

Cloud Services Selection by Load Balancing between Clouds

A Hybrid MCDM/Markov Chain Approach

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Abstract: With the rapid growth of cloud computing, a number of service providers have appeared who offer similar services at various prices and performance levels. So, the increasing number of cloud services has made service selection a challenging decision-making problem. In a multi cloud environment, we need to find a service from multiple clouds by taking into account several requirements (user and system ones). In this paper, we present a cloud service selection model in which we focus on load-balancing across the replicas of services placed at different clouds, this, by taking into account end-user requirements for the service price.

1 INTRODUCTION

Web Intelligence presents excellent opportunities and challenges for the research and development of new generation Web-based information processing technology, as well as for exploiting business intelligence. With the rapid growth of the Web, research and development on WI have received much attention (Yao et al., 2001). In this optic, Cloud computing has emerged as a new paradigm which provides a set of accessible computing resources as services that can be accessed through the network from anywhere in the world. The aim of the cloud computing model is to increase the opportunities for cloud user by accessing leased infrastructure and software applications from anywhere anytime manner (Whaiduzzaman et al, 2014). The NIST (National Institute of Standards and Technology) (Mell and Grance, 2011) classifies cloud services in three models: SaaS (Software as a Service), PaaS (Platform as a Service) and IaaS (Infrastructure as a Service). Also, a service provider can use four types of cloud deployment models: private cloud, community cloud, public cloud, and hybrid cloud. The first three deployment models are ordered from the least to the most dynamic in terms of provisioning elasticity, and the hybrid cloud is a mix of resources from two or more of the other models. In this paper, we will consider services based on the SaaS model.

In a multi cloud environment, a difficult decision emerges when a customer has to select a Cloud service because of the growth of public Cloud offerings. When several, and often conflictive, criteria should be taken into account to select one Cloud service from a set of similar services, the decision becomes more difficult. In such a situation, however, it is challenging to find an appropriate service by taking into consideration two criteria: load balancing between the different clouds and minimizing the service cost. So, There is a need for a cloud service selection approach that takes into account the multitude of available cloud services, variations in QoS performance (as well as service cost), and the user's criteria to rank available cloud services, and then assists in selecting the best and most advantageous service (Zia et al, 2013).

In previous work (Hioual and Boufaida, 2011), we have proposed an agent based architecture for web services composition. In this regard, we propose a Cloud service selection solution based on the agent paradigm, which has proved to be effective for distributed applications. Also, the selection of alternatives in the presence of multiple properties or attributes is referred to as a Multiple Attribute Decision Making (MADM) problem (Roy, 1990). Therefore, it seems natural to use multi-criteria decision-making methods in order to evaluate a set of Cloud services alternatives.

In this paper, we focus on load-balancing across clouds containing replicas of services. And since cloud services are payable, we try to minimize, the most possible, the cost to pay by a Cloud customer. The literature shows that MCDA techniques are indeed effective and can be used for cloud service selection. Also, several works do reveal that TOPSIS and both outranking methods (ELECTRE and PROMETHEE) are more suitable for this purpose. If the number of available services is very large, then TOPSIS is appropriate because of its computational simplicity, so we will use this later in order to rank service alternatives and in order to select the best one. And, since our system changes dynamically (Cloud states change dynamically according to service requests), we will use Discrete Time Markov Chain (DTMC) that is well established analytical tool for understanding dynamic systems behavior (Kemeny and Snell, 1976), and it has been applied to a variety of practical problems in real-world domains.

The remainder of the paper is structured as follows: In Section 2 some related works are presented. In Section 3, first the overall model of the cloud service selection, in multiple cloud environments, is presented, and then how this model can minimize the cost and in the same time how it balances the load between the different clouds, is discussed. The paper is concluded and an outlook on future work is given in Section 4.

2 LITERATURE REVIEW

Making a decision involves that there are alternative choices to be taken into account and in a such situation we need to choose the one that best fits with our goals, objectives, desires, values and so on. Several researches show that MCDA techniques are effective and can be used for cloud service selection.

In this regard, several approaches which are based on MCDM techniques, that assist a user in making a service selection decision in the Cloud environment, exist. For instance TOPSIS (Qu and Chen, 2009), AHP (Zuo et al, 2008), and PROMETHEE (Karim et al, 2011) were applied for service selection. Chen et al. In (Qu and Chen, 2009), the authors developed a general QoS-based service selection method. By importing the proposed QoS ontology into OWL-S standards, the proposed method can express Web service's nonfunctional attributes in a semantic and extensible way. Web service QoS based selection is formulated as a multi-criteria decision making (MCDM) which can be solved by using different MCDM models to evaluate QoS criteria of the

candidate Web services. The values of quality parameters of a Web service are normalized to a non-negative real-valued number where higher normalized values represent higher levels of service performance.

(Zuo et al., 2008) focused on the problem that how to select the optimal service among many Web services which all meet the functional needs, establishes an index system for Web services products selection from four aspects, namely the supply side, the user, product and environment. Based on this, the authors collected the views of 30 experts by Analytic Hierarchy Process (AHP) method and calculated the weight of each index at all levels based on the data collected from questionnaire survey. In the overall sample data analysis, the authors put two types of sample data namely business operation experts and academics for comparative analysis. The Web services selection model proposed could provide the reference to Web services managers when they selecting Web services, and also contributed to in-depth research on the adoption of Web services based information system.

In (Karim et al., 2011), the authors proposed to use an enhanced PROMETHEE model for QoS-based web service selection. The first enhancement of authors was to take into account the QoS interdependency by using the Analytical Network Process (ANP) to calculate the weight/priority associated with each criterion. User's QoS requirement is not considered in the original PROMETHEE model. As a consequence, the second enhancement of authors was to check the outranking flows of each service with respect to the request in the ranking step, so that they knew how well a service satisfies the user requirement.

(Chen et al., 2012) proposed a system that enables automatic conflict detection between the user's criteria and enterprise policies in cloud service selection for enterprises. Their system checks various conflicts which result from the violation of enterprise policies and inconsistency in a cloud service user's requirements. Then, it selects an appropriate service that satisfies the user's requirements and also complies with enterprise policies, using constraint programming. Zia et al. (Rehman et al., 2011). presented the cloud service selection problem as a multi-criteria decision making problem by proposing a mathematical framework for multi-criteria cloud service selection.

A few numbers of existing approaches, however, simultaneously consider user requirements (as well as cost) and load balancing between Clouds. In contrast to the above research works and discussion, we approach cloud service selection in a multiple cloud

environment by proposing multi agent based architecture. We assume that each Cloud Collaborator Agent (CCA) has a complete knowledge of all services deployed in its Cloud. The Selection Decision Maker Agent (SDMA) selects the best service alternative which minimizes both load and cost.

3 PROPOSED CLOUD SERVICE SELECTION MODEL

3.1 Load Balancing and Minimizing Cost: A Bi-criteria Issue

For making the choice between different instances of the same service, we have considered two criteria, which are very critical when selecting a cloud service, which are: the load balancing through clouds and the minimization of the cost of a service instance. Our research problem can be considered as a schedule tasks problem on heterogeneous clouds in order to minimize both maximum load and maximum service cost.

3.2 Overview of the Proposed Agent based Architecture

Our architecture (cf. Fig.1) is an agent based one. The main agents that compose this architecture are:

- Selection Decision Maker Agent (SDMA) coordinates and assembles the Cloud Collaborator Agents (CCA) to execute the required operations. It also initializes the selection process by sending to CCAs the call for proposal to be realized.
- A set of Cloud Collaborator Agents (CCAs): each one controls a specific cloud; it means it has a global idea of the services provided by this cloud and also, some interesting information like, for example, the cost of each provided service and the number of request incoming to its specific cloud.

3.3 SDMA and CCAs Behaviors

In this work, we use the well-known contract net protocol (CNP) (Smith, 1981). in order to select a proper service by balancing load between clouds and resolving consumer requirements. As it is known, the rules that define the reaction of agents to events (e.g., reception of a *call-for-proposals* message) define an agent behavior. For each type of agent that constitutes our architecture, one or a set of behaviors is defined. Selection Decision Maker Agent and Cloud

Collaborator Agents interact among each other to select a persistent Cloud service by adopting a set of agent behaviors as it will be discussed in the next sub-sections.

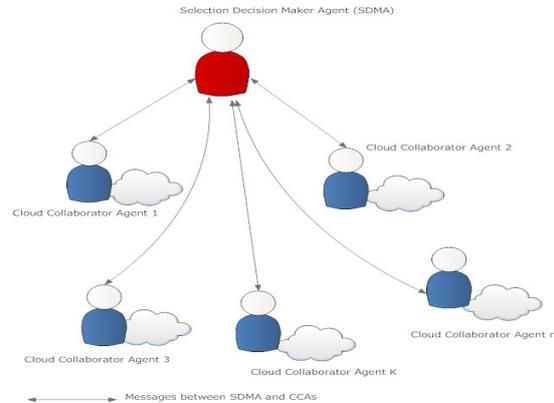


Figure 1: A simplified overview of our architecture.

3.3.1 SDMA Behaviors

A SDMA has a main behavior and a sub behavior. The first one is derived from the *contract net protocol initiator* behavior that submits consumer preferences to CCAs. The second one is the *Result evaluator behavior* which receives proposals from CCAs, and then it selects an adequate cloud service according to two criteria: the load balancing between clouds and the service cost.

➤ CNP_SDMA_Initiator Behavior

This behavior is shown in Table 1:

Table 1: Initiator behaviour of a SDMA.

<i>CNP_SDMA_Initiator Behavior</i>
Input: (i) Cloud Consumer request
Output: (i) A single virtualized service
1: Send <i>call_for_proposals(Reqi)</i> to <i>m</i> CCAs
2: $nProposals \leftarrow BlockReceive(Proposals, timeout)$
3: if ($nProposals > 0$) then
4: <i>Result_evaluator sub behavior</i>
5: Send <i>reject_proposal</i> to ($nProposals-1$) CCAs
6: Send <i>accept_proposal</i> to one (1) CCA
7: $BlockReceive(Reqi.Output)$
8: else
9: Treat exception
10: Gather outputs into a single virtualized service

We assume that it exist at least one proposal for each call for proposal.

➤ SDMA_Result_Evaluator Sub-behavior

For making the choice between different instances of

the same cloud service and in addition to consumer preferences, the SDMA has to consider another criterion, which is very critical when selecting a service, that is: the load balancing through clouds. For this, the SDMA will find a ranking of service alternatives, it uses TOPSIS method (*Technique for Order Preference by Similarity to Ideal Solution*).

The Technique for Order Preference by Similarity to Ideal Solution (TOPSIS) method, which is initially proposed by (Hwang and Yoon, 1981), is one of the well-known multiple criteria decision making (MCDM) methods. This technique shows preference for the similarity to an ideal solution, which tries to select an alternative that is closest to the ideal solution and simultaneously farthest from the anti-ideal solution. In this technique, the decision matrix is first normalized using vector normalization, and the ideal and anti-ideal solutions are identified within the normalized decision matrix (Whaiduzzaman et al, 2014). The main steps of TOPSIS are given in the next section

This SDMA behavior is illustrated in Table 2:

Table 2: Result evaluation behaviour of a SDMA.

SDMA Result evaluator Sub- Behavior
<p>Input: (i) A set of CCAs proposals (a set of $Rinf$)</p> <p>Output: (i) A selected alternative cloud service</p> <p>1: Rank service alternatives, provided by under loaded clouds, by using TOPSIS method</p> <p>2: Select the alternative service which has the minimum cost according to load balancing between clouds</p>

NB. We assume that the weights of criteria are as follow: $W_{load}=0,9$ and $W_{cost}=0,1$. It means load balancing criterion has bigger weight than the cost service criterion.

➤ **TOPSIS steps**

Given the positive solution A^* and the negative solution A^- which are calculated as follow:

$$A^* = \{g_1^*, \dots, g_j^*, \dots, g_n^*\}$$

Where g_j^* is the best value for the j^{th} criteria of all the alternatives.

$$A^- = \{g_1^-, \dots, g_j^-, \dots, g_n^-\}$$

Where g_j^- is the worst value for the j^{th} criteria of all the alternatives.

The procedure of TOPSIS can be expressed in a series of six steps:

Step1. Calculate the normalized decision matrix. The normalized ratings $r_j(x_i)$ are calculated as:

$$r_j(x_i) = \frac{g_j(x_i)}{\sqrt{\sum_{i=1}^m (g_j(x_i))^2}}$$

Where $i = 1, \dots, m$ and $j = 1, \dots, n$

Step2. Calculate the weighted normalized decision matrix. The weighted normalized rating $v_j(x_i)$ is calculated as:

$$V_j(x_i) = w_j r_j(x_i) \text{ for } i = 1, \dots, m \text{ and } j = 1, \dots, n;$$

Where w_j is the weight of the j^{th} criterion.

Step3. Determine the positive and negative ideal solutions as follow:

$$A^* = \{v_1^*, \dots, v_j^*, \dots, v_n^*\} \\ = \{(\max_i v_j(x_i) / j \in J1), (\min_i v_j(x_i) / j \in J2)\}$$

$$A^- = \{v_1^-, \dots, v_j^-, \dots, v_n^-\} \\ = \{(\min_i v_j(x_i) / j \in J1), (\max_i v_j(x_i) / j \in J2)\},$$

Where $J1$ is associated with benefit criteria, and $J2$ is associated with cost criteria.

NB. In this paper, we focus only on two cost criteria, we have not benefit criteria.

Step 4. Calculate the separation measures, using the n dimensional Euclidean distance. The separation of each alternative from the positive ideal solution, and with respect from the negative ideal solution, is given as:

$$d^+(x_i) = \sqrt{\sum_{j=1}^n (v_j(x_i) - v_j^*)^2}$$

$$d^-(x_i) = \sqrt{\sum_{j=1}^n (v_j(x_i) - v_j^-)^2}$$

Step5. Calculate the relative closeness to the ideal solution. The relative closeness of the alternative A_j with respect to A^* is defined as:

$$c(x_i) = d^-(x_i) / (d^+(x_i) + d^-(x_i))$$

Step6. Rank the preference order. For ranking alternatives, we use the index $c(x_i)$, we can rank them in decreasing order.

3.3.2 CCAs Behaviors

The main behavior of CCAs handles call for proposals to fulfill requirements coming from SDMA. Participants' (CCAs') proposals contain,

essentially, service alternatives costs, ID providers, and the load probability of the managed cloud.

Table 3: Participant behaviour of a CCA.

<i>CNP_CCA_Participant Behavior</i>
Input: (i) <i>call_for_proposals</i> from SDMA
Output: (i) A ranking of CS _i alternatives or a Failure message
1: BlockReceive(<i>call_for_proposals(Reqi)</i>)
2: if (exist (CS _i)) then
3: Prepare and Send Proposal
4: Else
5: Send <i>Failure</i> message
6: Start over

The *Prepare and Send Proposal* step (line 3 of *CNP_CCA_Participant Behavior*) determines the main functionality of CCAs.

The proposal of a CCA is a set of information noted *Rinformation* :

Rinformation = $\langle C_LoadProbability, A\ list\ ranking\ of\ (S_alt_x, ID_provider, C_inf) \rangle$

Where:

- *C_LoadProbability* is the actual load probability of the managed cloud;
- *S_alt_x*: the Xth alternative of S / S is the requested cloud service;
- *ID_provider*: the corresponding provider of the Xth alternative of S;
- *C_inf*: contains the cost of a service alternative.

A list ranking of (*S_alt_x*, *ID_provider*, *C_inf*) is ranked in increasing order according to service cost.

To determine the value of *C_LoadProbability*, we use Discret Time Markov Chain Model (Kemeny and Snell, 1976). We assume that the set of state space of our model is $S = \{G_i; O_i; R_i\}$, where:

- G_i : is the state of the Cloud CL_i when it is underloaded i.e. Green State ($Load \leq \lambda_2$) (cf. Figure 2).
- R_i : is the state of the Cloud CL_i when it is overloaded, i.e. Red State($Load \geq \lambda_1$). .
- O_i : is the state of the Cloud CL_i when it is between the two G and R states, i.e. Orange State ($\lambda_2 < Load < \lambda_1$)

Each cloud has its Discrete Time Markov chain.

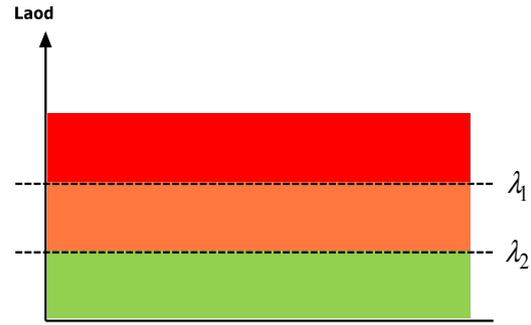


Figure 2: Load states of the cloud.

The state transition probabilities are derived as follows. Given states S_i, S_j , where $i, j= 1...3$ and $(S_i, S_j) \in S$, p_{ij} , is the probability of transitioning for state S_i to state S_j written as $S_i \rightarrow S_j$.

We can distinguish between nine (9) kinds of state transition probabilities, which are (cf. Figure 3):

- G1: is the probability that the cloud still in Green state
- G2: is the probability that the state cloud changes from Green to Orange
- G3: is the probability that the state cloud changes from Green to Red
- O1: is the probability that the cloud still in Orange state
- O2: is the probability that the state cloud changes from Orange to Red
- O3: is the probability that the state cloud changes from Orange to Green
- R1: is the probability that the cloud still in Red state
- R2: is the probability that the state cloud changes from Red to Orange
- R3: is the probability that the state cloud changes from Red to Green

We note that:

$$\checkmark \sum_{i=1..3} G_i = 1$$

$$\checkmark \sum_{i=1..3} O_i = 1$$

$$\checkmark \sum_{i=1..3} R_i = 1$$

These probabilities are used to calculate the frequency (probability) of states, we have three kinds of frequency:

- π_G : frequency of Green State
- π_O : frequency of Orange State
- π_R : frequency of Red State

The $C_LoadProbability$ represents the frequency of Green state(π_G).

Since all states of our Markov Chain model, are in the same recurrent class, then, according to Steady-State Probabilities (Tijms, 2003), the probability to going from state i to state j in n steps is:

$$r_{ij}(n) = \sum_k r_{ik}(n-1)P_{kj}$$

take the limit as $n \rightarrow \infty$ we have the equilibrium equations

$$\pi_G = \pi_G * G_1 + \pi_O * G_2 + \pi_R * G_3$$

$$\pi_O = \pi_O * O_1 + \pi_R * O_2 + \pi_G * O_3$$

$$\pi_R = \pi_R * R_1 + \pi_O * R_2 + \pi_G * R_3$$

$$\pi_R + \pi_O + \pi_G = 1$$

From these equilibrium equations we conclude that π_G is evaluated according the formula (1) below:

$$\frac{G_3(1-O_1)(R_1-R_2-1) + G_2(1-R_1)(O_1-O_2-1)}{(O_1-O_2-1)[G_2(R_3-R_1+1) + (G_1-1)(R_1-R_2-1)] + G_2(1-R_1)(O_1-O_2-1)}$$

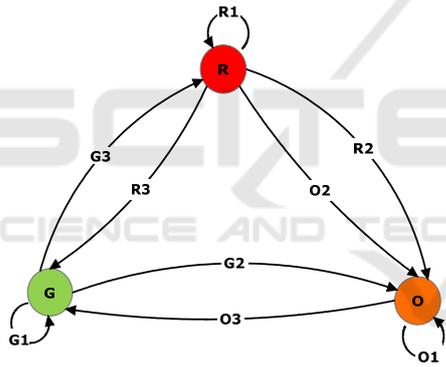


Figure 3: Markov Chain Model.

The resulting Transition Probability Matrix (TPM) is a 3×3 stochastic matrix, shown in Figure 4. Here rows stand for the state the transition originates from, and columns represent states the transition goes to. Each cell in a TPM (cf. Figure 4) represents a p_{ij} , where $p_{ij} = O_i, R_i$ or G_i and $i=1..3$. As in any stochastic TPM, the transition values of all columns in a row must sum to one (1.0).

$$TPM = \begin{pmatrix} O_1 & O_2 & O_3 \\ R_1 & R_2 & R_3 \\ G_1 & G_2 & G_3 \end{pmatrix}$$

Figure 4: Transition Probability Matrix.

Table 4: How to calculate $C_LoadProbability$.

Calculate $C_LoadProbability$ Function
Output: $C_LoadProbability$
1: Calculate π_G according to the formula (1)
2: Return π_G

CNP_CCA Accept Proposal Behavior

In the case when a CCA receives an accept proposal from a SMDA, it must update its TPM according to its state. Here we can distinguish Three cases:

- The case when the load of the cloud is less than λ_2
- The case when the load of cloud is more than λ_1
- The case when the load of the cloud is between λ_1 and λ_2

Table 5: Accept proposal behaviour of a CCA

CNP_CCA Accept Proposal Behavior
Input: Accept Proposal
Output: TPM updated
1: If State Cloud = Green
2: $G_1 \leftarrow G_1 * \pi_G$
3: $G_2 \leftarrow G_2 * \pi_O$
4: $G_3 \leftarrow G_3 * \pi_R$
5: $G_i \leftarrow \frac{G_i}{\sum G_1 + G_2 + G_3}, i=1..3$
6: State Cloud \leftarrow State of transition of $\max(G_i)$
7: If State Cloud = Orange
8: $O_1 \leftarrow O_1 * \pi_O$
9: $O_2 \leftarrow O_2 * \pi_R$
10: $O_3 \leftarrow O_3 * \pi_G$
11: $O_i \leftarrow \frac{O_i}{\sum O_1 + O_2 + O_3}, i=1..3$
12: State Cloud \leftarrow State of transition of $\max(O_i)$
13: If State Cloud = Red
14: $R_1 \leftarrow R_1 * \pi_R$
15: $R_2 \leftarrow R_2 * \pi_O$
16: $R_3 \leftarrow R_3 * \pi_G$
17: $R_i \leftarrow \frac{R_i}{\sum R_1 + R_2 + R_3}, i=1..3$
18: State Cloud \leftarrow State of transition of $\max(R_i)$

The lines 5, 11 and 17 allow to guaranty that $\sum_{i=1..3} X_i = 1$, where $X \in \{G, O, R\}$

4 CONCLUSION

The cloud service selection problem is a challenging research issue because of the tremendous growth in the number of available services, the dynamic environment and changing user needs. In this paper, we have presented our proposed model for the dynamic cloud service selection problem by taking into account two critical criteria: the load balancing through the different clouds, and the minimization of a cloud service cost. We have focused on demonstrating the effectiveness of adopting agent-based techniques, MCDA methods and Markov chain model for Cloud service selection by showing the desirable property that our agents can autonomously and successfully deal with changing service requirements.

To improve our proposed solution, we will address the problem where the selected service is overloaded in an unloaded cloud over the other clouds, this will result response time increasing. Also, we aim to evaluate our approaches more extensively through some case studies.

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