Bus Schedule Rationalisation
An Analysis of Trip Completion Times

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1 INTRODUCTION

One-third of India's population lives in dense urban agglomerations (UA). The transit modal share varies from UA to UA. Citizens in most UAs can access public transit modes such as auto rickshaws and buses; larger UAs maintain commuter trains and metro rail services. Bengaluru is India's fourth largest UA, with a population of 10 million. Over the past three decades, a prosperous IT industry has brought a steady influx of workers into the city. Business parks and residential areas located on the periphery have expanded the size of the city to 700 sq km. Sweeping infrastructural changes are frequently made to accommodate the increased use of privately owned vehicles that often transport a lone passenger and contribute to widespread congestion.

Public transit services in India have their share of problems (Badami and Haider, 2007). After devising metrics that are appropriate to this context, Badami and Haider compare the performance of bus services across various UAs. Their analysis shows that ridership numbers have steadily fallen over time. They highlight a "viability-affordability dilemma": faced with mounting expenses, transit operators are forced to hike fares, which causes ridership to decline.

Unreliable arrival times and overcrowding are other factors that make commuters switch to using private vehicles. With the objective to plan services more effectively, public transit operators have begun to invest in technologies such as automatic passenger counters (APC) and automatic vehicle location (AVL) systems. However, only a select few have developed the capabilities to process the large volumes of collected data. A strong decision support tool can facilitate effective trip scheduling and monitoring, maintenance management, trend analysis and a host of other activities (Furth et al., 2003).

Traffic in Indian UAs is vastly heterogeneous; buses and heavy vehicles jostle for space with two-, three- and four-wheelers on congested roads. Lane discipline is not maintained. Arterial roads are perennially under repair. Traffic signals malfunction. These factors invalidate the simplifying assumptions made by most transportation models. Statistical analyses with time-location data can generate more actionable insights (Vanajakshi et al., 2009).

Trip completion or run time is a key consideration for commuters deciding on their mode of transit. Reliable run time estimates are critical for a transit operator to build and display “rational” schedules and retain ridership. AVL and APC data have been harnessed to estimate trip run times in a predictable traffic setting (Têtreault and El-Geneidy, 2010).

We shall take up the complex problem of run time estimation in an Indian context, by examining a popular all-day bus route operated by Bengaluru Metropolitan Transport Corporation (BMTC). Our analysis shows that a seasonal ARIMA model best fits the trip completion data, and can be used by schedule planners to arrive at reliable timetables.

The paper is organised as follows. Section 2 high-
lights some operational realities at BMTC. Section 3 details the intelligent transportation system (ITS) under implementation, and computing infrastructure to further process the data. Section 4 exposes the problem of trip run time variance, which impacts schedule compliance. Using techniques from time series analysis, we model the run times in Section 5, and compare model accuracies. The paper concludes with some directions for investigation.

2 OPERATIONAL CONTEXT

The Bengaluru Metropolitan Transport Corporation (BMTC) is the city’s sole public bus transit provider. Its 6,400-strong fleet services the needs of commuters travelling to urban and suburban areas. Each day, the fleet completes 75,000 trips and covers 1.15 million service km. By facilitating 5 million rides, these buses cater to 40% of the city’s demand. BMTC’s premium services, which have been in operation since 2006, comprise 10% of the fleet. These services are efficient and somewhat profitable (Hanumappa et al., 2016).

Every bus follows a designated schedule termed as Form-IV, which lists the specific up and down trips to be covered on a route (Figure 1). Created years ago, these schedules have remained unchanged, whereas traffic on Bengaluru’s roads has increased manifold. This has led to significant deviations from the Form IV stipulation as well as revenue projections. Occasionally, drivers rushing to complete their schedule tend to commit serious mistakes.

BMTC management has responded by prioritising the rationalisation of its Form-IVs, which number a formidable 6,100. The new schedules must take into account variations in the traffic conditions, which are governed by a diverse set of parameters such as the month, day of week, time of day and whether or not it is a holiday. The pivotal role of trip run time estimation in this exercise is fairly obvious.

2.1 Objective of our Study

It is our mission to assist planners at BMTC with drawing up rational schedules. The first step would be to examine trip run patterns in order to arrive at reliable estimates. By “piecing together” these estimates for the up and down trips, we can decide on a workable number to include in the schedule.

For our research, we choose Schedule 365R, whose trips run all day along a route of 21 km, connecting a national park on the outskirts of Bengaluru with the hub for BMTC in the city centre. Figure 2 lists the main bus stops for this route. On weekdays, trips are delayed anywhere between 10 to 60 minutes. Since peak hour kicks in by 8:30 a.m., we choose to investigate Trip 3, which is scheduled to run between 8:00 a.m and 9:10 a.m (see Figure 1).
3 ITS AT BMTC

In what was a first for Indian public transit operators, BMTC launched a comprehensive ITS initiative in June 2016. Vehicle tracking units (VTU) have been installed on all buses, and are successfully relaying their latitude-longitude coordinates every 10 seconds via GPS to a central ITS server. Conductors have been relaying their ticket sales using GPS-enabled Electronic Ticketing Machines (ETMs). Staff who are stationed at a Control Centre can now track buses in real time, and attend to any emergencies.

3.1 Data Collection

On a given duty date, a bus makes multiple trips. The conductor uses the ETM to key in the schedule and trip number, as well as the start and end times for the trip. The ITS stores all of this information in the waybill table (Figure 3). The VTU on-board the bus periodically reports a device ID and a geo-location, along with a timestamp, all of which are recorded in a separate table \( \text{vts} \text{parse} \text{data} \). The remaining tables contain reference data for schedules, routes, bus stops and bus to GPS device associations.

3.2 Processing Infrastructure

Whereas the waybill table receives two million updates each month corresponding to the 75,000 trips made everyday, the geo-location data relayed every 10 seconds generate close to a billion updates to the VTS table each month. All of this data is transferred from the production ITS server to a 10-node Hadoop Distributed File System (HDFS) cluster, which runs a SQL-friendly Hive database. We use a Python/Spark program to query this database and generate a time series of trip completion times. We then avail of the strong support by the R platform for time series modelling and visualisation, using packages like xts, forecast, ggplot.

3.3 Missing Data

There are a few instances in which trip data have gone missing; this may be attributed to worker strikes, trip truncation, absence of service (formally termed as missed trips) and a simple lack of records. We have chosen to impute the missing data with the average of times taken for “neighbouring” trips that correspond to the same weekday. We then obtain a contiguous time frame of four months between August-November 2016 (Figure 4).
3.4 Unlinked Information

In the existing setup, neither the VTU nor the ETM performs any pre-processing steps; both devices simply relay the data they gather to the ITS server. This can be problematic. The specific trip number of the schedule that a bus is plying on is unavailable, and must be separately ascertained. Anomalies can arise due to a bus missing one or more stops en route, making incomplete trips, or skipping a trip altogether. These events are not flagged. Finally, there is no record of events such as arrivals of a bus at the designated stops along its route and more critically, the times of arrival; these issues hinder trip analysis.
3.5 Trip Reconstruction

We make intensive use of the VTS data to reconstruct the trips. We employ a geo-fence of fixed radius to detect the presence of a bus at or near a designated stop, on the basis of its recorded lat-long values. Whereas a liberal value for the radius could indicate that a bus is present at multiple stops, too tight a setting could result in transits through bus stops not being detected. A smaller geo-fence radius is advantageous; the arrival time at a bus stop is accurately derived, and there is reduced chance of multiple observations lying within a single fence. For each trip, we consult the waybill to determine the start and end times entered via the ETM, and add a relaxation to compensate for lags in data entry. We use this time window to extract rows that are relevant to the trip from the VTS table. In order to determine the sequence of halts, one approach would be to take each recorded lat-long value, and check if it falls within the geo-fence of a bus stop on the route. This is where parallelised computations prove to be handy.

4 SCHEDULE VARIANCE

Examine the Form IV for our chosen schedule in Figure 1. On an ordinary service day, Trip 3 must be completed within 70 minutes. The ITS data reveals that this is not always the case; at 4,100 seconds the observed average for the 4 month period is less than the stipulated time. However, the run times show a wide variation between 2,300 and 7,600 seconds, with a standard deviation of 860 seconds.

Figure 6 depicts the overall variation in run times, which hints at possible delays. For instance, median levels for Trip 3 on Monday and Wednesday far exceed the stipulated 70 minutes. Such delays might have a cascading effect on remaining trips for the day, leading to a fall in the total number of trips. Conversely, the median run time for Sunday is vastly lower than 70 minutes; examining the actual data reveals that all 13 trips are completed on Sundays.

We have built a dashboard using the Shiny package of R to interactively visualize trips and transit events, by applying filters such as month, day of week and trip number (Figure 5). Ignoring the first and final dead trips in Figure 1, 11 trips have to be completed. However, Figure 5 makes it clear that Trips 9 and 10 are usually missed on Wednesdays; these are expected to cover the full route of 20.8 km. Trip 9 in Figure 5 (in red) is actually Trip 11 in the Form IV listing, with a run distance of 8.8 km.

5 ANALYSIS OF RUN TIMES

Planners would benefit from a prediction model for trip completion times that takes into account com-
plex traffic conditions. With the reconstructed trip data, we now undertake a systematic analysis using techniques from time series analysis (Hyndman and Athanasopoulos, 2014). Our training dataset consists of trip run times for the first 16 weeks; the models are then validated against the final week of November 2016.

5.1 Characterisation

Despite wide variations in run times across the week (Figure 6), one would expect that they will demonstrate a fair amount of seasonality; one Monday's traffic pattern would be comparable to another Monday's, barring exceptions like holidays.

We shall employ an additive decomposition for the run times (Figure 7) because the magnitude of the seasonal fluctuations around the trend cycle is unaffected by the level of the time series. Barring the peaks in September and November, the time series appears to be stationary; this is attested by an Augmented Dickey-Fuller test \((p < 0.01)\). The trend cycle for the period follows no predictable pattern. It is clear that there is weekly seasonality. The random signal has the characteristics of white noise.

5.2 Modelling

The peaks and troughs in the series fail to show any regularity. Consequently, a seasonal-naive model fit with frequency = 7 results in an inaccurate forecast (Figure 8a). The 7-day moving average fit captures the trend in the series (Figure 8b), but misses the amplitudinal variations. Both of these fits are unusable by schedule planners. A better fit is achieved by a Holt-Winters model with damping, which captures the trend as well as seasonal variation (Figure 8c). It is still insensitive to high swings.

Because travel times on corresponding weekdays are correlated, we shall seek a seasonal ARIMA fit. The \texttt{auto.arima} utility in R exhaustively searches the space of ARIMA models with lags \(p\) (for AR) and \(q\) (for MA) of up to 5. The algorithm settles on an ARIMA model fit with trend-differencing.

\[
\text{ARIMA}(1,1,1)(1,0,1)[7] \\
\begin{array}{cccc}
ar1 & ma1 & sar1 & sma1 \\
0.1818 & -0.9829 & 0.7948 & -0.5321 \\
\end{array} \\
s.e. & 0.0965 & 0.0241 & 0.1583 & 0.2278
\]

The coefficient of MA in this model is close to unity, which is undesirable. The trend in the series being unpredictable, we shall choose to ignore it and drop the differencing. We shall model using seasonal differencing alone, and obtain the fit shown below.

\[
\text{ARIMA}(1,0,1)(1,1,1)[7] \\
\begin{array}{cccc}
ar1 & ma1 & sar1 & sma1 \\
0.1847 & 0.0241 & 0.1812 & -0.8282 \\
\end{array} \\
s.e. & 0.4225 & 0.4255 & 0.1572 & 0.1254
\]

The residuals turn out to be normally distributed, indicative of white noise. Carrying out a Ljung-Box test on this new model, we conclude that the residuals are also not correlated (with \(p = 0.55\)).

Table 1 lists a set of standard measures used to compare the models. The Holt-Winters and ARIMA models outperform the base naïve model on all metrics; MASE values less than 1 suggest that forecasts made using either of these models perform better than the naïve model.
We finalise on an ARIMA(1,0,1)(1,1,1)[7] model, which has the lowest criterion values (AIC and BIC).

5.3 Forecast

We use the final model to forecast trip run times; the results are depicted in Figure 9. Planners may choose to build their schedules on a rolling basis using the 80% confidence level. The MAPE calculated for the testing data at 20.7% is higher than the 14.16% corresponding to the training data.

6 CONCLUSIONS

This paper goes over common problems that impact bus transit authorities in the crowded cities of India.
Given the traffic congestion and pollution, it is imperative to explore ways in which commutes using private vehicles can be reduced. A sizeable segment of the citizenry would take to buses if their quality of service could be improved. Large schedule variance and unpredictable arrival times have had a negative impact on commuters seeking predictable transits. In 2016, BMTC, which is Bengaluru’s public bus transport provider, invested in an ITS platform to capture large volumes of AVL and ETM data generated by its fleet of 6,400 buses. The paper throws light on how this data is stored and processed in a cluster of machines that are enabled by big data technologies such as Spark/Hadoop/Python/R.

For our study, we select a popular route (356R) of BMTC, and examine Trip 3 on the schedule, which operates during the peak hours of the morning. By querying the AVL and ETM data, we ascertain run times for this trip over a 4 month period. Our analysis exposes a problem of schedule variance. To suggest remedies to this problem, we undertake a time series analysis of trip run times, and finalise on a seasonal ARIMA model.

Weekly forecasts based on our time series analysis can be of utility to schedule planners. By piecing together the forecasts for different trips, planners will be able to design schedules for better compliance by drivers, who are rushing to complete trips.

Our next mission would be to help planners rationalise the 6,100 schedules maintained by BMTC; this will require strong computational support. Revised schedules based on credible forecast numbers have the potential to remedy some of the problems faced by transit operators. Efforts are underway to display the expected time of arrival (ETA) of different buses at a bus stop; this step is predicted to have a significant positive impact on the ridership numbers.

Besides consuming time and resources, there is a risk of committing mistakes while reconstructing the trip information from two disparate sources, namely the VTU and ETM. This problem may be addressed by a simple mechanism onboard the bus, such as a mobile listening device, that rolls up this data in real time, and relays the combination of device ID, schedule, trip number, geo-location and timestamp to the ITS. For this to work, the VTU and ETM may have to be suitably modified to communicate with the device using a short-range protocol such as Bluetooth.

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REFERENCES


