Algorithmic Fairness Applied to the Multi-Label Classification Problem

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Abstract: In recent years, a concern for algorithmic fairness has been increasing. Given that decision making algorithms are intrinsically embedded in our lives, their biases become more harmful. To prevent a model from displaying bias, we consider the coverage of the training to be an important factor. We define a problem called Fairer Coverage (FC) that aims to select the fairest training subset. We present a mathematical formulation for this problem and a protocol to translate a dataset into an instance of FC. We also present a case study by applying our method to the Single Cell Classification Problem. Experiments showed that our method improves the overall quality of the qualification while also increasing the quality of the classification for smaller individual underrepresented classes in the dataset.

1 INTRODUCTION

The use of algorithms for decision making is only increasing. They are used in a wide range of fields, such as the selection of university students (Waters and Miikkulainen, 2014) and allocation of resources during natural disasters (Wang et al., 2022). Decision algorithms are even used on the justice system to aide on trials, parole concession, and sentencing (Christin et al., 2015). Although the usage of algorithms aims to improve process by either making it faster or finding a better solution, they are not exempt from societal flaws like discrimination.

It has become apparent through several studies that algorithms also have the potential to be discriminatory. O'Neil (O'Neil, 2017) presented in her "Weapons of Math Destruction" book several examples of how algorithms are being used in the decision making process and, more importantly, how they affect society. The more concerning of these cases is how a portion of the population can receive more damage than others.

Many studies showcase how these algorithms

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have negatively impacted the lives of minorities. One example is the study presented by the ProPublica news agency, showing that black defendants are two times more likely to be given a score indicating high risk of recidivism by the system used in Florida, USA (Angwin et al., 2016). As per the study, these scores result in harsher sentencing and a lesser chance of parole. Another study points out the discrimination against minority neighborhoods by an online service. The study indicated that the vast majority of places not covered by a same-day delivery are inhabited by black people or other ethnic minority in the USA (Ingold and Soper, 2016). Discrimination based on stereotypes is also presented in deployed robots, showing racist and sexist actions (Hundt et al., 2022).

Cases such as the aforementioned are referred to as algorithmic injustice or algorithmic racism, when the discrimination perpetrated by the algorithm has racial influence.

Silva (Silva, 2020) presented a compilation of news coverage of algorithmic racism in the form o a timeline. The first news report dates from 2010, when a facial recognition software failed to identify the eyes of a person of Asian decent as open and another software failed to identify a black person and their movement (Rose, 2010). The more recent report in the same timeline is from 2020, which points to a study that identified a large racial disparity in speech recognition tools (Koenecke et al., 2020). The researchers found that the average word error rate for

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black speakers is more than double the average for white speakers. They attributed this disparity to the lack of diversity in the training dataset.

Silva's timeline only covers the years 2010 through 2020, and it is notorious how much the number of reports has increased in the second half of the decade. Although the timeline does not present more recent cases, it is not hard to find more and more reports about algorithmic racism such as the work of Gichoya (Gichoya et al., 2022), which determined that standard machine learning models can determine with accuracy the race of an individual based on medical imaging such as X-ray and mammograms.

Chung (Chung, 2022) presented an in-depth study on algorithmic racism with examples of how it has impacted minorities. The study points out ways to remedy algorithmic racism, including creating new rules for algorithmic design and inserting sensitive data in the auditing processes. The study concludes that we should not only strive to design algorithms and systems that are not racist but to develop algorithms that are anti-racist by improving equitable outcomes.

As response to this phenomenon, the field of Algorithmic Fairness has been emerging in the literature with growing interest. The field usually studies manners in which algorithms can be modified to prevent bias and subsequent discrimination.

Kleinberg *et al.* (Kleinberg et al., 2018) presented a study that shows the benefits of considering sensitive characteristics in a prediction algorithm. Galhotra *et al.* (Galhotra et al., 2020) introduced a method for selecting features to obtain a fair dataset. Lin *et al.* (Lin et al., 2020) showed methods to identify regions of a dataset that have lower coverage and performed experiments showing that explicitly including these areas improved the overall accuracy of the methods. Roh *et al.* (Roh et al., 2021) presented a method to pick a fair sample at the training batch level.

These works assume that the bias can be inserted into the model via the dataset, and target different areas to treat this problem. Considering this assumption, Asudeh *et al.* (Asudeh et al., 2022) developed an optimization problem to select a fair sample of a dataset. They considered that in a fair sample, every class of attributes has the same coverage. This problem was called Fair Maximum Coverage (FMC) and it models samples as subsets of attributes.

The objective the FMC problem is to find k subsets of attributes such that the sum of the attribute's weights is maximum and each class of attributes is equally represented. This problem was proven to be NP-hard (Asudeh et al., 2022).

In this paper, we propose a method for selecting a fair training sample based on the FMC and apply this method to a cell classification problem. The main difference of our method is that we consider justice not as a restriction, but a goal to strive towards. For this, we define a modified version of the problem and use an Integer Linear Programming (ILP) model to obtain an optimal solution. Through computational experiments we show how our method has impacted the classification process using a dataset of cell images provided by the Human Protein Atlas¹ (HPA). We chose to work with this dataset as proof of concept because of its size, variety of classes and disparity of frequency of different labels, that will affect the level of fairness we can achieve. We show that our method has improved not only the classification of the smaller and less frequent classes, but also the overall result.

Our main contributions are (i) to present a new model based on ILP approach to cope with fairness selection of subsets, and (ii) to assess our model on a multi-label classification task, showing best results compared to the random selection.

The remainder of this paper is organized as follows. In Section 2, we present the dataset, the notation, and concepts for our method, as well as the experiments' setup details. In Section 3, we report and discuss our results. Lastly, in Section 4, we draw our conclusions and discuss future work.

2 METHODOLOGY

In this section, we present our methods for generating a fair coverage, followed by a description of the the dataset. and evaluation metric. We also describe the setup details for generating a solution to the ILP model, as well as the setup for the classification task.

2.1 Fairer Coverage

In this section, we present the Fair Maximum Coverage and proposed problem, called Fairer Coverage. We first introduce the notation and definitions necessary for the discussion.

Suppose we have a universe set \mathcal{U} formed by the elements u_j . A set composed of subsets \mathcal{S}_{ℓ} of the universe set \mathcal{U} is called a *family*. We say an element u_j of \mathcal{U} is *covered* by a subset \mathcal{S}_{ℓ} of \mathcal{S} if \mathcal{S}_{ℓ} contains u_j . A subset X of the family \mathcal{S} is a *cover* of \mathcal{U} if all the elements of the universe set are covered by at least one element of X. Moreover, if X has size k, then X is called a k-cover of \mathcal{U} . Now, given a set C of χ distinct colors, such that $C = \{1, 2, ..., \chi\}$, we call a *coloring* of the universe set \mathcal{U} a function that assigns one color

¹https://www.proteinatlas.org

 $c \in C$ to each element $u_j \in U$, that is, a coloring *C* is a function $C : U \to C$. We call a *class* a set of elements colored with the same color.

Asudeh *et al.* proposed the Fair Maximum Coverage (FMC) Problem to incorporate fairness in the problems of covering (Asudeh et al., 2022). Given a *k*-cover X and a coloring C, they defined a *k*-cover X as *fair* if for each pair of colors $c, d \in C$ the number of covered elements colored with the color c is the same as the number of covered elements colored with the color d. Given a universe set \mathcal{U} , a family S, a coloring C, a positive integer k and a weight function $w : \mathcal{U} \to \mathbb{R}$, Asudeh *et al.* defined the FMC as the problem to find a fair k-cover such that the sum of the weights of the covered elements is maximum. This version of the problem has applications in Data Integration and Facility Location and is proven to be NP-hard (Asudeh et al., 2022).

The version of the fair coverage problem presented by Asudeh *et al.* has two critical assumptions. Firstly, fairness is interpreted as equality among all classes and, secondly, there is a restriction that forces the cover size to be exactly k. These two characteristics applied together might only be suitable in some applications, as they create a very restricted solution pool and define a problem that is NP-Hard even when restricted to finding a feasible solution (Asudeh et al., 2022).

In particular, this approach becomes undesirable in the case of data integration with highly unbalanced classes, such as the case of the HPA dataset. In data integration, we are interested in selecting a fair set of samples for the training, such that the training results in a model with a reduced bias towards the smaller classes. With this application, an element u_j could represent a label in multilabel classification problem, a set would represent the group of labels attributed to a single sample, and a family could represent a group of samples from a dataset.

To better adapt the fair coverage problem for the data integration, we present a modification of the FMC presented by Asudeh *et al.*. We propose that fairness can be treated as the objective of the problem and not as a restriction. In this interpretation, we still assume that a fair cover is a cover in which each class is represented equally, but admit that this might not always be possible. For this version of the problem, we also propose to remove the maximization of the covered elements to avoid working with two potentially conflicting objectives. Instead, we add a new parameter *s* that indicates the minimum number of elements u_j that need to be covered. We call this version the Fairer Coverage Problem (FC). We present this version of the problem in Definition 2.1.

Definition 2.1. Fairer Cover – FC			
Input:	A universe set \mathcal{U} , a family \mathcal{S} , a		
	coloring function C, a positive in-		
	teger s, and a positive integer k.		
Objective:	Find a k-cover that is as fair as		
	possible and covers at least s el-		
	ements.		

To solve this problem, we present an Integer Linear Programming (ILP) model in Restrictions (1a) -(1g). This model uses three types of decision variables. The first two are binary variables of the form $x_i \in \{0,1\}$ and $y_\ell \in \{0,1\}$ and represent the elements u_i of the universe \mathcal{U} and the family \mathcal{S} , respectively. If $x_i = 1$ in the ILP solution, then the element u_i is covered by the resulting k-cover. Similarly, if variable $y_{\ell} = 1$ in the solution, then the subset S_{ℓ} from the family S is part of the *k*-cover. The last decision variable is $z \in \mathbb{Z}^{\chi,\chi}_+$, where χ is the number of colors used in the coloring C. Let X_c be the number of covered elements colored with a color c. The pair of variables $z_{c,d}$ and $z_{d,c}$ together indicate the absolute value for the difference between X_c and X_d . Note that if X_c is greater than X_d , then $z_{d,c}$ will be zero because of the parameter k is positive. This model also uses constants *m* and *n* to indicate the sizes of \mathcal{U} and \mathcal{S} , respectively. Also, the constant C_c denotes the number of elements u_i from \mathcal{U} that are colored with c by the coloring function C.

$$\min \sum_{c=1}^{\chi} \sum_{d=1}^{\chi} z_{c,d}$$
(1a)
s. t. $x_i < \sum y_\ell \forall j \in \{1, 2, \dots, m\}$ (1b)

$$x_j \leq \sum_{\ell \mid u_j \in \mathcal{S}_\ell} y_\ell \forall j \in \{1, 2, \dots, m\}$$
(1b)

$$y_{\ell} \leq x_j \qquad \forall u_j \in \mathcal{S}_{\ell}, \forall \mathcal{S}_{\ell} \in \mathcal{S}$$
 (1c)

$$y_{\ell} = k \tag{1d}$$

$$\sum_{j=1}^{m} x_j \ge s \tag{1e}$$

$$\sum_{u_j \in C_c} x_j - \sum_{u_i \in C_d} x_i \le z_{c,d} \quad \forall c, d \in \mathcal{C}$$
(11)

$$x \in \mathbb{B}^{m}, y \in \mathbb{B}^{n}, z \in \mathbb{Z}_{+}^{k \cdot k}$$
 (1g)

We consider the level of unfairness in a *k*-cover to be the sum of the differences between the number of elements of each pair of colors in said *k*-cover. As such, a solution that is as fair as possible needs a level of unfairness as small as possible. Considering this, Equation (1a) denotes the objective of the problem, which is to minimize the level of unfairness. The following two Restrictions ((1b) and (1c)) guarantee that the solution is a cover. Restrictions (1b) define that if an element u_j is covered ($x_j = 1$), then there needs to be at least one subset S_ℓ that contains u_j that is part of the of the solution ($y_{\ell} = 1$). On the other hand, Restrictions (1c) enforce that if a subset S_{ℓ} is in the solution ($y_{\ell} = 1$), then all elements $u_j \in S_{\ell}$ are covered. Restriction (1d) specifies that precisely k subsets S_{ℓ} from the family S are part of the solution and, together with the previous constraints, ensures that the solution is indeed a k-cover. In Restriction (1e), the sum of x_i will result in the number of covered elements, which is then set to be at least the value of the parameter s. In Restriction (1f), we can interpret each sum as the number of covered elements of colors c and d, that is, X_c and X_d . Therefore, the restriction defines that each variable $z_{c,d}$ needs to be at least as big as the difference between X_c and X_d . If $X_c < X_d$, $z_{c,d} = 0$ and the inequality holds. Now, if $X_c > X_d$, then $z_{c,d}$ could be any value greater than $X_c - X_d$, but we guarantee that this will not be the case with the minimization in the objective function (Equation (1a)). Lastly, Restriction (1g) defines the domain of the decision variables.

2.2 Dataset

In order to train and evaluate our method, we used a public image benchmark, which was presented by Human Protein Atlas (HPA) program in the form of a Kaggle challenge named "Human Protein Atlas -Single Cell Classification"². The challenge's goal is to classify and segment protein location labels on cell images obtained by microscopes.

The dataset has 18 location labels that can be assigned to each image, and each one can have multiple protein locations, making this task a multi-label classification. Each sample is composed of four different images, representing channels of information: red channel, highlighting the microtubules; blue channel, indicating the nuclei; yellow channel, where the endoplasmic reticulum is shown; and lastly the green channel shows the protein of interest.

The competition's website provided two sets of cell images, one for training and one for testing. As the competition did not supply the labels of the testing images, we split the original training set into training, validation, and testing sets. We present in Table 1 the number of images per set in our version of the dataset (last row), as well as the number of images per label in the different sets. From this table, we show the difference in coverage for specific classes. Note-worthy cases are the Mitotic spindle label, which appear in less than 100 images, and the Nucleoplasm label that has the maximum presence in the dataset, with almost 9000 appearances in total.

ID	Name	Train.	Valid.	Test
p 1	Nucleoplasm	5630	1418	1749
p ₂	Cytosol	3631	952	1102
p ₃	Plasma membrane	1991	488	632
p_4	Nucleoli	1587	386	478
p5	Mitochondria	1307	309	397
p ₆	Golgi apparatus	1164	281	401
p ₇	Nuclear bodies	1137	291	364
p ₈	Centrosome	1126	275	333
p9	Nuclear speckles	903	248	274
p ₁₀	Nucleoli fibrillar center	797	211	254
p ₁₁	Nuclear membrane	705	168	222
p ₁₂	Actin filaments	629	145	224
p13	Intermediate filaments	608	149	207
p ₁₄	Microtubules	521	144	153
p ₁₅	Endoplasmic reticulum	488	118	169
p16	Vesicles	359	113	121
p17	Aggresome	160	39	53
p18	Mitotic spindle	40	26	12
Number of images		13955	3489	4362

2.2.1 Obtaining a Fairer Training Subset from the HPA Dataset

This section describes how we transformed the HPA dataset into an instance of the Fairer Coverage problem and detail the protocol for obtaining the fairer training dataset. We illustrate in Figure 1 a general idea of the steps we followed.

To transform the training dataset into an instance of FC, we defined that every identified protein in an image is a distinct element u_j of the universe set \mathcal{U} , totaling 22783 elements. Next, we determined that the set of training images is the family \mathcal{S} , and each image is a subset \mathcal{S}_{ℓ} , totaling 13937 subsets. Since the HPA dataset is also multi-class, we end up with subsets of sizes varying from one to five. We also defined 18 colors for the coloring function, one for each label that indicates a protein in the image.

Since each element is a label representing a protein, the coloring function follows directly. We defined six arbitrary values for the parameter $k \in$ {1000, 2000, 3000, 4000, 5000, 10000}. To define the value of s, we looked at the training dataset as a whole and defined what are the maximum and minimum number of elements that could be covered, regardless of fairness. To find the maximum number of elements covered by k subsets, we considered a greedy approach that adds to the cover first the images with larger number of labels. Conversely, to find the minimum we used a greedy approach that favors first the images with smallest number of labels. Given these numbers, we calculated the average and use it as the value for the parameter s. We show in Table 2 the values of maximum and minimum covered elements in

²https://www.kaggle.com/competitions/ hpa-single-cell-image-classification



Figure 1: Pipeline of the creation of a fair training data subset for the HPA dataset.

the HPA training dataset. With these variations, we created six instances for the FC that will result in different levels of fairness.

Table 2: Auxiliary data to define the values of parameter *s* (Average) with the HPA dataset.

k	Maximum	Minimum	Average
1000	3117	1000	2059
2000	5656	2000	3828
3000	7656	3000	5328
4000	9656	4000	6828
5000	11656	5000	8328
10000	18846	16745	17796

The next step illustrated in Figure 1 is to solve the instances created for the FC problem. To find this solution, we use an Integer Linear Programming model described in Section 2.1, the implementation of which is described in more detail in Section 2.5. Each solution of the FC will give us a *k*-cover, that is, a subset of the family S. Note that this will correspond to a subset of images of the HPA dataset. Therefore, we save the reference to which images shall be used for the training. We end up with six training datasets of different sizes, which are not necessarily disjoint.

2.3 Classification Method

For the classification task, we used ResNet50 (He et al., 2016) convolutional network. Based on the pre-

trained architecture on ImageNet dataset (Krizhevsky et al., 2012), we fine-tuned this model on our database.

As the most important information about the proteins in this dataset is presented in the green image of each data, we applied only this channel to our experiments, considering images with 512 pixels of width and 512 pixels of height.

To improve the results of our classification method, we ran a grid search after the training step to define a threshold. To do so, based on the prediction of the validation set, we looked for the best value for each label, that is, the threshold value that maximizes the F_1 score for each label. In this search, we used values ranging from 0.01 to 1.00 in steps of 0.01.

2.4 Evaluation Metric

Based on the F_1 Score of each label, we calculated the mean of F_1 scores, called macro F_1 score, the official metric on HPA dataset, to assess our method. Equation (2) presents the formula macro F_1 score, where *i* represents the *i*-th label and *N* the number of labels.

Macro F₁ Score =
$$\frac{1}{N} \sum_{i=1}^{N} F_1$$
 Score_i (2)

2.5 ILP Setup Details

The ILP model represented by the Equations (1a) - (1g) was implemented using the programming language C++ and compiled with g++ (version 11.3.0), flags C++19, and -03. The IBM CPLEX Studio (version 12.8) was used as the integer programming solver, with the multi-thread function turned off. The experiments reported with the ILP model in the following section were executed in a laptop running a Intel[®] CoreTM i5-10210U CPU, with eight cores of 1.60GHz, 8GB of RAM, and Ubuntu 22.04.1 LTS as the operating system. For each execution, we set a time limit of 30 minutes.

2.6 Classification Setup Details

For the classification task, we fine-tuned each ResNet50 during 200 epochs, with binary crossentropy loss function, Adam (Kingma and Ba, 2017) optimizer with starter learning rate equal to 10^{-5} , early stopping technique per 20 epochs and reduced learning rate by a factor of 10^{-1} if the model did not improve the validation loss in 10 epochs.

In all experiments, we employed TensorFlow ³ library and Google Colab virtual environment.

³https://www.tensorflow.org



Figure 2: Number of covered elements by color class and instance.

3 COMPUTATIONAL RESULTS

In this section, we present and discuss the experimental results obtained with our classification method.

ILP Results. We executed the implemented ILP model with the six instances based on the HPA dataset. All instances finished execution well before the time limit, so the solutions are optimal. In Figure 2, we illustrate the solutions returned. Each graph represents an instance with a different value for the parameter $k \in \{1000, 2000, 3000, 4000, 5000, 10000\}$. The y-axes of the graphs in Figure 2 show the number of elements of a given color covered by the k-cover. Note that these axes are in logarithmic scale (base 2) to improve readability, since some labels can be much more frequent than others. The x-axis is shared by all graphs and is labeled p_1 through p_{18} indicating the 18 labels, such that p_1 represents the most frequent label, p_2 denotes the second most frequent label, and so on, until p_{18} , which represents the least frequent

Training Size	Random	Fair
1000	0.393 ± 0.012	$\textbf{0.396} \pm \textbf{0.009}$
2000	0.455 ± 0.013	$\textbf{0.457} \pm \textbf{0.010}$
3000	0.481 ± 0.009	$\textbf{0.500} \pm \textbf{0.008}$
4000	0.504 ± 0.009	$\textbf{0.505} \pm \textbf{0.018}$
5000	0.519 ± 0.008	$\textbf{0.521} \pm \textbf{0.010}$
10000	0.559 ± 0.011	$\textbf{0.570} \pm \textbf{0.009}$

label. See Table 1 for more details on the labels, such as name of the location and frequency in the dataset.

In an ideal case, each bar of the same color in the graph from Figure 2 would have the same height. However, this cannot happen due to the disparity within the number of elements in each color class. The smallest of the classes has only 40 elements, while the largest has 5630 elements, which is over one hundred times more. To satisfy the Restrictions (1d) and (1e) there will necessarily be a difference in the height of the bars between these two classes, at least.

The reduction of unfairness will manifest more prominently among the middle classes. By comparing the intermediary classes, we can see they are almost the same height, except for instance k = 10000. In this instance, a more significant number of color classes are fully included in the cover, and yet they are not able to match the frequency of the larger classes to achieve a fairer coverage.

Classification Results. After solving the ILP model and creating fair subsets of the original training set, we employed the classification method. We also considered a random sub-sampling of the original training set without reposition of images, in order to compare to our fair selection of training images.

We assessed our method considering the six different training subset sizes (1000, 2000, 3000, 4000, 5000, and 10000). For each size and type of subset, we ran the classification method 10 times. In Table 3, we present the mean and standard deviation results on the test set considering the fair and random subsamplings of the original training set.

As seen, the fair subsets show the best outcomes for all training sizes. Considering the sizes of 1000, 2000, 4000, and 5000 training images, the fair subset generation confirmed improvements on macro F_1 score between 0.001 and 0.003. Considering the training sets of 3000 and 10000, fair selection surpassed random selection by a more significant amount, 0.019 and 0.011, respectively.





Figure 3: Accumulated macro F_1 score, from least to most frequent class.

Fairness Analysis. In the previous section, we showed that the training with our fair subset of images did not worsen the overall F_1 score of the classification model when compared to the random sampling. We now expand the calculation of the macro F₁ score to show the impact of our method on each label. In Figure 3, we have six graphs, one for each instance. The x-axis contains a reference to the classes in reverse order of magnitude, from smaller to largest. The y-axis of each graph represents the accumulated macro F₁ score from the smallest class to the largest class. That is, the first point from left to right is the macro F₁ score of the smallest class; the second point is the macro F₁ score of the two smallest classes, and so on, until the last point, where we have the average of all classes that represent a protein.

The graphs in Figure 3 have one line representing the results for the fair training subset and one for the random training subset. The graphs reveal that the fair subset improved the macro F_1 score for the smallest classes. Since the final average is close in both cases, we can infer from the graphs that the fair training subset resulted in a worse macro F_1 score than the random training subset in the larger classes. We can

Table 4: Macro F₁ scores for larger and smaller classes.

1-	Macro F ₁ ^{large}		Macro F ₁ ^{small}	
K	Random	Fair	Random	Fair
1000	0.486	0.446	0.300	0.346
2000	0.547	0.501	0.363	0.414
3000	0.575	0.546	0.387	0.455
4000	0.599	0.560	0.408	0.449
5000	0.612	0.579	0.427	0.463
10000	0.646	0.639	0.471	0.502

confirm this fact, though this was expected since the number of samples in these classes reduces when the fairness condition is considered. But, notably, the individual gain in macro F_1 score for the smaller classes tends to be greater than the loss in the larger ones.

In Table 4, we show the macro F_1 scores for the labels divided into two groups: large containing the labels p_1 through p_9 (second and third columns) and small containing p_{10} through p_{18} (fourth and fifth columns). Each row in the table highlights the best macro F₁ scores for the respective group. For every training dataset size we can see a pattern where the random training datasets have a greater macro F_1 score in the *large* group, whereas the fair training datasets have a greater macro F₁ score in the small group. This showcases the overall balancing of the metric in the fair datasets, that can be seen as a reflection of the contrasts of fair and random datasets. We tend to have more elements of the larger classes in the random dataset, similar to the original distribution of the HPA dataset (see Table 1). Contrarily, when creating the fair datasets, we cannot match the presence of the smaller classes to that of the larger ones, due to the limitations of the dataset. Thus, the fair dataset reduces the number of covered elements of the *large* group and increases that of the *small* group.

We present in Table 5 a summary of the results shown in the graphs of Figure 3. The table has three columns: the first indicating the size of the training dataset, whereas the following two columns show the standard deviation of the F_1 scores for all the 18 labels, for the random and fair training dataset, respectively. In the last column, we have the difference between the random and fair standard deviations. In each row, we highlighted the smallest standard deviation. With the results in this table, we have that the fairer training dataset also results in a more stable classification. That is, the classification model does not favor the dominant classes. Note that the smaller training datasets are also fairer, and in these cases the difference in standard deviations is more accentuated.

$m{k}$	Random	Fair	Difference
1000	0.194	0.157	0.037
2000	0.191	0.163	0.029
3000	0.193	0.163	0.030
4000	0.196	0.169	0.027
5000	0.191	0.171	0.020
10000	0.187	0.174	0.013

Table 5: Standard deviation of the F_1 scores for all the 18 labels, considering the two training sets (Random and Fair).

4 CONCLUSIONS

In this work, we present and discuss a new algorithm to generate fair subsets from unbalanced datasets. The results of ILP algorithm in the multi-label image classification task showed consistent improvements compared to the random sub-selection of the original training set, considering both the global scope (macro F1 score), and the F1 score of the less frequent labels.

As future research directions, we envision the investigation of the computational complexity of the Fairer Coverage Problem and the application of our method to different datasets. The HPA dataset is a special case where we have a single characteristic for each sample, but our method could easily be adapted to select a fairer dataset from a more complex dataset, i.e., containing more than one attribute. We also believe the method will be useful when applied to large datasets that cannot be used in full for the training phase due to computational limitations.

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