

A Stochastic Game Model for Cloud Platform Security

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Abstract: The extensive use of virtualization technologies in cloud platforms has caused traditional security measures to partially fail. It was a hard struggle for static protection mechanisms to get work done in time when facing constantly evolving network threats. In this paper, an active defense approach is proposed to address the dynamic and variable security threats in cloud environment. Stochastic game model is introduced to model the cloud platform security elements. An attack-defense payoff function and matrix are also defined based on the features of the cloud platform. To accurately describe the attack action and the corresponding defense action, the overall attack graph and single-point defense graph are optimized. Based on proposed game model and attack-defense graph, the optimal defense strategy algorithm for the cloud platform is designed. The optimal defense strategy is obtained after a multi-stage stochastic game considering the long-term gain. Finally, the model's reliability is evaluated using stochastic Petri nets and Markov chains. Experimental simulation demonstrates that the presented model outperforms the existing mainstream game models, such as the evolutionary game model and Bayesian game model, in terms of the optimal strategy, defense success rate, and steady-state availability.

1 INTRODUCTION

While cloud platforms bring various beneficial services, they also increase more security threats and challenges (Almorsy et al., 2016). On one hand, the complexity of resources allocated in cloud platforms, such as data, compute, services, and tenants, leads to an expanded attack surface. Because the cloud platform stores more data, the risks associated with data leakage will be more severe. Easy key or certificate systems, weak passwords, and simple authentication methods are the main sources of attacks. A multi-tenant computing architecture is introduced by the cloud platform, allowing many tenants to share memories, databases, and other nearby resources. As a result, more users are affected at once by known system flaws and software security problems, increasing the cloud platform's attack surface. On the other hand, cloud platforms have more serious security issues than traditional networks

because they comprise virtual machines, cloud resources, cloud management systems, etc. (Sabahi, 2011). After attacking the cloud platform's virtual machines and other resources, they can access the relevant servers. If the cloud platform's administration system is breached, the attacker can also get access to a lot of important data, including user names and passwords, information about virtual machines and servers, etc. In order to reduce data loss, user privacy leakage, cloud service paralysis and other problems, it is necessary to study the cyber security of cloud platforms and prevent it in time. Traditional attack-defense techniques must be paired with active attack-defense measures in order to effectively defend against the growing network threats. At the same time, game theory is the key technology in active attack-defense, where players make decisions that are best for themselves under the influence of each other. In network security, game theory has been applied to capture the essence of network conflicts, attackers and defenders be

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modeled as competitors in the game model, the attacker's decision strategy is closely related to the defender's, and vice versa (Liang & Xiao, 2013).

The popular active attack-defense game models include Stackelberg game, evolutionary game, Bayesian game, signaling game, and stochastic game. These game models have been used in network security modeling by numerous domestic and international academics. (Jiang et al., 2019) constructs an attack-defense game based on the Stackelberg game to model the interaction between the attacker and the defender. (Abdalzaher et al., 2016) devises two protection schemes based on the Stackelberg game model to protect the nodes of WSN. However, the Stackelberg game has an action sequential order for both attackers and defenders, which has limitations for practical scenarios. In an evolutionary game, players' actions and strategies are modified and improved through continuous imitation and learning (Sotomayor et al., 2020). The authors constructed a network attack-defense multi-stage game model based on bounded rationality constraints (Huang et al., 2017). A security method for generating attack and defense graphs is applied to Vehicular Ad Hoc Network in (Zhang et al., 2019), which is based on evolutionary game theory and offensive and defensive interaction models. However, the design of dynamic replication equations for evolutionary games and the process through which they attain a stable state are more challenging. A detection means of wireless ad hoc network based on the Bayesian game model is presented to analyze the interactions between pairs of attacking/defending nodes (Islam et al., 2021). (Liu et al., 2021) studies the quantitative and automatic modeling and analysis of cyber-physical attacks on ICS key information systems and physical equipment. (Lalropuia & Gupta, 2020) constructs a Bayesian game model to capture the interaction between attackers and defenders under bandwidth spoofing attacks. While Bayesian games are based on games with imperfect information, their predictions are inaccurate. Taking into account the dynamic confrontation of spear phishing attacks in ICS and the cost of defense strategy deployment, a multi-stage spear-phishing attack-defense signal game model is constructed (Chen et al., 2019). A method of active defense strategy selection based on a two-way signal game is designed in (Liu et al., 2019). However, the signal game not only suffers from the issue of the attackers' and defenders' action sequential, but also plays with inadequate information.

The stochastic game is a combination of game theory and Markov decision, which mainly applies to the defense with bounded rational constraints and the

active attack-defense of cloud computing networks (van Ravenzwaaij et al., 2018). The virtual machine migration technology and the optimal strategy of honeypot deployment are well applied to improve the security of the cloud computing network. The attack path is also predicted qualitatively and quantitatively using the stochastic game, the invasion of a black box, and the attack-defense map (Kandoussi et al., 2020). However, the current model adopts staged game methods, which provide limited guidance for the continuous real-time selection of a network defense strategy (Chen et al., 2019). (Elmir et al., 2022) studies the interaction between service providers and attackers using a stochastic game model and optimizes cloud computing security. However, the game model does not take into account potential long-term benefits. The SBS structure and offensive and defensive actions are modeled as a two-player stochastic game model (Fanti et al., 2016), and the optimal strategy is obtained by calculating the Nash equilibrium. However, both attack chains and attack trees have to be remodeled if the architecture of the system is modified (Jakóbič, 2020).

Aiming at the issues with the aforementioned model, a new stochastic game model for the cloud platform is proposed, which takes into account the long-term interests and determines the current optimal attack-defense strategy after a multi-stage stochastic game. The overall attack graph and single-point defense graph of the cloud platform are also optimally designed to accurately describe the system attack-defense information. In addition to this, we use stochastic Petri nets and Markov chains for reliability modeling and compare the loss rate of the system under different policies. Experimental simulations demonstrate that the presented model can raise system reliability.

The rest of the paper is organized as follows. Section 2 describes the definitions related to the proposed game model, discusses the attack-defense graphs, the attack-defense payoff matrix and the optimal strategy algorithm design, and analyzes them with instances. Section 3 presents experimental simulations and a reliability study of this model based on real environment data, and compares it to popular gaming models. Section 4 discusses the conclusion and future works.

2 STOCHASTIC GAME MODEL FOR CLOUD PLATFORM

A new game model is proposed based on the stochastic game. In this model, the offense-defense

payoff function, the offense-defense payoff matrix, and the offense-defense graph model are redesigned. In addition, stochastic Petri nets and Markov chains are used to model and analyze the reliability.

2.1 Definition of Game Model

The stochastic game model for cloud platform (CSGM) is represented by a 6-tuple CSGM = (N, S, A, D, U, δ), which is described below.

(1) $N = \{N_A, N_D\}$ represents the set of game players, where N_A represents the network attacker, and N_D represents the defense system for cloud platform.

(2) $S = \{S_0, S_1, \dots, S_n\}$ represents the state set of CSGM. S indicates that the offensive and defensive confrontation is at different stages, where attacker gains different privileges and the defending system loses differently.

(3) $A = \{a_1, a_2, \dots, a_n\}$ represents the set of attacker actions. The set of attacker's actions under state S_k , $A_k = \{a_1, a_2, \dots, a_k\}$ and $A_k \subset A$.

(4) $D = \{d_1, d_2, \dots, d_n\}$ represents the set of defender actions. The set of effective defense actions for the attack action a_k , $D_k = \{d_1, d_2, \dots, d_k\}$ and $D_k \subset D$.

(5) $U = (U_1, U_2, \dots, U_n)$ represents the set of payoff functions for game players. We consider the player's long-term gain and design the utility function for attacker and the defender, $U = U_{now} + U_{exp}$, where U_{now} is the current gain and U_{exp} is the expected future gain. The utility function formulas for both sides are designed as shown in Eq. (1) and (2).

$$Ua_{si}^{ai} = (1 - \beta)(R_{si} + \delta \cdot R_{sj}) + \beta(-C_{ai}) \quad (1)$$

$$Ud_{si}^{ai} = \beta R_{si} + (1 - \beta)(\delta \cdot R_{sj} - C_{di}) \quad (2)$$

Ua_{si}^{ai} represents the attacker's gain for selecting action a_i under state S_i ; Ud_{si}^{ai} represents the defender's gain for selecting action a_i under state S_i ; R_{si} is the current gain under state S_i and R_{sj} is the expected gain under the next state S_j ; β represents the probability of defense success; δ represents the discount factor, which indicates the attack-defense preference of current and future payoffs; C_{ai} and C_{di} denote the cost of attack action a_i and defense action d_i , respectively.

2.2 Attack-Defense Diagram Model

The essence of network security is the game between network attackers and defenders, so network security modeling should be considered from the perspective of both attackers and defenders. The attack-defense diagram comprehensively reflects the essence of

network attack and defense by incorporating network security information into security analysis and decision-making, including attack actions, defense measures, and corresponding cost. It is built from the perspective of the defender and is often referred to as a defense diagram.

Considering the characteristics of the cloud platform such as variable states and various means of attack and defense, we separately store the attack path and defense path of the defense diagram. The overall attack graph and single-point defense graph are designed to precisely explain the network status, attack action, and corresponding defense action for each state. The overall attack graph is shown in Figure 1, where $S_0 \sim S_k$ denote the k game states and $a_1 \sim a_m$ denote the m attack actions. If S_i can reach S_j , there is a matching attack action a_i , otherwise, there is none.

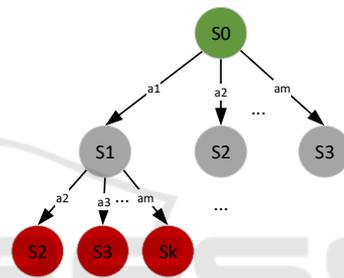


Figure 1: Overall attack graph.

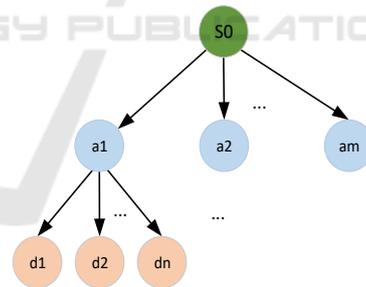


Figure 2: Single-point defense graph.

2.3 Attack-Defense Payoff Matrix

A matrix of attack-defense activities, as shown in Eq. (3), is a typical attack-defense payoff matrix. Under the state S_k , the set of attacker actions is $A = (a_1, a_2, \dots, a_{nk})$, and the set of defender actions is $D = (d_1, d_2, \dots, d_{mk})$. A complex game matrix G_k of order $n_k \times m_k$, whose elements represent the direct gains achieved by the attacker and the defender under attack-defense strategies (a_i, d_j) , can be used to represent the game in state S_k .

$$G_k = \begin{matrix} & \boxed{d_1} & \boxed{d_2} & \cdots & \boxed{d_{m_k}} \\ \begin{matrix} \boxed{a_1} \\ \boxed{a_2} \\ \vdots \\ \boxed{a_{n_k}} \end{matrix} & \begin{pmatrix} r_{11}^* & r_{12}^* & \cdots & r_{1m_k}^* \\ r_{21}^* & r_{22}^* & \cdots & r_{2m_k}^* \\ \vdots & \vdots & \vdots & \vdots \\ r_{n_k1}^* & r_{n_k2}^* & \cdots & r_{n_k m_k}^* \end{pmatrix} \end{matrix} \quad (3)$$

Combined with our game model and algorithm, the designed attacker gain matrix is shown in Eq. (4). The matrix tuples represent the gains of the attacker and the defender when the attack action a_i is taken in state S_j . The calculation method of $U_{a_{s_i}^i}$ is shown in formula (1), and the calculation method of $U_{d_{s_i}^i}$ is shown in formula (2).

$$G = \begin{matrix} & \boxed{a_1} & \boxed{a_2} & \cdots & \boxed{a_m} \\ \begin{matrix} \boxed{S_0} \\ \boxed{S_1} \\ \vdots \\ \boxed{S_k} \end{matrix} & \begin{pmatrix} U_{a_{S_0}^1}, U_{d_{S_0}^1} & U_{a_{S_0}^2}, U_{d_{S_0}^2} & \cdots & U_{a_{S_0}^m}, U_{d_{S_0}^m} \\ U_{a_{S_1}^1}, U_{d_{S_1}^1} & U_{a_{S_1}^2}, U_{d_{S_1}^2} & \cdots & U_{a_{S_1}^m}, U_{d_{S_1}^m} \\ \vdots & \vdots & \vdots & \vdots \\ U_{a_{S_k}^1}, U_{d_{S_k}^1} & U_{a_{S_k}^2}, U_{d_{S_k}^2} & \cdots & U_{a_{S_k}^m}, U_{d_{S_k}^m} \end{pmatrix} \end{matrix} \quad (4)$$

2.4 Algorithm for Optimal Strategy Selection

Aiming at the fact that the majority of current payoff computations are based on current payoffs, a multi-stage gaming algorithm is proposed that takes into account long-term payoffs. The play the game multiple times until the end condition is reached, and then calculates the impact of future gains on the present. For each state, iterates over all of the attack actions associated with that state to determine the long-term benefits under various assault actions. Simultaneously, the attack success rate and the defense success rate are computed, so the long-term process is also considered when computing the success rate. The flow of the optimal strategy selection algorithm is shown below.

Input: CSGM = (N,S,A,D,U, δ)

Output: payoff matrix and optimal attack-defense strategies

Step1:

Input parameters:

$S \leftarrow (S_0, S_1, \dots, S_k)$

$A \leftarrow (a_1, a_2, \dots, a_m)$

$D \leftarrow (d_1, d_2, \dots, d_n)$.

1) Input attributes of the parameter S , which contains the set of available attack action *attlist* and the system loss rate.

2) Input attributes for parameter A , which include *benefit, cost, next state, valid set of defenses, and attack success rate*.

3) Input attributes for parameter D , which include *benefit, cost, and defense success rate*.

4) Determine the value of *discount factor*

step2:

For $S_i \in S$ and ($i=1,2, \dots, k$), $a_i \in S_i.attlist$ is calculated by the Eq. (1) and (2). R_{s_j} denotes the future expected gains, which is obtained after a multi-stage game.

Step3:

When either of the following game-end conditions is encountered: a. the final state S_k is visited, b. the current state has been visited, or c. there is no optional attack action in the current state, return $(U_{a_{s_i}^i}, U_{d_{s_i}^i})=(0,0)$ as the future expected gain R_{s_j} and bring it into the above formula for calculation, otherwise, repeat the steps of step2 and step3.

Step4:

In the above procedure, the attack/defense success rate is calculated recursively at the same time. Attack success rate equals iteration of defense failure probability, defensive success rate equals iterative defensive success rate

Step5:

Obtain the payoff matrix and the attack/defense success rate matrix, based on these matrices, produce the optimal attack-defense strategies.

End

2.5 Instance and Analysis

2.5.1 Experimental Environment of the Instance

To further clarify the game model and optimal strategy algorithm described in the preceding section, we describe a common cloud network topology example, as shown in Figure 3.

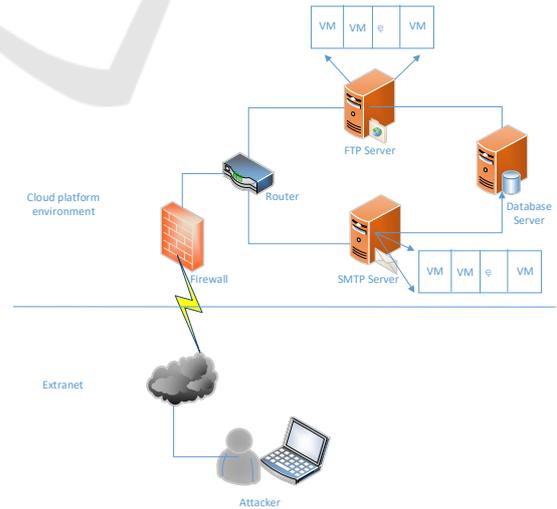


Figure 3: Network topology graph.

In this instance, the cloud platform consists of three servers: a FTP server, a SMTP server, and a

database server. Using virtualization technology, each server is partitioned into many virtual machines. FTP server and SMTP server are servers that users can rent and utilize. The database server manages the FTP server and SMTP server, which is inaccessible to common users. An attacker in the extranet, who initially has no access to servers, can launch attacks on the above cloud platform.

2.5.2 Attack-Defense Diagram of Instance

The overall attack graph of the cloud platform is shown in Figure 4, including 9 states and 17 attack actions.

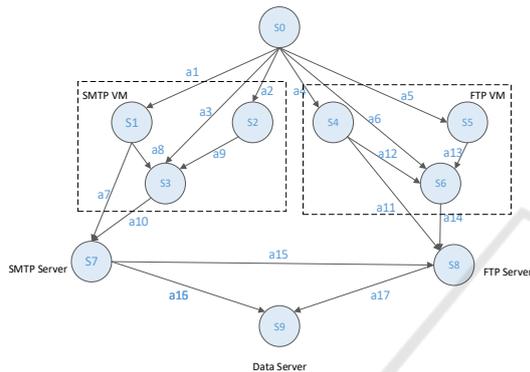


Figure 4: Overall attack graph of Instance.

The definitions of each state are shown in Table 1. For the state S_0 , the attacker can take the attack action when he has not obtained any authority $A_0 = \{a_1, a_2, a_3, a_4, a_5, a_6\}$. Similarly, the set of attack actions in other states can be obtained, $A_1 = \{a_7, a_8\}$, $A_2 = \{a_9\}$, $A_3 = \{a_{10}\}$, $A_4 = \{a_{11}, a_{12}\}$, $A_5 = \{a_{13}\}$, $A_6 = \{a_{14}\}$, $A_7 = \{a_{15}, a_{16}\}$, $A_8 = \{a_{17}\}$.

Table 1: This caption has one line so it is centered.

State	Definition
S_0	Normal State
S_1	Gain SMTP VM user privileges
S_2	Gain SMTP VM memory privileges
S_3	Gain SMTP virtual machine Root privileges
S_4	Obtain virtual machine user access to FTP
S_5	Obtain virtual machine memory access to FTP
S_6	Obtain virtual machine Root access to FTP
S_7	Gain host Root privileges of SMTP
S_8	Gain host Root privileges of FTP
S_9	Obtain database server Root privileges

Each state is owned with a unique single-point defense graph. As shown in Figure 5, the single-point defense graph for state S_0 is utilized as an illustration. There are six optional attack actions in state S_0 , where a_1 corresponds to the effective defense action $D_1 = \{d_1, d_2, d_3, d_{15}\}$.

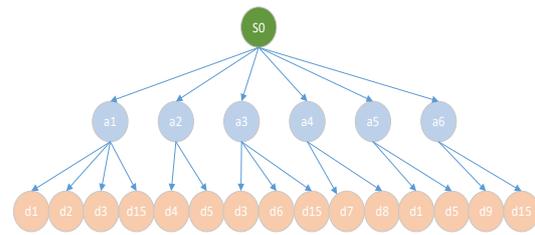


Figure 5: Single-point defense graph of S_0 .

2.5.3 Optimal Strategy Algorithm of Instance

In this instance, the inputs to the optimal strategy algorithm are $S = \{S_0, S_1, S_2, \dots, S_9\}$, $A = \{a_1, a_2, a_3, \dots, a_{17}\}$, $D = \{d_1, d_2, d_3, \dots, d_{15}\}$. For parameter S , the set of attack actions in each state is $A_0 = \{a_1, a_2, a_3, a_4, a_5, a_6\}, \dots, A_8 = \{a_{17}\}$; for the parameter A , we take a_1 and a_{17} as examples, $a_1 = \{benefit, cost, next\ state, valid\ set\ of\ defenses, attack\ success\ rate\} = \{10.0, S_1, (d_1, d_2, d_3, d_{15}), 0.6\}$, $a_{17} = \{7.5, S_9, (d_{14}, d_{16}), 0.4\}$, where *benefit*, *next state*, and *probability of defense success* can all be calculated based on the CVSS security vulnerability assessment system; for parameter D , we take d_1 and d_{15} as examples, $d_1 = \{benefit, cost, defense\ success\ rate\} = \{50, 20, 0.5\}$ and $d_{17} = \{10, 5, 0.5\}$, where the *benefit* is determined by the amount of attack activities that can be successfully defended, the *cost* is related to the complexity of defense, and the *defense success rate* = $1 - attack\ success\ rate$.

Table 2: State/attack-defense payoff matrix of instance.

	a1	a2	a3	a4	a5	a6	a7	a8	a9	a10	a11	a12	a13	a14	a15	a16	a17
S0	1.73, 2.93, 0.5, 4.56, 2.94, 0.86, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0																
S1	0, 0, 0, 0, 0, 0, 0, 3.96, 4.33, 0, 0, 0, 0, 0, 0, 0, 0, 0																
S2	0, 0, 0, 0, 0, 0, 0, 9.5, 25.6, 0, 0, 0, 0, 0, 0, 0, 0, 0																
S3	0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 6.35, 28.84, 0, 0, 0, 0, 0, 0, 0																
S4	0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 3.62, 5.67, 21.4, 25.6, 0, 0, 0, 0, 0																
S5	0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 6.03, 28.8, 0, 0, 0, 0																
S6	0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 4.52, 21.4, 0, 0, 0																
S7	0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0.84, 2.12, 20.8, 9.0																
S8	0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0.84, 2.12, 20.8, 9.0																

The optimal strategy algorithm is implemented using Python language. The state/attack-defense payoff matrix are obtained as shown in Table 2. The corresponding attack success rate and defense success rate for each state are obtained as $P_a = \{0.06, 0.36, 0.14, 0.24, 0.36, 0.14, 0.24, 0.4, 0.4, 0\}$ and $P_b = \{0.03, 0.14, 0.09, 0.14, 0.14, 0.09, 0.14, 0.24, 0.24, 0.24, 0\}$, respectively. Based on this matrix and the attack-defense success rates, the optimal attack- defense

strategy for each state are obtained as $A_{opt} = \{a_4, a_8, a_9, a_{10}, a_{12}, a_{13}, a_{14}, a_{16}, a_{17}, a_1\}$ and $D_{opt} = \{d_8, d_2, d_2, d_2, d_2, d_2, d_2, d_{14}, d_{14}, d_{15}\}$.

2.5.4 Reliability Analysis

Combined models such as reliability block diagrams, fault trees, and s-t connectivity networks are commonly used for system reliability and availability analysis. These models can offer a succinct description and an effective evaluation for the system under study, but they are unable to capture the dependencies that exist in real systems (Sahner & Trivedi, 1987) (Veeraraghavan & Trivedi, 1988), such as non-zero detection/reconstruction times, incomplete coverage, correlated failures, repair dependencies, and performance reliability dependencies. On the other hand, state-space-based models, such as Markov model, are able to capture various dependencies that appear in reliability/availability models (Dugan et al., 1986) (Goyal et al., 1986). In this paper, stochastic Petri nets (SPN) and Markov model are used to model and analyze the system's reliability.

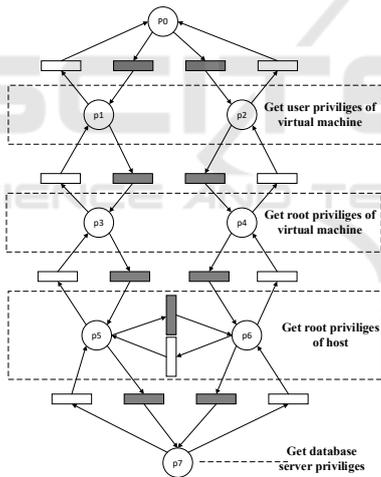


Figure 6: SPN model of instance.

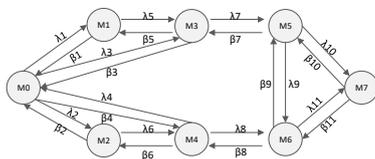


Figure 7: Markov chain model of instance.

The SPN model of the instance is shown in Figure 6, where the black rectangular nodes indicate the attack action, the white rectangular nodes indicate the defense action, and the circular nodes indicate the

system states in which the attacker has different system privileges.

The Markov chain model corresponding to the SPN is shown in Figure 7, where M_k related to the different states of the system, and λ_i and β_j represent the transfer probability between different states. λ_i and β_j correspond to the attack and defense success rate respectively.

We set the following assumptions:

- state M_1 can be transferred from state M_0 by various attack actions as $A_1\{a_1, a_2, \dots, a_n\}$.
- the set of defensive actions corresponding to the attack action a_i is $D_i\{d_1, d_2, \dots, d_n\}$.
- the optimal defense action for a_i is d_{opti} , and its defense success rate is P_{dopti} .
- The steady-state probability of M_0 - M_7 is $SSP = \{m_0, m_1, \dots, m_7\}$
- The system loss rate of M_0 - M_7 is $Loss = \{0, 0.2, 0.2, 0.25, 0.25, 0.3, 0.3, 0.4\}$

Based on the above assumptions, λ_i and β_j are calculated as shown in Eq. (5) and (6). In addition, the reliability of the system is calculated as shown in Eq. (7)

$$\lambda_i = \frac{(1 - P_{dopt1}) + (1 - P_{dopt2}) + \dots + (1 - P_{doptn})}{n} \quad (5)$$

$$\beta_j = \frac{(P_{dopt1} + P_{dopt2} + \dots + P_{doptn})}{n} \quad (6)$$

$$Ra = 1 - (m_0 * 0) - (m_1 + m_2) * 0.2 - ((m_3 + m_4) * 0.25) - (m_5 + m_6) * 0.3 - (m_7 * 0.4) \quad (7)$$

3 EXPERIMENT SIMULATION

3.1 Experiment Data

The experimental data of a cloud platform is collected and stored using neo4j as shown in Figure 8. The orange node represents the attack condition, which must exist before the attack action can be carried out. The blue node represents the attack action, which the attacker carries out in order to reach a specific attack state. The red node denotes the system state, where the attacker's authority varies. The gray node denotes the defense action, where there may be numerous defense actions for one attack action or a single defense action may apply to multiple attack actions.

The relationships include *trigger*, *gain*, *further*, and *defense*. The relationship between orange nodes and blue nodes is *trigger*, which indicates that if specific attack conditions are met, a particular attack action can be triggered. The *gain* connect blue nodes and red nodes, that is, after an attack action is

launched, another state can be reached. Red nodes and blue nodes have a *further* relationship, which means that the attacker can initiate further attacks in a certain state. *Defense* is the interaction between gray nodes and blue nodes, and it is a strong defensive response to an attack.

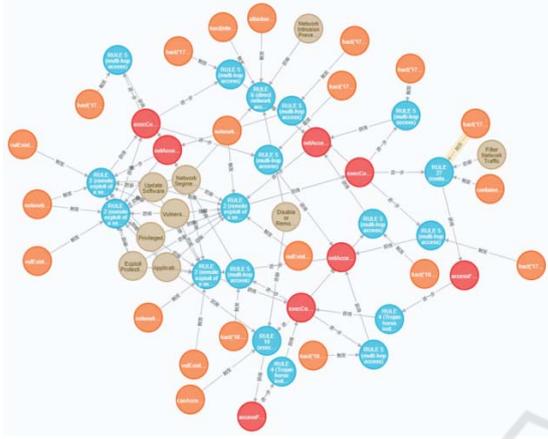


Figure 8: Attack-defense graph of Experiment.

3.2 Optimal Strategy Algorithm of Experiment

We gather the necessary data from the above experimental environment, including the information of state, attack action, and defense action. We can get the following values from the Neo4j database for the attributes of state and attack action: $S_k = \{\text{status_id}, \text{attack_list}\}$; $a_k = \{\text{attack_id}, 0, \text{attack_reward}, \text{attack_cost}, \text{defense_list}, \text{attack_prob}\}$. For the attributes of defense action, we set $d_k = \{\text{defense_id}, 0.44, 33.5, 1.2\}$. The gathered information is inputted into the optimal strategy algorithm and the attack-defense payoff matrix is obtained as shown in Table 3.

Table 3: State/attack-defense payoff matrix of experiment.

	a2	a4	a7	a9	a11	a14	a15	a18	a20	a22	a27	a31	a33	a35	a38	a40	a42	a46
s1	0	0	0	0	0	0	0	0	12.9	0	5.69	0	0	0	0	0	7.27	0
s3	2.68	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	11.63
s6	0	10.32	0	5.69	0	0	0	0	0	0	0	0	0	0	11.18	0	0	0
s8	0	0	9.01	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
s13	0	0	0	0	5.69	0	0	0	0	0	0	6.26	0	0	11.31	0	0	0
s15	0	0	0	0	0	14.04	0	0	0	0	0	0	0	0	0	0	0	0
s32	0	0	0	0	0	0	0	0	0	0	0	11.69	0	0	0	0	0	0
s37	0	0	0	0	0	0	0	0	0	0	0	0	0	11.69	0	0	0	0

Based on the payoff matrix, the attack/defense profit sum is calculated as shown in Figure 9. The horizontal coordinate represents the eight system states of the cloud platform with unique number, and

the vertical coordinate indicates the profits. The optimal attack/defense strategy for each state is also obtained, as shown in Figure 10. The meanings of the horizontal coordinates are consistent with Figure 9, and the red dots and blue dots indicate the optimal strategies of attackers and defenders in a certain state, respectively. In addition to this, the attack/defense success rate is obtained as shown in Figure 11.

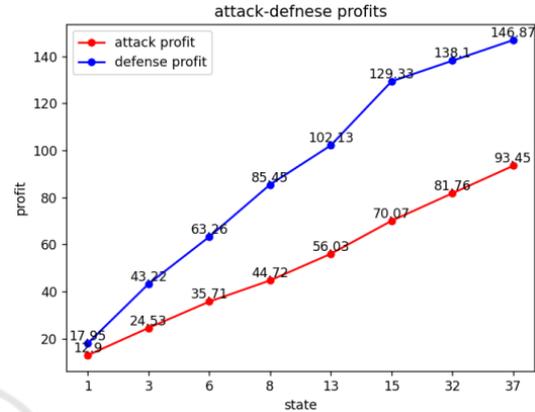


Figure 9: Attack and defense profit sum.

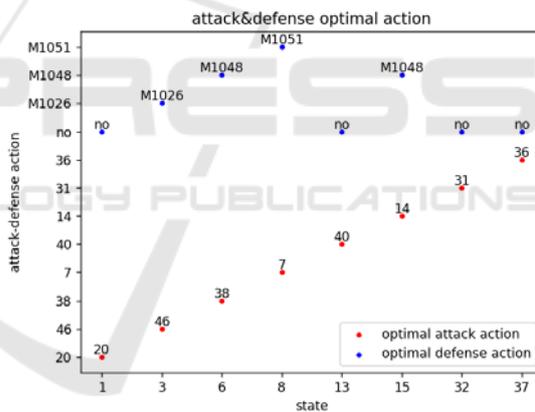


Figure 10: Attack and defense optimal strategy.

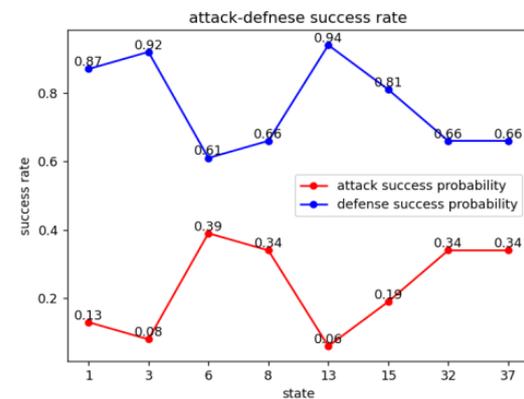


Figure 11: Attack and defense success rate.

3.3 Reliability Simulation

To verify the validity of the presented model in this paper, reliability simulations are conducted in four cases based on above experiment environment. Simulations verify that the system loss rate is lower and the reliability is higher under the proposed model. We assume that the initial state vector is $P_0 = (P_{M0}, P_{M1}, P_{M2}, P_{M3}, P_{M4}, P_{M5}, P_{M6}, P_{M7}) = (0.5, 0.15, 0.15, 0.08, 0.08, 0.02, 0.02, 0)$. Also assume that: state loss rate = attack profits in the state / total attack profits, $Loss = \{0.16, 0.05, 0.24, 0.05, 0.27, 0.05, 0.09, 0.09\}$.

In the first scenario: all defensive actions are deployed, and the attacker chooses the attack action averagely. The transfer probability between states is equal to the average success rate of the optional attack actions. Using Python to walk through the Markov transfer process, the final steady-state probabilities are obtained as shown in Figure 12, $P_m = (m_0, m_1, m_2, m_3, m_4, m_5, m_6, m_7) = (0.117, 0.132, 0.221, 0.127, 0.121, 0.127, 0.08, 0.077)$. Calculate the system's reliability based on Eq. (6): $Ra = 86.2\%$.

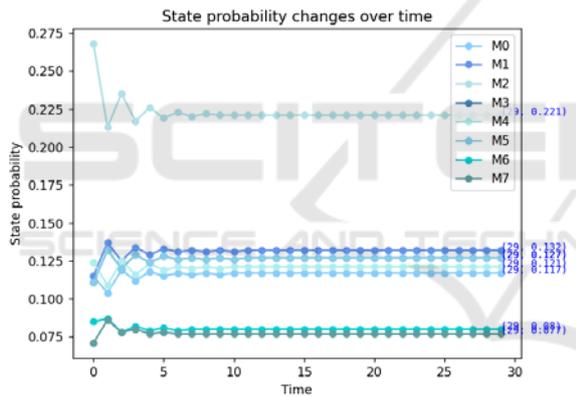


Figure 12: State transfer probability for first case.

In the second scenario: the defender deploys the optimal defense strategy according to the game model, while the attacker merely takes into account the short-term profit and selects the most profitable attack action. If the defense action is effective against the attack action, the state transfer probability is the attack success rate, otherwise, the state transfer probability is 1. All other calculations are left unaltered, and the state transfer probabilities are obtained as shown in Figure 13. The final steady-state probabilities are $P_m = (m_0, m_1, m_2, m_3, m_4, m_5, m_6, m_7) = (0.0, 0.0, 0.444, 0.17, 0.0, 0.0, 0.0, 0.255)$. Calculate the system's reliability based on Eq. (6): $Ra = 84.1\%$.

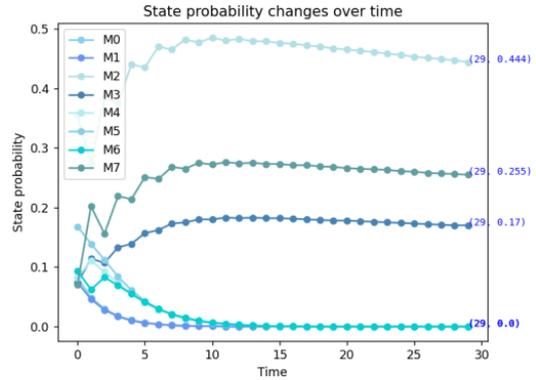


Figure 13: State transfer probability for second case.

In the third scenario: The attacker still takes into account the short-term profit and selects the most profitable attack action, while the defender do not deploy any defense strategy. Without modifying any other calculations, the probability of transition between states is derived as depicted in Figure 14. The final steady-state probabilities are $P_m = (m_0, m_1, m_2, m_3, m_4, m_5, m_6, m_7) = (0.008, 0.003, 0.406, 0.123, 0.024, 0.014, 0.139, 0.283)$. Calculate the system's reliability based on Eq. (6): $Ra = 84.1\%$.

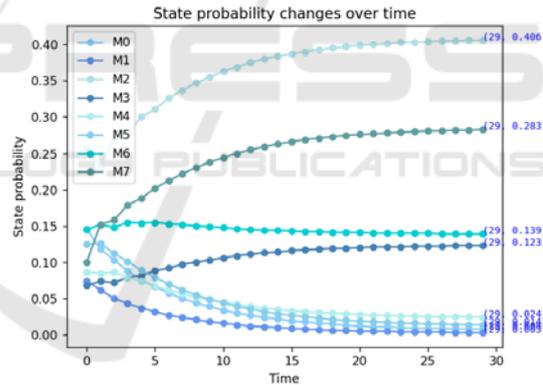


Figure 14: State transfer probability for third case.

In the fourth scenario: Based on the proposed game model, the defender deploys the optimal defense strategy in advance and the attacker launch the action according to long-term gain. The calculation is the same as in the previous scenarios. The state transfer probabilities are as shown in Figure 15. The final steady-state probabilities are $P_m = (m_0, m_1, m_2, m_3, m_4, m_5, m_6, m_7) = (0.099, 0.151, 0.22, 0.084, 0.099, 0.151, 0.0, 0.126)$. Calculate the system's reliability based on Eq. (6): $Ra = 87.4\%$.

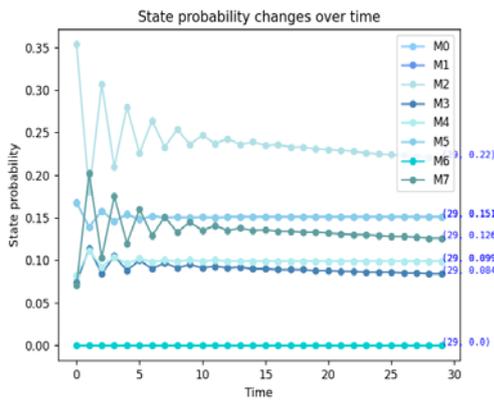


Figure 15: State transfer probability for fourth case.

Although the first scenario's reliability of 86.2% is also ideal, it necessitates the deployment of all defense actions, which will undoubtedly raise the cost of defense system. The reliability of the second and third cases are 84.1% and 84.9%, which are significantly lower than the proposed model in this paper. In summary, the proposed model improves the reliability of the system to a certain extent and also reduces the defense cost.

3.4 Experimental Comparison

3.4.1 Optimal Strategy Comparison

In the existing game models, the optimal strategies calculated by Nash equilibrium are mostly mixed strategies that cannot be applied directly to the actual environment. In contrast, the optimal strategy in this paper is a pure policy that uses a recursive multi-stage game to calculate the current gain, which is more practical and decreases the complexity of management deployment. Table 4 compares the mixed strategies from the (Huang et al., 2017) with the pure strategies from the CSGM in this paper.

Table 4: Optimal strategy comparison.

	Game model of (Huang et al., 2017)		CSGM	
	Attack strategy	Defense strategy	Attack strategy	Defense strategy
S0->S1	{0.45,0.4, 0.15}	{0.5, 0.5}	a20	no
S1->S2	{0.3, 0.7,0}	{1,0,0}	a46	M1026
S2->S3	{0.47, 0.23,0.3}	{0.45,0.5, 0.05}	a38	M1048
...

Table 5: Defense success rate and profits comparison.

	Highest defense success rate	lowest defense success rate	Average defense success rate	Average defense profits
SAR-RG	0.95	0.75	0.8	89.5
GFQL	0.75	0.6	0.7	87.5
IS-RS/PS	0.55	0.65	0.6	72.5
CSGM	0.94	0.61	0.76	90.6

3.4.2 Defense Success Rate and Profits Comparison

Comparing the average gain, defense success rate, and detection accuracy of the three game models in the (Balaji et al., 2019), the superiority of the SAR-RG model is highlighted. As indicated in Table 9, we compare the defense success rate and average profits of these three models to CSGM in this paper. In terms of defense success rate, The CSGM is demonstrably superior to the GFQL and IS-RS/PS models, and is comparable to the SAR-RG model. Moreover, this model has a greater average defense profits than the other three models.

3.4.3 Steady-State Probability Comparison

(Lalropuia & Gupta, 2020) analyzes the impact of DoS attacks on the system availability using stochastic reward network. The SSP variation of their simulations is shown as Table 6, with an average SSP of 0.85. The SSP obtained using CSGM for defense deployment is 0.874. The stability of the proposed model in this paper is superior to the presented model in the (Lalropuia & Gupta, 2020).

Table 6: Steady-state probability comparison.

	State	SSP(simulation)	Average SSP
Game model in (Lalropuia & Gupta, 2020)	$\omega=0.1$	0.81	0.855
	$\omega=0.2$	0.82	
	
CSGM	$\omega=0.9$	0.89	0.874
	Case 4	0.874	

4 CONCLUSIONS

In order to satisfy the requirement for network security defense of cloud platforms, A new active defense model for cloud platforms is proposed which

is based on stochastic game theory and merges the concept of active defense. The model enhances the attack-defense graph, redefines the reward function and payoff matrix, and provides the optimal defense strategy algorithm. This algorithm calculates the attack and defense payoff matrix by taking into account the long-term interests and then determines the best defense strategy based on this. To verify the effectiveness of the model, we simulate the reliability of four scenarios using stochastic Petri nets and Markov chains. The results demonstrate that the model outperforms both the deployment of all defense actions and the absence of defense actions. Compared with mainstream models, the proposed model outperforms in terms of optimal strategy form, defense success rate and gain, and system stability probability. The model's backtracking algorithm complexity is too high, making it more taxing for larger cloud platform systems. In the future, we will continue to optimize the algorithm's time complexity.

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