

Clustering Stability and Ground Truth: Numerical Experiments

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Abstract: Stability has been considered an important property for evaluating clustering solutions. Nevertheless, there are no conclusive studies on the relationship between this property and the capacity to recover clusters inherent to data (“ground truth”). This study focuses on this relationship resorting to synthetic data generated under diverse scenarios (controlling relevant factors). Stability is evaluated using a weighted cross-validation procedure. Indices of agreement (corrected for agreement by chance) are used both to assess stability and external validation. The results obtained reveal a new perspective so far not mentioned in the literature. Despite the clear relationship between stability and external validity when a broad range of scenarios is considered, within-scenarios conclusions deserve our special attention: faced with a specific clustering problem (as we do in practice), there is no significant relationship between stability and the ability to recover data clusters.

1 INTRODUCTION

Stability has been recognized as a desirable property of a clustering solution – e.g., (Jain and Dubes, 1988). A clustering solution is said to be stable if it remains fairly unchanged when the clustering process is subject to minor modifications such as alternative parameterizations of the algorithm used, introducing noise in the data or considering different samples. In order to evaluate stability, the agreement between the different clustering results originated by such minor modifications should be measured. Several indices of agreement (IA), such as the adjusted Rand (Hubert and Arabie, 1985), are commonly used for this end.

Some authors warn of a possible misuse of the property of clustering stability noting that the goodness of this property in the evaluation of clustering results is not theoretically well founded: “While it is a reasonable requirement that an algorithm should demonstrate stability in general, it is not obvious that, among several stable algorithms, the one which is most stable leads to the best performance” – ((Ben-David and Luxburg, 2008), p.1.) Bubeck et al., express a similar concern: “While model selection based on clustering stability is widely used in practice, its behavior is still not well-understood from a theoretical point of view”- ((Bubeck et al., 2012), p.436). Therefore, this study

on clustering stability aims to contribute to clarify the role of this property in the evaluation of clustering results.

We focus on the relationship between clustering stability and its external validity i.e. agreement with “ground truth” – the true clusters’ structures that are “a priori” known. Our aim is to obtain new insights based on diverse experimental scenarios.

We analyze diverse clustering results referred to 540 synthetic data sets generated under 18 different scenarios. Synthetic data sets provide straight-forward clustering external evaluation and enable to control for diverse relevant factors such as the number of clusters, balance and overlapping – e.g., (Milligan and Cooper, 1985), (Vendramin et al., 2010), (Chiang and Mirkin, 2010).

2 THE PROPOSED METHOD

2.1 Why Stability?

Clustering stability, along with cohesion-separation, are commonly referred as a desirable properties of a clustering solution.

Cohesion-separation is intrinsically related with the concept of clustering and it can be related with the clusters' external validity - Milligan and Cooper

(Milligan and Cooper, 1985) and Vendramin (Vendramin et al., 2010).

The value of stability is clearly related with the need to provide a useful clustering solution, since an inconsistent one would hardly serve practical purposes. On the other hand, the theoretical value of stability is yet to be understood.

Literature contributions on stability are discussed in Luxburg (Luxburg, 2009) and Ben-David and Luxburg (Ben-David and Luxburg, 2008), for example. These are specifically related with the capacity to recover the "right" number of clusters and to K-Means results. Another perspective of stability is offered in (Hennig, 2007) by measuring the consistency with which a particular cluster appears in replicated clustering - cluster-wise stability.

The lack of a systematical relationship between clusters validity and stability is occasionally pointed out by diverse studies - e.g., (Cardoso et al., 2010). Thus, a systematical study of the relationship between stability and clustering external validity is in order.

2.2 Cross-Validation

In order to evaluate clustering stability cross-validation can be used. Cross-validation referred to unsupervised analysis is described in (McIntyre and Blashfield, 1980).

In this work we resort to the weighted cross-validation procedure proposed in (Cardoso et al., 2010) to evaluate the stability of clustering solutions—see Table 1.

Table 1: Weighted cross-validation procedure.

Step	Action	Output
1	Perform training-test sample split	Weighted training and test samples
2	Cluster weighted training sample	Clusters in the weighted training sample
3	Cluster weighted test sample	Clusters in the weighted test sample
4	Obtain a contingency table between clusters obtained in 2. and 3.	Indices of d agreement values, indicators of stability

The “weighted training sample” considers unit weights for training observations (50% in the data sets considered) and almost zero weights to the remaining (test) observations. The “weighted test sample” reverses this weights’ allocation. The use of

weighted samples overcomes the need for selecting a classifier when performing cross-validation. Furthermore, sample dimension is not a severe limitation for implementing clustering stability evaluation, since the Indices of agreement values are based on the entire (weighted) sample, and not in a holdout sample.

2.3 Adjusted Agreement between Partitions

In order to measure the agreement between two partitions we can resort to indices of agreement (*IA*).

In the literature, multiple *IA* can be found – e.g., (Vinh et al., 2010), (Warrens, 2008). They are generally quantified based on the cells values of the contingency table $[n_{kq}]$ between the two partitions P^K and P^Q being compared with K and Q clusters (respectively) - and on the corresponding row totals n_{k+} and column totals n_{+q} .

Among the *IA*, the Rand index (*Rand*) is, perhaps, the most well-known - (Rand, 1971).

$$Rand(P_I^K, P_{II}^K) = \frac{\binom{n}{2} + 2 \sum_{k=1}^K \sum_{q=1}^Q \binom{n_{kq}}{2} - \sum_{k=1}^K \binom{n_{k+}}{2} - \sum_{q=1}^Q \binom{n_{+q}}{2}}{\binom{n}{2}} \quad (1)$$

It quantifies the proportion of all pairs of n observations that both partitions (P_I^K and P_{II}^K) agree to join in a group or to separate into different groups. Since agreement between partitions can occur by chance, (Hubert and Arabie, 1985) propose an adjusted version of *Rand* using its expected value under the hypothesis of agreement by chance (H_o):

$$E_{H_o} \left[\sum_{k=1}^K \sum_{q=1}^Q \binom{n_{kq}}{2} \right] = \frac{\sum_{k=1}^K \binom{n_{k+}}{2} \times \sum_{q=1}^Q \binom{n_{+q}}{2}}{\binom{n}{2}} \quad (2)$$

Then this *IA* is adjusted according with the general formula:

$$IA_a(P^K, P^Q) = \frac{IA(P^K, P^Q) - E_{H_o}[IA(P^K, P^Q)]}{Max[IA(P^K, P^Q)] - E_{H_o}[IA(P^K, P^Q)]} \quad (3)$$

The adjusted index (IA_a) is thus null when agreement between partitions occurs by chance. Some *IA* are based on the concepts of entropy and information. Among these *IA*, Mutual Information (*MI*) is particularly well-known:

$$MI(P^K, P^Q) = \sum_{k=1}^K \sum_{q=1}^Q \frac{n_{kq}}{n} \log \left(\frac{n_{kq}}{\frac{n_{k+} n_{+q}}{n}} \right) \quad (4)$$

(Vinh et al., 2010) advocate a strategy similar to that of Hubert and Arabie, (Hubert and Arabie, 1985), to adjust MI for agreement by chance. These authors also advocate the use of a particular mutual information form resorting to joint entropy $H(P^K, P^Q)$ – ((Horibe, 1985), ((Krasov et al., 2005))):

$$MIH(P^K, P^Q) = MI(P^K, P^Q)/H(P^K, P^Q) \quad (5)$$

where

$$H(P^K, P^Q) = - \sum_{k=1}^K \sum_{q=1}^Q \frac{n_{kq}}{n} \log \left(\frac{n_{kq}}{n} \right) \quad (6)$$

In this work we use the adjusted indices $Rand_a(P^K, P^Q)$ and $IMH_a(P^K, P^Q)$ to investigate agreement between two partitions. They offer different perspectives on agreement – paired agreement and simple agreement (Cardoso, 2007). These views are meant to provide useful insights when referring to external validation (comparison between the clustering solution and the “true” cluster structure) or to the evaluation of stability (comparison between two clustering solutions deriving from minor modifications in the clustering process).

3 NUMERICAL EXPERIMENTS

The pioneer study of Milligan and Cooper, (Milligan and Cooper, 1985), established the use of synthetic data to support the external validation of clustering structures. In this general setting, clustering solutions are to be compared with *a priori* known classes associated with the generated data sets. Since then, several works referring to external validation of clustering solutions have developed this line of work trying to overcome some drawbacks of this first study such as using the “right number of clusters” to quantify external validity is limited in scope, (Vendramin et al., 2010). Also, overlap between clusters should be properly quantified on the generation of experimental data sets (Steinley and Henson, 2005).

The present research considers three main design factors for the generation of synthetic data sets:

1. balanced (1- clusters are balanced having equal or very similar numbers of observations; 2- clusters are unbalanced)
2. number of clusters (K=2, 3,4)
3. clusters separation (1- poor; 2-moderate; 3- good)

The 18 resulting scenarios are named after the previous coding – for example, the scenario with balanced clusters (1), 3 clusters (3) and moderate separation (2) is termed “132”.

The first design factor is operationalized as follows: balanced settings have classes with similar dimensions and for unbalanced settings classes have the following *a priori* probabilities or weights: a) 0.30 and 0.7 when K=2; b) 0.6, 0.3 and 0.1 when K=3; c) 0.5, 0.25, 0.15 and 0.10 when K=4.

The increasing number of clusters is associated with increasing number of variables (2, 3 and 4 latent groups with 2, 3 and 4 Gaussian distributed variables) and, in order to deal with this increasing complexity, we consider data sets with 500, 800 and 1100 observations, respectively.

The following measure of overlap between cluster is adopted, (Maitra and Melnykov, 2010):

$$\omega_{kk'} = \omega_{k|k'} + \omega_{k'|k} \quad (7)$$

where $\omega_{k'|k}$ is the misclassification probability that the random variable X originated from the k^{th} component is mistakenly assigned to the k'^{th} component and $\omega_{k|k'}$ is defined similarly.

In order to generate the datasets within the scenarios, we capitalize on the recent contribution in (Maitra and Melnykov, 2010) and use the R MixSim package to generate structured data according to the finite Gaussian mixture model:

$$g(\underline{x}) = \sum_{k=1}^K \lambda_k \phi(\underline{x}; \underline{\mu}_k, \Sigma_k) \quad (8)$$

where $\phi(\underline{x}; \underline{\mu}_k, \Sigma_k)$ is a multivariate Gaussian density of the k^{th} component with mean vector $\underline{\mu}_k$ and covariance matrix Σ_k . Therefore

$$\omega_{k'|k} = P \left[\lambda_{k'} \phi(\underline{x}; \underline{\mu}_{k'}, \Sigma_{k'}) > \lambda_k \phi(\underline{x}; \underline{\mu}_k, \Sigma_k) \mid \underline{x} \sim N_p(\underline{\mu}_k, \Sigma_k) \right] \quad (9)$$

Based on this measure, we consider three degrees of overlap in the experimental scenarios: 1) $\omega_{kk'}$ is around 0.6 for poorly separated clusters; 2) $\omega_{kk'}$ is around 0.15 for moderately separated; 3) $\omega_{kk'}$ is around 0.02 for well separated classes (these thresholds are indicated in (Maitra and Melnykov, 2010)).

For each of the referred 18 scenarios, we generate 30 datasets and run our experiments by:

- clustering each data set;
- evaluating stability of the clustering solution (see 2.1 and 0);

- evaluating clustering external validity based on the *a priori* known classes (see 0);
- correlating results from stability and external validity to assess the role of the stability property.

The Rmixmod package is used for clustering purposes (Lebret et al., 2012). EM algorithm is found to be particularly suited for the clustering tasks at hand, since the data generated follow a finite Gaussian mixture model. We use the general Gaussian mixture model - [P_KL_KC_K] in (Biernacki et al., 2006).

The first results obtained are summarized in Table 2 and Table 3. They reveal the pertinence of the design factors, the overlap measure in particular: stability and external validity increase with the increase in separation, the *IA* being close to zero when separation is poor and near one when well separated clusters are considered. In general, the adjusted Rand index and normalized mutual information values illustrate the same underlying reality, although the *MIH_a* values provide a more conservative view of the degree of agreement between two partitions.

The general results referring to the relationship between stability and agreement with ground truth (inter experimental scenarios) are illustrated in Figure 1 and Figure 2. The corresponding Pearson correlation values are 0.958 and 0.933, respectively,

indicating a high linear correlation between stability and external validity (both measured by *MIH_a* in Figure 1 and *Rand_a* in Figure 2). These results corroborate the general theory on the relevance of the property of stability in the evaluation of clustering solutions.

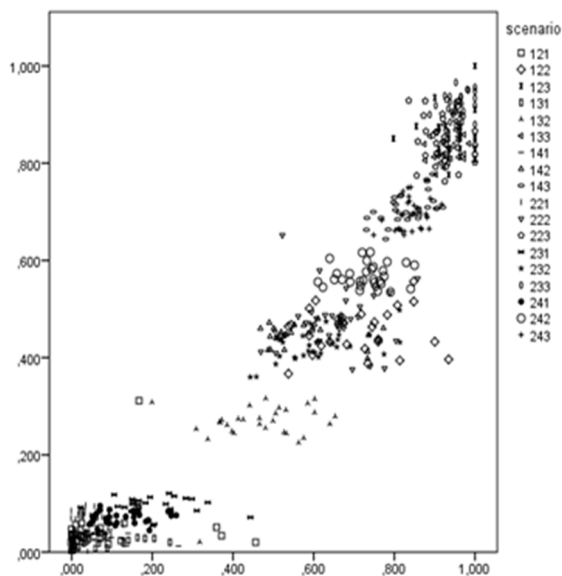


Figure 1: Inter-scenarios Pearson correlation between stability (yy') and agreement with ground truth (xx'): the *MIH_a* perspective.

Table 2: Adjusted Rand index values corresponding to external validity and to stability (values averaged over 30 datasets).

Rand _a	Separation	External validity			Stability		
		K=2	K=3	K=4	K=2	K=3	K=4
Balanced	Poor	0.055	0.038	0.041	0.111	0.118	0.085
	Moderate	0.728	0.388	0.624	0.865	0.652	0.688
	Good	0.963	0.943	0.855	0.987	0.979	0.918
Unbalanced	Poor	0.097	0.211	0.133	0.053	0.280	0.166
	Moderate	0.765	0.690	0.820	0.864	0.822	0.898
	Good	0.962	0.980	0.887	0.981	0.991	0.949

Table 3: Normalized mutual information adjusted values corresponding to external validity and to stability (values averaged over 30 datasets).

MIH _a	Separation	External validity			Stability		
		K=2	K=3	K=4	K=2	K=3	K=4
Balanced	Poor	0.046	0.024	0.031	0.073	0.054	0.073
	Moderate	0.458	0.263	0.449	0.700	0.465	0.578
	Good	0.865	0.832	0.707	0.949	0.931	0.833
Unbalanced	Poor	0.048	0.093	0.070	0.036	0.189	0.124
	Moderate	0.477	0.440	0.569	0.660	0.613	0.732
	Good	0.850	0.920	0.694	0.922	0.957	0.840

Table 4: Intra-scenarios Pearson correlations between stability and agreement with ground truth for synthetic data.

	Separation	MIH _a			Rand _a		
		K=2	K=3	K=4	K=2	K=3	K=4
Balanced	Poor	0.143	-0.018	-0.129	-0.079	-0.155	-0.303
	Moderate	0.122	0.264	-0.015	0.068	0.215	0.111
	Good	0.084	0.222	0.527	0.046	0.177	0.624
Unbalanced	Poor	0.329	0.126	0.172	0.367	-0.42	-0.079
	Moderate	-0.003	0.593	0.084	0.085	0.666	0.084
	Good	-0.151	0.272	0.245	-0.084	0.159	0.218

A completely different view is however provided intra-scenarios were very low correlations between stability and external validity are obtained – see Table 4. Within a specific scenario - the “real deal” for any clustering analysis practitioner - the correlation between external validity and stability is negligible. Both $Rand_a(P^K, P^Q)$ and $MIH_a(P^K, P^Q)$ lead to the same conclusion. Only two exceptions contradict this rule: scenarios “232” and “143”.

consistency of a clustering solution (resisting minor modifications of the clustering process) provide indication towards a greater agreement with the “ground truth” (true structure) of the data?

In order to address this issue, we design an experiment in which 540 synthetic data sets are generated under 18 different scenarios. Design factors considered are the number of clusters, their balance and overlap. In addition, different sample sizes and space dimensions are considered.

Through the use of weighted cross-validation, we enable the analysis of stability, (Cardoso et al., 2010). We resort to adjusted indices of agreement (excluding agreement by chance) to measure agreement between two clustering solutions and also between a clustering solution and the “true” classes: we specifically use a simple index of agreement - the adjusted normalized Mutual Information, (Vinh et al., 2010) - and a paired one - the adjusted Rand index (Hubert and Arabie, 1985).

A macro-view of the results does not contradict the current theory - there is a strong correlation between stability and external validity when the aggregate results are considered (all scenarios’ results).

However, when it comes to perform clustering analysis within a specific experimental scenario, what can we say about the same correlation? The conclusions derived in this case support the previously referred concerns – there is an insignificant correlation between stability and external validity when it comes to a specific clustering problem.

Of course, it is still true that an unstable solution is, for this very reason, undesirable: then, which results should the practitioner consider? However, in a specific clustering setting, there is clearly no credible link between the stability of a partition and its approximation to ground truth.

This work contributes with a new perspective for a better understanding of the relationship between clustering stability and its external validity. To our

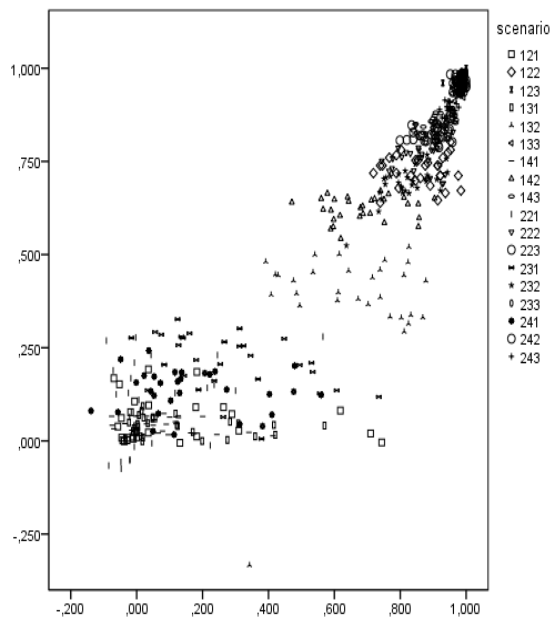


Figure 2: Inter-scenarios Pearson correlation between stability (yy') and agreement with ground truth (xx'): the $Rand_a$ perspective.

4 CONTRIBUTIONS AND PERSPECTIVES

In this work we analyze the pertinence of using stability in the evaluation of a clustering solution. In particular, we question the following: does the

knowledge, is the first time a study distinguishes between the macro view (all experimental scenarios considered) and the micro view (considering a specific clustering problem) and clearly differentiates the corresponding results.

In the future, stability results in discrete clustering should also be assessed and possible additional experimental factors also considered (e.g., the clusters' entropy).

In the future, clustering stability results in real data sets should also be assessed.

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