

Towards Formal Foundations for BORM ORD Validation and Simulation

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Abstract: Business Object Relation Modelling (BORM) is a method for systems analysis and design that utilises an object oriented paradigm in combination with business process modelling. BORM's Object Relation Diagram (ORD) is successfully used in practice for object behaviour analysis (OBA). We, however, identified several flaws in the diagram's behaviour semantics. These occur mostly due to inconsistent and incomplete formal specification of the ORD behaviour. In this paper, we try to amend this gap by introducing so called input and output conditions, which we consider to be the most important first step towards a sound formal specification of the ORD.

1 INTRODUCTION

1.1 Motivation

Business Object Relation Modelling (BORM) is a complex method for systems analysis and design that utilises an object oriented paradigm in combination with business process modelling. It originated at the Loughborough University, UK in 1993. Successful utilisations have been reported and published ever since, mostly in the area of IT and knowledge systems analysis and design (Knott et al., 2003), Object Behavior Analysis (Knott et al., 2000), (Merunka and Merunkova, 2013), Organization Modelling and Simulation (Brozek et al., 2010), ontological analysis (Pergl, 2011) and Business Intelligence (Merunka and Molhanec, 2011). Several other methods and techniques are based on the BORM method, such as FSM-Based Object-Oriented Organization Modelling and Simulation (Merunka, 2012), the C.C Language (Merunka et al., 2008) or a complexity estimation method called "BORM Points" (Struska and Merunka, 2007).

We agree with BORM's authors Knott, Merunka and Polak that there is a need for a simple, yet expressive tool for process modelling – and such a tool is BORM. In our experience, we can fully support (Knott et al., 2000) statement that it is a good approach to "start with a limited set of high level concepts which can subsequently be transformed

into more software-oriented concepts necessary for the construction of a software oriented conceptual model", or – as other work on BORM suggests – into other types of artefacts and interpretations.

We have been using BORM successfully in practice for several years, as discussed in (Struska and Pergl, 2009), that we had an honour to present at ICEIS in 2009. Our professional focus is mostly on analysis and design of enterprise processes and behavioural analysis. Our practical experience led us to develop our own CASE tool to satisfy our needs in practical BORM usage. The first achievements were published in (Pergl and Tuma, 2012). After building a modelling tool that suited our needs, we started working on implementing *simulation* of BORM ORD (Object Relation Diagrams)¹, which is the core of BORM's behaviour aka process description (Knott et al., 2000). We were mostly inspired by Craft.CASE², for – as far as we know – there is no other comparable tool for BORM diagrams simulation available today. Even though, one of BORM authors – Vojtech Merunka – gave a series of lectures on the Craft.CASE development, as witnessed in (Merunka, 2010), it seems, unfortunately, that there is no foundational paper that would explain the simulation semantics and rules in detail.

¹This diagram is called "BOBA" ORD in (Knott et al., 2000), an abbreviation from "BORM Object Behaviour Analysis".

²<http://craftcase.com>

1.2 Goals

As advocated above, the main advantage of the BORM methodology and Object Relations Diagrams in particular is their great practical usefulness. On the other hand, we see one big disadvantage and it is a lack of sound formal foundations which would allow to clearly and precisely define the structure and semantics of ORD and other concepts related to BORM. Nowadays, many of such concepts are understood only intuitively. Therefore, the main goal of our work is to create sound formal foundations for BORM, which would not only help in understanding the semantics of BORM, but it will also help us to implement advanced software tools for this method.

The first results are presented in this paper, which addresses issues related to simulation and execution of the Object Relation Diagrams. The specific goals are:

- to thoroughly describe the semantics of BORM Object Relation Diagrams,
- to identify and discuss the main issues and ambiguities of the ORD semantics,
- to suggest an extension or modification of the ORD such that the above issues can be overcome and
- to start laying down the sound formal foundation for the ORD.

1.3 Structure of the Paper

In section 2 we introduce BORM's Object Relation Diagram, being the focus of our study. We describe the basics of ORD together with minor changes to the meta-model we propose. In section 3 we inspect the semantics of ORD and we try to deal with its basic ambiguities. In section 4 we introduce the concept of input and output conditions which should resolve the described issues. The rest of the paper follows a common structure: Discussion, Related work, Future work and Conclusion.

2 BUSINESS OBJECT RELATION MODELLING

This section introduces the *Business Object Relation Modelling (BORM) methodology*. We limit ourselves just to the Object Behaviour Analysis method (OBA)³, its purpose, advantages and also details with

³For a more thorough description of BORM itself, we refer the reader to the references.

respect to the issues we discuss here. In the following text, we abbreviate BORM OBA to "BOBA", as seen in (Knott et al., 2000).

Since BOBA generally studies processes, it is appropriate to explain our use of the term, in particular given the amount of definitions available in the literature. For the purposes of this work, we stick to the simple, practically-oriented definition provided by ISO 9000:2000:

Definition 1. Process is a set of interrelated or interacting activities that transforms inputs into outputs.

As the term activity has a specific (narrower) meaning in BOBA, we substitute ISO's term *activity* in the definition by *task* in this paper. Thus the term task will have a general informal meaning "something that needs to be done in order to accomplish a particular goal in a process".

2.1 Object Relation Diagrams

BORM methodology introduces *Object Relation Diagram (ORD)* to model processes and perform BOBA. Since in (Knott et al., 2000) only a very brief description of the ORD notation can be found, we start by a thorough description of the basic concepts of this modelling notation (Figure 1).

2.1.1 Participants, States, Activities

The Object Relation Diagram is a graphical description of a process. It is essentially a collection of *participants* (depicted as grey rectangles), which are in turn collections of *states* (white rectangles) and *activities* (white ellipses). Each participant in ORD represents a person, an organization or a system participating in the process. Participants follow the structure of the Mealy's machine (Mealy, 1955). States are thus the primary components of each participant. Each participant has exactly one start state (marked with black arrow) and at least one final state (drawn with double-line border) – this is **our first proposal** for ORD change, as the original syntax uses special symbols for a start state and a final state similar to UML Activity Models, while our concept is completely aligned with the definition of Mealy's machine, where the start state and end states are regular states.

States are connected by *transitions* which are represented as arrows. If two states *A* and *B* are connected by a transition, the participant being in state *A* can continue to state *B*.

On each transition, there may be an activity which describes what is happening when the participant

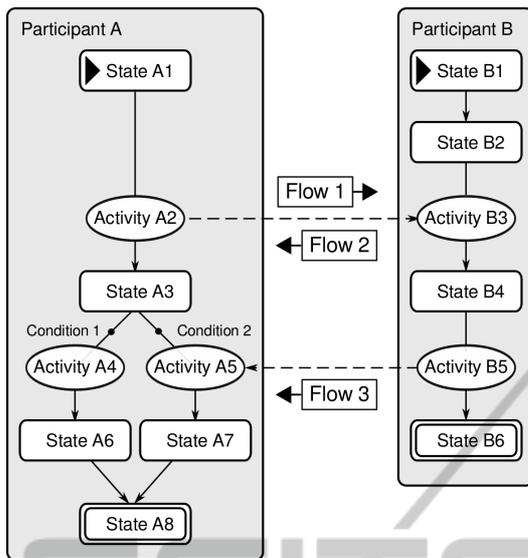


Figure 1: A sample Object Relation Diagram.

transitions from one state to the other. The word “may” represents **our second proposal** for the ORD notation: In the original notation, the activities are required between the states, which is sometimes not wanted – analysts⁴ then invent artificial activities like “no action”, etc. Our proposal is nothing more than incorporating the notion of the ϵ -transition from the theory of finite state machines, i.e. a spontaneous transition from one state into the other.

The purpose of activities is twofold. First, following the semantics of the Mealy’s machine, an activity represents an action which produces some kind of an output. Such an output may or may not be in fact tangible. In the end, an activity may simply be a task⁵ that needs to be done by the participant in order to advance to the next state. The mere fact, that the task was done, is being considered as the output.

2.1.2 Communications and Data Flows

The second purpose of the activities is that they allow participants to communicate with each other. Activities can be connected by *communications* (drawn as horizontal dashed-line arrows). Communications represent channels for sending outputs of an activity of a participant to another participant. Such outputs are called *data flows*. Data flow is information or an artefact that is sent from a participant to another participant. The participant containing the activity with the outward communication arrow is always the *initiator* of the communication. Data flows sent by the initiator

⁴Let us call the person doing the modelling an “analyst”.

⁵We use the term *task* with the meaning explained in section 2.

are called *input data flows*. In reaction, the receiving participant may send *output data flows* back to the initiator.

The original concept of communications in ORD presumes that both initiating and receiving participants must be in the initiating and the respective receiving activity at the same time in order for the communication to take place. We call such a communication *direct*. However, in practical applications of ORD, we often find ourselves in the need for an indirect communications, as well. A direct communication models the situation where two interacting participants need to actually meet each other either personally, over a phone or using some other direct medium. On the other hand, if for example Bob writes an email to Alice, she does not have to wait at the other end to receive it. The e-mail waits for her until she opens it and Bob may in the meanwhile continue in his agenda. Thus, this represents **our third proposal**: the communication may be marked as *indirect*, which means that the initiator does not have to wait until the receiver arrives at his receiving activity and he may go right to the following state. The receiver, on the other hand, always needs to wait, until the respective data flow arrives.

2.1.3 Conditions

Transitions may be also restricted by *conditions*. If more than one transition comes out of a state, a condition may be placed on any number of the transitions. The participant may go forward along a transition only when its condition is met. Example of such a situation is shown in Figure 1. Conditions are used to express restrictions on decisions of participants and they are usually expressed in the natural language.

2.1.4 Other Constructs

So far, we have described the basics of ORD semantics and graphical notation. There are also other, more advanced constructs in ORD. A state, for example, may contain a nested process; Conditions may be placed on communications as well. However, we do not deal with these constructs in this paper, since we identified that they bring serious complexity to the interpretation and simulation of processes.

2.2 ORD Simulation

Apart from structural aspects of ORD, we need to discuss the behavioural aspects. In fact, simulation or execution of processes defined by ORD is the main challenge of our work. As already mentioned in the

Introduction, there is no canonical definition of how the ORD process should be executed. As far as we know, the only implementation of ORD simulation is offered by the Craft.CASE modelling tool.

Figure 2 illustrates the first five steps of simulation of one simple participant, as performed by the Craft.CASE tool. When the participant is in a particular state, or it is performing a particular activity, such state or activity is highlighted with dark grey background. We say that such a state or activity is being *visited*. We see that the participant in the figure faces a decision at the start state *X* and chooses to proceed both of the possible ways simultaneously. We call such parallel ways *branches*. This illustration enables us to inspect the main issues with the simulation of processes defined by ORD.

3 REVISION OF ORD PROCESS BEHAVIOUR

ORD in the BORM methodology is a simple, yet a powerful way of describing and visualising business process. Its semantics can be easily described, especially to people with little technical knowledge in process modelling. That, of course, is a great advantage in the business environment. On the other hand, ORD still suffers from ambiguities in definitions and that, consequently, causes serious troubles especially when process simulation and analysis come to play.

3.1 Decision Making and Parallelism

Let us discuss the ambiguities and issues of the ORD behaviour that we mentioned above. Decision making and parallelism are the fundamental ones. There seems to be a lack of agreement on them. On the one hand, Knott, Merunka and Polak state in (Knott et al., 2000) that “BOBAs process model is strictly based on the theory of finite automata”, namely on Mealy’s machines. On the other hand, Brozek, Merunka and Merunkova explain in (Brozek et al., 2010) that “visual simulation of a business process is based on marked-graph Petri net” – but neither explain how these two different perspectives should merge together into a consistent and sound theoretical foundation and interpretation of the process specified by the ORD.

3.2 The Simultaneity Principle

The basic difference between Petri nets (Peterson, 1981) and Mealy’s machines (Mealy, 1955) lies in the

fact that Petri nets operate on the basis of massive parallelism, whereas Mealy’s machines, when executed, always follow one simple path. The Craft.CASE tool obviously uses Petri nets to simulate processes as documented by Figure 2. However, this approach imposes a serious challenge of an ontologically correct interpretation of the notion of parallelism. From this perspective, we propose a notion of the *simultaneity principle*:

Principle 1. The **simultaneity principle** states that no participant can be split into multiple instances and thus perform several tasks in parallel.

This principle states that even though any participant may *be* in several states at once, no participant can actually *perform* several activities at once. The parallel branches in ORD have, therefore, ontologically this meaning – the activities belonging to different branches do not depend on each other. From that follows that such activities can be done *regardless of order*, which allows one to perform them *virtually* in parallel. Therefore, if a participant is required to do activities in parallel, the actual meaning is that it can choose to do them in any order desired, or switch between doing them, as wanted⁶. It is evident that this concept imposes some constraints on the general behaviour of Petri nets, where multiple parallel tokens are moving independently through the structure of the net. The simultaneity principle is illustrated in Figure 2. If the participant A finds itself in the state *X*, it faces a decision where to go next. In the next step it appears to perform both the following activities at the same time which is, in fact, only a graphical illustration of the principle described above.

Furthermore, it is necessary to ontologically clarify what happens once the participant arrives to the state *F*. For example, if the participant arrives to *F* by the shorter of the two possible branches, should it wait in *F* until the other branch is completed as well? If so, what happens once the participant had chosen only one branch at the state *X*? In such a case the process falls into a deadlock. On the other hand, if we just follow the Petri net behaviour, no merge is performed and we get an ontologically extravagant situation as depicted in 2, where the participant actually arrives to *F* multiple times. This is in direct contradiction with the dependency principle.

The above issue could be solved simply by stating that *F* waits only for those branches, that had been actually chosen. Unfortunately, the nature of this issue seems to be deeper. When creating a process model, the analyst should be given a way to explicitly define

⁶The situation may be compared to the preemptive multitasking of a computer processor.

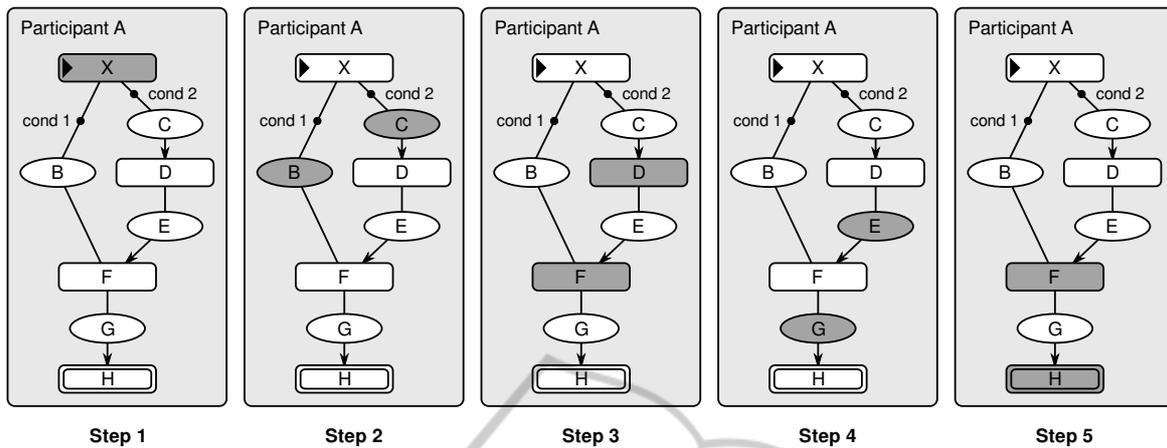


Figure 2: Simulation of a participant facing a decision.

which decisions are valid in a given state and which are not. For instance, executing several branches may not be possible in some situations in the reality. Instead, a process may require that there is precisely one of the possible branches that needs to be completed in order to advance further. Since simultaneous and exclusive choices are both valid in process definition and simulation, we come to the conclusion that neither Mealy's machines, nor Petri nets provide a sufficient formal description of the ORD process behaviour.

3.3 The Dependency Principle

Before we introduce the second principle of ORD semantics, we first need to clarify some terminology. From the perspective of ORD, we talk about states and activities, states being the primary components of a participant in the process. When a transition is made from one state to another, an activity is performed and we say that the participant completed a *task*. To identify that task, we associate it with the state at which the participant has arrived. So the notions of task and state will be synonymous from our point of view.

Above, we already informally touched the notion of the *task dependency*, which is a very essential principle of process definition regardless of particular methodology. The terms “interrelated and interacting” in Definition 1 denote the fact that often several tasks have to be completed prior to completing another task. From now on, we refer to this principle as the *dependency principle*:

Principle 2. The **dependency principle** states that a task A may require other task to be completed before A can be completed.

The rules that determine on which tasks the task A

depends, may be quite complex. Let us have a set of tasks $\{X, Y, Z\}$. For example, the task A may require a completion of *exactly two* tasks from this set. Thus, we need a sufficiently expressive system for specifying such dependency conditions – we introduce such a system utilising boolean algebra in the next section.

4 INPUT/OUTPUT CONDITIONS

Having explained the main challenges, we may start formulating new formal foundations of the ORD. We start by introducing the concept of input and output conditions, which incorporates the dependency principle into the ORD and targets the formalisation of the simultaneity principle.

4.1 Input and Output Conditions

To be able to express the dependency principle in an ORD, we attach an input condition to each state:

Definition 2. **Input condition** of a state is a boolean expression whose variables are the transitions ending in that state. It specifies that the execution of the process cannot advance further from the given state until its input condition is met, i.e. until the corresponding boolean expression is evaluated as being true.

Similarly, each state also has an output condition.

Definition 3. **Output condition** is a boolean expression whose variables are the outgoing transitions from the given state. It specifies admitted combinations of branches into which the process execution may split itself from this state.

Figure 3 shows an example of input and output

conditions allowing precisely two distinct paths through the participant's state graph. State *A* has an output condition which says that exactly one of two possible transitions may be chosen to continue forward. The state *D* has, in turn, an input condition saying, that exactly one branch is allowed to complete.

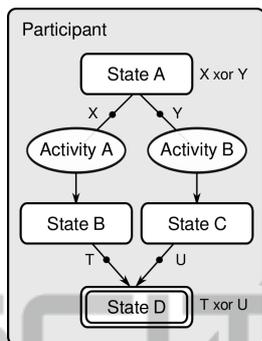


Figure 3: Sample input and output conditions.

The input condition of a state is interpreted as follows: When several branches merge in one state, then this state waits for all of them to complete and only then evaluates its input condition. If the condition is met, the participant may advance to the next state, otherwise the process fails.

The output conditions, on the other hand, ensure that when the process flow splits into several branches, only the appropriate branches are allowed to be chosen, i.e. the branches that do not allow the process to fail – falling into deadlock. Therefore, input and output conditions provide a solution to addressing both the simultaneity and the dependency principles. Since each state waits for all the branches to complete before evaluating its input condition, it prevents the situation, where the participant would split into several independent instances, because one branch took more steps to complete. Moreover, each state now specifies exactly on what branches it depends and thus perfectly expresses the dependency principle.

5 DISCUSSION

The solution of the issues with ORD process behaviour interpretation and simulation proposed here lies in the introduction of the input/output conditions of states. The solution has the following features:

1. Input/output condition are expressions in boolean logic and therefore general and unambiguous.
2. They address both the simultaneity and dependency principle.

3. No additional elements in the ORD are needed, so the diagrams remain clear and simple as was intended by the authors.

6 RELATED WORK

As we stated above, we are not aware of any systematic effort to build formal foundations of BOBA. Given that, our work is very likely quite novel for BORM. However, looking at model execution, simulations and behaviour analysis from a broader perspective, we may identify other attempts similar to ours – and at these, we want to look at now. There are generally two complementary approaches:

1. Start with a formal apparatus and build a practically applicable domain-oriented method and/or tool.
2. Start with a method used in practice and upgrade it into a simulation-able or an executable model.

Starting with the first type of approach, Brand's and Zafropulo's Communicating Finite State Machines are an example. Their purpose was to design communication protocols (Brand and Zafropulo, 1983). The authors took the finite state machines (FSM) theory and upgraded it consistently for modelling several together-bound FSMs. Another example of such an approach is Pattavita's and Trigila's proposal to combine the FSM with Petri nets for modelling communicating processes (Pattavina and Trigila, 1984). Another example is the Jasper tool for workflow modelling and analysis (van Hee et al., 2006); it is based on Petri nets enriched by several practical concepts from the domain of process analysis (hierarchies, choices, roles and others).

The second mentioned approach, i.e. to upgrade an existing method, is exemplified by our work. Kindred spirit to ours is Barjis: he proposed a method for developing executable models of business systems. Barjis' method is based on the DEMO method (Dietz, 2006). To make the static DEMO models executable, Barjis proposed a transformation into Petri nets (Barjis, 2007). His insight has been recently followed by, for instance, Vejrazkova and Meshkat (Vejrazkova and Meshkat, 2013).

We are also aware of similar approaches focused on standard "industry" notations UML and BPMN. In spite of general popularity of these notations, we do not deal with them, as they suffer from vagueness, ambiguities and ontological flaws, as mentioned by e.g. Silver in (Silver, 2011) or Dijkman et al. in (Dijkman et al., 2008). Guizzardi performed a deep analysis of BPMN suitability for expressing simulation

models in (Guizzardi and Wagner, 2011) with quite discouraging results for researchers and practitioners focused on ontological soundness of modelling.

Though we could continue in compiling a list of similar approaches, our goal was just to document that a combination of a practical approach with a robust formal foundation leads to a new level of understanding of modelling methods, improving their expressiveness, power and, ultimately, their usefulness.

7 FUTURE WORK

As implied by the title of the paper, our goal was just to make first steps towards sound formal foundations of BORM. The future work means to specify a complete formalism for ontologically sound execution and simulation of processes defined by ORD. This formalism should encompass the needed features of Mealy's machine and Petri nets, while at the same time not allowing ontologically extravagant situations.

In this paper, we omitted advanced ORD constructs (communication conditions and nested processes). These constructs should be also studied in the future work.

8 CONCLUSION

We described the syntax and semantics of BORM Object Behaviour Analysis (BOBA) – Object Relation Diagrams (ORD). We discussed the main issues and ambiguities of the ORD semantics with the respect to execution and simulation of processes defined by ORD. We proposed minor changes and enhancements for the model. Then, as the first step towards a sound formalisation of BOBA, we introduced the input and output conditions enhancement for states.

Our honest hope is that our contribution may be an inspiration for both BORM practitioners and formalists to join their forces to bring BOBA to a new level of expressive power and possibilities.

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