

# Fetal Health Classification Using One-Dimensional Convolutional Neural Network

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Keywords: 1D-CNN, CTG, Deep Learning.

Abstract: Within the medical field, machine learning has the potential to allow doctors and medical professionals to make faster, more accurate diagnoses, empowering specialists to take immediate action. Early diagnosis and prevention of fetal health conditions can be achieved based on the biomarker data derived from the cardiotocography signals. The study proposes using a one-dimensional convolutional neural network for fetal health classification and compares it to conventional machine learning algorithms. A one-dimensional convolutional neural network is shown to outperform traditional machine learning algorithms in both data sets (CTU-CHB and UCI), with an accuracy of 89% - 94%.

## 1 INTRODUCTION

Artificial intelligence for early diagnosis of medical cases is invaluable to saving lives and preventing other chronic patient conditions due to late diagnosis. Several machine-learning models have been applied successfully in cancer detection and diagnosis (Simes, 1985; Maclin et al., 1991; Cicchetti, 1992), tumor classification and malignant cases through X-Ray examination (Bocchi et al., 2004). Artificial intelligence allows doctors and medical professionals to diagnose faster and more accurately empowering specialists to take immediate actions based on the biomarker data provided to the model.


Cardiotocography (CTG) is used during prenatal and birth with the intention that the status of a foetus can be classified as normal, suspect, or pathological. The classifications are based on derived features from the Fetal Heart Rate (FHR) and Urinary Contractions (UC) for a given signal and are outlined in the Cardiotocograph Interpretation and Response (car, 2020) as well as the International Federation of Gynecology and Obstetrics (FIGO) consensus guidelines on intrapartum fetal monitoring (de Campos et al., 2015).


The main objective of this study is to build a computerised model that will, to a certain precision, classify different cases of intrapartum-related conditions.

The study aims to address the shortage of the current models that cannot classify suspected cases well (Cömert et al., 2016; Sundar et al., 2012) by comparing various models and their macro accuracy for classifications. The contribution of this research to the classification of CTG signals is to compare the performance results of five supervised machine learning models to improve Accuracy, F1-Score, Precision and Recall across both the UCI and CTU data sets.

The single-classifier machine-learning models K-Nearest Neighbours, Support Vector Machine, and Decision Tree are considered based on their success in previous studies. A decision tree is extended to a Random Forest ensemble method to reduce the spread of predictions and create a more robust model. Lastly, a multi-layer perceptron (MLP) is used due to its predictive capabilities originating from its hierarchical neuron structure. MLPs can solve problems stochastically, allowing for solutions to complex problems to be approximated accurately.

The outline of the paper is structured as follows. Section 2 indicates related work in fetal cardiac classification and the best-performing machine learning models. Section 3 specifies the data sets. Section 4 discusses the results on different data sets, with section 5 concluding the research study.

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## 2 RELATED WORKS

Existing works has seen the following machine learning models being used: K-means, Decision Trees, Random Forests, Multi-Layer Perceptron, Radial Basis Function Support Vector Machines, and Extreme Learning Machines (Comert and Kocamaz, 2017; Arif et al., 2020; Ayres-de Campos et al., 2005; Chamidah and Wasito, 2015) due to their excellent accuracy in evaluation and classifications of CTG signals. A study done by Ogasawara et al. (Ogasawara et al., 2021) claims that a deep neural network-based classification consisting of three convolutional layers outperform conventional algorithms in accuracy and precision for the same time window.

Kanika et al. (Agrawal and Mohan, 2019) assert that a decision tree and a support vector machine achieved above 90% accuracy, rivalling a deep neural network model. Likewise, Sihem et al. (NITA et al., 2018) believe that random forest is better suited for CTG predictions due to its lower chance of overfitting a model to cardiac-centred data. In 2017, Anish et al. (Batra et al., 2017) focused on cardiocography analysis using decision trees, support vector machines, random forests and neural network machine learning algorithms by comparing their overall accuracy through a confusion matrix. Anish et al. concluded that most machine learning algorithms were similar in accuracy (> 90%), with a decision tree achieving the highest accuracy between these methods with a 95% accuracy.

The use of deep learning algorithms is a well-established approach (Francis et al., 2022; Liang and Li, 2021; Sahin and Subasi, 2015) to the classification of fetal cardiocography signals and overall fetal well-being. Sai and Qia used a two-layer Convolutional Neural Network for the classification of a CTG signal (Chudáček et al., 2014) and evaluated it against seven trained models.

The utilisation of ensemble models leads to not only better performance in multi-class classification but provide more accurate results over conventional models (Rosly et al., 2018) within the medical applications.

## 3 METHODS

### 3.1 Data Sets

The CTU-CHB Intrapartum Cardiocography Database (Chudáček et al., 2014) consists of 552 intrapartum CTG recordings, acquired between 2009 and 2012 at the obstetrics ward of the University

Hospital in Brno, Czech Republic (Chudáček et al., 2014). The ground truth labels of this data set were not provided, and a manual classification based on the umbilical artery pH balance, with a threshold lower than 7.25, a low Apgar score at 5 minutes and an increase in heart accelerations were used. An increase in heart accelerations is a strong indicator of a well oxygenated foetus, and, in conjunction with pH and Apgar scores from the FIGO guidelines (Sehgal et al., 2017) and a study done by Allanson et al. (ER et al., 2016), are the most distinguishing features between normal and pathological outcomes.

The UCI dataset contains 2,126 fetal cardiograms, which have been subjected to feature extraction (Chudáček et al., 2014) and classified by three professional obstetricians (de Campos et al., 2015; Kadhim and Abed, 2020). The depictions of the classes are (Sehgal et al., 2017; C et al., 2012): *Normal* where all morphological features fall within the reassuring category. *Suspect* where some morphological features fall within one of the non-reassuring categories, while the remainder resides within the reassuring category. *Pathological* in the case where two or more morphological features fall within multiple non-reassuring categories. In both datasets a notable class imbalance exists, the CTU dataset feature double the amount of pathological outcomes versus normal and suspect. In the UCI dataset the normal class is heavily oversampled, constituting of 78% of the entire dataset.

### 3.2 Data Pre-Processing

The CTU dataset required extensive pre-processing to extract the best representation of the recorded signal. The figures below display the heart's beats per minute, which has been sampled at a frequency of 4Hz to provide four data points every second.

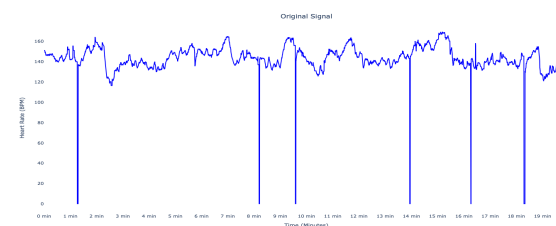


Figure 1: Raw unfiltered CTG Signal from the CTU data set.

As seen in Figure 1, the raw CTG signal is subject to gaps where the heart rate incorrectly drops to 0; for that reason, a 20 minute window of the signal was extracted to stay consistent across signals. Based on the FIGO guidelines, a reading of 30 minutes is required for the assessment of a CTG signal and ex-

tended if the FHR pattern seems suspicious (SIG, 2014). A sliding window was used to determine a valid, stable starting point by ensuring that a change of 10 bpm is not achieved for a minimum of 5 samples. Gaps shorter than five samples were then filled with the mean value of the valid segment, and the signal is interpolated using the Hermite spline interpolation mathematical function. The sample outliers were then addressed, such that all values reside within  $80 \leq N \leq 200$ , in line with FIGO Guidelines.

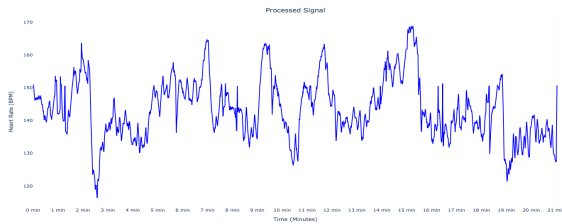


Figure 2: Filtered and interpolated CTG Signal after processing.

### 3.3 Feature Extraction

Morphological Features refer to an organ's shape, structure, and functional characteristics. The FIGO Guidelines focus on visually defined macroscopic features of the fetal heart, along with numerous other morphological measures (Sehgal et al., 2017). The morphological features that were used in this study are as follows: the mean FHR Baseline heart rate in which the presence of accelerated and decelerated heart rate is not present; the mean FHR heart rate for the valid segment; the Number of Decelerations in which the FHR slows down, as a result of the hormones released from the parasympathetic flow (Resnik et al., 2018), by more than 15 bpm over a 10-second window; Number of Accelerations in which the FHR speeds up due to the hormones released from the sympathetic flow (Resnik et al., 2018), by more than 15 bpm over a 15-second window. In addition to these features, the mean absolute deviation is computed for the average distance between each data point and the mean FHR value. After the morphological features have been extracted, the data is no longer constrained to the time domain but instead considered as a representation of the most prominent identifiers within the 20-minute extracted signal. The non-morphological features used were present in the accompanying signal meta-data and contained supplementary information such as the pH value, Apgar scores, foetus weeks, Meconium and Hypertension.

### 3.4 Model Selection and Implementation

The choice of machine learning models used in this research study, is drawn from the comprehensive review of the literature in this field. The following models and their respective implementations are listed below:

1. K Nearest Neighbours (KNN). The KNN algorithm employed Euclidean distance calculation as its metric to assess the proximity of data points.
2. Decision Tree. The implemented decision tree algorithm is based on the Classification And Regression Trees (CART) algorithm. The implementation utilises the Gini index as the splitting criteria and incorporates bagging to generate multiple subsets of samples and training multiple decision tree instances.
3. Random Forest. The random forest algorithm used the same structure as the decision trees with pruning to ensure trees are less susceptible to overfitting.
4. Support Vector Machine. One-vs-One classifier consisting of  $N$  classes and  $N = \frac{N(N-1)}{2}$  binary models are trained, with the sample classified as the most voted class. A One-vs-One classifier was used to mitigate potential class imbalances along with a linear kernel to avoid overfitting and the impact of potential outliers.
5. One-Dimensional Convolutional Neural Network (1D-CNN). The traditional one-dimensional convolutional neural network consists of three main layers - a convolutional layer, a pooling layer and a fully connected layer.

The convolutional layer is responsible for the computation of various features from the input data by applying a mathematical convolution operation to produce a feature map before being pooled to downsample the feature map and reduce computational costs.

Employing a scalable hyperparameter optimisation framework, various 1 Dimensional CNN configurations were tested for their overall accuracy, with the following topology being the most accurate. One key factor during the training of the one-dimensional convolutional neural network was the learning rate, considered the contributing factor to the convergence of the model. Using the loss graph against each training step indicated the pivotal section where the loss decreased the fastest as well as the learning rate used at that step. This

learning rate was determined to be 0.001 and was selected for subsequent model training iterations. Further to the learning rate, the convolutional and dense layers were diversified. Different combinations of accuracies were evaluated through sparse categorical cross-entropy as the loss function. Whilst tuning hyperparameters, an early stop with a patience of 20 epochs and model checkpointing after each epoch was implemented for model evaluation. Each tested configuration varied in layers and neurons and trained for 100 epochs to establish the most accurate model topology. The model parameters are as follows:

1. Three one-dimensional convolutional layers of filter and kernel size 8, 6, and 3, respectively, are responsible for feature extraction.
2. One dimensional max pooling layer of pooling size 3 is responsible for reducing the dimensionality.
3. One layer to flatten the feature map to a one-dimensional input for the fully connected layers.
4. Three fully connected dense layers with 132 and 68 neurons and a relu activation function for the first two layers and the final layer consisting of 3 neurons and the softmax function.

The simplicity of this CNN network topology reduces the chance of the model overfitting during training whilst ensuring the least impact on the performance degradation.

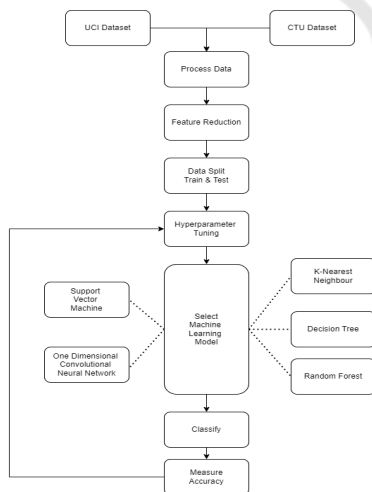


Figure 3: Applied machine learning methodology.

Figure 3 shows the outline of the steps taken, substituting different machine algorithms and tuning the hyperparameters of each of these to obtain the best accuracy.

Each model was evaluated using a confusion matrix obtained in a one-vs-all manner where the Precision, Recall, and F-1 score values were computed for each class separately. Each evaluation metric was calculated for the respective classification classes, and the overall performance of a multi-class classification model could be determined by summarising the micro value of each class, based on different hyperparameters.

## 4 RESULTS AND DISCUSSION

An initial objective of the project was to evaluate and compare the accuracy of different machine-learning algorithms when classifying fetal cardiac conditions. The accuracy of both 80/20 and 70/30 training/test set configurations were evaluated. The larger training set was chosen to ensure an ample test set for model evaluation. Evaluation metrics used within similar studies (Ogasawara et al., 2021; Bernardes, 2022; C et al., 2012; Arif et al., 2020) are Accuracy, F1-Score, Precision, and Recall with the following class mappings: *N=Normal, S=Suspect, P=Pathological*

### 4.1 K Nearest Neighbours (KNN)

Table 1: K Nearest Neighbours performance metrics on the CTU-CHB Interpartum data set.

K=5			
	Precision	Recall	F1-Score
N	84 %	74 %	78 %
S	82 %	78 %	80 %
P	82 %	88 %	85 %
Accuracy	82.17 %		

Table 2: K Nearest Neighbours performance metrics on the UCI data set.

K=5			
	Precision	Recall	F1-Score
N	85 %	72 %	78 %
S	85 %	75 %	79 %
P	80 %	90 %	85 %
Accuracy	88.06%		

Table 1 presents the summary statistics for the K Nearest Neighbours algorithm applied to the CTU-CHB Interpartum data set. The K Nearest Neighbours machine learning model could consistently and accurately form a robust decision boundary and correctly classify samples with a marginal increase in accuracy ( $\approx 0.3 - 0.8$ ) between 7 and 11 neighbour considerations. Hakan and Abdulhamit also reported a similar

finding (Sahin and Subasi, 2015), albeit with higher accuracy.

Table 2 shows strong evidence of an accurate K Nearest Neighbours classifier, with an overall accuracy of 88.06%, lower than previously reported by Hakan and Abdulhamit (Sahin and Subasi, 2015) on the same data set. It could therefore be hypothesised that the K Nearest Neighbour algorithm accurately classifies fetal cardiac state as clustered samples are homogeneous in terms of their features. The K Nearest Neighbours algorithm inherently doesn't make assumptions on data distributions and the effectiveness of the algorithm might indicate that the algorithm is able to clearly identify complex and non-linear relationships latent in the data. A comparison between the two results of the respective data sets, reveals that the K Nearest Neighbours is an effective fetal cardiac classification algorithm, given clear decision boundary separations between clusters can be determined.

## 4.2 Decision Tree

Table 3: Decision Tree performance metrics on the CTU-CHB Interpartum data set.

Max Depth=5			
	Precision	Recall	F1-Score
N	88 %	69 %	77 %
S	78 %	80 %	79 %
P	81 %	88 %	84 %
Accuracy	81.39 %		

Table 4: Decision Tree performance metrics on the UCI data set.

Max Depth=5			
	Precision	Recall	F1-Score
N	92 %	94 %	93 %
S	56 %	57 %	57 %
P	89 %	72 %	80 %
Accuracy	86.89 %		

The results obtained from the analysis of decision trees on fetal cardiac classification are summarised in Table 3 and Table 4 for both the CTU-CHB Interpartum and UCI Repository data sets, respectively.

It is encouraging to compare the findings of this research study with those of other studies (Batra et al., 2017; Sahin and Subasi, 2015; Rosly et al., 2018) who found the accuracy of decision trees in fetal cardiac classification to be highly accurate. The single most striking observation to emerge from the data comparison was the ability of the model to resist bias in undersampled classes and maintain accuracy across different data sets. These results further support the hypothesis that multiple perpendicular splits to the fea-

ture axes, combined, are capable of inferring complex non-linear relationships within the entire feature space to determine an effective decision boundary. Surprisingly in both instances, changes in the maximum depth of the tree did not yield a noticeable improvement in the overall accuracy of the classifier.

In the current study, comparing the results of the decision tree classifier for the two different data sets showed the model is flexible in the number of features used for classification, with a mean difference of 3% in accuracy between varying tree parameters. These results seem to be consistent with other research, which found that the decision tree algorithm is scalable to larger data sets whilst preserving its classification accuracy (Arif et al., 2020).

## 4.3 Random Forest

The findings illustrated below are consistent with that of similar studies (Sahin and Subasi, 2015; Batra et al., 2017) who noted that the accuracy of the Random Forest algorithm and decision tree differ by no more than 10% when utilising the same tree structure. However, as indicated by Sihem et al. (NITA et al., 2018), the accuracy of a Random Forest is proportional to the number of trees present and the maximum depth of each tree. This is confirmed when a forest of 325 trees with a maximum depth of 5 is constructed, and a resulting accuracy of 80.87% and 88.90% are obtained respectively.

Table 5: Random Forest performance metrics on the CTU data set.

Trees=325, Max Depth=5			
	Precision	Recall	F1-Score
N	82 %	73 %	77 %
S	78 %	78 %	78 %
P	82 %	86 %	84 %
Accuracy	80.87 %		

Table 6: Random Forest performance metrics on the UCI data set.

Trees=325, Max Depth=5			
	Precision	Recall	F1-Score
N	93 %	95 %	94 %
S	63 %	62 %	63 %
P	91 %	74 %	82 %
Accuracy	88.90 %		

The marginal increases between the decision tree and random forest classifiers are most likely attributed to the limited data complexities and may not exploit the advantages of a random forest to the fullest extent. The compact nature of the dataset cannot be



dismissed, as it may exhibit constraints in terms of diversity and limited instances for classification classes. These constraints can impact the generalising capabilities of the random forest classifier. Unlike previous studies, this study has been unable to demonstrate that the ensemble method is better suited for fetal cardiac classification, so that these findings may be limited.

#### 4.4 Support Vector Machine

Table 7: Support Vector Machine performance metrics on the CTU data set.

<b>Func=OVO, Kernel=Linear</b>			
	Precision	Recall	F1-Score
N	80 %	75 %	77 %
S	81 %	74 %	77 %
P	82 %	88 %	85 %
Accuracy	81.13 %		

Table 8: Support Vector Machine performance metrics on the UCI data set.

<b>Func=OVO, Kernel=Linear</b>			
	Precision	Recall	F1-Score
N	91 %	97 %	94 %
S	67 %	56 %	61 %
P	95 %	69 %	80 %
Accuracy	88.90 %		

As seen from Table 7 and Table 8, the Linear kernel and One-vs-One (OVO) performed well in both data sets when classifying fetal cardiac state. This outcome is contrary to a previous study which only achieved an overall accuracy of  $\approx 63\%$  without standardisation techniques of a 2-class diagnosis (Nahiduzzaman et al., 2019). The results obtained in this study for a linear Support Vector Classifier (SVC) are in alignment with a similar study where a SVC was successful in the classification of the fetal cardiac state (Chamidah and Wasito, 2015) when given a feature space that is linearly separable. When we compare the results of the SVM to that of the K Nearest Neighbour, it can be seen that there exists linear hyperplanes that can correctly identify decision boundaries between the various classes using a One-vs-One approach as opposed to a One-vs-All approach.

#### 4.5 One-Dimensional Convolutional Neural Network

The results, as shown in Table 9 and Table 10, reveals that a one-dimensional Convolutional Neural Network is highly effective at determining classifications across both CTG data sets while accounting for

Table 9: One-dimensional convolutional neural network performance metrics on the CTU data set.

<b>Epochs=3000, Training Size=70%</b>			
	Precision	Recall	F1-Score
N	95 %	82 %	88 %
S	99 %	96 %	97 %
P	91 %	98 %	95 %
Accuracy	93.79 %		

Table 10: One-dimensional convolutional neural network performance metrics on the UCI data set.

<b>Epochs=3000, Training Size=70%</b>			
	Precision	Recall	F1-Score
N	93 %	95 %	94 %
S	72 %	60 %	65 %
P	79 %	85 %	82 %
Accuracy	89.21 %		

potential bias resulting from a lack of a large data set.

Per the present results, previous studies (Batra et al., 2017; Sahin and Subasi, 2015; Ogasawara et al., 2021; Liang and Li, 2021) have demonstrated that an artificial neural network is better able to discern relationships that might be overseen by conventional machine learning algorithms based on the network topology used. This theory is clearly highlighted when the accuracy is compared to a relatively simple classification model such as the K Nearest-Neighbour model, where an increase in accuracy can be observed but is limited to the data set and features used. This increase in accuracy highlights the potential of the 1D CNN being able to discern and capture local patterns that are of importance within the signal data to extract important features.

One such network topology is a Long-Short Term Model and should be considered in future research due to its excellent performance on time-sensitive data, such as in the CTU data set. It can therefore be assumed that Artificial Neural Networks outperform conventional algorithms when classifying fetal cardiac state, with the possibility of time dependencies being highlighted and compared to traditional algorithms for the same period.

This study supports evidence from previous observations that deep learning architectures are excellent at function approximation for learning representations of data through weights and biases. The results displayed in Tables 9 and 10 match those observed in earlier studies where deep learning methods outperformed conventional machine learning methods (Chamidah and Wasito, 2015; Ogasawara et al., 2021; Batra et al., 2017) for classification. Moreover, it was noted that an increase in the training data size (80/20) resulted in an increase in accuracy

(> 4%) for the same model topology, albeit small data sets for an Artificial Neural Network domain. In both data set instances, the CNN could infer the presence of an under-sampled class better than conventional models and effectively distinguish between them. This is a rather significant outcome and has not yet been described by previous studies from Sia, and Qia (Liang and Li, 2021) and Wafaa et al. (Alsaggaf et al., 2020), where oversampling was addressed using the synthetic minority oversampling technique (SMOTE).

This study aims to expand the domain of deep learning methods applied to fetal cardiocography classification, by providing an additional Convolutional Neural Network topology, that is one dimensional, and effective at classifying signal data. This network topology differs from the previous Convolutional Neural Networks used (Liang and Li, 2021) as well as previous Multi-layer Perceptron topologies (Batra et al., 2017) and Long-Short Term Memory (LSTM) topologies (Chamidah and Wasito, 2015; Ogasawara et al., 2021).

## 5 CONCLUSION

Fetal cardiocography signals are exclusively used to determine the cardiac state of a foetus during pregnancy. This study set out to compare machine learning algorithms applied to the classification of fetal cardiac state to determine the most suitable approaches. The K Nearest Neighbours, Decision Tree, and Random Forest algorithms results corroborated the findings in previous studies (Batra et al., 2017; Sahin and Subasi, 2015; Alsaggaf et al., 2020) with similar accuracies on a shorter signal window. The study noted the importance of features provided to machine-learning classifiers and are inline with more recent findings (Zhong et al., 2022) where the baseline FHR, accelerated and decelerated FHR patterns observed play a vital role in the analysis of foetus heart rate. Results observed from the CNN applications on both datasets raise thought provoking questions regarding the nature and extent of neural networks and their ability to uncover latent relationships, even in smaller datasets where diversity could be small. This idea is further strengthened by the fact that 20-minute signal excerpt is used over the previously used 30-minute signal excerpt by Ogasawara et al. (Ogasawara et al., 2021). Moreover, a smaller set of self-extracted signal features were used for the 1-Dimensional CNN for which the model could still discern relationships to classify foetus state accurately. A further study focusing on relationships between

fetal cardiac features and one-dimensional convolutional neural networks are encouraged with different network topologies.

In conclusion, the study successfully achieved accurate classification of fetal cardiac states based on features provided to various machine learning algorithms. This study indicated that conventional machine learning algorithms are well suited for fetal cardiac classification with a one-dimensional convolutional neural network being best at discerning relationships between different classes and, therefore classify samples more accurately than conventional machine learning methods. Together these results provide important insights into successful machine-learning fetal cardiac classification with the importance of deep learning methods for future research.

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