

Exploring BIM Data by Graph-based Unsupervised Learning

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Abstract: This paper presents an unsupervised learning method for mining the Industry Foundation Classes (IFC) based Building Information Modelling (BIM) data by exploring the inter-relational graph-like building spaces. In our method, the affinity propagation clustering algorithm is adapted with our proposed feature extraction algorithm to get exemplars of certain spaces with similar usage functions. The experiments are conducted on a real world BIM dataset. The experimental results show that some build spaces of typical usage functions can be discovered by our unsupervised learning algorithm.

1 INTRODUCTION

Modelling and accessing knowledge of architecture design from the BIM (Building Information Modeling) data is an important issue for construction industry and some other related field including psychology, sociology, and behaviour learning. Even with Computer Aided Design, it is not easy to achieve general knowledge extraction from construction data. According to Space Syntax Theory (Hillier and Hanson, 1989), such systems like buildings should be regarded as discrete systems, in which indivisible individual components act on each other through description retrieval mechanism to form the rule of the whole; however, the description is not carried within these components jointly or separately. As a result, the interactions between building components should be learned to obtain knowledge from building models.

The recent adoption of Building Information Modelling (BIM) makes it easier to deal with buildings as a whole (S. Azhar al., 2008). In BIM representation, building related information is kept in interlinked context rather than isolated entities. It contains a large amount of semantic information which is all machine-interpretable. In this paper, we address the problem of extracting knowledge from spaces within buildings based on the IFC (Industry Foundation Classes, de facto standard for BIM data) representation (T.M. Froese al., 1999). Our techniques can be applied for retrieval, reference, and

evaluation of designing, as well as generative design (C. Soddu, 2006).

IFCSPACE is defined in IFC as an area or volume bounded actually or theoretically. IFCSPACES are designated to provide for certain functions within a building. Our data mining is focused on the relationship between building space structure and functions. In general, the relationship between building structure and functions is a philosophic problem. Philosophers have proposed different theories to interpret it, but it is commonly accepted that the relationship does exist. Therefore, we take Space Syntax Theory as our main basis, and develop our spatial knowledge extraction model with machine learning techniques.

Our main contributions: We present a novel machine learning algorithm to obtain functional knowledge from building space structures. We extract the physical properties of each space and their boundary relationships in BIM model (using IFC standard) and build several boundary graphs with space boundary relationships. In our algorithm the properties of each space propagate along the edges of these graphs, we employ mathematical moments to make the result of propagation into new features. Based on the graph representation of building structure, we adapt the affinity propagation algorithm to perform building space clustering analysis, in order to get representative samples of spaces within one or several multi-spatial buildings.

To the best of our knowledge, this is the first approach that is able to automatically learn spatial design knowledge from IFC based BIM data. The

experiments are conducted on real building BIM models. The experimental results show that our method is very effective for building data mining, especially to explore the relationship between the building space structures and the functions.

2 RELATED WORK

2.1 Machine Learning on Construction

Contemporarily, machine learning has been applied in construction and more and more attentions are attracted from the research and industry communities. With monitoring devices and systems, machine learning methods are taken upon the tasks of architecture maintenance. G. Li al. (G. Li al., 2017) adopt SVM in their noise elimination algorithm for the task of bridge crack recognition and evaluation. W. Z. Taffese and E. Sistonen (W. Z. Taffese and E. Sistonen, 2017) conclude the recent advances and future directions of machine learning for durability and service-life assessment of reinforced concrete structures. Back-propagation neural network (BPNN), radial basis function neural network (RBFNN), SVM, and decision tree are all adopted in carbonation depth prediction, chloride prediction and evaluation, and coupled transport processes in concrete. E. Rodrigues al. (E. Rodrigues al., 2017) use hierarchical agglomerative clustering algorithm to cluster architectural floor plans. They present 4 sorts of shape representations of 2-D floor plans, and compared them with the clustering results.

Learning from building data has been studied in several perspectives. A. Henn al. (A. Henn al., 2011) present a classifier on building types, which is based on SVM. They use coarse low resolution data that is wildly available as their dataset, manually labelled them, extracted about thirty features via the functions of spatial analysis in spatial databases with some necessary pre-processing, and classified these obtained samples with SVM. Z. Lun al. (Z. Lun al., 2015) introduce a structure-transcending style similarity measure on three-dimensional models. They translate the presence of similarly shaped, salient, geometric elements into an algorithmic measure. It works well when aligned with human perception of stylistic similarity. T. Krijnen al. (T. Krijnen al., 2015) investigate the application of several machine learning method on BIM models. They use unsupervised learning to detect outliers of the geometrical attributes of the elements in a model, and supervised neural networks to classify floor plans with 8 manual features.

2.2 Building Space Modelling

There are a lot of theories of modelling building space. The most inspiring proposition for automatic building space classification is the theory of space syntax (B. Hillier, J. Hanson, 1984; B. Hillier, 2015). The theory of space syntax includes a lot of topological properties such as depth measurements, which enable quantitative analysis on the features of space form and functioning. T. Markus and D. Cameron (T. Markus and D. Cameron, 2002) propose a five-step procedure of the generation of building space classification, in which the original discourse comes to categories, and then to labels, to space and form, while finally to the actual use and management of the building space. In practice, S. Daum al. (S. Daum al., 2014) present an approach to generating building fingerprints automatically based on a spatial-semantic query language for BIM. They retrieve accessibility and adjacency relationships among spaces in IFC models, therefore build an accessibility graph and an adjacency graph between spaces within a building model.

3 BUILDING SPACE KNOWLEDGE EXTRACTION

In this section, we present our interactive algorithm to extract features of building spaces. Our method takes IFC files as the input. We extract IFCSPACES and their related properties. We learn the features of different dimensions from the space boundary graphs. These features can be integrated with clustering methods to mining the knowledge of building space design.

3.1 Properties and Boundary Graphs of IFCSPACES

The IFC data is organized in a structure similar to a tree. The root node is an object of IFCPROJECT, while the other information is distributed in its direct and indirect child nodes. IFCSPACES are the objects on the lowest layer of spatial structure, with an unfixed number of defining properties. Figure 1 shows the position of IFCSPACES in the tree-like structure of IFC data, and how their defining properties are placed. Besides these properties, there are also inter-IFCSPACE boundary relationships in the structure. Each boundary is contributed by an IFCSPACE and an IFCELEMENT such as an IFCDOOR, an IFCWALL or an

IFCVIRTUALELEMENT. In other words, it is an IFCELEMENT that separates two IFCSACES. By combining boundaries sharing the same separating IFCELEMENT, we can reduce IFCSACES along with their boundary IFCELEMENTs into several boundary relationship graphs. Primarily, each type of space boundary element corresponds to a graph alone; and in addition, we sum up all types of boundary elements to make the adjacency relationship graph on one hand, while select the types through which the neighbouring space is accessible to make the accessibility relationship graph on the other hand. Figure 2 and Figure 3 show the extraction of adjacency and accessibility relationships, and Figure 4 is an example set of spaces and their adjacency and accessibility relationship graphs.

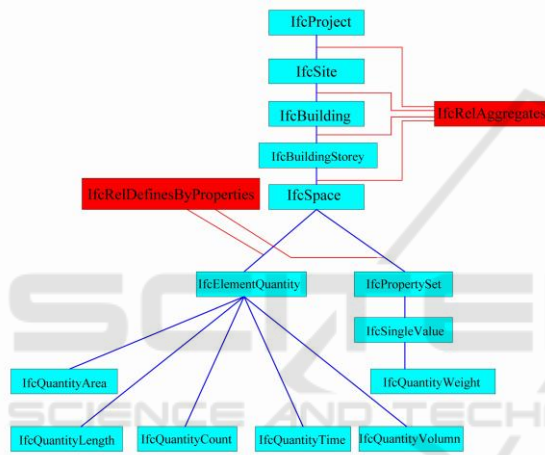


Figure 1: IFCSPACE in the IFC Tree-like Structure.

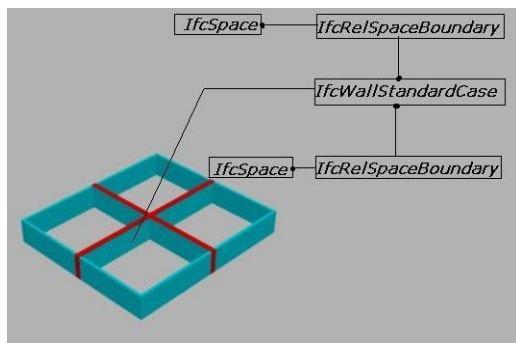


Figure 2: Extraction of Adjacency Relationships.

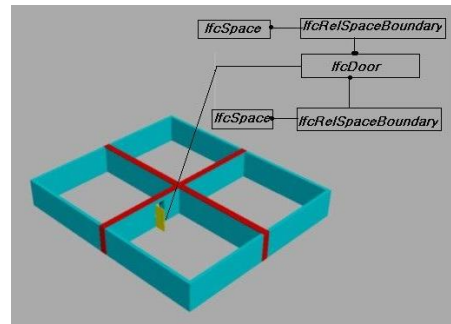


Figure 3: Extraction of Accessibility Relationships.

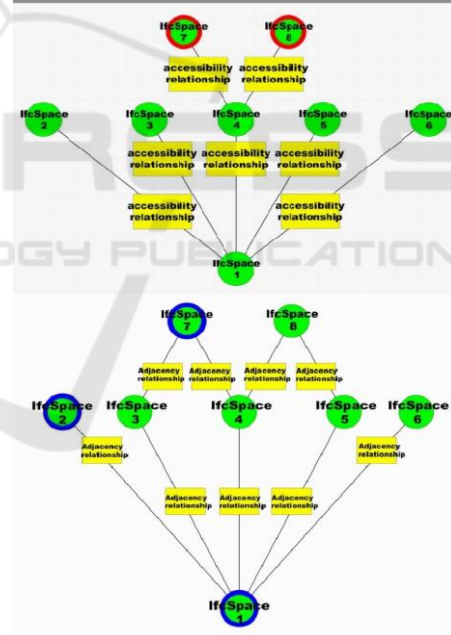
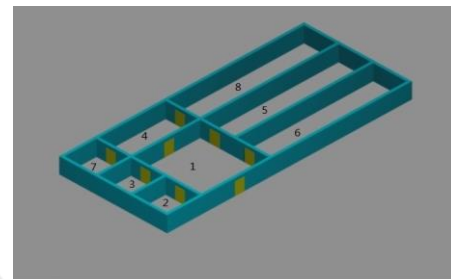


Figure 4: An Example Set of Spaces and Their Adjacency and Accessibility Relationship Graphs.

3.2 Count Propagation

According to various theories, building spaces interact with each other on determining their functions. Therefore, we build our feature extraction mechanism on the inter-relationships among IFCSACES. With each space corresponding to a node in every boundary relationship graph, we let the

parameters of each space propagate along the edges. The propagation within boundary relationship graphs carries semantic meanings to each of the nodes, which can be summarized in 2 dimensions: adjacency/accessibility and count/property. These 2 dimensions come up with 4 combinations: adjacency count propagation, accessibility count propagation, adjacency property propagation, and accessibility property propagation.

In count propagation, each space contributes a count to its neighbouring space. Through different boundary relationship types (edges in the graphs), different semantic information is passed to the neighbours: through IFCWINDOW edges, meaning about openness is transported to the neighbouring spaces; through IFCWALLSTANDARDCASE edges, meaning about privacy is transported to the neighbouring spaces; through IFCCURTAINWALL edges, the transported meaning to the neighbouring spaces is sorts of openness and privacy, to some extent; through IFCSLAB edges, something concerning vertical relationships such as noise transmission and water seepage are transported; and through total adjacency edges, meaning about the complexity is transported to the neighbouring spaces. The receiving space sums up the counts it receives.

We keep the radius of all types of adjacency propagation to 1 step, which means only the direct neighbours will be affected by one space. However, the radius of accessibility propagation is designed to be larger. In the space graph, semantic meanings transport through accessible boundaries, from one space to another, and then to the next. They may attenuate or diffuse in the graph. The accessibility propagation could be summarized as the expression below:

$$R = DS \quad (1)$$

Where S stands for the vector of source parameters of propagation, R stands for the vector of received parameters, and D is the matrix of diffusion functions. We learn D from the structure of the accessibility graph.

3.3 Propagation of Spatial Properties

By assigning spatial properties to S in expression (1), we have some other dimensions of propagation. We select 2 of the main properties to be propagated: Space area and Space Circumference, for the reason that they are various in all the spaces, and expressive in space characteristics. Instead of summing up

received parameters simply, our receiving function is defined with mathematical moments:

$$M_i = \text{Moment}_i(s). \quad (2)$$

We select moment ordinals from 1 to 6. These received parameters are mapped on different dimensions of features describing the space. We finally have features of 197 dimensions, including 4 simple features which are directly space properties, and 193 other complex features as the result of inter-spatial parameter propagation. All the features are shown in Table1 and Table 2.

3.4 Affinity Propagation Clustering

Similar to the manner of parameter propagation in the boundary graphs making space features, affinity propagation is a method of clustering data with graph-based message passing mechanism (Brendan J. Frey and Delbert Dueck, 2007). Besides, affinity propagation simultaneously consider all samples as the candidate cluster centers instead of picking up start points randomly and deciding number of clusters at the beginning of clustering, so we adapt and integrate it in our unsupervised algorithm, propagating parameters about features between building spaces, to discover potential knowledge of them. Moreover, affinity propagation choose a sample itself as an exemplar to represent one cluster, thus we can explore the characteristics of a type of spaces by analysing their exemplar. Therefore, we apply affinity propagation on our extracted features.

Affinity propagation starts from the similarity matrix S, where

$$S(i, j) = \|X_i - X_j\|^2 \quad (3)$$

And exchange 2 sorts of messages between samples, availabilities and responsibilities. The responsibility matrix R and the availability matrix A iterate crossly according to the expressions below to identify exemplars:

$$r(i, k) \leftarrow s(i, k) - \max_{k' \text{ s.t. } k' \neq k} \{a(i, k') + s(i, k')\} \quad (4)$$

$$a(i, k) \leftarrow \min \left\{ 0, r(k, k) + \sum_{i' \text{ s.t. } i' \in (i, k)} \max\{0, r(i', k)\} \right\} \quad (5)$$

$$a(k, k) \leftarrow \sum_{i' \text{ s.t. } i' \neq k} \max\{0, r(i', k)\} \quad (6)$$

Table 1: Simple Features.

Space area	Extracted from IfcPropertySingleValue“area”
Space circumference	Extracted from IfcPropertySingleValue“circumference”
Space height	Extracted from IfcPropertySingleValue“room height”
Floor level	Extracted from IfcPropertySingleValue“level”

Table 2: Complex Features.

	Numbers of boundaries of this space	Mathematic moments of geometric measurements of the spaces sharing boundaries with this space
Each type of boundary alone	$N_{s,k} = \sum_{T_i=k, i \in B_s} 1$	$M_{s,k,f}^n = M^n(F_{f,i})_{T_i=k, i \in B_s}$
Adjacency relationships	$Naj_s = \sum_{i \in B_s} 1$	$Maj_{s,f}^n = M^n(F_{f,i})_{i \in B_s}$
Accessibility relationships	$Nac_{s,d} = \sum_{D_{s'}=d} 1$	$Mac_{s,d,f}^n = M^n(F_{f,s'})_{D_{s'}=d}$

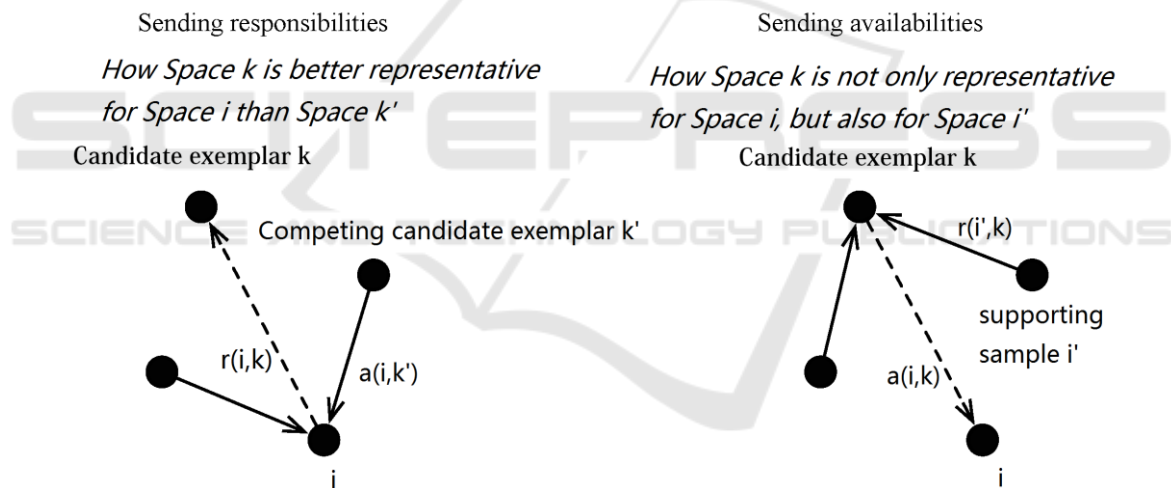


Figure 5: Affinity Propagation between Spaces.

Figure 5 illustrates the process where affinity propagation works following feature extraction among spaces .

4 EXPERIMENT

In this section, we use the analysis of our clustering results on the data of a real building to demonstrate how knowledge of building spaces is extracted from

BIM data. We use both label examination and exemplar evaluation to assess our experiment. Two major discoveries are made by our experiment:

1)Dense and large cluster centers are inclined to have the same/similar labels,hence they can be harnessed to detect mislabelling; and

2)Typical usages of the building spaces can be extracted from the clustering results beyond/without space labels.

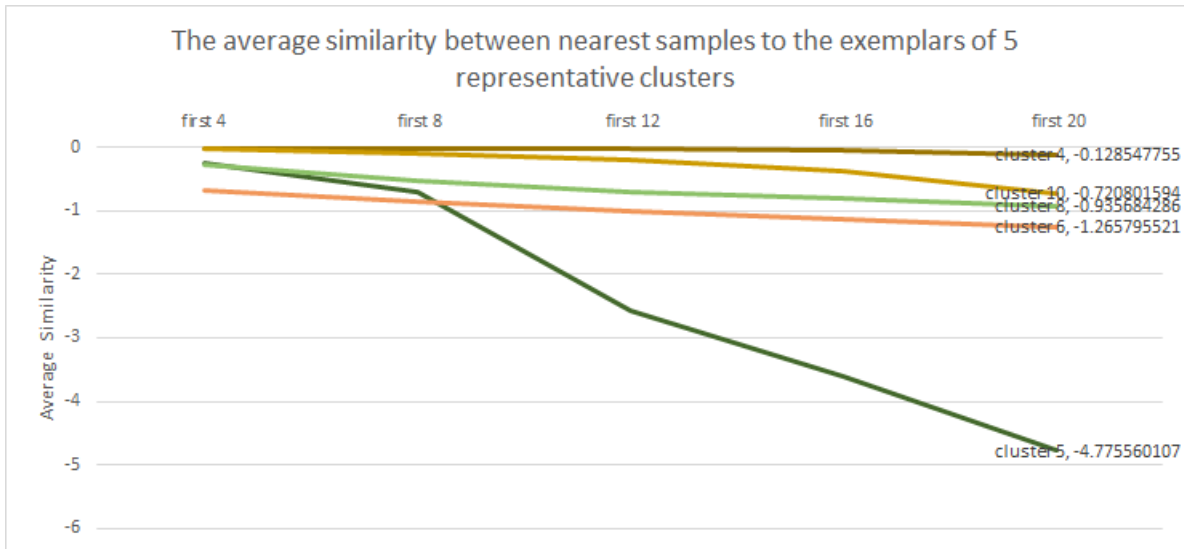


Figure 6: The Average Similarity between Nearest Samples to the Exemplars of 5 selected representative cluster.

4.1 Dataset

The dataset contains a 3D building models containing a number of details of the indoor spaces in BIM, which applies IFC Architecture. Our data consists of 595 spaces from a 20-storey building (Building A). In IFC data, each IFCSPACE has a longname, which marks the usage of the space. We use the longnames of the IFCSPACES in our dataset as the labels of spaces. There is quite a variety of labels in the samples from Building A, with a fair distribution on each type.

4.2 Label Examination

We have applied our approach on Building A, which has 595 spaces. By setting preference in affinity propagation to -50, 11 clusters are obtained. Longname labels of the samples are used to examine the result of clustering. Our goal is to find exemplars representing typical functions of building spaces, thus we use the exemplars of each cluster to stand for a type of function; besides, we believe the samples with

most similarities with the exemplars are also sorts of representatives of the cluster.

Figure 6 shows the density and the scale of the cluster center near exemplars. The higher the similarity curve locates, the denser the cluster center is; the earlier the similarity curve goes down, the smaller the cluster center turns to be. The cluster 4 is a typical that has both dense and large center, while cluster 10 stands for those who have dense centers small in size. Cluster 8 and 6 have less dense but large centers. Cluster 5 is rather worse judged by these 2 measurements. Figure 7 shows the composition of space usage labels of the first 8 samples near exemplars including exemplars themselves in each cluster. The cluster 4, 2 and 9 are dominated by faculty offices, department offices, and unlabelled rooms. Chief offices and director offices are the theme of the cluster 11. The cluster 6 is majorly smoking areas, while the other clusters has a more diverse composition of their cluster centers. This proves our evaluating criterion of clustering: the denser and larger the cluster center is, the better the exemplar represents spaces of a certain function.

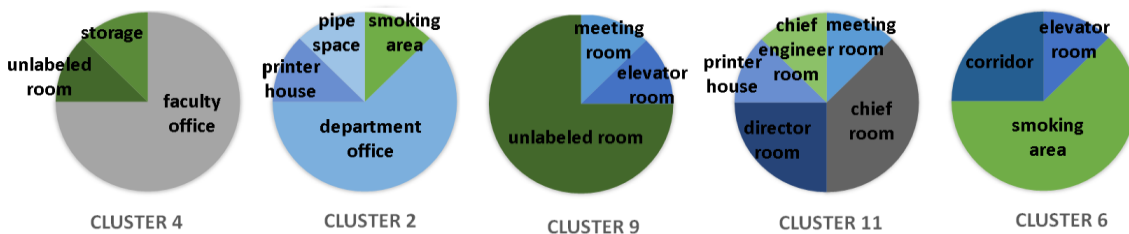


Figure 7: The Composition of Space Usage Labels of 5 Representative Cluster.

4.3 Exemplar Evaluation

Our unsupervised learning method is designed to find a way describing the hidden structure of building spaces, so other than label examination, it is more appealing to expect what could be learned without labels or beyond labels, expressing undiscovered knowledge about building spaces. By studying exemplars and the samples with most similarities in their clusters, we get several typical building spaces from our learning results.

The 3 typical functional spaces below correspond to the cluster 11, 4, and 6, which enjoy dense and large cluster centers. Difference between “offices” is found between cluster 11 and 4, as the difference between senior offices and open offices. On the other hand, it is found that chief offices and director offices share a lot of similarities, for which they could be considered as a same type on some occasions. And the cluster 6 tells us there is something common among elevator rooms, smoking areas, corridors, and open working spaces. These offer us the knowledge of demarcating spatial functions rather than labels. With the clustering we can predict the function or guide the usage of unlabelled spaces: for instance, the most of the unlabelled room in cluster 9 can be assigned the labels of a sort of public space. The density and large scale of its cluster center enable us to specify the unlabelled spaces in it according to their labelled cluster mates. Generally, we study the exemplar and the samples close to it obtained in each cluster, choosing the features they have in common most (least distances on those dimensions) as their most salient structural characters.

The mining results:

Senior Offices

Our method has found some extent of isomorphism between the 17th floor and the 18th floor of Building A in our data set. As shown in Figure 8, the spaces along the right curve are all spaces functioning as senior offices. They are quite independent, with only one door connecting with the outer spaces, high floor levels and windows providing a good sight and mood, and close distances to elevators through the corridor. Independence, sight, and convenience can thus be employed as the key words describing this type of usage.

Open Offices

Some offices are designated to opening usages, e.g. public visits, agencies, and receptions. Such open offices which mostly stand for this are shown in

Figure 9 marked in black. They have larger degrees of adjacency and accessibility, which imply openness.

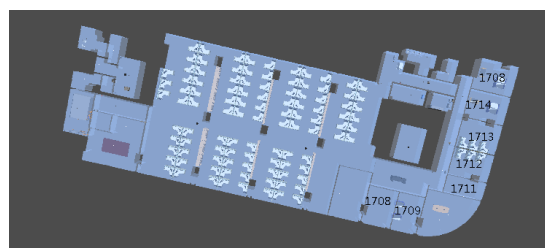


Figure 8: Senior Offices.

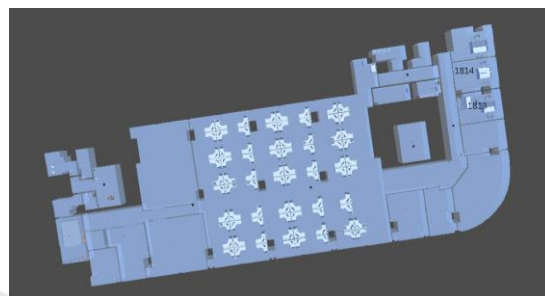
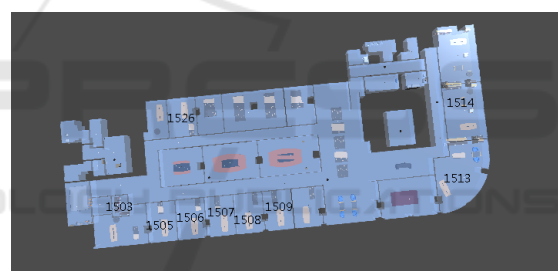


Figure 9: Open Offices.



Circulation Spaces

Circulation spaces are distributed in a number of stories, with various sizes, but all public. They can be accessible from a lot of neighbouring spaces, and function as the connecting, transitional, and sorts of recreational (such as smoking area) spaces. Some samples of this cluster are shown in Figure 10 marked in red, including elevator rooms, smoking areas, corridors, and small open working areas.

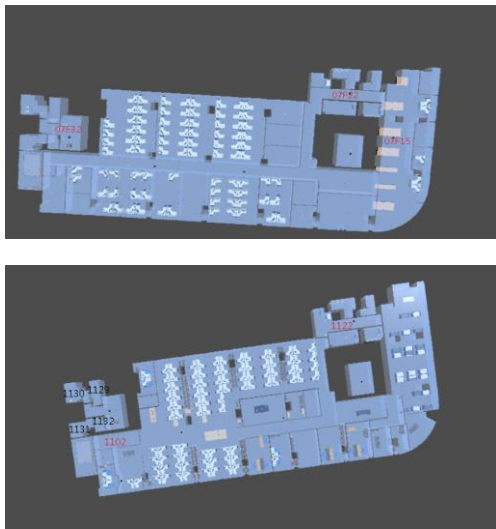


Figure 10: Circulation Spaces.

5 CONCLUSIONS

We present a novel machine learning method for BIM model mining. An interactive algorithm is proposed to get features of inter-relational graph-like building spaces, and these parameters are propagated along edges of the graph to generate features. These features are expressive of describing the structure of building spaces. We apply the unsupervised affinity propagation clustering algorithm to mining the exemplars of typical spatial functions based on the above feature representation. To the best of our knowledge, this is the first work that intends to mining the IFC based BIM data for the relationship between functional spaces and architecture design.

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