

There is More than Mean and Variance on Waiting

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Keywords: Queuing Theory, Discrete-Time Modelling, Waiting Times, Skewness, Kurtosis.

Abstract: Processes in material flow systems, which can be regarded as queuing systems, are discrete in time. Nevertheless, the main research work considering queuing theory focuses on time-continuous modelling. However, for G/G/m-queues in continuous time, analysis relevant parameters can only be estimated and not exactly calculated anymore. These approximations are based on the first two central moments of the inter-arrival and service time distribution only and can be arbitrarily wrong. Considering discrete-time approach, the parameters can be calculated exactly. This means that also other central moments of according distributions may have an effect that is not to be neglected. Thus, in this paper we investigate the effect of skewness and kurtosis of service time distributions on the expected waiting times for queuing customers. In order to do so, we modelled queuing systems in a discrete-time manner and calculated resulting waiting times for distributions having the same mean and variance. In continuous time approximation, the result is always the same. Exact calculations following a discrete-time approach show differences of more than 15 %. Afterwards, we investigated on the effect the skewness and kurtosis of the according distributions have. First findings and need for further research are presented in this position paper.

1 INTRODUCTION

Time (perhaps not physically speaking) is a continuous flow. Thus, the normal assumption when modelling material flow systems by applying queuing theory is to consider processes to happen in continuous time. For the M/M/1- or M/G/1-queue this works perfectly well and relevant parameters such as waiting or sojourn times can be calculated exactly. However, as soon as the Markovian property isn't valid for the arrival process anymore, i.e. inter-arrival times are generally distributed, these parameters can't be calculated exactly anymore, compare (Furmans, 1999). They can only be estimated approximately. Common to all these approximations is that they are based on the mean as well as the standard deviation of the arrival process exclusively. Consequently, the result of such an approximation is always the same even for different distributions as long as their mean and standard deviation are identical. Besides, different approximations lead to different results. And they can – even worse – be arbitrarily wrong, according to (Furmans, 1999). However, processes in material flow systems can be seen as time discrete,

compare (Schleyer, 2007): Even if the time remains continuous, certain events do only take place at certain points in time: Let's take the arrival process of trucks at a warehouse for example. Here, it is not relevant if trucks arrive in time considering milliseconds or even seconds. It is enough to measure it in minutes or with regards to even coarser time windows of e.g. 30 mins each. Or take milk runs for material supply at production areas. Also here, it's minutes that count in general. Even for production itself, cycle times are measured in seconds. Thus, discrete-time modelling can be used. When applying discrete-time modelling, all relevant parameters (waiting time, sojourn time, number of customers within the system...) can be calculated exactly as now the complete distributions for the arrival as well as the service process are known – at least in an ϵ -environment as denoted in (Schleyer, 2007). No approximations are needed, different distributions lead to different results. An example for the beneficial applying of discrete-time queuing theory for analysing a manufacturing line can be found in (Furmans, Berbig and Fleischmann, 2009). Consequently, we apply discrete-time modelling

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within this paper. The target of this work is to identify if the third (skewness) and fourth (kurtosis) centralized moment of the inter-arrival time distribution have an effect on customer's waiting times – and if so, which effect could this be. Reason for this is that approximations in continuous time can be calculated rather easily, however exact calculations with discrete-time modelling is more complex and cannot be done as easily.

2 G/G/1-QUEUEING SYSTEMS IN CONTINUOUS AND DISCRETE TIME

In the following, we use Kendall's Notation $A/B/m$ where A indicates the inter-arrival time distribution, B the service time distribution and m the number of servers, as depicted e.g. in (Schleyer, 2007). G indicates that the distribution is a general one, i.e. the Markovian property is not given, the underlying distribution is not an exponential one.

We consider $G/G/1$ -queues where inter-arrival and service times are iid. For these, amongst others (Marchal, 1976) has derived an approximation formula (1) to calculate the customer's waiting times in the queueing system. It can be denoted as:

$$E(t_w) \approx \frac{1+c_b^2}{1/\rho^2+c_b^2} \cdot \frac{\lambda(Var(T_a)+Var(T_b))}{2(1-\rho)} \quad (1)$$

Where

- $E(t_w)$ = expected waiting time
- c_b^2 = variability of service process
- ρ = utilization of service station
- $Var(T_a)$ = variance of inter-arrival time distribution
- $Var(T_b)$ = variance of service time distribution
- λ = arrival rate of customers at service station

Besides, several other approximations have been developed, e.g. by (Krämer-Langenbach-Belz, 1977) or (Buzacott and Shantikumar, 1993). All these follow the same basic principle as they are based on the description of stochastic processes by the first two moments only. Everything else is neglected. Thus, they are more or less precise, any size of relative relative errors can occur (Furmans, 1999). But each of these approximations will always lead to the same result even for totally different distributions as long as their mean and variance are the same. (Schleyer

and Furmans, 2007), (Huber, 2011) and (Matzka, 2011) confirm the above-mentioned findings as well.

In contrast to this, (Grassmann and Jain, 1989) have shown an exact approach (at least within an ϵ -neighbourhood) for determining waiting times by considering a discrete-time $G/G/1$ -queue. However, this algorithm is more complex in application. We use these approximations as well as the algorithm for comparison as the starting point for further analysis. Table (acc. Schleyer, 2007) shows the according results: An arbitrary inter-arrival time distribution (a) and five different service time distributions (b_i), all of these having the same mean value and variance, have been taken. With these, the expected waiting times for customers arriving at the queueing system are calculated in time-continuous domain, always following the three above mentioned approximations. As expected, each approximation leads to the same waiting times for all five cases while each approximation leads to different expected values. The relative difference between the smallest and the biggest result is 13.17 % taking the lowest result as basis. Afterwards, the exact algorithm proposed by Grassmann and Jain applying discrete-time modelling has been implemented to calculate the exact expected waiting times for all five cases (b_i). Here the results differ due to the different service time distributions. They have a difference of nearly 9 % taking the lowest result as basis again. Finally, the maximum absolute and relative deviations between each approximation and the exact algorithm result have been calculated. The difference in this case is between 7.73 % and 10.90 %, always based on the result calculated according to (Grassmann and Jain, 1989). Those numbers show that there is a significant difference that may not be neglected. Consequently, the question on the effect of further central moments of the distributions arises. Thus, we investigate on the effect of the skewness (third central moment) and the kurtosis (fourth central moment) in our work.

3 DETERMINATION OF DISTRIBUTIONS

To investigate these effects further, we first derive additional discrete distributions that all have the same mean and variance. This means, the following conditions have to be fulfilled where α and β are values that can be arbitrarily chosen:

$$\sum_{i=1}^n P(X = x_i) = 1 \quad (2)$$

Table 1: Comparison for G/G/1-queue in time continuous and discrete-time consideration (acc. Schleyer, 2007).

i	a(i)	b ₁ (i)	b ₂ (i)	b ₃ (i)	b ₄ (i)	b ₅ (i)
0	0.000	0.000	0.000	0.000	0.000	0.000
1	0.070	0.000	0.324	0.074	0.050	0.206
2	0.080	0.350	0.000	0.149	0.033	0.144
3	0.110	0.175	0.000	0.315	0.660	0.104
4	0.130	0.150	0.000	0.250	0.024	0.000
5	0.150	0.115	0.475	0.000	0.043	0.175
6	0.140	0.100	0.201	0.000	0.011	0.371
7	0.110	0.040	-	0.111	0.000	
8	0.090	0.025	-	0.101	0.179	--
9	0.070	0.025	-	-	-	-
10	0.040	0.02	-	-	-	-
11	0.010	-	-	-	-	-
Mean value	5.300	3.905	3.905	3.905	3.905	3.905
Squared coefficient of variation	0.220	0.275	0.275	0.275	0.275	0.275
Utilization		0.737	0.737	0.737	0.737	0.737
Marchal (cont.)	E(t _w)	2.239	2.239	2.239	2.239	2.239
Krämer-Langenbach-Belz (cont.)	E(t _w)	2.019	2.019	2.019	2.019	2.019
Buzacott and Shantikumar (cont.)	E(t _w)	2.285	2.285	2.285	2.285	2.285
Grassmann & Jain (dis.)	E(t _w)	2.243	2.079	2.230	2.266	2.121
Δ _{max} (absolute)	E(t _w)	0.224	0.206	0.211	0.247	0.164
Δ _{max} (relative)	E(t _w)	9.99 %	9.91 %	9.46 %	10.90 %	7.73 %

$$E(X) = \mu = \sum_{i=1}^n x_i \cdot P(X = x_i) = \alpha \quad (3)$$

$$Var(X) = \sigma^2 = \sum_{i=1}^n x_i^2 \cdot P(X = x_i) - \mu^2 = \beta \quad (4)$$

For identifying distributions that fulfil equations (2) – (4), we implemented a small Java program that follows the logic shown in Figure 1:

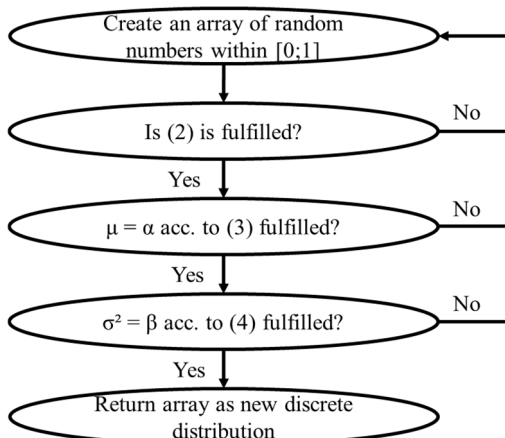


Figure 1: Program logic for distribution determination.

This program only requires two arbitrary numbers as input variables: the desired mean value as well as the desired variance. The result of the algorithm are different discrete distributions which do all fulfil equations (2) – (4). Consequently, only the first two centralized moments of each distribution are predetermined and known. Further centralized moments, like skewness and kurtosis, are just a consequence. Even if the program is quite simple, it is working effectively. All the user has to do is to wait for results. Using it accordingly, we were able to identify way more than 150 different distributions fulfilling restrictions (2) – (4), also applying different values for α and β. These distributions can serve for both – as distributions for the inter-arrival times or for the service times. It should only be noted that for each selected combination of service and inter-arrival times, the mean value of the inter-arrival time has to be greater than the mean value of the service time. In these cases, the utilization of the queueing system is less than 1 which means that the queueing system is in balance. Having this as the basis, we were able to perform according analyses.

4 FIRST FINDINGS

For further examination, we used the G/G/1-Batch-Analyser and the DTQNA, both tools resulting from research work of the IFL at the KIT. With these tools, it is possible to calculate e.g. waiting times in queueing systems applying discrete-time approaches. One of the main calculation basics of these is the above-mentioned approach proposed by Grassmann and Jain. Thus, these tools are ideally suited as basis for our research. The only input needed are the inter-arrival time distribution A_x and the service time distributions B_y . B_y represents a group of distributions that all have the same mean and variance. A_x can be taken out of the following four different inter-arrival time distributions:

- $A_1: (0; 0.07; 0.08; 0.11; 0.13; 0.15; 0.14; 0.11; 0.09; 0.07; 0.04; 0.01)^T; \mu = 5.3, \sigma^2 = 6.19$
- $A_2: (0; 0.2; 0.3; 0.15; 0.05; 0.025; 0; 0; 0; 0; 0.025; 0.1; 0.125; 0.025)^T; \mu = 5.025, \sigma^2 = 22.37$
- $A_3: (0; 0.125; 0.125; 0.125; 0.125; 0.125; 0.125; 0.125; 0.125)^T; \mu = 4.5, \sigma^2 = 5.25$
- $A_4: (0; 0; 0.542; 0.026; 0; 0; 0; 0; 0.247; 0.146; 0.039)^T; \mu = 5.274, \sigma^2 = 13.913$

As service time distributions, we took several different ones resulting out of our simple Java program. In our first experiment, we used A_1 and 10 different service time distributions of the type B_1 where $\mu = 2$ and $\sigma^2 = 0.92$. We calculated $E(t_w)$ for all 10 cases. Afterwards, we sorted the 10 service time distributions according to their corresponding skewness in an ascending order and drew a diagram for $E(t_w)$ in relation to the skewness of the service time distributions as illustrated in Figure 2. This shows a monotonous increase of the waiting time over the skewness. R^2 is 99.25 % and thus nearly maximum.

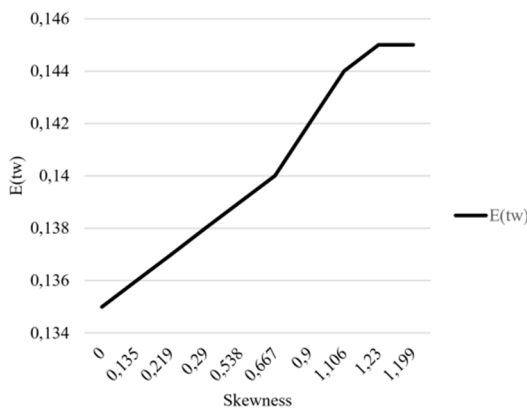


Figure 2: $E(t_w)$ with A_1 and B_1 over skewness of B_1 .

Afterwards, we analogously considered the effect of the kurtosis on $E(t_w)$. This result is depicted in Figure 3.

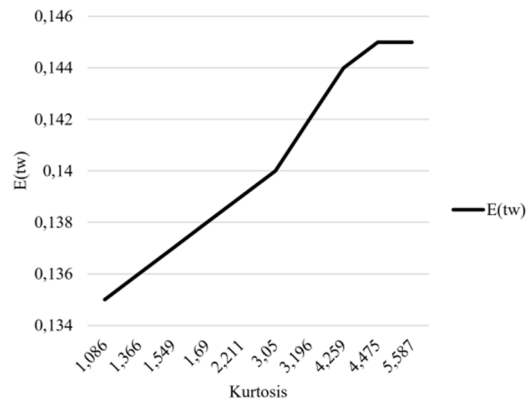


Figure 3: $E(t_w)$ with A_1 and B_1 over kurtosis of B_1 .

Here, too, a monotonous increase can be seen, even if R^2 is slightly lower but with still 94.23 % significantly high. Thus, it seems as if there is a link between the skewness and the expected waiting time as well as the kurtosis and $E(t_w)$: The bigger these central moments are, the longer is the waiting time for customers arriving at the service station. This effect has to be evaluated closer.

5 CONSIDERATION OF FURTHER DISTRIBUTIONS

Having seen these behaviours, we changed our service time distributions to the set B_2 which contains 26 distributions where $\mu = 3.32$ and $\sigma^2 = 4.745$. We acted as before, i.e. we calculated the expected waiting times for customers whose inter-arrival times are distributed with A_1 while the service time at the G/G/1-queueing system is always one out of B_2 . Figure 4 shows the according results.

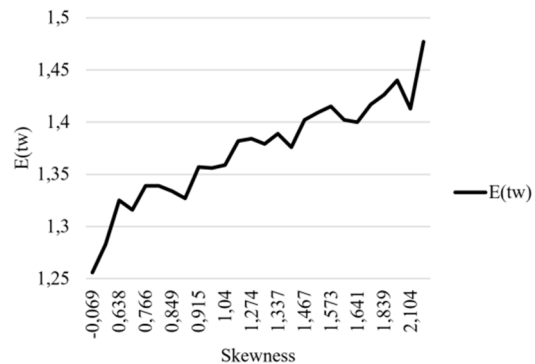


Figure 4: $E(t_w)$ with A_1 and B_2 over skewness of B_2 .

Interestingly, we can see two effects:

- The overall effect of the skewness still confirms the first findings: A higher skewness means higher waiting times. R^2 of 91.60 % is still significant.
- However, the trend is not a monotone one anymore. There are cases when a (slightly) increased skewness leads to a (slightly) decreased waiting time.

Thus, some questions arise:

- What is the reason for this behaviour?
- Can we see the same behaviour when considering the kurtosis?
- Which effects do different A_x have?

Let's start with the last two questions and postpone the first. Considering the kurtosis, the same two effects confirm: Overall, an increased kurtosis leads to an increased waiting time. But the development seems even more "erratic" as depicted in Figure 5 and thus an R^2 of only 51.90 %. Here, a linear relationship cannot be assumed anymore:

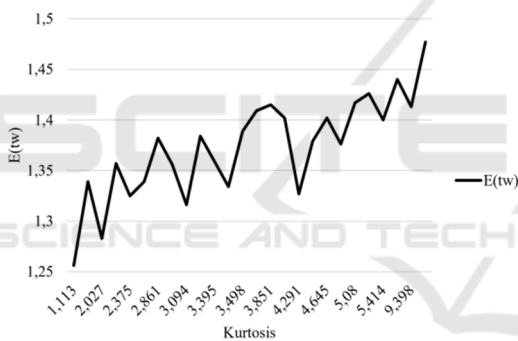


Figure 5: $E(t_w)$ with A_1 and B_2 over kurtosis of B_2 .

In order to be able to get some hints regarding this behaviour, we rearranged the data and sorted $E(t_w)$ in an ascending order and had a look on how the skewness and the kurtosis develop. Here, we can see an interesting result: Whenever the skewness increases from one waiting time to another, the kurtosis does so as well. However, the kurtosis has way higher fluctuations than the skewness as Figure 6 shows.

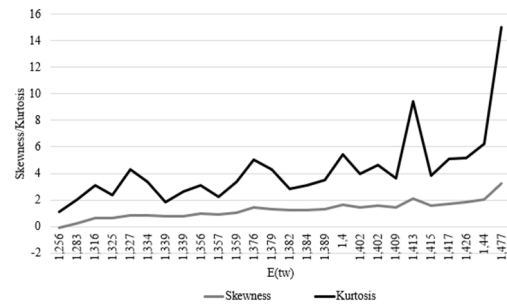


Figure 6: Skewness and kurtosis of B_2 over $E(t_w)$.

Here, R^2 is 79,04 % between the skewness and kurtosis indicating that there could be a connection between the two moments.

In order to analyse the third question, we did the same analysis for B_1 and B_2 in combination with A_2 . Considering B_1 at first, the result is shown in Figure 7. Interestingly, there is still a monotonic relationship between $E(t_w)$ and the skewness. R^2 is even 99.42 %. However, the relationship is now opposite: An increased skewness leads to a reduced waiting time.

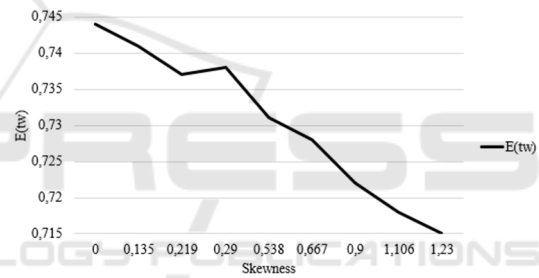


Figure 7: $E(t_w)$ with A_2 and B_1 over skewness of B_1 .

The same is valid considering the effect of the kurtosis on the expected waiting time. Even if R^2 with 90.69 % is slightly smaller, it is still rather high. However, the trend is not that smooth than it is when considering the skewness. This can be seen in Figure 8.

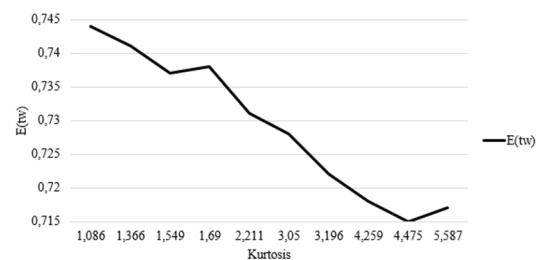


Figure 8: $E(t_w)$ with A_2 and B_1 over Kurtosis of B_1 .

What is now the result when considering B_2 ? Here, the same change in behaviour is seen as for B_1 , as can be seen in Figure 9: The overall trend does now

show a reduction of $E(t_w)$ when skewness and kurtosis increase. Here as well, the according R^2 is now smaller than when considering A_1 , namely 42.22 % or 5.50 % indicating that a linear connection cannot be assumed anymore.

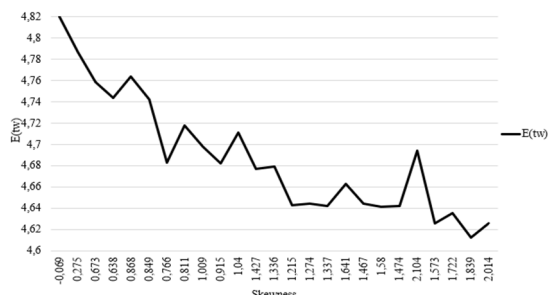


Figure 9: $E(t_w)$ with A_2 and B_2 over skewness of B_2 .

Having seen these results, we calculated the results for applying A_3 and B_1 , A_3 and B_2 , A_4 and B_1 or A_4 and B_2 respectively as input distributions. Applying A_3 leads to the same behaviours like A_1 , A_4 doesn't nearly show any systematic behaviour anymore. Why can this be the case? Considering the squared coefficients of variation (SCV) of the four inter-arrival time distributions, we get the following results:

Table 2: SCV for different A_i .

Inter-arrival distribution	time	Squared coefficient of variation
A_1		0.220
A_2		0.886
A_3		0.259
A_4		0.500

Considering these results, it could be that a squared coefficient of variation...

- which is below 0.5 indicates a positive
- which is higher than 0.5 leads to a negative
- which is around 0.5 leads to no

correlation between the expected waiting time for arriving customers and the skewness or kurtosis of the service time distribution. The same seems valid when considering the skewness of these four distributions which is:

Table 3: Skewness for different A_i .

Inter-arrival distribution	time	Skewness
A_1		0.120
A_2		0.927
A_3		0.000
A_4		0.312

To further explore the above-mentioned findings and ideas, we conducted another experiment in which we chose an arbitrary inter-arrival time distribution A_5 :

$$A_5: (0; 0; 0.419; 0.224; 0.143; 0.002; 0.04; 0.119; 0; 0.039; 0; 0.014)^T; \mu = 3.67, \sigma^2 = 4.69$$

For A_5 , the squared coefficient of variation is 0.348, the skewness is 1.411, the kurtosis is 1.146. Again, we took the set B_1 for service time distributions and calculated the according expected waiting times for arriving customers at the queuing system. Afterwards, we arranged them again over the skewness and kurtosis of B_1 . The result can be seen in the following Figure 10:

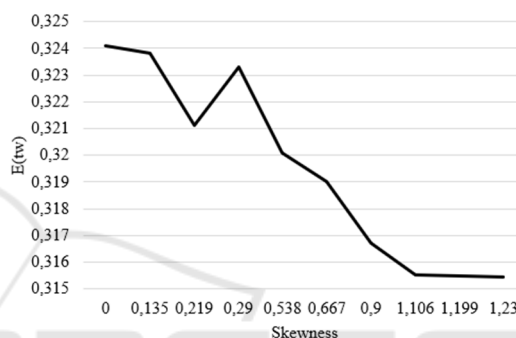


Figure 10: $E(t_w)$ with A_5 and B_1 over skewness of B_1 .

In this case, increasing skewness – at least considering the trend – leads to a shorter waiting time. The same behaviour can be observed when considering the kurtosis of B_1 . However, since in this case the SCV of A_5 is smaller than 0.5, this behaviour contradicts the above assumption. The skewness of A_5 , however, is much larger than 0.5. This could indicate that SCV and skewness may not be considered individually, but in combination:

- SCV and skewness below 0.5 indicate a positive
- SCV below 0.5, but skewness > 1 indicate a negative

correlation between the expected waiting time for arriving customers. However, these are just first assumptions needing further and more detailed research.

6 CONCLUSION AND OUTLOOK ON FURTHER RESEARCH

Even if we were not able to identify a clear correlation between the skewness or kurtosis of the service time

distribution and the expected waiting times, we generated some important findings and were able to show the need for further research:

1. Considering the mean value and the variance only for inter-arrival and service time distributions is not sufficient. There can be differences in the resulting expected waiting times from more than 15 % (e.g. considering case A_1 and B_1).
2. Skewness and kurtosis seem to have an influence on $E(t_w)$.
3. Skewness and kurtosis show similar behaviours regarding the development of $E(t_w)$.
4. There might be a correlation between the squared coefficient of variation and the skewness of the inter-arrival time distribution and the effect the skewness or kurtosis have on the expected waiting time for arriving customers.
5. Fluctuations within the effect of kurtosis on $E(t_w)$ could be higher due to the underlying statistics as skewness incorporates the difference between the observation and the mean to the power of three, i.e. negative results can be possible, whereas the kurtosis incorporates the same difference but to the power of four, i.e. there can be only values ≥ 0 and the effect of the difference can be higher (in case it is > 1) than regarding the skewness or lower (otherwise).

These findings serve as basis for further research we are currently conducting.

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