

Product Lifecycle De-trending for Sales Forecasting

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Abstract: This work introduces a new way to improve the sales forecasting accuracy of time series models using product's life cycle information. Most time series forecasts utilize historic data for forecasting because there is no data available for the future. The proposed approach should change this process and utilize product life cycle specific data to obtain future information including product life cycle changes. Therefore a decision tree regression was used to predict the shape parameters of the bass curve, which reflects a product's life cycle over time. This curve is used in a consecutive step to de-trend the time series to exclude the underlying trend created through the age of a product. The sales forecasts accuracy was increased for all 11 years of a luxury car manufacturer, comparing the newly developed product life cycle de-trending approach to a common de-trending by differencing approach in a seasonal autoregressive integrated moving average framework.

1 INTRODUCTION

As more data and computational power becomes available, machine learning is used in many parts of a manufacturer's value chain, such as development, procurement, logistics, production, marketing, sales, and after-sales, followed by a connected customer after the purchase (Stock and Seliger, 2016). Analysing past and current data to improve business is an important task, but predicting the future is even more important as several of a company's decision-making processes are based on forecasts. Important decisions such as strategic planning, production planning, sales budgeting, marketing planning or new product launches are influenced by forecasts. Therefore, many practitioners and researchers have focused on new forecasting methods and improved forecasting accuracy as money can be saved and a business's competitive advantage could be improved (Wright et al., 1986; Armstrong, 2001).

Machine learning models can outperform traditional statistical models as they can utilise more features of the available data, for that reason companies use data driven approaches that are able to do so. Whilst emerging machine learning models increase accuracy they have challenges and shortcomings from a practical aspect as they typically have a dense black box structure which often make them difficult to explain them within a business environment. It is important for businesses to not only increase the accuracy of a forecast, but also to focus on explainability for the

wider business network. Understanding the main features that drive the prediction is not only important for forecasting but also essential for other departments to affect the important features and thereby increase future sales (Langley and Simon, 1995).

Various techniques are able to model this process, such as seasonal autoregressive integrated moving average (SARIMA) models but suffer from drawbacks being applied on real-world problems. One drawback of SARIMA models is that they are not capable to capture non-linear patterns. For that reason non-linear models were used as well in order to explain them (Gurnani et al., 2017). To overcome these problems a new approach was developed based on a ARIMA model. So far ARIMA models have not been combined with product life cycle (PLC) de-trending based on estimated parameters for increased sales forecasting accuracy as well as increased business interpretability.

This work focuses in particular on improving sales forecasting with the help of machine learning by the integration of product life-cycle information in traditional forecasting methods. This approach is of special interest in the automotive world, where a car sells better after its introduction to the market and sells less over time when newer models from competitors are introduced, especially when the start of the successor of the car is already conceivable.

2 RELATED WORK

Time series forecasting is a frequently researched topic with many extensions for different special cases. This topic solves problems in different areas such as forecasting financial markets or sales for a supermarket. For all these cases there are many different models to choose which have different extensions to their forecasting capabilities (Montgomery et al., 2008). Various researchers and practitioners used PLCs to generate better sales forecasts such as (Solomon et al., 2000; Hu et al., 2017).

Usually they have a huge number of different products where individual forecasting is not feasible for different reasons, therefore they cluster products into different groups. In order to improve the forecasting for new products they use the average PLC curve sales numbers from clusters that share similar products. Usually this type of forecasting is used for products with short PLCs, different to this case where the life cycle spans over more than seven years. Other related work uses different data sources in order to increase the accuracy of monthly car sales forecasts by including economic variables and Google online search data (Fantazzini and Toktamysova, 2015). The previously mentioned approach improves forecasting but does not include product specific parameters such as its age, which will be included in this work.

For statistical models like ARIMA models, there is no extension to our knowledge that includes a products life cycle into the prediction based on machine learning estimation of its future sales. For that reason the following subsection gives an overview about time series forecasting with a focus on ARIMA models in Subsection 2.1 as well as an introduction to PLCs in Subsection 2.2, neural networks in Subsection 2.3, and decision trees in Subsection 2.4. A combination of the models named above is then used to create the new proposed PLC de-trending model in Section 3 to improve sales forecasts.

2.1 ARIMA Models

Many time series forecasting methods were developed over the years where the ARIMA model is one of the most prominent ones. The ARIMA model originated from the auto regressive moving average models. Auto regressive refers to the use of past values in the regression equation for the series; moving average specifies the error of the model as a linear combination of error terms that occurred at various times in the past (Ho et al., 2002). An ARIMA model is described by its values (p, d, q) , where p and q are integers referring to the order of the auto regressive and moving

average models and d is an integer that refers to the order of differencing (Zhang, 2003). The equation for an ARIMA(1, 1, 1) model is given by (Ho et al., 2002)

$$(1 - \phi_1 B)(1 - B)Y_t = (1 - \theta_1 B)\varepsilon_t \quad (1)$$

Where ϕ_1 is the first order auto regressive coefficient and B is a backward shift operator given by $BY_t = Y_{(t-1)}$. The time series at time t is Y_t , θ_1 is the first order moving average coefficient and ε_t is the random noise at time t (Arunraj and Ahrens, 2015). The ARIMA model can be used when the time series is stationary and there is no missing data within the time series. In the ARIMA analysis, an identified underlying process is generated based on observations of a time series to create an accurate model that precisely illustrates the process-generating mechanism (Box and Jenkins, 1976). An extension of this model is the seasonal auto regressive integrated moving average model, which relies on seasonal lags and differences to fit the seasonal pattern (Yaffee and McGee, 2009). By including seasonal autoregressive, seasonal moving average, and seasonal differencing operators a SARIMA(p, d, q)(P, D, Q) $_S$ can be stated as (Arunraj and Ahrens, 2015)

$$\phi_p(B)\phi_p(B^S)(1 - B)^d(1 - B^S)^D Y_t = c + \Theta_q(B)\Theta_Q(B^S)\varepsilon_t \quad (2)$$

where S represents the seasonal length, B the backward shift operator of a time series observation lag k symbolized by

$$B^k X_t = X_{t-k}, \phi_p(B) \quad (3)$$

represents the autoregressive operator of p -order $(1 - \phi_1(B) - \phi_2(B^2) - \dots - \phi_p(B^p))$, $\phi_p(B)$ represents seasonal autoregressive operator with P -order $(1 - \phi_1(B) - \phi_2(B^{2s}) - \dots - \phi_p(B^{2^p}))$, $(1 - B)^d$ represents the differencing operator of order d to remove non-seasonal stationarity, $(1 - B^S)^D$ represents the differencing operator of order D to remove seasonal stationarity, c is a constant, $\Theta_q(B)$ represents the moving average operator of q -order $(1 - \Theta_1(B) - \Theta_2(B^2) - \dots - \Theta_q(B^q))$, and $\Theta_Q(B)$ represents the seasonal moving average operator with Q -order $(1 - \Theta_1(B) - \Theta_2(B^{2s}) - \dots - \Theta_Q(B^{Q^S}))$. There are various methods for model selection with the most prominent ones Akaike-Information-Criterion (AIC) and Bayesian-Information-Criterion (BIC). Despite various theoretical differences the main difference here is that BIC penalizes a models complexity more heavily (Kuha, 2004). The AIC is used for model comparison in this work and is given by (Kuha, 2004)

$$AIC(k) = -2\hat{l}_k + 2|k| \quad (4)$$

where k is the number of model parameters and \hat{l} represents the log likelihood, a measure of model fit.

2.2 Product Life Cycle

The new PLC de-trending approach introduced in Section 3 is based on the PLC that every manufacturer's products go through. Figure 1 depicts this process over time. After a product idea goes through research, development, production, and market roll-out, it is in the introduction phase. If the product is successful, sales increase in the second growth phase. When the product is widely available on the market and sales stop increasing, the product is in the maturity stage. The demand for the product eventually declines, and the product reaches its last phase, the decline stage (Vernon, 1966).

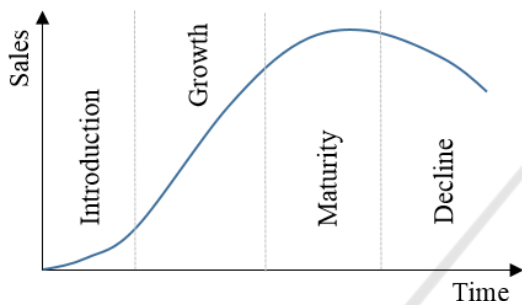


Figure 1: Product life cycle curve.

If the product is successful or the manufacturer sees it becoming more successful with improvements, a new product will replace the old one, which restarts in the first phase. The restarts of PLC curves result in an up and down movement in sales for a particular product over time. The time frame of a PLC varies and depends on product, market, and industry aspects (Meyer, 1997). If a manufacturer produces more than one product, this information is hard to include and filter out in classic time series approaches, like ARIMA models. For that reason a new approach was developed in order to include this up and down movement generated by different PLCs of all products a company has on the market. This was initially done by using neural networks, explained in the following subsection.

2.3 Artificial Neural Networks

Neural networks were chosen as a promising approach to model the dependencies of the PLC model. For this reason a short introduction to artificial neural networks is given in the following subsection.

One of the most commonly used methods in ML is artificial neural networks (ANNs), which try to mimic the biological brain (Bishop, 1995). The equation for a simple neural network, the multilayer perceptron, is given by (Bishop, 1995)

$$y = \sum_i a_i \varphi(w_i^T x + b_i) \quad (5)$$

where w is a vector of weights, x denotes the input vector, b the bias, φ is a non-linear activation function and a are the weights in the output layer. An ANN consists of several connected nodes, called neurons, which receive input from other neurons and send their output to the next neurons. The larger the network, the more input every neuron receives and the more neurons in the next layer receive their output (Bishop, 1995). An important feature of ANNs are that they are nonlinear models as well as universal approximators that provide competitive results by using effective training algorithms. Different training algorithms were used and developed over time: from back-propagation by (E. Rumelhart et al., 1986) to newer methods that aim to accelerate the convergence of the algorithm. Although ANNs do not need any prior assumption to build models, as a model is mainly determined by the characteristics of the data, the architecture of the network needs to be predefined (Haykin, 1994). In 1960, shallow neural networks with few neurons were used due to the difficulty of training deeper neural networks. More recently, new techniques have been found to train these networks and provide state-of-the-art performance. Depending on the problem, different neural network architectures evolved over the years. For example, convolutional neural networks are useful for vision problems (Goodfellow et al., 2016). Over time, many suitable extensions have been developed, especially for time series forecasting, such as recurrent neural networks, which are designed to learn time varying patterns by using feedback loops (Fausett, 1994). As from a business perspective the feature importance of the resulting model is usually very important to explain the model to stakeholders, other ML techniques were explored with a focus on decision tree regression for their better understanding of feature importance, which are explained in the next subsection.

2.4 Decision Tree Regression

As described in the previous subsection the same problem of estimating parameters was done using a decision tree regressor which then was compared to a neural network. Decision trees have their origin in machine learning theory and can be used effectively for classification and regression problems. They are based on a hierarchical decision scheme like a tree structure. Every tree has a root node followed by internal nodes that end at one point in terminal nodes. Each of these nodes takes a binary decision to decide which route to take in the tree until it ends in a

leaf node. By splitting up a complex problem in several binary decisions, a decision tree breaks down the complexity into several simpler decisions. The resulting tree is easier to interpret and understand. Decision tree regression is a type of a decision tree that approximates real-valued functions. The regression tree is constructed based on binary recursive partitioning in an iterative process. All training data is used to select the structure of the tree. The sum of the squared deviations from the mean is used to split the data into parts based on binary splits starting from the top. This process is continued until a user defined minimum node size is reached which leads to a terminal node (Breiman et al., 1984).

This section provided an overview of various techniques used for forecasting. Although different academics and practitioners use these techniques to improve forecasting, this work identifies a new approach that improves forecasting accuracy based on the methods presented. The introduced forecasting methods range from neural network algorithms to pure time series methods, like ARIMA models. This new approach includes model life cycle information in a time series forecast and is detailed in the following section. These new findings support sales and demand forecasting for a variety of different businesses.

3 PRODUCT LIFECYCLE DE-TRENDING

The following section explains how PLC information can be used to improve sales forecasting (Section 3.1). The estimation of the Bass curve parameters, that are used to model the PLC curve is explained further in Subsection 3.2. The improvements are outlined in Section 4, based on an application using car sales data from a luxury car manufacturer in the UK. Implications and future improvements to the proposed approach are discussed in Section 5.

3.1 Bass Sales De-trending

In the following subsection, a new way to improve the forecasting accuracy of time series models using PLC information is introduced. Bringing a product to market requires a business plan that has to contain not only an estimated production number over time to justify financial costs but also an estimated time frame of production until a new product launches (Stark, 2015). Both numbers are based on forecasts and have limitations, but the important factor is that they tend to be consistent over time and give a rough estimate about time and volume of the product. The proposed

approach leverages this information and uses it to de-trend the time series, consisting of all products offered by the manufacturer. There is no clear definition of de-trending a time series as there are various approaches (Fritts, 1976; Anderson, 1977; Chatfield, 1975). The most common approach is to fit a straight line to the data and then remove it to yield a zero-mean residue. Another commonly used procedure is to take the moving mean of the time series and remove it. This operation needs a pre-defined time scale, which has little rational basis. Regression analysis or Fourier-based filtering are examples of more sophisticated trend extraction methods, which share the problem of justifying their usage as they are based on many assumptions (Wu et al., 2007).

Within the new approach, every product needs a life cycle curve to be fitted based on the expected production number and the time frame of production as well as two shape parameters. By adding all PLC numbers together, the PLC de-trending curve is created and, in a second step, is removed from the sales time series history. As this information is also available for a limited time in the future as well, the new approach adds the lifecycle information to the forecast as well.

There are different ways to fit the PLC curve to the sales data. In a different approach using the PLC for new product forecasting, (Hu et al., 2017) used three different ways to fit a curve to the sales numbers. They compare piecewise linear curves with polynomial approaches and with the Bass diffusion model (Bass, 1969). Since their approach clusters the resulting PLC curves, they choose the linear piecewise over polynomial and Bass curve. However, for this research, the Bass diffusion model fits the data best as there are fewer products (five compared to hundreds) on the market, which have longer life cycles (7 to 15 years compared to half a year). Piecewise linear curves as well as polynomial approaches were explored as well but have not delivered better results than the Bass curve. Also the estimation of parameters is not as straight forward as from the bass curve parameter estimation described later in this subsection. The Bass diffusion curve draws a smooth diffusion curve, including the slow rise of sales in the beginning and a saturation after the demand increases over time (Massiani and Gohs, 2016). The Bass diffusion curve is fitted to the available yearly sales numbers from 2003 to today. Yearly sales numbers, instead of monthly, were used because of the huge seasonality of car sales, which is not caused by a product's life cycle, but instead is the result of targets within the business. The seasonality for demand is much flatter throughout the year as the main impulse

for demand is new model introductions, which vary in time around the world, thus flattening the real demand. There is also seasonality within the demand; for example, convertibles have higher demand in summer, but summer varies around the world. The resulting Bass curve is then split per month for the proposed approach by converting the sales numbers from a yearly to a monthly basis, based on the Bass function. The Bass curve consists of three parameters p, q and m where m represents the lifetime sales volume and p and q are shape parameters which representing the coefficient of innovation and imitation. Therefore, sales at time T are given by (Bass, 1969)

$$S(T) = pm + (q - p)Y(T) - \frac{q}{m}[Y(T)]^2 \quad (6)$$

Given the yearly sales numbers, the curve was fitted using a non-linear least squares fitting. As the cars used for training were already sold m was calculated by the sum of all past sales. For the years where no sales numbers were available as a new product was launching, the Bass curve was calculated using the parameters predicted by the newly developed approach later in this subsection. The sales, m , for new products were calculated using lifecycle business plan sales numbers (LCBPSN), which are only available to the business itself. The LCBPSN are used to calculate the business case of a new car over its entire lifecycle and are a good approximation of how many cars will be sold from this model.

Figure 2 depicts the monthly sales numbers in dark grey as well as the PLC curves fitted with the Bass diffusion model for two products in blue and orange. The green curve represents the sum of all PLC curves for 10 years and was used later for division through the sales numbers to generate a new time series for forecasting with improved PLC information by

$$\text{PLC de-trended time series} = \frac{\text{car sales}}{\sum \text{bass curves}} \quad (7)$$

3.2 Bass Parameter Estimation

Although the bass curve can be fitted based on assumptions as described above, there is a new way of estimating the parameters p and q found within this research. A new approach of fitting the Bass curve for new products is proposed in the following. By using sales data from sold products with features like size and weight it is possible to predict the parameters of the bass curve for new products by using machine learning. The data used in this research is a combination of all car models sales numbers, Bass parameters calculated for every model based on past sales

numbers and car specific features from Car Database API (Seo and Ltd., 2019) for more than 1000 different car models. The Car Database API features *power, length, width, height, weight, wheelbase and displacement* are numeric and no pre-processing was necessary; *coupe* and *drive* were pre-processed by using one-hot encoding. In total these features are available for over 28.000 car models. Yearly sales numbers are taken from a dataset available within the company providing the data which consist of all car models sold since 1990. Out of these sales numbers the Bass parameters m, p and q were calculated as described in Subsection 3.1. The following Table 1 shows an extract from the dataset for two different car models.

The resulting dataset consists of over 1000 different car models. The decrease in total car models from 28.000 is due to merging both datasets and removing entries with missing values. The internal dataset containing car model sales number only has around 1400 car models whereas the CAR DATABASE API data lists all cars with different engines separate. This results in a dataset with no missing values for over 1000 different car models. By fitting a bass curve to the yearly sales numbers of products already sold, it is possible to use them as an desired output for the model. As input, the features of the car models described above is used.

For the prediction of p and q a multi regressor approach using a random forest regressor was compared to a neural network. The results indicate that the underlying problem can be modelled with a simple neural network with one hidden layer consisting of 20 neurons. The mean absolute error (MAE) for the neural network is $p = 0.06$ and for $q = 0.29$. These results were improved by the multi regressor approach with 100 estimators and a maximal depth of 30 with an MAE of $p = 0.02$ and $q = 0.11$. Also within the business environment where this model is used, it was important to get the feature importance for every single feature as this information is useful for stakeholders in the business to understand the model and use the information for the product development of future cars. As this could be delivered from the linear model it was the used in the next Section 4. To summarise the steps from the new PLC approach the following Table 2 gives a broad overview of all steps. All of them are conducted on a real world application in the following section.

4 APPLICATION

The proposed approach of PLC de-trending is presented for several sales forecasts of the luxury car

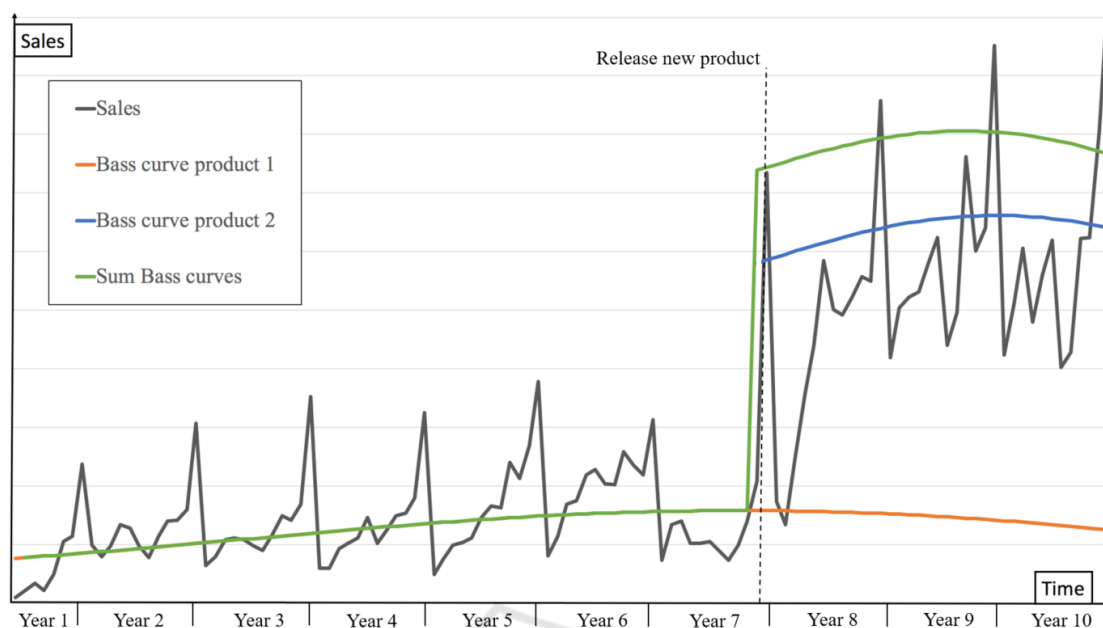


Figure 2: PLC curves for monthly sales data.

Table 1: Data extract for Bass curve fitting.

name	year 1	year 2	year 3	year 4	year 5	year 6	year 7	m	p	q
Suzuki Ertiga	59467	62220	61154	60194	63850	68355	56408	431648	0.055	0.112
Subaru Legacy	219945	280027	244614	244749	228710	198540	187271	1603856	0.089	0.208
name	power	rpm	coupe	length	width	height	displacement	fuelSystem	drive	weight
Suzuki Ertiga	105	4500	1	4395	1735	1690	1462	1	2	1180
Subaru Legacy	156	5000	4	4685	1745	1415	2457	2	4	1589

Table 2: PLC algorithm steps.

Step	Input	Algorithm	Output
1.	Features of over 1000 cars	Decision tree regression	p and q for bass curve
2.	Companies car model features	Decision tree regression from 1.	p and q for companies car model
3.	p and q from 2. + m from business plan	Bass curve	PLC curve (cumulated bass curves)
4.	Sales time series/ PLC curve from 3.	SARIMA model	Forecast of PLC de-trended time series
5.	Forecast from 4.	Multiplication with PLC curve from 3.	Final forecast

manufacturer who made the data available with five products. The proposed approach outperforms de-trending by differencing, which is a common approach to de-trend a time series (Solo, 1984). The sales data used ranges from May 2003 to December 2018. The forecasts are compared in Table 3 using the the root mean squared error (RMSE) and MAE for the years from 2008 to 2018, where the lower error is highlighted in gray. To build a reasonable SARIMA model, a minimum of 50 observations was needed, so more than four years of monthly data were used (Wei, 1990). To achieve enough input data for the SARIMA model, only predictions for years after 2007 were considered. The SARIMA model creation itself was completed following the classic Box-Jenkins

methodology (Box and Jenkins, 1976).

The models' hyper parameters $p, d, q, P, D,$ and Q were chosen from a grid search between zero and three based on the AIC score. As the business that generated the sales numbers measures their forecasting accuracy in absolute errors, the MAE was used for comparison. As the MAE does not penalize huge outliers as much as other metrics, the RMSE was used as well, so both measurements are in the same units as the forecasted values of car sales. As Figure 2 shows, the company introduced a new product at the end of Year 7, which led to an increase in sales. Also, in 2013, 2015, and 2018, new products were released. Table 3 compares the RMSE and MAE of a classic SARIMA forecast with de-trending by differencing

Table 3: PLC de-trending comparison 2008-2018.

Error\Year	2008	2009	2010	2011	2012	2013	2014	2015	2016	2017	2018
PLC RMSE	30.6	32.7	188.5	57.5	69.1	65.2	56.8	25.9	85.9	76.2	80.9
PLC MAE	22.7	25.1	167.5	49.2	49.7	55.5	50.9	22.1	73.3	68.9	61.7
NDT RMSE	46.1	119.2	2205.2	145.3	124.1	70.9	71.7	46.5	96.8	103.9	192.1
NDT MAE	35.2	77.2	1949.6	117.6	109.7	64.5	62.7	41.9	84.1	89.5	183.6

with the proposed approach, highlighting the lower error in bold. All years indicate an improvement with the proposed PLC de-trending approach. For, 2010, a huge difference is also apparent because it was the year in which the PLC of one product started with the introduction of a new product, resulting in higher sales that were covered within the new approach. In all 11 years, the new approach resulted in an increased accuracy for 11 years measured for the MAE as well as the RMSE.

For all years combined the improvement of the PLC model for the RMSE is 77% and for the MAE is 78%. Implications for the business were not only increased accuracy in their monthly forecasting, it also delivered new insights into which features were most predictive within the decision tree regression and how they affect shape parameters. Especially newer body types such as sport utility vehicles have different life cycle curves compared to traditional sedan models. They result in a steeper increase at the beginning of the PLC which was also felt in reality. This information can be used for the future planning of new products.

5 CONCLUSIONS

The proposed approach has the advantage of including information on PLCs in a sales forecast. Other methods also include new product information to improve forecast accuracy. However, these methods are often based on a business's marketing department's forecasts (Kahn, 2002). Hierarchical procedures, like those proposed by (Lenk and Rao, 1990; Nee-lamegham and Chintagunta, 1999), use a Bayesian modelling framework to include various information sources to make new product forecasts but focus more on new products than on existing products, unlike the new PLC approach proposed in this work.

Forecasting every product is also possible, but this approach has two drawbacks. The first one is the limited amount of historic data for a new product, and the second one is that new products influence other products, so forecasting the total number of sales better includes the influence from a new product onto other products. In particular, cannibalization from

one product to another product from the same manufacturer is not included, which is an issue that could further improve the accuracy. As products from other manufacturers influence the sales of a product as well, a general PLC curve containing information about the life cycles of all products in the same market could improve forecast accuracy even more. Typically start and end dates for competitor's PLCs and their business cases are not publicly available, and therefore including this information was not possible. Other approaches to fit the PLC curve could be considered as well, such as extended Bass diffusion models that include supply constraints, which was not considered so far (Kumar and Swaminathan, 2003).

Overall sales numbers reflected by parameter m were determined from the business case, which makes it difficult for people outside of a business to use the same approach. Therefore an approach which estimated m using a similar approach to the estimation for p and q was attempted, but the estimate had a large error which is a consequence of the limited available data. Further work is required to establish whether the sales numbers can be estimated reliably from new car features which would make the approach more widely applicable. This work would need to explore larger feature sets as well as suitable modelling approaches. Although the dataset was using car sales data in theory the approach should work for other products as well if there is enough data about the features of the product. As the needed data contains confidential information it was not possible to get datasets from other industries and products which could open the proposed approach to a wider variety of implementations.

The neural networks accuracy as well as the one from the decision tree regression could have been improved even further but with that it gets harder to compare both of them. As from a business point the resulting feature importance was more important compared to the accuracy, the decision tree was used. As the data contains confidential features unique to each business, it was not possible to get different datasets the algorithms could be compared and tested on. For that reason the time series given by the car manufacturer was reversed and then forecasted from the opposite side. The results were even better comparing the

PLC approach to the classic de-trending by differencing.

Neural networks itself can also be used to forecast time series and not only for modelling the shape parameters of the bass curve. They are not well suited for capturing seasonal or trend variations for unpre-processed data but by de-trending or de-seasonalization their performance could be increased drastically (Zhang and Qi, 2005). This could be another approach to change the used SARIMA model into a neural network model to improve its accuracy even more with the proposed PLC de-trending as a pre-processing step for an improved neural network forecasting model. The problem of de-seasonalization would not be solved here so this would need a different pre-processing step.

Although the proposed approach performed better compared to the current forecasting done by the company itself there is also room of improvement especially in how the code is currently executed. Running the system in a cloud based system would decrease the time spend running the code with extracting all the data from different sources. This would allow to outsource work into the cloud which has proven to be more efficient for data scientist within a company (Aulkemeier et al., 2016). This would not only save time, it could also be run throughout the month more often in order to get an actual status, live from all regions.

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