

# IT-Application Behaviour Analysis: Predicting Critical System States on OpenStack using Monitoring Performance Data and Log Files

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**Abstract:** Recent studies have proposed several ways to optimize the stability of IT-services with an extensive portfolio of processual, reactive or proactive approaches. The goal of this paper is to combine monitored performance data, such as CPU utilization, with discrete data from log files in a joint model to predict critical system states. We propose a systematic method to derive mathematical prediction models, which we experimentally test using a downsized clone of a real life contract management system as a testbed. First, this testbed is used for data acquisition under variable and fully controllable system loads. Next, based on the monitored performance metrics and log file data, we train models (logistic regression and decision trees) that unify both, numeric and textual, data types in a single incident forecasting model. We focus on 1) investigating different cases to identify an appropriate prediction time window, allowing to prepare countermeasures by considering prediction accuracy and 2) identifying variables that appear more likely than others in the predictive models.

## 1 INTRODUCTION

With today's companies vitally relying on continuous service of their IT infrastructures, predictive analytics as a tool to "foresee" problems has become indispensable. With many software solutions out in the wild, the problem of data acquisition and model design is still to a wide extent a matter for a domain expert to make design decisions, such as (i) which performance metrics can be monitored, but more importantly (ii) which among the ones possible should be monitored for a good predictive model? Last but not least, we strive for *explainable* models, meaning that the model's predictions should be comprehensible by a human. While the diversity of predictive models is rich and data science has lots to offer to study, the construction beforehand enjoys a much smaller set of theoretical aids. Our work is meant to close this gap in a twofold way: first, we fit a series of models (one stochastic, one deterministic) to a set of variables to determine which among them are likely to play a role in either model. This is to answer the previous question (i) to equip an

administrator with a reasonable initial guess about what to monitor. Second, towards answering question (ii), we describe how to unify two kinds of data sources in the same model, namely monitoring data and textual log files. Almost all predictive models in the literature focus exclusively on one or the other type of data. Our proposal is the first study of a combined model. A careful initial choice about which data should go to a further analysis can substantially save efforts (time and costs) here. This paper will answer the following research questions (RQ):

**(RQ1):** Which method mix can be used to combine numeric and continuous with textual and discrete IT-system data to be suitable for a single incident forecasting model?

**(RQ2):** Which variables are most likely to be relevant for predicting the system state by a (yet unspecified) model, so that we know which variables should be monitored?

**(RQ3):** To what extent does prediction window size influence the prediction quality and the impact of the variables on the system state?

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We start with an overview of related work. To close a gap identified in previous related literature, we empirically substantiate the added value of predictive modelling that pursues a combined use of monitoring data and log files. The main body of this work is predictive modelling based on IT-system data. Finally, we present our results and findings, which will further be investigated as mentioned in the future work section.

## 2 RELATED WORK

A lot of different research in the IT-service-management (ITSM) area focuses on approaches and methodologies to keep the quality and availability of IT systems (ITS) at a maximum level. A common way to improve ITS quality and availability is the orientation on processual best practice frameworks like ITIL and has been widely studied (Hochstein et al., 2005), (Potgieter et al., 2005), (Cater-Steel et al., 2007). Beside these frameworks and their recommendations, analytics based approaches, which are actually not part of the frameworks, come to the fore. There are a vast amount of event pattern mining and summarization approaches for log file analysis available, which can be structured as suggested in (Kubiak/Rass, 2018) following the question what the practitioners do want to learn from or do want to do with the data: Recognition of interdependencies, which often manifest themselves as patterns (Ma/Hellerstein, 2001), (Li et al., 2005), (Tang et al., 2012), (Zöller et al., 2017) or understanding the system and its dynamics as such, which can be presented as summaries (Kiernan/Terzi, 2009), (Wang et al., 2010), (Peng et al., 2007). A taxonomy for online failure prediction methods and its major concepts has been presented in (Salfner et al., 2010). Some of the methods use time series data from monitoring metrics to predict the system state but the taxonomy includes predictions based on log file event occurrence as well. A limited number of research papers focus on the complementary use of monitoring data and log file events to generate further insights (Luo et al., 2014).

## 3 DATA ACQUISITION

For data acquisition, we defined a concept for a load and performance measurement in scenarios that resemble real life user interactions with the system. We used a small-scale digital twin of a real life IT-

system environment, which resembles a productive system without being one, to fully control and manipulate the systems behaviour as requested. There was no continuous load on the system because it was a training environment mainly used for irregularly employee trainings. Therefore, test scripts were generated using *VuGen* and scheduled using *LoadRunner Enterprise*, which both are software products of *Micro Focus*. These scripts generate regular system load (client transactions sent to the system) and load peaks. As a major advantage of using a digital twin here, the scripts enabled us to produce any sort of unwanted behaviour known to be different from noise. In particular, rare events and incidents of diverse kinds can be triggered to the amount and extent required.

### 3.1 Application Architecture and Implementation

The application of our choice for the experimental setup is a contract management system (CMS), which is a web application based on *Java*. Fig. 1 illustrates the architecture of our experimental testbed, which is an on-premise cloud application hosted at our data centre. Essentially, the application consists of an infrastructure as a service (IaaS) as backend component and a platform as a service (PaaS) as frontend component. Both run within an *OpenStack* environment, which is an open source software for creating public or private clouds.

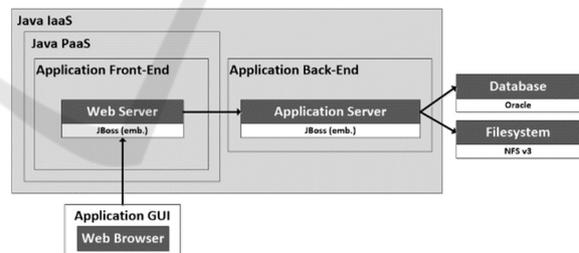


Figure 1: Architecture of the CMS.

The IaaS component ran on a node with 8 CPUs (Intel Xeon CPU E5-2680 v4 @ 2.40GHz), 8GB RAM, and 20 GB hard disk. The PaaS component ran on a node with 4 CPUs, 8 GB RAM, and 2 GB hard disk. The web and application servers both run on *Linux RHEL 7.x* operating system. As application runtime, the web server uses *WildFly* while the application server uses *JBoss EAP*. *WildFly* is an open source application runtime and part of the *JBoss* middleware framework. Furthermore, it is the basis for the commercial version *IBM Red Hat JBoss EAP*. For collecting monitoring

data, we used *DX Application Performance Management* (formerly known as *CA APM*).

### 3.2 Load and Performance Test Design

To generate necessary monitoring data and log files, we designed a concept for a 10-day long load and performance test. From data quality perspective, our focus was to evaluate the suitability of our models with data whose underlying generative processes are entirely known to us. We simulated a specific number of user interactions within the CMS, based on real system transactions like contract search, creation, modification and termination for fixed time windows. The load and performance test consists of different scenarios to simulate normal as well as anomalous behaviour, which we defined as unusually high system load (peaks), i.e., as critical system state from application performance perspective. The number of virtual users working on the CMS simultaneously was the trigger for the system load intensity. We decided to switch from normal to anomalous behaviour in a 15-minutes interval within an 8 hours period for each test day. The reason to switch from normal behaviour to load peaks in a 15-minutes interval was to enrich the data set with as much as possible behaviour changes to train the models. An earlier experimental setup showed that imbalance between the number of data rows for normal load and anomalies had significant (negative) influence on prediction accuracy. For the load peaks, we decided to use a high grade of variety for the stepwise load increases to avoid patterns. We defined normal behaviour as  $\geq 5$  and  $\leq 17$  virtual users working simultaneously, a number of  $\geq 18$  virtual users represents the threshold for anomalous behaviour. Due to internal regulations, the test design was restricted to a system load generated by  $\leq 25$  virtual users working at the same time. The collected data consists of  $\approx 25$  GB raw text file documents (log files) and 4,800 monitoring data records (measured in a 1-minute interval).

**Remark 1:** Alternative other such conditions are of course possible, say, defining the trigger levels based on resource consumption as induced by the user's transactions. Such anomaly triggers bear an intrinsic stochastic element, since the system load that a transaction causes may vary depending on what a user does specifically.

## 4 DATA PREPARATION

Because the data results from different sources, harmonization of textual and numeric data into one

common format was the main challenge (besides the standard steps like data cleansing, which is not discussed further here).

### 4.1 Log File Data

Since most data harvested from a normal IT-application comes in textual form of log files, our first task is to convert the textual information into numeric data, usable with analytic models. To this end, we followed the standard practice of taking these steps: i) filtering out error messages from the overall log textual corpus; ii) use document-term-matrices (DTM) to extract signalling keywords from the text, to recognize "topics" that the log entries refer to (Imai, 2017; Xu et al., 2003); and iii) run a clustering algorithm to associate each log entry with one out of a few clusters that correspond to variables in a predictive model to be constructed. Each cluster created in the last step is then a log-data related variable in our predictive model, and the association of a log entry with a cluster manifests itself as the respective indicator variable in the model coming in with the proper (numeric) value. Together with the log entry's timestamp, we obtained a set of 0-1-valued variables, which are the first part of the data set. For the clustering, we chose DBSCAN (Ester et al., 1996) as the simplest method to apply in absence of specific domain knowledge. This choice is consistent with our initial assumption of the administrator not yet having much insight about what variables to measure at all, so an algorithm that determines the number of clusters itself is more desirable here. After testing different configurations without considerable differences for the result, we decided to use the configuration with  $minPts = 4$  and  $\epsilon = 0.4$ .

### 4.2 Monitoring Data

We collected monitoring data using agents installed on the IaaS and PaaS components. These agents are exclusively for application performance monitoring and do not monitor the infrastructure layer, i.e., metrics for the physical hardware are not available. Each group of monitoring metrics consists of at least one but usually several variables – (for example, CPU is a variable and a metric group at the same time while the average response time group contains measures of the response times of  $>50$  different *JavaBeans*):

- **Average Response Time (AR):** The average response time in ms of a *JavaBean* from method call until response

- **Memory Pools (MP):** The dedicated part of the *heap memory* in bytes, which allocates memory for all instances and arrays at runtime
- **Concurrent Invocations (CI):** The number of simultaneous calls of a *JavaBean*
- **CPU:** The CPU utilization in percentage
- **% Time Spent in Garbage Collection (GC):** The percentage time within an interval in which obsolete in-memory code is removed
- **Responses per Interval (Rpl):** The number of application responses within an interval
- **Sockets (Sock):** The number of available Communication Points of the Application

### 4.3 Merging Log File and Monitoring Data

After preparing the log file and monitoring data, we merged both data sets into a single data set based on the timestamps of their entries. Because the granularity of the monitoring data was less (recorded in a fixed 1-minute interval) than that of the (sporadically occurring) log events, several rows of the log file data were lost through the (inner) join. Afterwards, we labelled the entries resulting from the merge by adding a column "Alarm". Values for Alarm are "0" denoting normal behaviour and "1" denoting anomalous behaviour. Resulting from the scripted induction of anomalies in our experimental setup for the data acquisition task, the data labelling was reliably automatable. As result, we obtained a data set that consists of 4,800 rows and 139 variables. Returning to our requirement of explainability and interpretability, 139 variables is a lot to handle, and not all of them are equally important. In a final step, we used  $\chi^2$ -tests (alternatively, also Fisher's exact test) to further filter this set of variables keeping only those variables that show a statistically significant interplay with the alarm indicator. Through this final step, the dataset was reduced to 106 (out of 139) statistically significant variables.

## 5 EXPERIMENTAL SETUP

We do not only want to train models to achieve a suitable prediction quality, we moreover want to have an entirely transparent system devoid of black-box parts. Thus, we want to give IT-operators guidance on which variables they should focus on to indicate reasons for the system state turning critical. Our general prediction scheme is illustrated in Fig. 2.

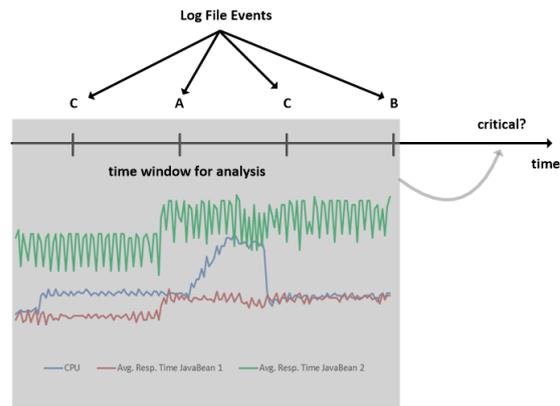


Figure 2: Our approach for predicting the system state.

### 5.1 Choice of Prediction Models

Our first choice is logistic regression as a predictive model of an alerting system. This alert, or *alarm*, is a binary random variable, whose probability, or equivalently the logarithm  $\ell$  of the respective odds, is linearly dependent on any choice of variables  $X_1, \dots, X_k$ . The model takes the form

$$\ell(\text{alarm}) = \beta_0 + \beta_1 X_1 + \beta_2 X_2 + \dots + \beta_k X_k + \varepsilon$$

where  $\ell(\text{alarm})$  is the log-odd of the alarm probability  $p = \Pr(\text{alarm})$  (defined as  $\ell = \log\left(\frac{p}{1-p}\right)$ ), and  $\varepsilon$  is an error term having a Gaussian distribution with zero mean. Although such a logistic regression model generally presumes a stochastic part in the data, this may not accurately reflect reality when alerts are generated by deterministic rules (such as we sketched above using peak thresholds or similar). Nevertheless, fitting a logistic regression model offers the appeal of telling us – during the fitting – if the alarm variable has a deterministic dependence on the variables in question. For that case, decision trees are our second choice. They are recursive partitions of an instance space and used for classification or regression tasks. A decision tree compiles a sequence of threshold decisions using the predictor variables, each decision splitting the instance space into  $\geq 2$  subspaces, until the final decision associated with a leaf of the decision tree. Based on a certain discrete function of the input variables, each internal node represents a decision and its consequences along the further tree. We shall not go into much detail about the statistical background and refer the reader to (Hosmer/Lemeshow, 2000) and (Rokach/Maimon, 2010). For the evaluation, we decided to experiment with different configurations based on a matrix

consisting of the forecasting horizon and the number of historic data rows used for prediction. These cases each are evaluated within a loop of 1,000 repetitions and in each repetition, a different training and test data set for evaluation is randomly sampled. Our evaluation focuses on counting the number of appearance of each variable that was relevant for fitting the 1) logistic regression and 2) decision tree. Regarding 1), we measured the significance of the variables by counting the number of a variable having a  $p$ -value  $< 0.1$  within the loops. Regarding 2), we counted the number of appearance for each variable being part of the fitted decision trees. We stress that this is conceptually different from the usual model diagnostics asking for statistical significance or importance of a variable; our analysis is here only to quantify the (frequentist) likelihood for a variable to appear in a model at all, whereas the counts cannot say anything about its significance or importance for a specific model. This is consistent with our goal of helping a model builder with an a priori choice of variables to measure, rather than doing a standard a posteriori quality judgement of a model or variables therein. For an a posteriori evaluation of the prediction quality, we calculated the average accuracy measure within the 1,000 repetitions. For a rough decision about the quality of the prediction, the accuracy is enough here for our purposes. Future work will include more detailed diagnostic studies and many more scores.

## 5.2 Model Construction

If the model shall be such that it predicts alarms for a future time window  $\Delta t$ , based on the events over a fixed past time window  $\Delta h$ , we proceeded as follows: at time  $t$ , collect all records timestamped within the period  $H = [t - \Delta h, t]$  and concatenate the records into a larger new record containing all data within this time window. Naturally, each  $X_i$  will then occur with multiple copies in the record set, for example, if there were three records in the past history, each carrying the variables  $X_1, \dots, X_k$ , we got a record with predictor variables  $X_1^{(0)}, \dots, X_k^{(0)}, X_1^{(1)}, \dots, X_k^{(1)}, X_1^{(2)}, \dots, X_k^{(2)}$ , where the notation  $X_i^{(j)}$  denotes the  $i$ th variable at  $j$  time steps before the current time  $t$ . The setting of the variable  $alarm$  is then determined by how far we look into the future: essentially, with the predictors constructed as above, the predicted variable  $alarm$  is then set to 1 in the so-constructed training data if and only if there was an alarm in the recorded data between the current time  $t$  and the (fixed) forecasting horizon  $t + \Delta t$ . For example, if there was no alarm in

the records falling into the range  $[t, t + \Delta t]$ , we would instantiate the current training data record with  $alarm = 0$ , and with the historic values collected from the records falling into  $[t - \Delta h, t]$ . Otherwise, we set  $alarm = 1$ , since there has been a race condition occurred after time  $t$  within the forecasting horizon  $\Delta t$ , which we seek to predict based on the current situation and history.

## 5.3 Configuration Cases

Resulting from our experimental setup for data acquisition, the maximum for the forecasting horizon is 15 minutes because the intervals from normal load and peaks switch all 15 minutes at every test day. We decided to use 1, 5, 10 and 15 as intervals for the forecasting horizon (in minutes) and the number of historic data rows used for prediction (1 row  $\triangleq$  1 minute) as well. Tab. 1 shows the resulting configurations.

Table 1: Configuration cases.

		Historic data rows used			
		1	5	10	15
Prediction window	1	C1	C5	C9	C13
	5	C2	C6	C10	C14
	10	C3	C7	C11	C15
	15	C4	C8	C12	C16

**Remark 2:** We imposed a practical time limit for our experimental evaluation per configuration, considering that the evaluation of “larger” configurations C13-C16 exceeded this practical limit (up to 2 weeks per configuration for the model construction and evaluation).

## 6 RESULTS

Since the number of variables can be large in practice, it may be useful to arrange variables of similar semantics in groups to ease the interpretation, presentation and visualization of the results. This is the sought initial guidance for monitoring operations, as a decision aid on which variables to monitor in first place, before later going into the matter of constructing concrete models and analysing them (for statistical significance, importance or other scores related to individual variables therein).

### 6.1 Logistic Regression

Tab. 2 presents the results for the logistic regression, which are limited to C1-C4. For the logistic

regression, we counted the number of appearances of each metric group that contains at least one variable having a  $p$ -value  $< 0.1$  within 1,000 repetitions to identify the significance of the variables in that metric group for the prediction. The analysis clearly shows that three of the nine groups of metrics dominate in case of the appearance and that the other groups could be neglected for monitoring. Furthermore, the significance of the *% time spent in garbage collection* (GC) group of metrics is continuously increasing the more historic rows are used in the data set while the *memory pools* (MP) group decreases and the *concurrent invocations* (CI) group first increases until case C3 and then decreases.

Table 2: Results of the logistic regression models.

Case	Accuracy	Metric group	Number of appearance
C1	96%	MP	783
		CI (PaaS)	140
		GC	2
C2	98%	MP	777
		CI (PaaS)	437
		GC	181
C3	97%	CI (PaaS)	868
		MP	711
		GC	310
C4	96%	GC	846
		CI (PaaS)	317
		MP	194

Summarized, we identified that there are three dominating groups of metrics to predict the system state using logistic regression. Thus, model complexity could be reduced by removing variables of all other metric groups. Furthermore, the resulting guidance for monitoring operations is to give threshold warnings based on metrics falling into the three dominating groups. Those deserve preferential treatment as containing the most promising indicators for an incoming critical system state. In all other cases, we found (quasi-)perfect separation, as indicated by the maximum likelihood fitting of the logistic regression model failing to converge. This failure carries a useful diagnostic information, since it tells us that a deterministic model is in this case more advisable. The separation phenomena are easy to explain, as it is an artefact of the quasi deterministic raise of alarms in our scripts. This makes the labelling follow a deterministic pattern, which becomes recognizable via the diverging behaviour of the maximum likelihood fitting algorithm.

## 6.2 Decision Trees

Applying the decision tree was possible for all cases. Nevertheless, some metric groups show no meaningful trend over all cases and could be ignored as well. Therefore, we limited visualizations on important metrics groups using bubble plots, which are shown in Fig. 3-5. In all diagrams, the x-y location of the bubble corresponds to the configuration in the column/row of the experimental setting in Tab. 1. The size of the bubble is proportional to the percentage frequency of the variable group to appear in a model within the given configuration. Thus, the larger the bubble, the more likely is a variable (group) to be relevant in the respective prediction setup. This is a direct pointer for a practitioner to see which variables or groups are relevant and which are less relevant. We remark that our particular experimental setup with a rule-based alarming makes decision tree analysis the most promising candidate here. Our practical advice is thus to nonetheless start by fitting a logistic regression model, since it will distinguish the need for a deterministic or a stochastic model very well. Memory pools are a good indicator for predictions from 1 to 5 minutes but become less relevant if forecasting horizon is set to  $\geq 10$  minutes. The meaning of concurrent invocations of the PaaS lacks within C5, C6, C9 and C10 but are consistently a good indicator over all cases using one historic data row. CPU, somewhat surprisingly, turns into a meaningful indicator only if the number of historic data rows is  $> 1$ . The analysis shows that the CPU value 2 minutes before  $t$  is the only relevant CPU variable. All other metric groups did not show reliable trends and cannot be declared as generally meaningful indicators although a case specific use could be considered.

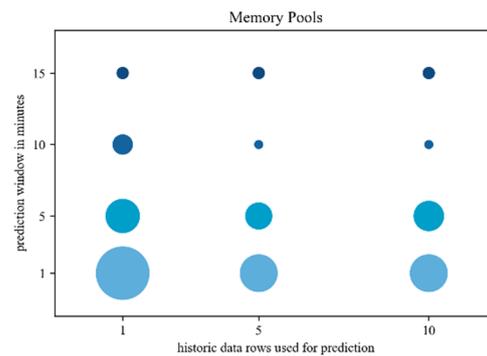


Figure 3: Results of decision trees – memory pools.

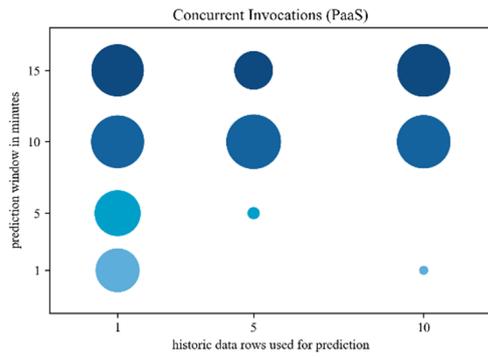


Figure 4: Results of decision trees – Concurrent Invocations.

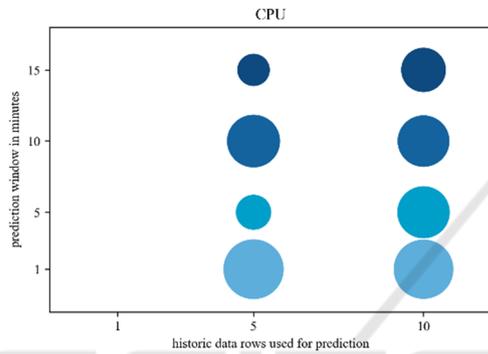


Figure 5: Results of decision trees – CPU.

Tab. 3 presents the detailed results for the decision trees but limited to the top 3 metric groups per case. In summary, it was possible to reduce the large set of variables that could be monitored by determining relevant metric groups using two different models, which both achieved an outstanding prediction accuracy. More importantly, we could identify variables that are very likely to be useful for prediction and therefore should receive primary attention, thus saving resources and gaining efficiency for the IT-operating.

## 7 THREATS TO VALIDITY

We judge our results using following threats to validity. A threat to construct validity is the design of our load and performance test scenario. Related to the restriction of having only  $\leq 25$  simulated users interacting on the system at the same time, we cannot guarantee that this system load intensity was seriously endangering the system state. This allows the question if the load intensity was high enough to jeopardize normal application behaviour and if necessary log file events, i.e. “fatal” events, were

Table 3: Results of decision tree models.

Case	Accuracy	Metric group	Number of appearance
C1	95%	MP	1,100
		CI (PaaS)	742
		AR (PaaS)	285
C2	98%	CI (PaaS)	1,204
		CI (IaaS)	486
C3	99%	CI (PaaS)	1,001
		GC	686
		CI (IaaS)	260
C4	96%	CI (PaaS)	1,332
		AR (PaaS)	722
		GC	537
C5	95%	CPU	976
		MP	370
		GC	338
C6	97%	AR (PaaS)	2,170
		CPU	1,000
C7	99%	MP	563
		CI (PaaS)	1,024
		CPU	965
C8	93%	GC	67
		AR (PaaS)	1,624
		CI (PaaS)	1,424
C9	99%	CPU	990
		MP	964
		GC	382
C10	100%	GC	347
		CPU	1,000
		AR (PaaS)	494
C11	99%	CI (IaaS)	478
		CI (PaaS)	1,035
		CPU	954
C12	99%	AR (PaaS)	159
		CI (PaaS)	1,400
		CPU	1,000
		GC	597

generated (although our data set contains more than 40 different types of error messages, which are the event type with the highest severity of the CMS). This could falsify the assumption that log file events do not have any relevance as predictor for the system state. We address the threat of internal validity by repeating the experiments 1,000 times for both models using randomly sampled training and test data sets in each repetition. The main threat to external validity is the generalizability of our results. Even if the described method mix should be applicable to any IT-application, the results are specific to the chosen CMS training environment.

## 8 CONCLUSION AND FUTURE WORK

The combination of monitoring performance metrics and log files allows the unification of necessary system parameters into one predictive model. In this paper, we propose 1) a method mix to unify numerical and textual data as well as 2) a method to obtain (automated) guidance on what sort of model to construct for the prediction of alarm states.

**On RQ1:** The described mixed application of logistic regression and decision trees accomplishes the unified use of continuous monitoring with discrete event data in the same model.

**On RQ2:** Limited to our experimental setup, our results show that the occurrence of log file events does not have any impact on the system state turning critical so far. Hence, prediction based on monitoring performance metrics seems to be the most promising way to predict incoming critical system states.

**On RQ3:** We clearly see that the different configurations influence the relevance of the variables as well as the accuracy.

Future work will complement our analysis with a posteriori analysis of the respective prediction models. Thus, we will statistically compare the significance and importance that variables play in the respective models.

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