detected during a polysomnography in a sleep laboratory. In this work, a contactless camera-based oxygen desaturation detection and oxygen desaturation index (ODI) estimation method based on the analysis of multispectral videos is proposed. The method is based on the extraction and analysis of remote photoplethysmography (rPPG) signals at wavelengths of 780 nm and 940 nm from the forehead and a breath temperature signal via far-infrared (FIR) thermography from the subnasal region. A manual feature extraction is designed to extract relevant medical and physiological parameters out of the aforementioned signals in order to design a Feed-Forward Neural Network (FFNN)-based classifier, which classifies between periods with and without desaturation events. For the evaluation of the proposed method, a patient dataset involving 23 symptomatic sleep apnea patients is collected. The classification accuracy between desaturation events and periods without a desaturation based on the leave-one-patient-out cross-validation (LOPOCV) metric is 95.4 %. The ODI stage estimation resulted in a correct estimation in 22 out of 23 patients for a two-stage ODI classification and in a correct estimation in 21 out of 23 patients for a four-stage ODI classification.

SCIENCE AND TECHNOLOGY PUBLICATIONS

1 INTRODUCTION

The sleep apnea syndrome (SAS) is a sleeping disorder characterized by recurring cessations of airflow during sleep, leading to a number of complaints, such as daytime sleepiness, concentration problems, and risk of cardiovascular diseases (Rundo, 2019). Recurrent breathing cessation leads to the reduction of the blood oxygen level and eventually hypoxemia (Rashid et al., 2021). Episodes of hypoxemia during sleep are referred to as oxygen desaturation events (Smith et al., 1996). A desaturation is defined as a decrease in the SpO₂ value by at least 3 % (Berry et al., 2020). The prevalence of desaturation events is summarized in the oxygen desaturation index (ODI), which is the average number of desaturation events per hour of sleep (Temirbekov et al., 2018). The ODI, together with the apnea-hypopnea index (AHI), is one of the two most important indicators for the severity of SAS (Rashid et al., 2021).

The gold standard for diagnosing SAS is polysomnography (PSG), a multi-parametric measurement conducted in sleep laboratories. A PSG involves a high number of contact-based sensors, resulting in patient discomfort and unnatural sleeping behavior, which may lead to biased measurement results (Smolley, 2023). A contactless alternative the potential to reduce the drawbacks of a PSG and furthermore, enable sleep diagnostics outside of sleep laboratories. A very promising direction for contactless sleep diagnostics are camera-based solutions.

In this work, an oxygen desaturation detection and ODI estimation method based on the analysis of multispectral videos is proposed. The method is based on the extraction and analysis of remote photoplethysmography (rPPG) signals from two nearinfrared (NIR) wavelengths from the forehead and a breath temperature signal from the subnasal region.

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2 RELATED WORK

The first method for measuring a photoplethysmography (PPG) signal without direct contact to the human skin was proposed in (Humphreys et al., 2005). Light from two infrared LEDs (760 nm and 880 nm) was emitted through the index finger and the transmitted light was measured by a CMOS camera 40 cm away. Later the same year, in (Wieringa et al., 2005), the concept for a contactless PPG-based measurement of the peripheral oxygen saturation (SpO₂) via rPPG was introduced. Between 2005 and 2023, a total of twelve studies dealing with the contactless measurement of SpO₂ have been obtained in a literature screening conducted as a part of this study. An overview of these studies is provided in Table 1.

Ten studies involved optical methods based on the analysis of rPPG signals from multiple wavelengths, while two are based on respiratory movement analysis via radar. The regions of interest (ROI) for the signal source varied between the hand (Wieringa et al., 2005) (Tsai et al., 2014) (Liao et al., 2023) and the face (Lingqin et al., 2013) (Guazzi et al., 2015) (Shao et al., 2016) (Addison et al., 2017) (Vogels et al., 2018) (Rosa and Betini, 2020) (Wieler et al., 2021) for methods based on rPPG, and the thorax (Tran and Al-Jumaily, 2019) (Toften et al., 2021) for methods based on the Doppler effect. All studies introduced a regression analysis method to determine the SpO₂ value, except (Addison et al., 2017), where detection of hypoxia was performed. Three studies involved sleeping subjects (Vogels et al., 2018) (Tran and Al-Jumaily, 2019) (Toften et al., 2021), out of which the latter two involved symptomatic SAS patients.

The following observations and conclusions are made based on the overview of related work: (1) the regression of the SpO_2 value via contactless methods is a non-trivial task; (2) there are still insufficient patient studies for conclusive evidence on the medical applicability of the proposed methods; (3) the majority (9 out of 12) of studies are conducted with



Figure 1: Absorption behavior of Hb (orange) and HbO₂ (blue) with respect to the wavelength of the incident light (Prahl, 1998).

healthy test subjects and only three included measurements in the hypoxemic range; (4) all studies have a small number of test subjects (in the one-digit or low double-digit range), which is insufficient for conclusive proof of principle concerning demographic variability; (5) none of the listed studies dealt with the detection of oxygen desaturation events nor the estimation of the ODI score; and (6) there is an evident necessity for further work in this area.

3 METHODS

3.1 Selection of Biosignals

Peripheral oxygen saturation (SpO_2) is the percentage of oxyhemoglobin in the total hemoglobin. Oxyhemoglobin and deoxyhemoglobin experience dissimilar light absorption behavior, as shown in Figure 1 (Prahl, 1998). In order to determine the amount of oxyhemoglobin in the blood, at least two rPPG signals at distinct wavelengths need to be measured. Furthermore, the first wavelengths should be chosen so that the absorption ratio of oxyhemoglobin is higher than the absorption ratio of deoxyhemoglobin, and vice versa for the second wavelength. Further details on this principle may be found in (Mannheimer et al., 1997).

An external light source is necessary for a continuous SpO_2 measurement during the night with a camera. In order not to interrupt the sleeping person, the light source, as well as the wavelengths of the rPPG signals, need to be selected in the NIR spectrum. By analyzing the Hb and HbO₂ absorption behavior from Figure 1, taking into account the selection criteria mentioned previously, and considering the specifications of optical components available on the market, a combination of the 780 and 940 nm wavelengths is selected.

Oxygen desaturation events often take place directly after a patient experiences an apneic event, due to the continued cessation in breathing. Figure 2 shows a section of a PSG measurement from a patient enrolled in this study which displays four biosignals: 1) the airflow measured with a nasal cannula; 2) the SpO₂ value measured with a pulse oximeter; 3) the movement of the thorax measured with an inductive respiration sensor; and 4) the movement of the abdomen measured also by an inductive respiration sensor. An obstructive apnea is detected and labeled on the airflow signal, while a desaturation event is labeled on the SpO₂ signal. By examining the timing of these two events, it can be noticed that the desaturation event starts approx. 20 seconds after the

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Publication	Study topic	ROI	Test subjects					
(Wieringa et al., 2005)	Proof of concept study	Hand	healthy, awake					
(Lingqin et al., 2013)	SpO ₂ Regression via rPPG	Face	healthy, awake					
(Tsai et al., 2014)	SpO ₂ Regression via rPPG	Hand	healthy, awake					
(Guazzi et al., 2015)	SpO ₂ Regression via rPPG	Face	healthy, awake					
(Shao et al., 2016)	SpO ₂ Regression via rPPG	Face	sick, awake					
(Addison et al., 2017)	Hypoxia detection via rPPG	Face	healthy, awake (porcine)					
(Vogels et al., 2018)	SpO ₂ Regression via rPPG	Face	healthy, asleep					
(Tran and Al-Jumaily, 2019)	SpO ₂ Regression via Radar	Thorax	sick, asleep					
(Rosa and Betini, 2020)	SpO ₂ Regression via rPPG	Face	healthy, awake					
(Toften et al., 2021)	SpO ₂ Regression via Radar	Thorax	sick, asleep					
(Wieler et al., 2021)	SpO ₂ Regression via rPPG	Face	healthy, awake (infant)					
(Liao et al., 2023)	SpO ₂ Regression via rPPG	Hand	healthy, awake					

Table 1: Overview of publications on contactless measurement of SpO₂.

apnea. Furthermore, the desaturation event ends approx. 20 seconds after the apnea has ended, leading to a restoration of the baseline SpO_2 level. This correlation between nocturnal respiratory events and oxygen desaturation events could therefore be a significant tool to detect oxygen desaturation events. Hence, in addition to the two rPPG signals, a new biosignal is introduced: the breath temperature signal measured in the subnasal region (equivalent to the measurement location of a nasal cannula during PSG) via FIR thermography.

3.2 Signal Acquisition

For the acquisition of the three aforementioned biosignals, a multi-modal camera system is used. The camera systems consists of: 1) a real-time NIR 3D sensor for analyzing head motion; 2) a NIR camera with a central wavelength of $\lambda_c = 780$ nm and a full width at half maximum bandwidth of *FWHM* = 10 nm; 3) a NIR camera with $\lambda_c = 940$ nm and *FWHM* = 10 nm; 4) a far-infrared (FIR) thermography camera with a noise equivalent temperature difference of *NETD* < 0.05 °C at 30 °C/50 mK; and 5) one LED with $\lambda_c = 780$ nm and *FWHM* = 28 nm and three LEDs with $\lambda_c = 940$ nm and *FWHM* = 37 nm. More details on the multi-modal camera system may be found in previous publications (Zhang et al., 2020) (Alić et al., 2023a) (Alić et al., 2023b).

Two ROIs are detected and tracked on the 3D image sequences, namely an ROI on the forehead for the extraction of the rPPG signals and an ROI in the subnasal region for the extraction of the breath temperature signal. The generated 3D ROIs are then projected onto the 2D images from the NIR and FIR cameras. The rPPG signals are extracted using the approach presented in (Zhang et al., 2020), which is based on Eulerian video magnification (Wu et al., 2012). The breath temperature signal is generated by pixel-wise averaging of temperature values in the ROI in each frame of the FIR thermography camera. The signal acquisition is demonstrated in Figure 3.

3.3 Data Labeling

The labeling of desaturation events in the PSG measurement is done semi-automatically. A first labeling iteration is done automatically by the Noxturnal sleep scoring software. In the second iteration, a sleep physician manually confirms the labeled events and checks for missed events. The extracted time-series signals are synchronized with the corresponding data from a PSG reference measurement by system clock alignment. The timestamps of the labeled desaturation events and periods with a stable SpO₂ value are applied to the extracted biosignals. Resaturation periods, i.e. periods after a desaturation in which the SpO₂ value is being restored to the baseline value, are not labeled.

3.4 Signal Preprocessing

The first step in the preprocessing of the three raw time-domain signals is detrending. Detrending is performed with the Detrending moving average algorithm with a window size of 150 samples (equivalent to ten seconds). Hereby, the superimposed DC signal components are removed for a more systematic data comparison. The DC components may differ during one or between two measurements due to environmental and lighting factors (e.g. ambient light, moonlight and sky clearness), patient demographics (e.g. age and skin type) and movements (e.g. sleep position, head rotation and restless leg syndrome).

After detrending, three finite impulse response band-pass filters with distinct cut-off frequencies are applied. The high-pass (HP) and low-pass (LP) cutoff frequencies for each filter are given in Table 2.



Figure 2: A section of a PSG recording in Noxturnal consisting of (from top to bottom): 1) Respiratory flow signal with a labeled obstructive apnea; 2) SpO_2 signal with a labeled desaturation event; 3) Thorax movement signal; and 4) Abdomen movement signal.



Figure 3: Extraction of rPPG and temperature (FIR) signals from multi-modal 3D video data.

The cut-off frequencies of each band-pass filter are designed in order to emphasize relevant information in designated frequency spectra: 1) to remove high-frequency noise; 2) to isolate signal components associated with the heart rate; and 3) to isolate signal components associated with the respiration rate. A list of filters, their respective cut-off frequencies, and the signals to which they are applied are given in Table 2.

3.5 Feature Extraction

The main challenge in differentiating between periods with and without a desaturation event is detecting and extracting medically significant features, which are able to distinguish between the two event classes. The feature detection process is conducted in two approaches: (1) through discussions with sleep medicine experts on expected physiological processes and biosignal behavior; and (2) through screening of the signal waveform, spectral and statistical analysis.

A desaturation event is expected to occur 10 to 30 seconds after the beginning of an apneic event (Borer, 2011). Consequently, the analysis of the respiratory activity prior to an event may contribute to the dis-



Figure 4: Section of the filtered 780 nm signal (above); and its Fourier transformation to determine the respiration rate (below).



Figure 5: Respiration rate estimation by peak-to-peak analysis of the 780 nm signal (above); and SpO₂ reference signal with labeled desaturation events (below).

tinction between desaturation events and stable SpO_2 periods. Furthermore, due to the restoration of respiratory activity after the end of the apneic event, higher respiratory activity is to be expected during and directly after desaturation events. To qualitatively ex-

HP (Hz)	LP (Hz)	HP (rpm)	LP (rpm)	Applied to 780 nm signal	Applied to 940 nm signal	Applied to FIR signal	Filter purpose
0.1	3	6	180	yes	yes	yes	Denoising
0.8	1.4	48	84	yes	yes	no	Isolating heart rate
0.1	0.5	6	30	yes	yes	yes	Isolating respiration rate

Table 2: Characterization of band-pass filters applied to the 780 nm and 940 nm rPPG signals and FIR thermography signal.



Figure 6: Section of the filtered 780 nm signal (above) and its Fourier transformation to determine the heart rate (below).

amine this hypothesis, a section of a 780 nm rPPG signal is selected and a Fast Fourier Transformation (FFT) is applied to it (after band-pass filtering) in order to detect the respiratory rate. The respiratory rate is assumed to be the highest peak in the frequency spectrum. This rPPG signal section is presented in Figure 4. By increasing the section to a 100-second-long sample, computing the instantaneous peak frequency, and applying a moving average filter (with a window size of four samples), the hypothesis stated previously is confirmed. A decreased respiratory activity is registered before both desaturation events in the sample, while an increased respiratory activity is registered during the desaturation events. This sample is presented in Figure 5.

Due to reduced oxygen intake, the body activates adaptation mechanisms to compensate for the lack of oxygen. This may lead to increased and arrhythmic heart rate (Rossi et al., 2012). In order to qualitatively analyze the correlation between changes in heart rate and oxygen saturation, the same analysis is performed on the same signal sample with the only difference being the cut-off frequencies of the band-pass filter. There is no qualitatively detectable change in heart rate during or after a desaturation event. This analysis is presented in Figures 6 and 7. Nevertheless, features for analyzing the correlation between arrhythmic heart activity and desaturation events are implemented and evaluated in the feature selection stage.



Figure 7: Heart rate estimation by peak-to-peak analysis of the 780 nm signal (above); and SpO₂ reference signal with labeled desaturation events (below).



Figure 8: Section of the filtered 780 nm signal (above); section of the filtered 940 nm signal (middle); and Ratio-ofratios estimation (below).

Having two PPG signals with correctly chosen wavelengths enables the direct computation of the SpO₂ value by using the ratio-of-ratios method. However, the SNR of rPPG signals is significantly lower compared to contact-based PPG. Qualitative analyses showed that the direct computation of the SpO₂ value with the collected rPPG signals and the ratio-of-ratios method is not feasible. Nevertheless, is it analyzed whether there is a correlation between the computed ratio-of-ratios and desaturation events by performing the same analysis as previously, with the addition of adding the 940 nm rPPG signal (Figure 8). The mov-



Figure 9: Ratio-of-ratios estimation (above); and SpO₂ reference signal with labeled desaturation events (below).



Figure 10: Histogram of the distribution of the Ratio-ofratios value between periods with and without a desaturation event.

ing average of the ratio value in Figure 9 shows no evident correlation neither to the reference SpO_2 nor to the periods before or during a desaturation event. The cross-correlation of the two signals resulted in r = 0.21, indicating a low correlation. To further analyze the significance of the ratio-of-ratios as a feature, a continuous histogram showing the statistical distribution of the value of this feature among the collected patient dataset is computed and presented in Figure 10. There is a significant overlap of the two classes with a slight tendency for a higher value in desaturation event samples.

Besides features implemented based on expected physiological behavior, statistical, spectral, and signal waveform features are implemented. Due to space restrictions, only a few selected features are presented in detail, while the best-performing features are presented in subsection 3.6. During the analysis of the expected physiological behavior, it is concluded that not only the behavior during the event is of interest, but also periods prior to and directly after the event.

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This approach is applied to the other types of features as well.

Figure 11 shows the continuous histograms of four selected features. The upper left histogram shows the distribution of the mean value of the 940 nm rPPG signal during an event. The upper right histogram shows the distribution of the median value of the FIR signal during an event. The lower left histogram shows the distribution of the total energy of the 780 nm rPPG signal during an event. The lower right histogram shows the distribution of the spectral centroid of the 940 nm rPPG signal prior to an event. The first observation that can be made is that there is no significant correlation between the features, meaning that the features show properties of statistical independence. The second observation with all four features is that there is no feature that can completely separate the two classes. However significant areas without overlap of the two classes exist, which could indicate that they may contribute to the classification among the event classes.

3.6 Feature Selection

A multi-stage sequential backward selection (SBS) method for feature selection is applied in order to determine the optimal feature subset for subsequent classification. The SBS is evaluated with a random forest classifier. The fourth iteration of SBS resulted in an optimal feature subset of the size 25 with a classification accuracy of 81 %. Additional SBS iterations give lower accuracies and are therefore discarded. The optimal feature subset, together with signals the features are applied to, filtering strategy, and the timing are summarized in Table 3. Regarding the type of features in the optimal subset, eight are related to respiratory activity, six are statistical, five are spectral, three are based on the signal waveform, two are related to heart rate activity and the final one is the ratio-of-ratios. Regarding the timing, thirteen are during the event, eight are prior to the event and four are after the event.

3.7 Event Classification

For the classification between desaturation events and events with a stable SpO_2 value, a fully connected feedforward neural network (FFNN) classifier is designed. The number of input neurons is equal to the number of features in the optimal subset (25), while there is a single neuron in the output layer. The network topology and hyper-parameter optimization are performed iteratively. The best-performing network topology is shown to be a two-hidden-layer



Figure 11: Histograms showing the distribution of four statistical features among classes with and without desaturation events.



Figure 12: Measurement setup in the sleep laboratory.

structure with 64 and 32 neurons in the first and second hidden layer respectively. The activation function in both hidden layers is the rectified linear unit (ReLU), while a sigmoid activation function is used for the output neuron. The optimal hyperparameter set, as well as the trial range for each hyperparameter, is shown in Table 4. The evaluation of the model accuracy is based on leave-one-patient-out cross-validation (LOPOCV). In LOPOCV, the data from one patient is left aside for validation and a model is trained using the data from the remaining patients. This process is repeated N times, where N is the number of patients in the dataset. As a result, N classification accuracies from the N cross-validation iterations are obtained. The final model accuracy is given as the average classification accuracy of the N iterations.

3.8 ODI Estimation

The ODI value estimation is performed with a linear regression analysis based on forming the quotient of the number of detected desaturation events n_{desat} and the recorded sleep duration t_{rec} . The mathematical description of the regression model is given in Equation 1. The coefficients *a* and *b* are computed in the training phase. The evaluation of the model is based on LOPOCV.

Feature	Signals	Filtering strategy	Period
Mean	940 nm, FIR	Denoising	During event
Mean	940 nm, FIR	Denoising	Prior to event
Median	940 nm, FIR	Denoising	During event
Spectral Slope	940 nm	Denoising	During event
Spectral Centroid	940 nm	Denoising	During event
Spectral Kurtosis	FIR	Denoising	During event
Spectral Entropy	780 nm, FIR	Denoising	During event
Auto-correlation	780 nm	Denoising	During event
Total Energy	780 nm, 940 nm	Denoising	During event
Fundamental Frequency	780 nm	Isolating respiration rate	Prior to event
Fundamental Frequency	780 nm, FIR	Isolating respiration rate	After event
Spectral Distance	780 nm, 940 nm, FIR	Isolating respiration rate	Prior to event
Peak to Peak Distance	FIR	Isolating respiration rate	Prior to event
Peak to Peak Distance	FIR	Isolating respiration rate	During event
Fundamental Frequency	780 nm, 940 nm	Isolating heart rate	After event
Ratio-of-ratios	780 nm, 940 nm	Isolating heart rate	During event

Table 3: The list of the best 25 features computed by a multi-stage sequential backward selection.

Table 4: Hyper-pinarameter tuning range and final parameter set for FFNN classifier.

Hyper-parameter	Trial set	Optimal set
Activation	Sigmoid,	ReLU
function	ReLU, Tanh	Kelu
Learning	0.001, 0.005,	0.001
rate	0.01, 0.05, 0.1	0.001
Epochs	50, 100,	200
Epochs	150, 200	200
Batch Size	1, 5, 20,	5
Datch Size	32, 64, 128	TECHN

ODI severity is typically classified either in two stages or in four stages (Varghese et al., 2022). The distinction between the stages is based on predefined ODI value thresholds. The threshold values are presented in Table 5.

$$ODI_{Est} = a \cdot \frac{n_{desat}}{t_{rec}} + b \tag{1}$$

3.9 Patient Study

In order to collect data and evaluate the proposed methods, a patient study is conducted in cooperation with the Center for Sleep Medicine of the University Hospital Essen. The multi-modal camera system is installed in a dedicated room in the sleep laboratory and patients undergoing a PSG are filmed with the camera system in parallel to the PSG. The measurement setup is shown in Figure 12. The sensor head is placed perpendicularly to the pillow at a 150 cm distance from the mattress. This sensor positioning allows for successful signal extraction while the patients sleep on their backs. However, a signal extrac-

Table 5: Distribution of ODI score severity in two and four stages.

Two-	stage ODI	Four-stage ODI			
ODI	Severity	ODI	Severity		
7		≤ 5	normal		
< 15	normal	5 < <i>ODI</i> < 15	mild		
≥ 15	abnormal	$15 \le ODI < 30$	moderate		
		\geq 30	severe		

tion is not possible if the head of the patient is completely rotated to the side, or the patient sleeps on their stomach. This leads to "blind" measurement periods.

A total of 40 patients between April 2022 and April 2023 were recruited for the study. All 40 patients were transferred to the Center for Sleep Medicine because of a suspected SAS and this was their initial diagnosis measurement. The patients slept without any therapeutic devices, such as continuous positive airway pressure (CPAP) machines or oral appliances. The study yielded 23 successful measurements with sleeping periods recorded by the camera system. Four measurements were unsuccessful due to camera failure, while no useful image sequences could be extracted from 13 measurements. The mean AHI in the 23 successful recordings is 26.8 (21.7), while the mean ODI is 26.0 (17.9). The trend that male patients suffer from SAS more frequently compared to female patients is noticeable in the sample since 70 % of the patients are male. The mean age is 53.6 (13.1) and the mean BMI is 26.9 (5.5). A total of 796 desaturation events and 799 periods with stable SpO₂ values are recorded. An overview of the patient sample is provided in Table 6. The column *Recorded time* [*h*] indicates the number of sleep hours successfully recorded by the camera system. The col-



Figure 13: Boxplot of the LOPOCV classification accuracy of the 64/32 FFNN classifier.



Figure 14: Training performance of the 64/32 FFNN classifier.

umn *Desats recorded* indicates the number of desaturation events present in that time (according to the PSG and not the camera-based detection algorithm). The column *ODI during recorded time* [h] represents the quotient of the two aforementioned columns, indicating the reference ODI value during the periods successfully recorded by the camera system.

This study is approved by the Ethics Committee of the Faculty of Medicine, University of Duisburg-Essen (approval no. 21-10312-BO).

4 RESULTS

The classification accuracy between desaturation events and periods with a stable SpO₂ value is determined by the FFNN model presented in subsection 3.7 and evaluated using LOPOCV. The accuracy for all 23 patients is presented in form of a boxplot in Figure 13. The mean classification accuracy is 95.4 %. A classification accuracy of over 90 % is achieved with 21 patients, having only two outliers at 75 % and 62 %. The training performance of the model is shown in Figure 14.

The results of the ODI value estimation are presented in the Bland-Altman plot in Figure 15. As can be seen from the plot, there is no evident bias present between the two values. Regarding the 95 % limits of agreement (LoA), 21 measurements are within the LoA, while there are only two outliers slightly over the LoA. The results of the ODI stage estimation are divided into a two-stage and a four-stage problem, as defined in Table 5. The two-stage problem resulted in a correct prediction with 22 out of the 23 patients (96 %). The four-stage problem resulted in a correct prediction with 21 out of the 23 patients (91 %). Figure 16 shows the true and predicted ODI stages for all 23 patients. Patients with the IDs 0000 and 0019 are the only two patients whose ODI stage is not predicted correctly. However, in both of these cases, the difference between the true and predicted stages is off by one stage. For patient 0000 a moderate ODI is predicted, while the reference system indicates a mild ODI. On the other hand, for patient 0019 a severe ODI is predicted, while the reference system indicated a moderate ODI. In both cases, the estimation algorithm overestimated the ODI stage of the patients.

5 DISCUSSION

The focus of this work is the detection of oxygen desaturation events and their distinction to periods without a desaturation event, rather than the regression of the SpO₂ value. The previous studies listed in Section 2 do not deal with such a distinction, thus making a direct comparison of algorithm accuracy unfeasible. Regarding the desaturation detection accuracy of existing sleep scoring software tools for PSG, a study was conducted in (Karhu et al., 2022), where the event detection accuracy of three sleep scoring tools was compared to manual scoring. The following accuracies were achieved on a sample of 100 patients: 1) Noxturnal: 97.3 %; 2) ABOSA: 97.1 % and 3) Profusion: 96.1 %. The detection accuracy of 95.4 % achieved by the contactless approach presented in this paper on a sample of 23 patients deviates from the detection accuracy of the best-performing sleep scoring tool Noxturnal by only 1.9 %. Sleep medicine experts from the University Hospital Essen gave a positive evaluation for this accuracy and stated that the accuracy is sufficiently high to be applied in medical practice.

Since ODI estimation with contactless methods was not conducted in any of the related studies mentioned in Section 2, a direct comparison and evaluation are not feasible. Therefore, the results of the ODI

Patient ID	Sex	Age	BMI	AHI	ODI	Sleep time [h]	Recorded time [h]	ODI during recorded time [h]	Desats. in PSG	Desats. recorded
0000	m	27	29.7	14.5	9.4	5.45	3.90	8.5	59	33
0001	m	48	30.2	11.9	33.7	2.85	1.18	17.8	144	21
0003	f	51	28.7	29.0	34.6	6.23	2.78	49.3	210	137
0006	f	52	22.0	12.2	10.2	5.00	0.90	8.9	64	8
0007	m	56	35.9	69.9	78.0	5.62	2.86	78.0	483	223
0008	m	37	33.6	30.2	28.9	1.52	0.68	23.6	179	16
0009	f	57	33.3	9.9	8.8	4.75	0.76	25.0	70	19
0012	m	52	32.1	12.7	12.2	5.58	0.79	41.8	91	33
0013	m	50	27.8	12.1	16.7	7.42	0.41	24.4	124	10
0014	m	80	21.1	20.9	10.7	5.40	3.69	14.1	64	52
0015	f	63	36.5	12.2	16.5	5.08	0.49	20.4	116	10
0016	m	67	28.7	7.4	25.9	5.23	0.09	0.0	152	0
0018	f	54	37.6	35.2	29.0	3.08	1.57	8.3	156	13
0019	m	58	35.1	59.7	62.8	6.18	0.96	21.9	422	32
0020	m	45	30.5	84.9	65.6	6.28	0.18	106.0	434	19
0021	m	51	34.6	55.6	63.3	5.97	0.22	68.2	435	15
0025	m	60	30.0	55.0	28.8	3.43	0.78	12.8	169	10
0026	f	27	18.9	5.2	10.7	5.78	0.77	46.8	67	36
0027	f	55	31.2	18.6	16.0	4.18	3.02	20.2	89	61
0029	m	62	24.8	53.3	44.5	3.96	0.09	55.6	252	5
0030	m	63	27.5	29.8	13.1	6.33	0.18	27.8	150	5
0033	m	79	25.2	14.0	22.8	6.86	0.07	100.0	157	7
0036	m	38	43.4	31.9	30.9	5.95	0.67	46.3	197	31
Mean	0.7 m	53.6	29.6	26.8	26.0	5.1	1.2	35.9	186.3	34.6
STD	n/a	13.1	5.5	21.7	17.9	1.4	1.2	28.5	128.4	48.9

Table 6: Overview of the collected patient sample.



Figure 15: Bland–Altman plot comparing the reference value ODI_{True} and the estimated value ODI_{Est} .

estimation are discussed with the sleep medicine experts from the University Hospital Essen. They have stated that the high prediction accuracy for the ODI stage is satisfactory and sufficient for diagnosis applications in sleep laboratories.

The core of the presented approach is the manual feature extraction based on both medical expert knowledge, as well as, statistical, signal waveform, and spectral analysis. The first novel approach is the introduction of periods 30 seconds before and after



Figure 16: Comparison of the predicted and true ODI stages.

an event into the feature analysis. The decision to include these phases is based on the findings presented in Section 3.5. By analyzing the optimal feature subset from Table 3, it can be observed that both the periods before and after an event have a significant contribution to the classification. Therefore, it can be concluded that changes in physiological processes before, during, and after an event are detectable by the presented method and that they exhibit a significant contribution in detecting desaturation events. The second novel approach is the introduction of features based on the analysis of the respiratory and heart rate behavior. These features are developed as a result of discussions with sleep medicine experts on the correlations between heart rate, respiration rate, and SpO₂. These features have also proven to be vital in the classification process.

Persistent hypoxemic SpO₂ values during sleep are associated with numerous severe health risks, such as organ damage, heart failure, tachycardia, persistent headaches, and shortness of breath (Berry, 2012). Additionally, several studies report the association with cognitive deficits, deficits in memory, visuospatial, and decision-making abilities (Bucks et al., 2013) (Delazer et al., 2016). These health risks emphasize the importance of SpO₂ monitoring and the timely diagnosis and treatment of sleep-related breathing disorders (SRBD). However, the vast majority of SRBDs remain undiagnosed mostly due to socioeconomic reasons associated with high cost and long waiting times for sleep lab examinations and patient unawareness of the condition (Faria et al., 2021). The introduction of alternatives to a PSG has the potential to reduce the prevalence of undiagnosed SRBDs and decrease the public health burden they pose by lowering costs and increasing the availability of SRBD diagnostic tools. The importance and benefits of contactless solutions for patient diagnostics have already been proven (Alić et al., 2023), but the number of solutions and research in this field is still scarce. This presents a challenge and an opportunity for further work in this, for both SRBDs and other types of illnesses as well.

6 CONCLUSION

The presented work introduces a novel approach for contactless camera-based detection of oxygen desaturation events and ODI score estimation in SAS patients. The core of the novel approach is the feature extraction method based on the analysis of medically significant events in the rPPG and breath temperature signals. The feature analysis includes not only the periods during the event but also 30-second-long periods before and after an event, in order to capture expected respiratory and heart rate activity associated with oxygen desaturation events. The method is evaluated on a balanced dataset of 1595 events captured in a patient study involving 23 symptomatic SAS patients. The classification accuracy between desaturation events and periods without a desaturation based on the LOPOCV metric is 95.4 %. The ODI stage estimation resulted in a correct estimation in 22 out of 23 patients for a two-stage ODI classification and in a correct estimation in 21 out of 23 patients for a four-stage ODI classification.

In future work, the presented method is to be evaluated with a larger patient dataset, taking into account the influence of various demographic parameters on the classification accuracy. Furthermore, the method shall be expanded in order to distinguish between desaturation depths instead of observing all levels of desaturation as a single class.

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