# Manifold Embedding based Visualization of Signals

Hee Il Hahn

Department of Information and Communications Eng., Hankuk University of Foreign Studies, 89 Wangsan, Mohyun, Yongin, Kyonggi-Do, 449-791, Korea

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Abstract: We address the problem of transforming statistically stationary waveform signals into their intrinsic geometries by embedding them into two or three dimensional space for the purpose of visualizing them. The graph Laplacian based manifold embedding algorithms basically generate geometries intrinsic to the signal characteristics under the conditions that it is smooth enough and sufficient number of patches are extracted from it. Especially, commute time is known to have the properties of shrinking the mutual distance between two points as the number of paths connecting them increases, which makes it possible to align the statistically different patches in the form of curves. Extensive experiment is conducted with speeches and musical instrumental sounds to investigate the relevance of the waveforms to their own inherent geometries.

## **1** INTRODUCTION

If data lies in a higher dimensional space, it is very hard to imagine what it looks like. However, if it is possible to visualize it in a two or three dimensional space, it can be a meaningful clue for a desired output in the area of pattern recognition or machine learning. When data set lies on or close to a linear subspace, PCA(principal component analysis) is most useful and optimal for dimensionality reduction in terms of maintaining maximum variance of the data set. However, when data set lies on a nonlinear space, PCA introduces severe error. The manifold learning algorithms replace PCA on a nonlinear space.

Over last decades, there have been several different embedding algorithms developed for dimensionality reduction in manifold ways. Isomap (Tenenbaum et al, 2000) and locally linear embedding (Roweis and Saul, 2000) are known to be the first manifold learning algorithms. Laplacian eigenmap (Belkin and Niyogi, 2003), based on ideas from spectral graph theory, attempts to represent data points using information involved in the eigenvalues and eigenvectors of the graph Laplacian. The spectral graph theory analyzes how information diffuses with time across the edges connecting nodes via eigenvalues and eigenvectors of the Laplacian matrix of the graph. The general principle of computing an eigenspace is to reduce the complexity

of a problem by focusing on a few relevant quantities and dismissing others. Many authors recently began to consider random-walk based similarity measure on the graph. The hitting time h(i, j) of a random walk on a graph is defined as the expected time for a random walk on a graph to start from a node  $v_i$  to arrive at a node  $v_i$ . However, it may not be symmetric, that is  $h(i, j) \neq h(j, i)$ , which makes it inappropriate for a distance measure between pairs of nodes. An alternative measure for the hitting time is a commute time c(i, j), which is defined as the average time taken for the random walk to travel from node  $v_i$  to reach  $v_i$  for the first time and then return to  $v_i$ , i.e., c(i, j) = h(i, j) + h(j, i). Commute time provides a distance measure between any pair of vertices. (Qiu and Hancock, 2007) showed the commute time can be computed from the Laplacian spectrum using the discrete Green's function. (Taylor, 2011) proposed methods to organize the patches extracted from images or waveform signals according to the graphbased metrics. They showed the embedding of the set of patches based on the eigenfunctions of the graph Laplacian can concentrate even the patches including high frequency components. Their recent studies on the patch graph and its embedding give convincing ideas of analyzing signals from the

 Hahn H.. Manifold Embedding based Visualization of Signals. DOI: 10.5220/0005017801840189 In Proceedings of the 11th International Conference on Informatics in Control, Automation and Robotics (ICINCO-2014), pages 184-189 ISBN: 978-989-758-039-0 Copyright © 2014 SCITEPRESS (Science and Technology Publications, Lda.) geometrical point of view. Although the usual shortest path distance is most common metric on a graph, it may not be always relevant, as mentioned above. The commute time distance, which has been widely used in mathematical chemistry or collaborative recommendation, began to be exploited in the graph based manifold embedding, Our paper starts from the assumption that a given

data set has the embedding result, i.e. its intrinsic geometry, if it is sufficiently correlated. In this paper, we address the problem of transforming statistically stationary waveform signals into its intrinsic geometries by embedding them into low dimensional Euclidean space.

The outline of the paper is as follows: In the next section, we explain how to extract patches from the segment of a signal and construct patch graphs using the patch set. We review the compute commute time embedding in section 3. In section 4, we present experiments and investigate the characteristics of the commute time embedding. We conclude with directions for future research in section 5.

## 2 CONSTRUCTION OF PATCH GRAPH

It is assumed that the signal of interest is given as a finite duration of samples  $\{x[k]\}_{k=1}^{K}$ , where maximally overlapped patches of size *p* samples are extracted around each time sample in the following way:

$$\overline{\mathbf{x}}_{n} = \frac{\mathbf{x}_{n}}{\|\mathbf{x}_{n}\|} \in S^{p-1}, \quad n = 1, 2, \cdots, N$$
(1)

where  $\mathbf{x}_n = (x[n], x[n+1], \dots, x[n+p-1])^T \in \mathbb{R}^p$ and  $S^{p-1}$  represents p-1 sphere. The patch  $\overline{\mathbf{x}}_n$  is obtained by normalizing  $\mathbf{x}_n$  with its magnitude so that it may not be sensitive to changes in the local energy of the signal. In this paper, a patch  $\overline{\mathbf{x}}_n$  is regarded as a vector on the p-1 dimensional sphere embedded on the p dimensional Euclidean space. We define the patch set as the collection of all patches extracted from the signal. Thus, the signal is reformatted as a patch set, with which the graph of patches is constructed.

In order to construct a patch graph, which is a simple, and connected graph organized from the patch set, we need to decide which node be connected with which. Since we may not know the geometry associated with the patch set, we first should investigate whether pairs of nodes  $v_i$  and  $v_j$ be adjacent. A similarity function on the patches is needed to define a meaningful local neighborhood. In this paper, we relate a similarity function, which measures how the nodes  $v_i$  and  $v_j$  are adjacent, to the Euclidean distance, where a Gaussian similarity function is adopted. Thus, the weight along the edge connecting nodes  $v_i$  and  $v_j$ , which are associated with  $\overline{x}_i$  and  $\overline{x}_i$ , respectively, is defined as follows:

$$w(i,j) = \begin{cases} e^{-\|\overline{\mathbf{x}}_i - \overline{\mathbf{x}}_j\|^2/2\sigma^2} & \overline{\mathbf{x}}_i, \overline{\mathbf{x}}_j : \text{connected} \\ 0 & \text{otherwise} \end{cases}$$
(2)

Given a set of patches  $\overline{\mathbf{x}}_1, \dots, \overline{\mathbf{x}}_N$  and some measure of similarity between all pairs of data w(i, j), we can construct a graph by representing each patch  $\overline{\mathbf{x}}_i$ as a vertex  $v_i$  in the graph, where two vertices  $v_i$ and v, are connected if the similarity w(i, j)between the corresponding data points is larger than a certain threshold, and the edge is weighted by w(i, j). There are several popular methods to construct a graph, such as  $\varepsilon$  -neighborhood graph, knearest neighbor graph, or fully connected graph, given a set of nodes. Among them, we adopt a scheme of k-nearest neighbor graph (Brito et al, 1997) in which nodes  $v_u$  and  $v_v$  are connected if  $v_u$ is among the k-nearest neighbors of  $v_{\nu}$  or  $v_{\nu}$  is among the k-nearest neighbors of  $v_{\mu}$ . Computing similarities between pairs of patches allows us to map the patches at the ambient space into some geometry at the embedding subspace.

## **3** REVIEW OF COMMUTE TIME EMBEDDING

Given the adjacency matrix W, whose entries are  $(W)_{uv} = w(u,v)$ , the degree matrix D is computed to be a diagonal matrix with entries  $(D)_{uu} = \sum_{v=1}^{N} w(u,v)$  and the graph Laplacian matrix is defined as L = D - W. It is assumed that a patch graph is connected and undirected. Let  $L = U\Lambda U^T$  be the spectral decomposition of L, where U is the matrix containing all eigenvectors as columns and  $\Lambda$  the diagonal matrix with the

eigenvalues  $\lambda_1, \dots, \lambda_N$ . Denote by  $L^{\dagger}$  the Moore-Penrose inverse of L. Then we have

$$c(i,j) = (z_i - z_j)^T (z_i - z_j)$$
(3)

where

$$z_i = \sqrt{vol} \cdot \left( \frac{u_{i,2}}{\sqrt{\lambda_2}}, \dots, \frac{u_{i,N}}{\sqrt{\lambda_N}} \right)$$
 . If

 $L_{sym} = D^{-\frac{1}{2}}LD^{-\frac{1}{2}}$  is used instead of L,  $LU = U\Lambda$ becomes  $L_{sym}V = V\Lambda'$  where  $\Lambda' = \Lambda D^{-1/2}$  and  $V = D^{-1/2}U$ . Thus,

$$z_{i} = \sqrt{vol} \left( \frac{v_{i,2}}{\sqrt{\lambda'_{2}d_{i}}}, \dots, \frac{v_{i,N}}{\sqrt{\lambda'_{N}d_{i}}} \right)$$
(4)

This allows us to interpret  $\sqrt{c(i, j)}$  as Euclidean distance between two nodes  $z_i$  and  $z_j$  on the embedding subspace.

For the dimensionality reduction, It is not needed to use all the components in the embedding defined by the above equation. We can use only the first qcomponents corresponding to the lower eigenvectors in the following way:

$$z'_{i} = \sqrt{vol} \left( \frac{v_{i,2}}{\sqrt{\lambda'_{2}d_{i}}}, \cdots, \frac{v_{i,q+1}}{\sqrt{\lambda'_{q+1}d_{i}}} \right)$$
(5)

Compare the commute time embedding with a Laplacian eigenmap (Belkin and Niyogi, 2003), defined as

$$y_i = \left(\frac{v_{i,2}}{\sqrt{d_i}}, \cdots, \frac{v_{i,N}}{\sqrt{d_i}}\right)$$
(6)

Likewise, its dimensionality reduction can be done in the following way:

$$y_i' = \left(\frac{v_{i,2}}{\sqrt{d_i}}, \cdots, \frac{v_{i,q+1}}{\sqrt{d_i}}\right) \tag{7}$$

Compared with the entries of  $y_i$ , the entries of  $z_i$  are additionally scaled by the inverse of eigenvalues of  $L_{sym}$  so that the entries with the lower eigenvalues are more stressed.

For the embedding purpose, It is supposed that the graph is connected; that is, any node can be reached from any other nodes of the graph. If this is not the case, the nodes of the graph can be decomposed into several disjoint subsets, which causes the eigenvalues of the Laplacian matrix have values of zero whose multiplicity corresponds to the number of the disjoint subsets. In case of commute time embedding, the coordinates of each node on the graph corresponding to eigenvalues of zero are mapped into zero on the embedding domain.

#### **4 EXPERIMENTS**

Patch sets associated with signals are constructed, where the size of patch is decided experimentally with p = 25 samples. When the commute time embedding is performed on the patch set composed of N patches, each vertex is mapped into an N-1dimensional vector, as shown in Eq. (4) which causes severe burden and makes it hard to get a feel for what the data looks like. In this paper, dimensionality reduction is employed so that the data can be embedded on three dimensional space because it is possible to visualize them on the embedding subspace if the patch sets can be represented on two or three dimensional space.

### 4.1 Investigating the Characteristics of Commute Time Embedding

In Fig. 1, we show an example of the segment of some sinusoidal signal, its PCA embedding and commute time embedding. The segment is composed of 700 samples, from which 676 patches are extracted so that they may be maximally overlapped. In this figure, patches of lower variance are encoded with blue color, while patches of higher variance with red color. Throughout this paper, lower variance means it is less than the median of the distribution of the variances over all patches in the patch set, while higher variance is larger than the median (Taylor, 2011). In PCA embedding, it is meaningless to reduce their dimensionality into three dimensional space, because the embedded points corresponding to the patches are randomly scattered around the three dimensional Euclidean space. It means that one cannot effectively encode the patches of 25 dimensional vectors into three dimensional vectors, because the patches lie on the curved manifold. However, the result of commute time embedding shows that each patch is mapped densely to generate a smooth curve inherent to the characteristics of the signal and even two dimensional space would be enough to represent them without severe loss of inherent information.

Then, we investigate how the number of patches in the patch set affects the embedding results. In order to understand how many patches are needed



Figure 1: An embedding comparison between PCA and commute time of a sinusoidal signal. (a) A sinusoidal signal. (b) PCA embedding. (c) Commute time embedding on three dimensional space. (d) Commute time embedding on two dimensional space.

IENC AN for the commute time embedding to have the intrinsic geometry of smooth curve, we comprise five patch sets, each of which is composed of samples extracted from a chirp signal with varying sample sizes of 700, 800, 900, 1,000, and 1,400. The number of patches for each patch set is 676, 776, 876, 976, and 1,376, respectively. Fig. 2 depicts the embedding of the patch sets associated with chirp signals, whose numbers of patches are varied, using the map given in Eq (5), where q = 3. When the number of patches in the patch set is not sufficiently enough compared with the statistics of the patches, such as correlation among them, the distances between pairs of patches are so randomly distributed that some patches appear to be scattered on the embedding subspace, while others are likely to be aligned along a smooth curve. It is observed that the embedding approaches its intrinsic geometry as the number of patches increases.

Because the patches  $\bar{\mathbf{x}}_n$  extracted from the chirp signal get to contain higher frequency components as *n* increases, more patches are needed for smooth and nearly continuous embedding compared with the signal in Fig. 1, where the sinusoidal is periodic and its patch set is sufficiently correlated. The commute time embedding preserves commute time distance between pairs of patches, which are equal to the mutual Euclidean distance after embedding, so that the distances between pairs of patches should be more densely distributed in order to get the continuous and smooth curve of embedding. That is why the chirp signal needs more than 1,000 patches for the embedding to be a smooth curve of inherent geometry.



Figure 2: Evolution of a commute time embedding as the number of patches extracted from a chirp signal increases. (a) a chirp signal, The number of patches are (b) 676, (c) 776, (d) 876, (e) 976, (f) 1,376.

According to (von Luxburg et al, 2010), however, the commute time c(i, j) between pairs of nodes

 $v_i$  and  $v_j$  for all  $i \neq j$ , converges to

 $vol(G)\left(\frac{1}{d_i} + \frac{1}{d_j}\right)$  as the number of nodes *n* 

increases. This does not reflect connectivity of the graph, just simply reflect the local degree information only. Here,  $d_u = \sum_v w(u,v)$  represents a degree of a vertex  $v_u$ . It means that the time to hit vertex  $v_j$  just depends on  $d_j$  if the number of nodes gets large, regardless of which vertex  $v_i$  the random walk starts from, and the random walk has forgotten where it came from, by the time it is close to vertex  $v_j$ . It is proved that this phenomenon begins to happen even when the number of nodes exceeds 1,000~2,000, depending on the statistics of

the patch set. Thus, we restrict the number of patches should be less than 1,500, to avoid such unwanted situations.

For the comparison purpose, we display in Fig. 3 the approximation errors of Laplacian eigenmap and commute time embedding, when the chirp signal of sample size of 1,400 is used. The approximation error is defined as

$$e_{P}(q) = \frac{\sum_{i,j=1}^{N} \left\| z_{i} - z_{j} \right\|^{2} - \sum_{i,j=1}^{N} \left\| z_{i}' - z_{j}' \right\|^{2}}{\sum_{i,j=1}^{N} \left\| z_{i} - z_{j} \right\|^{2}}$$
(8)

In case of Laplacian eigenmap,  $z_i$  and  $z'_i$  are replaced with  $y_i$  and  $y'_i$ , respectively, which are defined in Eqs. (4)~(7). The approximation errors of commute time embedding are less than those of the Laplacian eigenmap, as shown in Fig. 3. It means that scaling the entries of  $z'_i$  by the inverse of the eigenvalues of  $L_{sym}$  is tantamount to the effect of more energy compaction in the process of embedding, because it is expected the principal components are more stressed.



Figure 3: The approximation errors  $e_p(q)$  of (a) Laplacian eigenmap and (b) commute time embedding.

#### 4.2 Examples of Commute Time Embedding

Based on some understanding of the manifold embedding mentioned above, we assert that the intrinsic geometries for the given waveform signals can be generated using the manifold embedding.

Especially, graph Laplacian based embedding algorithms are shown to generate low-dimensional manifolds (geometries of smooth curves) given the patch sets extracted from the waveform signals.

In order to capture the intrinsic geometries of the musical instrumental sounds, we extract several patch sets from each different segment of the musical instrumental sounds – flutes, violins, cellos, and speech signals – vowels [a:], [o:], [u;], and then embed them on the three dimensional Euclidean



Figure 4: Commute time embedding results of the musical instrumental sounds. (a) flute, (b) violin, (c) cello.

space. It is shown in Fig. 4 some examples of segments from which patch sets of instrumental sounds are extracted and their corresponding commute time embedding.

Flute sounds, as shown in Fig. 4-(a), are very narrow-banded compared with those of violin or

cello sounds, and their embeddings are composed of two circles bounded. A close look at the figures implies the number of circular shapes in the embedding geometry is likely to be related to that of dominant frequency components such as formants of the waveforms. The waveforms are composed of two dominant formants. The waveforms of violin sounds, however, are more dynamic, i.e., have couples of dominant frequency components, compared with those of flutes, and are expected to have more complicated geometric structures, as shown in Fig. 4-(b). Indeed, the statistical distribution of the patch sets extracted from the different segments of the waveform varies according to their spectral variations. For this reason, patch sets, even though they are extracted from the same waveform, may have guite different-looking embedding. We get the similar results with the cello sounds, which are displayed in Fig. 4-(c).

It is shown in Fig. 5 some examples of commute time embedding of the patch sets extracted from the segments of vowel sounds [a:], [o:] and [u;]. As expected from the previous results, we observe the embedding geometries similar to those of instrumental sounds. The results given above strongly support our earlier assertion that the intrinsic geometries for the given waveform signals can be generated using the graph Laplacian based manifold embedding.

## 5 CONCLUSIONS

In this paper, we have explored the use of commute time embedding for the purpose of transforming the segments of some waveforms into their intrinsic geometries. The embeddings corresponding to the patch sets extracted from the dynamic regions of the signals are scattered around some curves. We can reduce such scatterings by smoothing the signals from which patch sets are extracted, or increasing the number of patches in the patch set. As long as the segments of the waveforms are smooth enough for the commute times between pairs of patches to be densely distributed, it can be asserted that commute time embedding generates their own intrinsic geometries corresponding to the waveforms on the embedding subspace. As a future research, we would like to explore its application to pattern classification or speech recognition in a geometric way.



Figure 5: Commute time embedding results of the vowel segments. (a) [a:], (b) [o:], (c) [u:].

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