

# Evaluating the Predictability of Future Energy Consumption Application of Statistical Classification Models to Data from EV Charging Points

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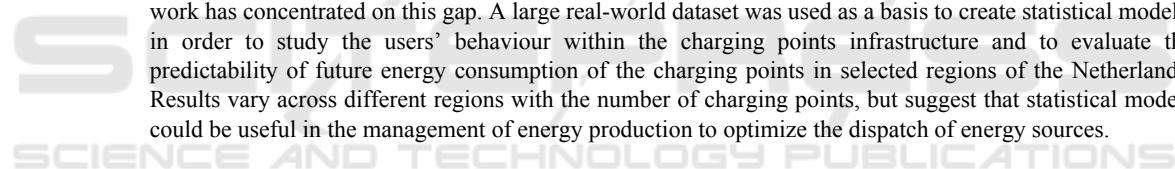
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**Abstract:** The overall purpose of our study has been to evaluate the predictability of future energy consumption analysing the electric mobility in the Netherlands. The climate and energy framework, the European energy production and main developments, as well as the European targets and policy objectives to reduce the current CO<sub>2</sub> emissions were first assessed. Then, a deeper look was taken at electric mobility and at Electric Vehicles (EVs). The adoption and development of EVs in the European Union and charging infrastructure were taken into account. The Dutch energy production and emissions, as well as, the mobility in the country and its infrastructure were investigated. Previous studies about electric vehicles and charging points have addressed the predictability of future energy consumption in larger areas to only very limited extent, so our research work has concentrated on this gap. A large real-world dataset was used as a basis to create statistical models, in order to study the users' behaviour within the charging points infrastructure and to evaluate the predictability of future energy consumption of the charging points in selected regions of the Netherlands. Results vary across different regions with the number of charging points, but suggest that statistical models could be useful in the management of energy production to optimize the dispatch of energy sources.



## 1 INTRODUCTION

The power supply has granted huge benefits for the modern society, but it has also come with a not negligible price tag: most of the energy is generated from fossil fuels (coal, oil and natural gas). This human activity is increasing the concentrations of greenhouse gases (GHG), while it is enhancing the greenhouse effect, which in turn is contributing to the warming of the Earth. It is therefore crucial to reduce GHG emissions, in order to maintain the stability of the Earth and its climate.

The European primary energy production includes a range of different energy sources: nuclear energy, renewable energy sources, solid fuels (largely coal), natural gas and crude oil. The primary energy consumption in European countries in 2015 amounted to 1,627 million tonnes of oil equivalent (Mtoe), while being 1.7% above the 2020 target. Primary energy consumption in the EU-28 countries has decreased in the past years, due to energy

efficiency improvements and the economic recession. Moreover, the share of the energy generated from hydro, wind and solar has been steadily increasing. Nevertheless, fossil fuels continue to dominate primary energy consumption, setting themselves at 72.5% in 2015. Renewable energy was 13% and the part of nuclear energy in primary energy consumption was 13.6% in 2015 (EEA, 2016).

In the transport sector, despite the improvements in fuel efficiency, there have been increases in passenger and freight transport demand. Higher transport demand has resulted from increased ownership of private cars, particularly in the new EU Member States, as well as from growing settlement and urban sprawl, leading to longer distances travelled, and changes in lifestyle. Between 2005 and 2013, final energy consumption in the transport sector decreased by 6% in the EU-28, but it still accounted for 32% of total energy consumption, followed by household sector (27%), the industrial sector (25%) and the service sector (14%) (IEA, 2017).

The transport sector is therefore the main factor responsible for air pollution in European cities, as it produces almost a quarter of all GHG emissions. There has been a decrease in the emissions since 2007, but they are still higher than in 1990. Road transport, in particular, was considered responsible for more than 70% of GHG emissions from transport sector in 2015. The European Commission has adopted a low-emission mobility strategy to facilitate shift towards a low-carbon circular economy. GHG emissions from transport should be at least by 60% lower than in 1990 and be firmly on the path towards zero. The strategy integrates a broader set of measures and supports creation of jobs, economic growth, investments and innovations. The strategy will benefit European citizens and consumers by improving the quality of the air, reducing the levels of noise, lowering the levels of congestion and ameliorating the safety (National Research Council, 2013).

Electromobility and renewable sources of energy are technologies with significant potential to contribute to these goals. In order to evaluate the predictability of future energy consumption, an analysis of electric mobility is done in this paper. In particular, this analysis is applied to a large real-world dataset. Studies based on the operational data from charging station started to appear in the scientific literature only very recently. Data collected from mobile phones and charging stations has been analysed and combined with mathematical modelling to analyse the relationship between mobility behaviour and the demand for electric energy (Colak, 2016). Regression methods were used to estimate the driving range of electric vehicles (Fetene, 2017). Combination of regression methods and data time series, that characterize the charging behaviour, was used to design a procedure how to predict the load profile imposed on the electrical grid by individual charging stations (Bickora, 2016). Classification methods of statistical learning (k-nearest neighbour, regression trees, general chi-squared automatic interaction detector, etc.) when applied to time series of electric energy consumption can identify households that are charging electric vehicles with accuracy higher than 80% (Verma, 2015). Similarly, classification has been applied to the data from the charging station network to analyse how the drivers of electric vehicles use the public charging stations and to predict their behaviour (Develder, 2016; Sadeghianpourhamani, 2018). Regression approach combined with characterization model based on fuzzy numbers was applied to data coming from 255 charging stations in UK and was used to propose an

index estimating the ability of electrical power grid to manage the future load imposed by charging electric vehicles (Xydas, 2016). One of our goals is to apply regression methods to maintain large interpretability of results. Interpretability can be enhanced by the use of methods that contain mechanisms to select potentially relevant predictors (Taylor, 2015; Hastie, 2009; James, 2013). From the point of view of optimization, these mechanisms and optimization methods that can be used to solve associated optimization problems are subject of very active research (Bertsimas, 2016; Hastie 2017).

## 2 BACKGROUND INFORMATION

Our case study is focused on the Netherlands, which was chosen as it is one of the European countries with the greatest developments in electric mobility in the past years. The advanced economy of the Netherlands is reflected also in a modern energy system and well-developed energy markets. The strategic location helped the country become an important transit and trade hub for natural gas, coal, oil and electricity. The Netherlands has significant natural gas production and a large oil-refining industry (IEA, 2014).

The Netherlands started the transition to a low-carbon economy by implementing broad spectrum of measures ranging from Renewable Energy Sources (RES), Carbon Capture and Storage in the North Sea, and to the enhancements of the security of oil and gas supply. The Dutch energy mix is dominated by fossil fuels, which represent more than 90% of Total Primary Energy Supply - TPES (*IEA - Statistics*, 2015). In Figure 1, it is possible to observe that the electrical energy sources have mainly been natural gas accounting for 42% and coal with 39%, oil has only a marginal contribution of 1.3%. In the last ten years, the renewables sources raised a lot, reducing the share of fossil fuels from 90.3% in 2002 to 82% in 2015. Nuclear energy represented 3.7% in 2015. The renewable sources in the Netherlands are mainly biofuels 2.7%, waste 3.3% and wind 6.9% (Centraal Bureau voor de Statistiek, 2016b).

Dutch citizens travelled on average 11,000 km in 2014. 70% of this distance was covered by car (while nearly three-quarters of the total number of kilometres as drivers and nearly a quarter as passengers), 9% of the total distance was done by train and 9% by bicycle (Centraal Bureau voor de Statistiek, 2016a).

The Dutch government's desire for electric driving is to reduce CO<sub>2</sub> emissions, improve energy efficiency and decrease the dependency on fossil fuels (Netherlands Enterprise Agency, 2015). Electric vehicles also help to reduce noise pollution from traffic, open up new opportunities for the commercial sector and generally improve the quality of life in cities.

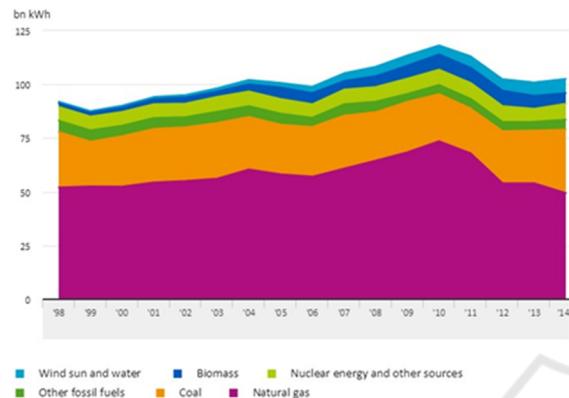


Figure 1: Generation of electrical energy by source in the Netherlands (Centraal Bureau voor de Statistiek, 2016b).

Table 1 reports for different years the number of EVs in the Netherlands.

Table 1: Number of electric vehicles in the Netherlands.

	Fully electric (FEV)	Hybrid (HEV)	Plug-in hybrid (PHEV)
2015	7,400	111,800	36,750
2016	9,950	124,400	76,250
2017	13,700	136,000	95,750

There were more than 8 million cars in the Netherlands at the beginning of 2017, almost 80% of them run on petrol and 16% on diesel. Nearly 250,000 are electric vehicles but in this group 90% consists of hybrid cars. There are also more than 13,000 fully electric cars, with just the electric engine (see Fig. 2). This number has doubled in the past two years and there are 26,000 public or semi-public charging points for EVs across the Netherlands, that is to say on average 4 electric vehicles per charging point (Centraal Bureau voor de Statistiek, 2016a).

### 3 MATERIALS AND METHODS

In this research, data recorded from individual charging transactions were considered at a more

aggregated level, to give a greater picture of the interaction between the charging point infrastructure and the power grid network. As for modelling smart grids, it is more important to predict how an aggregated subset of charging points will consume energy in a specific area, rather than to consider single points. An extensive amount of data from a large database gathered in the Netherlands was used with high temporal resolution, focusing on the variability in demand for electricity to charge electric vehicles. This is different from previous studies, where synthetic time-series were used because of a small number of transactions recorded (Bessa and Matos, 2013) or (Develder, 2016).

#### 3.1 Dataset

The Dutch company ElaadNL (ElaadNL, 2016) provided for this research a dataset which includes an overview of EVnetNL historic transactions data from January 2012 until March 2016. The dataset contains detailed information of more than 1 million transactions that took place at 1,747 different charging points, which are installed over the entire geographical area of the Netherlands. The dataset is a big data frame (table implemented in R language) with 17 columns and 1,060,703 rows - corresponding to every transaction registered.

The analysis on the dataset has been done using Rstudio - a free open source IDE (integrated development environment) software program for statistical analysis. There are many reasons for choosing this kind of software, above all it has a great availability of implemented advanced statistical methods and algorithms and it produces very high-quality graphs. Overall, Rstudio is a very powerful but at the same time an easy-to-use software.

#### 3.2 Statistical Methods

Before starting the data mining, it was necessary to build a statistical frame. Different classification models were considered to evaluate the predictability of future energy consumption of the charging points. There are many possible classification techniques, or classifiers, that could be used to predict a qualitative response (James, 2013). Four of the most widely-used classifiers - logistic regression (Logistic), linear discriminant analysis (LDA), quadratic discriminant analysis (QDA) and k-nearest neighbours (KNN) - were used in the study, in order to build a model to predict ( $Y$ ) for any given value of predictors ( $X_1, \dots, X_n$ ).

Rather than modelling the response  $Y$  directly, logistic regression models the probability that  $Y$  belongs to a particular category with the logistic function:

$$\log\left(\frac{p(X)}{1 - p(X)}\right) = \beta_0 + \beta_1 X + \cdots + \beta_n X_n \quad (1)$$

Model parameters  $\beta_1, \dots, \beta_n$  are estimated by the maximum likelihood method. For linear discriminant analysis the distribution of the predictors  $X$  is modelled separately in each of the response classes and then the Bayes' theorem is used to flip these around into estimates. LDA assumes that the observations within each class are drawn from a multivariate Gaussian distribution with a class-specific mean vector  $\mu$  and variance  $\sigma$  and covariance matrix  $\Sigma$  that is common to all the classes. By the symbol  $\pi_k$  is represented the prior probability that a randomly chosen observation comes from the  $k$ -th class. Then, LDA assigns an observation to the class  $X=x$  for which the value:

$$\delta_k(x) = x \frac{\mu_k}{\sigma^2} - \frac{\mu_k^2}{2\sigma^2} + \log(\pi_k) \quad (2)$$

is the largest. QDA provides the same approach but it assumes that each class has its own covariance matrix  $\Sigma_k$ .

Consequently, Eq. (2) generalizes to:

$$\begin{aligned} \delta_k(x) = & -\frac{1}{2}(x - \mu_k)^T \sum_k^{-1} (x - \mu_k) \\ & - \frac{1}{2} \log|\Sigma_k| + \log \pi_k \end{aligned} \quad (3)$$

The KNN classifier, given a positive integer  $K$  and a test observation  $x_0$ , first identifies the  $K$  points in the training data that are closest to classified observation  $x_0$  within the neighbourhood  $N_0$ . Finally, KNN applies Bayes rule and classifies the test observation  $x_0$  to the class  $k$  with the largest probability given by:

$$\Pr(Y = k | X = x_0) = \frac{1}{K} \sum_{i \in N_0} I(y_i = j) \quad (4)$$

where  $I(y_i = j)$  is indicator function that equals 1 if  $y_i = j$  and 0 otherwise.

### 3.2.1 Shrinkage Methods

In order to enhance the prediction accuracy and interpretability of the statistical model, Lasso method (least absolute shrinkage and selection operator) was implemented (Taylor, 2015). It is a shrinkage method that performs both variable selection and regularization. In this way, it is possible to select the most significant predictors and to eliminate those that do not contribute to the improvement of the forecast, obtaining at the end a lower test error. A model can be fitted containing all  $p$  predictors and then select a subset of them using Lasso that constrains or regularizes the coefficient estimates, or equivalently, that shrinks the coefficient estimates towards zero.

## 4 RESULTS

### 4.1 Basic Analysis of the Dataset

Having built the statistical frame, the dataset "Transactions" provided by ElaadNL was analysed. Four of the seventeen columns were selected: ChargePoint ID, Connector ID, Lat (latitude) and Lon (longitude) to create a map of the Netherlands with the positions, distinguishing the charging points with one connector from those with two connectors. 613 out of the 1,747 charging points contained in the data frame are with one connector while 1,134 are with two connectors. The charging points are well distributed across the entire territory of the country, while the majority of them is situated within or close to the major cities as shown in Figure 2.



Figure 2: Positions of charging points with 1 and 2 connectors derived from the dataset.

Next, columns from the “Transactions” data frame were selected, in order to describe the use of individual charging points: Connected Time, Charge Time and Idle Time. It was observed from data that in most cases, the number of transactions is lower than one thousand and the Connected Time is less than 10 hours, with a strong presence transactions that lasted up to 5 hours. Comparing the maximum power recorded during the transaction in terms of kW and the total number of transactions for each customer card, Figure 4 was obtained. Four power categories are clearly coming out from the scatter plot. The first category is slightly above 2 kW, the second stays between 3 and 4 kW, the third about 9 kW and the last one about 11 kW. Figure 3 gives also rough picture of the types of vehicles that are utilizing public charging stations; most of them with a maximum power around 3 kW, that is the typical value for hybrid plug-in electric vehicles.

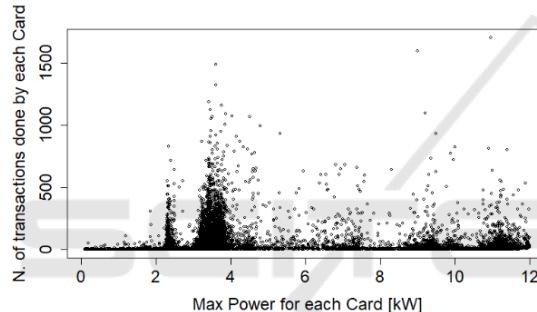


Figure 3: Maximum power observed for each customer card compared to the number of transactions done.

Considering all the points together, the recharge time was then analysed throughout the course of the day as represented in Figure 4. For more than half of the time, when the charging points were connected to the vehicles, they were not recharged, but simply occupied a parking position because the state of battery had already reached the maximum charge. At a first glance, it is clear that such behaviour of EV drivers is not favourable.

Figure 5 shows the trend obtained when considering all charging transaction done within the period starting from January 2012 to March 2016.

The pattern formed by the initial time of charging sessions over the course of the working day and weekends are compared in Figure 5. Working days follow a completely different pattern than weekends. During the working days, two peaks are very evident, the first is at about 7:30, the second is at about 17:30. Between 9:00 and 15:00 it is possible to observe approximately constant trend. Over the weekends, it is completely different: most of the charging

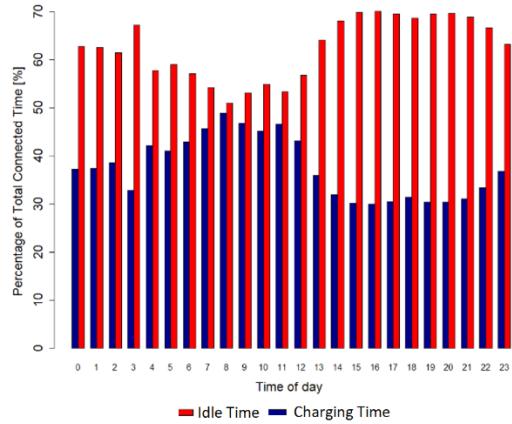


Figure 4: Charge Time and Idle Time as a percentage of the Connected Time analysed within the course of the day.

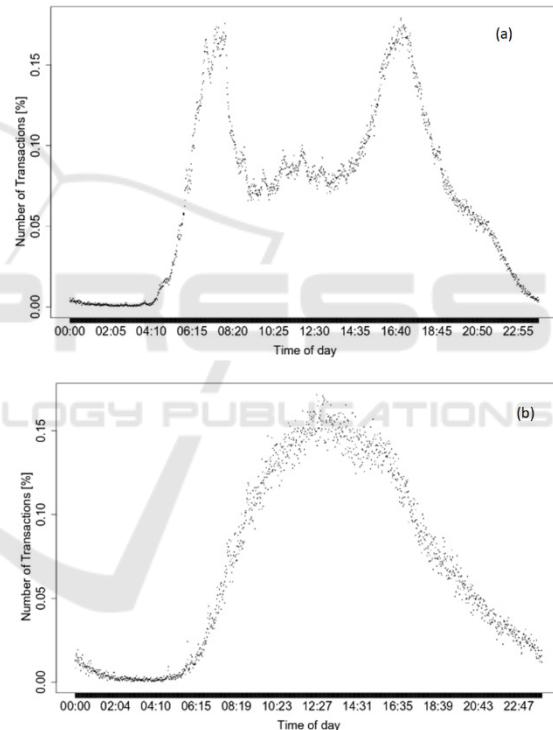


Figure 5: Initial time of charging sessions during (a) the working days and (b) weekends.

transactions start at 13:00, with a wider peak, which lasts from 10:30 to 15:30.

After taking the look at the charging points, the users were brought into focus. In the database “Transactions” there are two records for each charging session: *StartCard* and *StopCard*, that can be used to attribute charging session to individual RFID card holders. Having observed that the total amount of users (customer cards) is 53,850, the behaviour of the different users was analysed. The

first step was to find out the first use and the last use of the single card, in order to underline how long it was used during the period between January 2012 and March 2016.

Significant number of cards (about 15,000) were used only once. Considering the number of transactions for each unique card, it was possible to see that the majority of the cards were used only for few charging sessions during the period considered: 95% of the cards did less than 100 transactions. In Figure 6, it is possible to observe that the cards with a large consumed energy constitute only a small number and a focus is on the energy consumed.

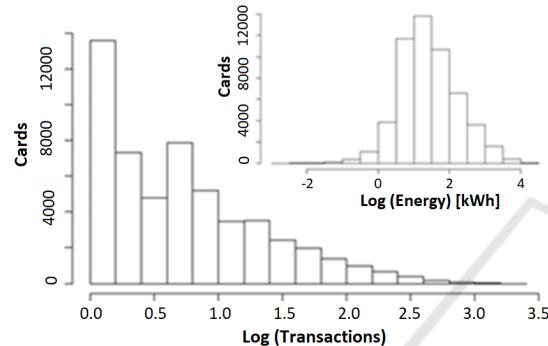


Figure 6: Number of customer cards as a function of the total number of realised transactions. The inset shows the dependency on the consumed energy.

## 4.2 Predictability of Energy Consumption

To aggregate the power consumed by individual charging points the following step was to extract from the coordinates (latitude and longitude) of the single charging point the address where each charging point is located. From the address the corresponding municipality was obtained and then associated with the COROP region it belongs to. The COROP are the Dutch sub-regions traditionally used in the spatio-statistical research. The association of charging points to COROP regions is shown in Figure 8, while different colours are used, depending on the region.

Five out of the 40 COROP regions were selected, based on the number of charging points available, to represent broad range of values. In Figure 7, it is possible to identify different zones, in particular:

- Delfzijl en omgeving indicated with number 1 (3 charging points);
- Zuidoost-Zuid-Holland indicated with number 2 (20 charging points);
- Flevoland indicated with number 3 (41 charging points);

- Overig Zeeland indicated with number 4 (57 charging points);
- Utrecht indicated with number 5 (172 charging points).

Through the association of charging stations with the regions it was possible to extract the aggregated trend of the energy consumption for the recorded period (January 2012 - March 2016). The next step was to restrict five selected benchmarks to the years 2014, 2015 and 2016. This choice was made because during these years the number of transactions is more substantial.



Figure 7: Charging points associated to COROP regions.

With the resolution of days, the transactions carried out on the charging points of a given COROP region were grouped: the 819 rows, each corresponding to one day, were recorded with the following structure of columns: Total Electric Energy Consumed, Total Connected Time (in hours), Total Idle Time (in hours), Total Transactions performed during a day, Total Number of single cards used during the day and Total Number of Charging Points used during the day (thus, overall 6 columns). Some auxiliary columns were subsequently added: the Total Electric Energy Consumed, the Connection Time and the Idle Time for each of the 7 days preceding the concerned day. In addition, the total number of customer cards used and the number of transactions made in the previous two days were considered, resulting in 25 new auxiliary columns.

As the output or response was considered the binary forecast of the increase (1) or decrease (0) in

energy consumption compared to the previous day. Thus, a column was added that indicates whether the total energy consumption of a day was higher or lower than the day before. This column is called direction. Values 1 and 0 are the two classes considered in the statistical methods.

Statistical models estimate the probability that with a set of predictor variables, the unknown response belongs to one rather than to the other class.

Basic statistical classification methods, described in Section 3.2, were applied to each of the five benchmarks, to find out which method is producing the lowest test error (James, 2013). For the KNN method, two versions were considered. First, version denoted KNN ( $K=5$ ), where the value of parameter  $K$  was set to 5 and KNN opt, where 10-fold cross validation method (James, 2013) was used, to find the value  $K$  leading to the minimum value of the test error. Furthermore, two extended versions of the methods were considered. First, the logistic regression was combined with the Lasso shrinkage and the second, in addition, it was followed either by the KNN opt (denoted as Logistic Lasso KNN opt) or LDA (denoted as Logistic Lasso LDA) depended on what resulted in lower test error. To evaluate the test error, predicted directions for the future energy consumption were calculated and evaluated using 10-fold validation method.

Figures 8, 9 and 10 show the test error rates considering the region of Delfzijl en omgeving, Zuidoost-Zuid-Holland and Flevoland. In particular, in the case (a) are reported the five basic classification methods and in the case (b) are reported results of two extended methods (logistic regression combined with the Lasso shrinkage and logistic regression combined with the Lasso shrinkage and followed by the optimal KNN method). To facilitate the comparison between extended and related basic methods the performance of basic methods is again shown in panel (b).

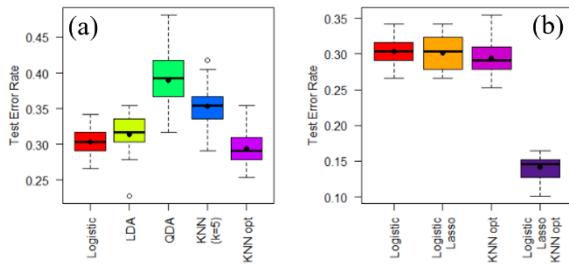


Figure 8: Region of Delfzijl en omgeving with (a) five basic classification methods and (b) two extended methods.

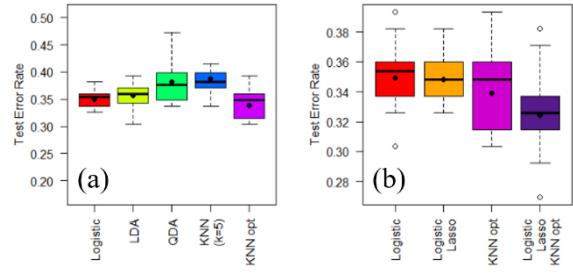


Figure 9: Region of Zuidoost-Zuid-Holland with (a) five basic classification methods and (b) two extended methods.

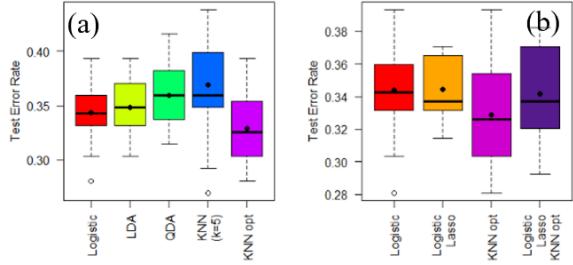


Figure 10: Region of Flevoland with (a) five basic classification methods and (b) two extended methods.

Average test error rates for logistic regression range from 0.19 to 0.35. On the smallest benchmarks, Delfzijl en omgeving, Zuidoost-Zuid-Holland, and Flevoland the logistic regression performed well, however, better results were obtained through KNN opt (see Figures 8a – 10a).

In opposite, for the other 2 benchmarks: Overig Zeeland and Utrecht a slightly better performance was gained with the logistic regression method (see Figures 11a – 12a). As expected, KNN opt always showed better results than KNN ( $K = 5$ ), and corresponding test error was the lowest among all basic methods for the first three datasets. Performance of LDA is systematically better than QDA, which is inferior when compared to all basic methods, indicating an overfitting.

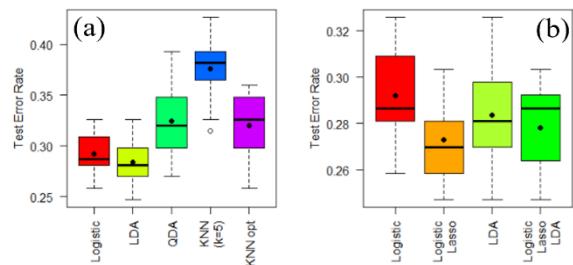


Figure 11: Region of Overig Zeeland with (a) five basic classification methods and (b) two extended methods.

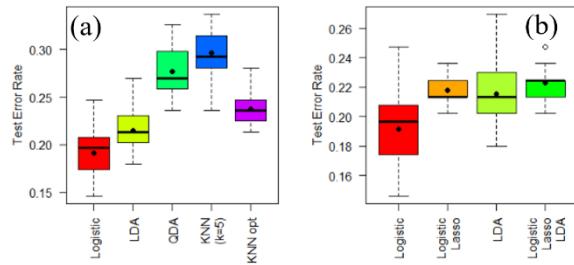


Figure 12: Region of Utrecht with (a) five basic classification methods and (b) two extended methods.

Logistic regression was further implemented for all the datasets together with the shrinkage method, in order to evaluate the most relevant variables among the 25 considered and possibly improve the accuracy of predictions. For the first dataset, leaving out predictors leads to only very small improvement of the Logistic regression. However, when applying KNN opt to the shrunken model (in this case the model was reduced by Lasso to only one predictor: the Total Electric Energy Consumed with the lag of one day) there was a significant improvement making the error fall below 15%. This is very good result, but unfortunately it was obtained only if consumption of only three charging stations was aggregated together and often less than ten transactions were recorded during the day, thus the energy consumption was also very small (see Figure 8). Such situations are not so relevant from the point of view of smart grid control. Nevertheless, apart from this exceptional case, logistic regression finds systematically the lowest test error for the last benchmark, where the consumption of the largest number of charging points (172) was aggregated together. This is aligned with the expectation that higher aggregation leads to higher predictability. Moreover, it has also practical implication as predicting higher loads in smart grids can be more relevant in the planning and management of load dispatch. For the last benchmark, the Logistic regression combined with Lasso shrinkage identified as the most relevant predictors: Total Electric Energy Consumed with the lag of 1 and 7 days, Total Connected Time with the lag of 2, 6 and 7 days, and Total Idle Time with the lag of 1 day. Interestingly, most often, relevant predictors have lag of 1 or seven days. Predictors selected by the Lasso method differ from one benchmark to another. However, one which was always present is the Total Electric Energy Consumed in the previous day. Since the selected predictors varied among the 25 initially considered, even the values of coefficients were significantly different across benchmarks.

## 5 CONCLUSIONS

The Dutch energy framework and the electric mobility were investigated using data collected within the large network of charging stations. The Netherlands is steadily working towards replacement of vehicles powered by traditional fossil fuels to build a future with significantly higher share of electric vehicles. For such a progressive country - with a low average length of daily journeys by private cars and a high number of commutes made by bicycle or public transportation - this could be possible in a close future.

The need to develop more and more charging infrastructure for electric mobility requires a detailed studies of energy consumption on already existing charging points. As an initial step, predictive models to estimate the trend in the electricity consumption one day ahead were built. At first glance, it seems that the data used during the study - the charging transactions done over three years - can be useful to approach this objective. The models managed to assess well the trends in five Dutch regions, although with different results. In summary, three main interesting findings arose from the analysis:

- It is shown that different models are more suitable in fitting the data depending on the region (level of aggregation). Most often, logistic regression or its combination with other method was found as the most successful method.
- The average test error ranges from 0.19 to 0.39. By increasing the number of charging stations aggregated in the analysed energy consumption signal, the test error tends to decrease. Thus, the idea to aggregate the charging points leads to the higher accuracy of predictions.
- As the most important variables for the predictions, were identified variables with the lag of 1 or 7 days, indicating the importance of the most recent history and the role of the week cycle.

Obtained results and the need for more efficient management of energy production in future smart grids justifies further studies where energy consumption could be modelled in a more detailed way, e.g. by introducing multi-class classification models to predict the amount of energy consumed on hourly basis.

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