Surface EMG Signal Classification for Parkinson's Disease using WCC Descriptor and ANN Classifier

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- Keywords: sEMG Signal Segmentation, Parkinson's Disease, Wavelet Cepstral Coefficient (WCC), Artificial Neural Network (ANN).
- Abstract: To increase the diagnostic accuracy, artificial intelligence techniques can be used as a medical support. The Electromyography (EMG) signals are used in the neuromuscular dysfunction evaluation. The aim of this paper is to construct an automatic system of neuromuscular dysfunction identification in the case of the Parkinson disease based on surface EMG (sEMG) signals. Our proposed system uses artificial neural network method (ANN) to discriminate healthy EMG signals (normal) from abnormal EMG signals (Parkinson). After detecting the EMG activity regions using Fine Modified Adaptive Linear Energy Detecor (FM-ALED) method, Discrete Wavelet Transform (DWT) has been used for feature extraction. An experimental analysis is carried out using ECOTECH's project dataset using principally the Accuracy (Acc). Moreover, a multi-class neural networks classification system combined with the voting rule and Wavelet Cepstral Coefficient (WCC) for healthy and Parkinsonian subjects identification has been developed. The diagnosis accuracy assessment is carried out by conducting various experiments on surface EMG signals. Proposed methodology leads to a classification accuracy of 100%.

1 INTRODUCTION

Parkinson's disease (PD) is a neurodegenerative disorder due to the dopaminergic degeneration in the *substantia nigra pars compacta* that projects to the basal ganglia. Heterogeneous symptoms such as bradykinesia, rigidity, tremor and gait disturbances are sources of major disability.

In literature, several approaches have been used for PD motor dysfunction evaluation such as: gait evaluation through stride intervals recording (Wendling, 2008; Bhoi, 2017), handwriting (Rosenblum et al., 2013), accelerometry (Ghassemi et al., 2016), voice (Manwatkar et al.,) and the gait analysis using sEMG recordings (Elamvazuthi et al., 2015; Raut and Gurjar, 2015; Nazmi et al., 2016).

Many studies have been conducted to analyse the gait variables in neurodegenerative diseases, includ-

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ing Parkinson's disease (Carletti et al., 2006; Henmi et al., 2009; Hausdorff et al., 1998; Sugavaneswaran et al., 2012). It has been presented that the stride interval fluctuations are increased in Parkinson's diseases and correlated to severity's degree (Hausdorff et al., 1997). The variability in Electromyogram (EMG) signal acquired from gastrocnemius muscle was found higher in PD patients (Miller et al., 1996). In our study, the muscle's sEMG recordings are considered to characterize the subject's gait. These sEMG signals are used to detect and classify the Parkinson from normal gait. The EMG signal is a bioelectrical manifestation of the neuromuscular activity which is used in the field of kinesiology studies and neuromuscular diagnostics.

Several techniques are used for PD classification such as : probabilistic neural network (Okamoto et al., 2009), support vector machine (SVM) (Surangsrirat et al., 2016), K-means clustering algorithm (Bhoi, 2017). In (Elamvazuthi et al., 2015), the ANN using linear prediction coefficients (LPC) features is developed to classify neuromuscular disorders (myopathy and neuropathy disorders). The ANN approach (ANN) was one of the techniques used for sEMG

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classification (Reaz et al., 2006). One of the ANN major advantages is its ability to represent both linear and non-linear relationships (Oskoei and Hu, 2007) (Reaz et al., 2006). Many studies have adopted this technique to classify time domain features using multilayer perceptron (MLP) as well as linear discriminate analysis (LDA) to achieve high classification accuracy up to 95 % (Oskoei and Hu, 2007) (Micera et al., 2010). Other works combined both time and frequency domains features and used the back propagation algorithm to increase the classification accuracy from 95 % to 96 % (Andrade and Soares, 2001).

Our main contribution is to design an automatic EMG signal classification system for Parkinson's diseases diagnosis. The proposed system is based on ANN classifier combined with the WCC descriptor and the voting rule. This system enables us to evaluate the developed segmentation system of EMG activity regions (Bengacemi et al., 2020) for the diagnostic task. The main task consists of searching for optimal parameters of ANN model and WCC coefficients to achieve the best classification performances. This approach is carried out in a learning and a test phases. The learning phase consists in modeling the two classes P and N (P: Parkinson and N: Normal), while the test phase aims to evaluate the performance of the classification systems using the ANN and K-NN method. These two phases require a step of extracting discriminating parameters from the two classes.

The rest of the paper is organized as follows: section 2 describes the problem formulation and the proposed methodology. Section 3 is dedicated to the performance analysis and discussions while section 4 is reserved for the concluding remarks.

2 METHODOLOGY

The typical EMG signals of muscles involved in gait activity contain inactive segments (noise region) with low activity and active segments (burst EMG activity) which are mainly composed of the motor unit action potential (MUAP). There are mainly three types of parameters which characterize the MUAP waveform such as: amplitude, duration and stability. These parameters provide information about certain spatial and temporal characteristics of motor fiber (MF) and motor unit (MU) activity. Neuromuscular diseases change the shape, characteristics of the MUAP and the firing patterns of the motor unit (MU) are also changed. In normal conditions, MUAPs show mean peak-to-peak amplitudes of around 0.5 mV and duration from 8 to 14 ms, depending on the size of the MUs. In neurogenic disorder, the amplitude is increased to achieve 5 to 10 times normal and the duration is also increased (Barkhaus, 2001). The size and shape of MUAPs are determined by certain structural and functional aspects of MUs (Rodríguez-Carreño et al., 2012).

In our study, the EMG activity bursts (EMG active segments) detected using the Fine Modified Adaptive Linear Energy Detector (FM-ALED) technique (Bengacemi et al., 2020), have been selected in order to classify PD subjects versus normal subjects. The whole task scheme is presented in Fig.1.



Figure 1: Block diagram for classification system.

The proposed classification system is composed of learning and testing phases. The learning phase consists of detection of EMG activity segments, extraction of features, modeling of the two classes P and N using the ANN method. The testing phase consists of detection of EMG activity segments, extraction of features, classification of each vector of features by ANN technique, then classification of the sequence of vectors of each signal from the test database using the voting rule in order to find the dominant class from this sequence. The database of surface EMG signal is collected from French national project ECOTECH (Buttelli, 2012). These sEMG signals were obtained from many subjects (9 healthy subjects and 8 subjects suffering from Parkinson's diseases).

2.1 Surface EMG Signal Database

For this research work, eight Parkinsonian patients and nine healthy subjects were recruited in the frame of the French national research project ECOTECH (Buttelli, 2012). This study was approved by the local ethics committee and subjects provided written consent prior to commencement.

A specific lower limb muscles of gait activity have been measured. Patients were prepared for electrodes placement by shaving the skin and cleaning it with alcohol wipes. EMG sensors were placed on the muscle belly parallel to the main direction of muscle fibres in accordance with study on the innervation zone (Barbero et al., 2012). Data were collected using an on board system of wearable sensors (20-450 Hz bandwidth, 16 bits per sample, 1926 Hz sampling rate). Data collection provides several burst activities from each right soleus muscle corresponding to several gait cycles. The data base description is reported in tables 1 and 2.

Table 1: Description of sEMG signals for healthy subjects. Manual

-f EMC h

	Subjects		Number of EMG bursts	Signal duration (second)
Data base for training ph		$Control_1$	22	26.0685
	Data base for training phase	$Control_2$	10	11.2128
		Control ₃	11	14.3998
		$Control_4$	11	14.7441
		Control ₅	11	11.1635
		Control ₆	6	7.7121
Da	Data base for testing phase	Control ₇	6	6.5298
		Control ₈	12	14.3458
		Control ₉	26	28.5702

Table 2: Description of sEMG signals for Parkinsonian subjects.

Subjects		Number of EMG bursts	Signal duration (second)
	Park ₁	10	28.5702
Data hasa far training phase	Park ₂	10	9.1317
Data base for training phase	Park ₃	5	4.8657
	Park ₄	37	39.6152
	Park ₅	10	11.2876
Data base for testing phase	Park ₆	9	8.9152
Data base for testing phase	Park ₇	5	4.4742
	Park ₈	5	4.6487

2.2 EMG Signal Preprocessing

Several techniques can be used for handling data of EMG signals before processing the feature extraction which represents the pre-processing stages such as data segmentation, filtering and rectification often considered to improve the data controller accuracy. In this study, the FM-ALED technique is used to identify and extract the EMG activity segments in order to eliminate the non EMG activity regions (noise regions) (Bengacemi et al., 2020). In order to evaluate the influence of the quality of this preprocessing step on the classification performance results, the double threshold method was also considered, as commonly used in activity EMG segmentation (Bonato et al., 1998).

2.3 **Features Extraction and EMG Signal Modeling**

The feature extraction plays a critical role to get a robust classification system. This process transforms the raw sEMG signal into a feature vector. Generally, the used features in EMG signals analysis can be divided into three categories: time domain, frequency domain and time-frequency domain features (Tsai et al., 2014) (Hogan and Mann, 1980) (Englehart et al., 1999). As a particular class within the time-frequency methods, the time-scale methods have gained high interest because the scale parameter provides a natural analysis of biological phenomena, that is to say a high time precision for rapid events (low scales) and conversely a poor time precision with high frequency precision for slow events (high scales). Moreover, they show a high tuning flexibility in their design useful for performance seeking. In our work, we are interested in the use of Discrete Wavelet transform, particularly the Wavelet Cepstral Coefficient (WCC) coefficients. In this study, we have also analysed the Discrete Wavelet Energy (DWE) normalized on total energy of window analysis, the logarithm of wavelet energy (LWE) and the Wavelet Cepstral Coefficient (WCC) computed from the discrete cosine transform (DCT) of LWE (Hacine-Gharbi and Ravier, 2018) (see Fig.2). All the features were calculated using the discrete wavelet transform (DWT) which mother wavelet is characterized by two digital low-pass and high-pass filters. The DWT provides coefficients by an iterative down sampling-filtering procedure achieved at successive scales beginning on the N-length original signal x[n] up to a desired decomposition level L_{decomp} (that should be lower than the maximum decomposition level $L_{max} = log_2[n]$ provided N is a power of 2 or rounded to its nearest high value). The iterative procedure extracts the set of wavelet coefficients $d_i[n]$ at each scale i from 1 up to L_{decomp} value plus the $a_{L_{decomp}}[n]$ at the last scale. Then the DWE features $E(d_i)$ and $E(a_{L_{decomp}})$ are composed of the energy values calculated as the squared absolute magnitude sum of the wavelet coefficients at each scale i. The LWE are the log of the DWE coefficients previously normalized by the number of samples per scale. Finally, the WCC coefficients are obtained by applying the inverse DCT on the previous LWE coefficients for decorrelation. In this work, we investigated the impact of these descriptors on the performance results of PD classification. Hence different experiences have been carried out to search for the optimal configuration. These features are widely used in: speech recognition (Lei and Kun, 2016),(Adam et al., 2013), Electrical Appliances Identification (Hacine-Gharbi and Ravier, 2018) and Recognition of Heart Sound (Xiong et al., 2019).

In this work, we have also integrated the dynamic features which are the first order differential coefficients (also called delta Δ) and second order (called delta-delta $\Delta \Delta$), resulting from the initially calculated coefficients DWE, LWE and WCC, considered as static features. The static's features contain only information on a given frame. In order to improve the representation of the frame's information, it is often proposed to introduce new features in the vector of features. (Furui, 1981) and (Furui, 1986) proposed the use of dynamic features which present the spectral transition information in the signal. The dynamic features are calculed using *HCopy* command of the HTK tools library (Hidden Markov Model Toolkit).

Let $C_k(t)$ is the extracted feature k of frame t, then the corresponding differential coefficient ΔC_k is calculated on $2\eta_{\Delta}$ analysis frames by estimating the slope of the linear regression of the coefficient C_k at time t (Young et al., 2006):

$$\Delta C_k(t) = \frac{\sum_{i=-\eta_{\Delta}}^{i=+\eta_{\Delta}} i.C_k(t+i)}{2.\sum_{i=-\eta_{\Delta}}^{i=+\eta_{\Delta}} i^2}$$
(1)

The second order differential coefficients $\Delta\Delta$ (deltadelta or acceleration) are calculated in the same way from the first order coefficients.

The proposed system can be seen as pattern recognition system which requires a training and recognition phases. The first one is used for modelling the temporal pattern classes and the second one is used for Parkinson's diseases classification. Hence, both phases require feature extraction step to convert each signal (EMG activity region) in sequence of features vectors obtained by dividing the signal into overlapping windows and computing from each window a set of features that constitutes the feature vector (see Fig.2). This sequence of vectors can be considered as input sequence of observations in modelling or classification steps.



Figure 2: Features extraction steps.

2.4 ANN for Subjects Classification

In this research, the ANN have been used with errorback propagation which is employed as a learning procedure for multi-layer, feed-forward neural network. By the means of this process, the network can learn to map a set of inputs to a set of output. In this work, we have used the reduced-size feature vector as an input vector. The network topology is made of one input layer containing N neurons, where N is the number of features considered, one hidden layer with 10 neurons and one output layer with one neuron which output gives the Parkinsonian subject or healthy subject decision (see Fig.3). The activation function used is sigmoid with Levenberg-Marquardt algorithm as learning method on Matlab environment.



Figure 3: ANN topology with back-propagation algorithm, with N neurons in input layer, 10 neurons in hidden layer and 1 neuron for output layer.

2.5 K-NN Classifier

In this work, we have also used the k-NN classifier which is commonly applied in the field of pattern recognition for its simplicity. k-NN is a supervised classification algorithm that requires a training phase and a testing phase. In the training phase, each class is represented by a set of labelled feature vectors, each feature vector being a class instance. In the testing phase, each testing input feature vector is compared to all the labelled feature vectors stored in the training dataset. The recognized class is the one obtaining the majority vote between the classes of the K nearest neighbors.

In this work, K-NN is used for classifying the feature vectors, each representing an analysis frame. The default choice k=1 and the Euclidean distance between two vectors for comparisons are applied.

2.6 Accuracy Measures and Voting Rule Method

Recall that each labelled signal is composed of a sequence of activity regions (previously manually or automatically segmented from the raw data). Each activity region is then decomposed in a sequence of feature vectors (LPC, DME, LWE or WCC) computed in successive overlapping analysis frames which temporal duration may vary. We investigated the following frame duration set 16.61 20.00 30.00 33.22 40.00 50.00 60.00 66.45 70.00 80.00 90.00 100.00 110.00 120.00 130.00 132.91 140.00 150.00 expressed in ms. Each duration value is tested and the best performance result is retained.

Performance results of the sEMG signal classification methods are measured using accuracy which can be differently computed. Basically, each feature vector is presented as input to ANN or K-NN classifier. The output of the system makes a decision that is correct or not, depending on the known label of the signal. From these individual decisions, we can compute the following accuracies:

- The averaged accuracy counts the number of correct decisions by the total number of input feature vectors; counts are done by concatenating all the signals.
- The voting rule method assigns the decision to the class label for which the decisions number follows majority rule among all the decisions; the decisions can be made from feature vectors, activity regions or the whole signal as the concatenation of activity regions; here, the voting rule for sEMG activity regions is applied twice: first to feature vectors for each activity region and second to the activity regions for each signal; accuracy is the number of correct decisions made for the signals by the total number of signals.
- The voting rule for sEMG signal is applied to feature vectors for each signal; accuracy is the the number of correct decisions made for the signals by the total number of signals.

3 RESULTS AND DISCUSSION

To evaluate our proposed method, the developed study is divided in three parts: the first one is dedicated to evaluate the ANN method for different descriptors for the optimal analysis frame duration. The second one is dedicated to analyse the selected descriptor for different mothers wavelet, while the third part is developed for studying the impact of the segmentation and EMG activity burst detection step.

3.1 ANN and K-NN Techniques

In this study, we have evaluated the K-NN and ANN techniques for different descriptors such as LPC, DWE, LWE and WCC. We have investigated the best *Acc* for the optimal analysis frame duration and

with/without the dynamic features¹. For this task, the mother wavelet *Coif5* for decomposition level $L_{decomp} = 4$ has been used. The obtained results are presented in tables 3 and 4. Note that the performance gain of the WCC descriptor combined with ANN technique shows the 100% of *Acc* compared to LPC, LWE and DWE descriptors for analysis frame duration equal to 132.91 *ms* using voting rule. For each descriptor, the use of dynamic features improve accuracy. Tables 3 and 4 show that both voting rule strategies always improve accuracy (except in one situation with DWE descriptor and KNN).

Table 3: Performance comparison of the Acc (%) for ANN method for LPC for p=6, DWE, LWE and WCC features for different analysis frame durations.

	ANN	Acc %	Frame (ms)
	LPC coefficients without dynamics features	68.67	150
I PC	LPC coefficients with dynamics features	69.70	110
LIC	Voting rule for EMG activity regions	75	30
	Voting rule for surface signal EMG	Acc % Frame (ms) atures 68.67 150 itures 69.70 110 nns 75 30 G 75 30 atures 54.07 110 tures 59.54 140 nns 75 66.45 G 75 80 catures 53.08 110 tures 64.45 130 nms 75 16.61 G 87.5 110 eatures 53.75 60 nutures 63.41 130 nms 75 100 G 100 132.91	30
	DWE coefficients without dynamics features	54.07	110
DWE	DWE coefficients with dynamics features	59.54	140
DWE	Voting rule for EMG activity regions	ANNAcc %Frame (n2 coefficients with dynamics features68.67150 $^{\circ}$ Coefficients with dynamics features69.70110Voting rule for EMG activity regions7530 $^{\circ}$ Coefficients with dynamics features54.07110Voting rule for surface signal EMG7530 $^{\circ}$ Coefficients with dynamics features59.54140Voting rule for Surface signal EMG7566.45Voting rule for surface signal EMG7580 $^{\circ}$ Coefficients with dynamics features53.08110Ve coefficients with dynamics features53.08110Ve coefficients with dynamics features53.08110Ve coefficients with dynamics features53.7516.61Voting rule for Surface signal EMG87.5110C coefficients with dynamics features53.7560CC coefficients with dynamics features63.41130Voting rule for EMG activity regions75100Voting rule for EMG activity regions75100Voting rule for EMG activity regions75100Voting rule for surface signal EMG100132.91	66.45
	Voting rule for surface signal EMG	75	80
	LWE coefficients without dynamics features	53.08	110
IWE	LWE coefficients with dynamics features	64.45	130
LWE	Voting rule for EMG activity regions	75	16.61
	Voting rule for surface signal EMG	Acc % Frame (ms) itures 68.67 150 ires 69.70 110 ns 75 30 3 75 30 atures 54.07 110 ires 59.54 140 ns 75 66.45 3 75 80 atures 53.08 110 ures 64.45 130 ns 75 16.61 G 87.5 110 atures 53.75 60 nures 63.41 130 ns 75 100 G 100 132.91	
	WCC coefficients without dynamics features	53.75	60
WCC	WCC coefficients with dynamics features	its without dynamics features 68.67 1 ints with dynamics features 69.70 1 for EMG activity regions 75 3 e for surface signal EMG 75 3 ts without dynamics features 54.07 1 nents with dynamics features 59.54 1 for EMG activity regions 75 66 for surface signal EMG 75 8 atts without dynamics features 53.08 1 nents with dynamics features 64.45 1 for EMG activity regions 75 16 e for surface signal EMG 87.5 1 for EMG activity regions 75 16 e for surface signal EMG 87.5 1 for EMG activity regions 75 16 ents with dynamics features 53.75 0 ents with dynamics features 63.41 1 for EMG activity regions 75 1 the with dynamics features 63.41 1 for EMG activity regions 75 1 thor EMG activity regions 75 1	130
mee	Voting rule for EMG activity regions	75	100
	Voting rule for surface signal EMG	100	132.91

Table 4: Performance comparison for K-NN method of the *Acc* (%) for LPC for p=6, DWE, LWE and WCC features for different analysis frame durations.

	K-NN	Acc %	Frame (ms)
	LPC coefficients without dynamics features	67.48	140
I DC	LPC coefficients with dynamics features	66.29	140
LIC	Voting rule for EMG activity regions	87.50	120
	Voting rule for surface signal EMG	75	16.61
	DWE coefficients without dynamics features	52.74	140
DWE	DWE coefficients with dynamics features	62.75	130
DWE	Voting rule for EMG activity regions	62.5	110
	Voting rule for surface signal EMG	62	100
	LWE coefficients without dynamics features	52.74	140
IWE	LWE coefficients with dynamics features	57.01	61.32
LWE	Voting rule for EMG activity regions	Acc % Frame (ms) ics features 67.48 140 ss features 66.29 140 regions 87.50 120 d EMG 75 16.61 nics features 52.74 140 cs features 62.75 130 regions 62.5 110 d EMG 62 100 nics features 52.74 140 cs features 57.01 132.91 'regions 75 60 d EMG 75 132.91	60
	Voting rule for surface signal EMG		
	WCC coefficients without dynamics features	52.74	140
WCC	WCC coefficients with dynamics features	57.01	132.91
wee	Voting rule for EMG activity regions	75	60
	Voting rule for surface signal EMG	75	132.91

3.2 Choice of the Mother Wavelet and Decomposition Level

After choosing the feature's descriptor, we investigate the appropriate mother wavelet and decomposition level L_{decomp} . We have considered L_{decomp} varied form 1 to log2 of samples number of analysis window

 $^{{}^{}l}\eta_{\Delta} = 1$ for equation (1) is the default value of HTK tools library

(max level=7). In this work, we consider the following wavelet families:

- The Daubechies family with orders 1 to 8: Db1, Db2, ..., Db10;
- The Symlets family with orders 1 to 8: Sym1, Sym2, ..., Sym8;
- The Coiflets family with orders 1 to 5: Coif1, Coif2,..., Coif5.

The obtained results of Acc and L_{decomp} are reported in the tables 5, 6 and 7 for each mother wavelet family respectively from which we can note that the best results:

- For Daubechies family, the mean of *Acc* is greater than 82 % and the best one is equal to 100% for *Db6* and *L_{decomp}* = 2;
- For Symlets family, the mean of *Acc* is greater than 75 % and the best one is equal to 87.5 % for *Sym7* and *L_{decomp}* = 4;
- For Coiflets family, the mean of *Acc* is greater than 82 % and the best one is equal to 100% for *Coif* 5 and $L_{decomp} = 4$.

Table 5: Performance results in terms of *Acc* for WCC features using **Daubechies** wavelet family.

Daubec	hies	Db1	Db2	Db3	Db4	Db5	Db6	Db7	Db8	Db9	Db10	mean
	Ldecomp	6	5	3	2	2	6	2	2	6	2	//
132.91 ms	Acc %	62.50	75	75	87.5	87.5	100	87.5	87.5	87.5	75	82.50

Table 6: Performance results in terms of *Acc* (%) for WCC features using **Symlets** wavelet family.

Symlets		Sym1	Sym2	Sym3	Sym4	Sym5	Sym6	Sym7	Sym8	mean
	Ldecomp	6	6	3	2	2	3	4	2	//
132.91 ms	Acc %	62.5	75	75	75	75	75	87.5	75	75

Table 7: Performance results in terms of Acc (%) for WCC features using **Coiflets** wavelet family.

Coiflets		Coif1	Coif2	Coif3	Coif4	Coif5	mean
	Ldecomp	3	3	2	7	4	//
132.91 ms	Acc %	75	87.5	75	87.5	100	82.14

3.3 Impact of Segmented Data Base for PD Diagnostic

In this section, we have studied the impact of the segmented database based on the FM-ALED and Double-threshold methods which have been reported in (Bengacemi et al., 2020) (the obtained results are presented in table.8). We have used the optimal configuration composed of descriptor WCC, mother wavelet *Coif* 5, decomposition level $L_{decomp} = 4$ for analysis frame duration equal to 132.91 *ms*. The obtained results are reported in the Table.9 from which we can note that the same results of *Acc* have been obtained for the both database (labelled and segmented) for FM-ALED method contrary to Double threshold

method. This result shows that our method is robust against segmentation inaccuracies. We thus can exploit the EMG activity bursts for Parkinson's disease diagnosis using the ANN approach combined with the efficiency of the FM-ALED technique for EMG signals segmentation.

Table 8: Comparison of error probability, mean and standard deviation (STD) of burst EMG activity detection for **RSol:** right soleus for healthy and Parkinson's subjects. Statistics are presented for each subject of the EcoTech dataset (8 Parkinson and 9 healthy) using Double-TH or FM-ALED method.

Sub	ject (S)	S_1	S ₂	S_3	S4	S5	S ₆	S7	S_8	S9	mean	STD
Parkinson	DoubleTH	0.2308	0.2402	0.1932	0.2108	0.2021	0.2200	0.1982	0.1708	//	0.2104	0.0230
Farkinson	FM - ALED	0.0264	0.1463	0.0823	0.0338	0.0978	0.0583	0.0792	0.1077	//	0.0790	0.0395
Healthy	DoubleTH	0.1211	0.1958	0.2058	0.1873	0.3401	0.2296	0.1804	0.1974	0.2201	0.2086	0.05816
incumiy	FM = AIFD	0.1047	0.0441	0.0600	0.0776	0.0760	0.0438	0.0507	0.0762	0.0760	0.2086	0.0196

Table 9: Performances comparison for labelled and segmented databases for WCC descriptors, mother wavelet Coif 5, decomposition level $L_{decomp} = 4$ and analysis frame duration equal to 132.91 *ms*.

	WCC coefficients without dynamics features	53.55		
laballad data basa (A aa %)	WCC coefficients with dynamics features	61.38		
Tabelled data base (Acc n)	Voting rule for EMG activity region	75		
	Voting rule for surface EMG signal	100		
	WCC coefficients without dynamics features	53.55		
Segmented database using FM-ALED (Acc %)	WCC coefficients with dynamics features			
Segmented database using TWI-ALED (Acc 10)	Voting rule for EMG activity region			
	wCC coefficients with dynamics features 53.35 Voting rule for EMG activity region 75 Voting rule for Surface EMG signal 100 WCC coefficients with dynamics features 51.38 Voting rule for EMG activity region 75 WCC coefficients with dynamics features 61.38 Voting rule for EMG activity region 75 Voting rule for EMG activity region 75 Voting rule for EMG activity region 75 VOC coefficients with dynamics features 53.96 WCC coefficients with dynamics features 53.95 Voting rule for Surface EMG signal 100 WCC coefficients with dynamics features 53.55 Voting rule for EMG activity region 62.30 Voting rule for Surface EMG signal 50	100		
	WCC coefficients without dynamics features	53.96		
Voting rule for surface EMG signa WCC coefficients without dynamics feat Segmented database using Double-TH (Acc %)	WCC coefficients with dynamics features	53.55		
Segmented database using Double-TTT (net 10)	(Acc %) WCC coefficients with dynamics features 61.38 Voting rule for EMG activity region 75 Voting rule for surface EMG signal 100 M-ALED (Acc %) WCC coefficients without dynamics features 51.93 Woting rule for surface EMG signal 100 75 Voting rule for Surface EMG signal 100 WCC coefficients without dynamics features 51.95 Voting rule for surface EMG signal 100 WCC coefficients with dynamics features 53.55 WCC coefficients without dynamics features 53.55 Voting rule for EMG activity region 62.50 Voting rule for EMG activity region 62.50 Voting rule for EMG activity region 62.50 Voting rule for Sufface EMG signal 50			
/		50		

Table 9 also shows that a high segmentation error (from 7% for FM-ALED to 21% for Double-TH) dramatically damages the signal classification performance (the best accuracy result is divided by 2). On the contrary, the segmentation error produced by FM-ALED has very few influence on the signal classification statistics.

4 CONCLUSION

Disease classification has important clinical applications. The present paper describes new approach to deal with Parkinson's disease classification based on WCC and ANN. The results show that WCC-ANN achieved high accuracy classification suitable for clinical applications. Hence, it represents an appropriate solution for the analysis of sEMG signals and its use for diagnosis purposes. We have also seen the effectiveness of the used method for surface EMG segmentation, named FM-ALED and the interest of voting rule on the performances of the proposed diagnostic system.

However, we are aware that the fact a classifier showing 100% correct classification may be a manifestation of inadequate testing. We have achieved testing with many combinations of features and parameters on a dataset of only 17 (9 + 8) patients in

order to find the best configuration. Our procedure is motivated by the relative limited dataset, which could be increased for example by the use of data augmentation methods. Indeed, in a classical way, it is imperative to have a sufficiently large dataset in order to have a separate validation set for selecting the best configuration. This validation set must be different from the test set, which should only be used for the final performance assessment. Evaluating different parameters on the test set, which is then used for reporting the final classification accuracy inevitably causes leakage, as such test set cannot be considered "new" or "unseen" by the algorithm since it was used for making modeling decisions. Alternative to the single training / validation / test split would be a procedure called nested cross-validation (Cawley and Talbot, 2010), often applied in tasks involving small data, which can be investigated in this work.

Future works will also investigate data of ECOTECH recorded on other muscles involved in gait movement.

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