

# Building an Intelligent Tutoring System for Chess Endgames

Matej Guid, Martin Možina, Ciril Bohak, Aleksander Sadikov and Ivan Bratko

Faculty of Computer and Information Science, University of Ljubljana, Tržaška cesta 25, Ljubljana, Slovenia

Keywords: Intelligent Tutoring Systems, Artificial Intelligence, Education, Problem Solving, Chess Endgames, Chess.

Abstract: We present the development of an intelligent tutoring system for chess endgames, and explain in detail the system's architecture that is comprised of five essential components. The rule-based *domain model* contains a conceptualized domain theory, which serves as a bridge between the basic declarative domain theory and procedural knowledge for concrete problem solving. The *search engine* is used to generate new chess problems and to validate students' solutions on the fly. The *tutoring model* represents pedagogical knowledge and follows the standard model-tracing approach. The *student model* contains the knowledge about the user in the form of a skill meter, aiming to show the level of a student's understanding of particular skills. Finally, the *user interface* is where the interaction between a student and the tutor takes place.

## 1 INTRODUCTION

Several studies have demonstrated benefits of chess in education. Namely, the findings showed that chess can lead to significant progress in problem solving, memory enhancement, focusing, scoring of IQ tests, creativity, critical thinking, visualizing, recognizing patterns, and enhancing meta-cognitive skills (Kazemi et al., 2012). Developing a successful intelligent tutoring system (ITS) for chess endgames would therefore have a significant practical value.

While our primary goal is to develop an efficient intelligent tutoring system that leads to *robust learning*, we deem the secondary goal to be equally important: to obtain a *formative evaluation* of our methods to support automated conceptualization of learning domains (Možina et al., 2012). The purpose of these methods is to partially automate the process of developing ITSs and thus considerably decrease the high costs of building them.

In the present paper, we present the development of the ITS for chess endgames. We describe in detail the architecture of the system and briefly address our future work. Our web-based tutoring application is available at <http://www.ailab.si/chesstutor>.

## 2 ARCHITECTURE

The basic architecture of our chess-endgame tutor is demonstrated in Fig. 1. The tutor uses three types of knowledge for teaching chess endgames:

- expert knowledge about the target chess endgame, stored in the *domain model*,
- pedagogical knowledge about the teaching strategies in this endgame, represented in the *tutoring model*,
- knowledge about the student and his or her learning progress, stored in the *student model*.

The other two components are the *user interface*, where the student and the tutor interact, and a *search engine* that enables the tutor to verify student problem-solving solutions and to generate appropriate feedback when required.

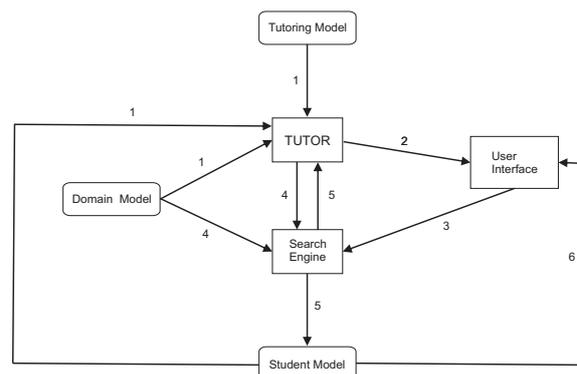


Figure 1: The chess-endgame tutor architecture. The arrows represent the data flow between individual components, and the numbers show the time order of the data interchange in a tutoring session.

### 2.1 A Cycle in the Tutoring Session

In a typical problem-solving session with the student,

the task of the tutor is to present a chess problem (chess position with a suitable goal) with respect to the student's abilities and her current state of knowledge about the domain. For example, if the student has just failed to achieve the given goal from the same position on her previous attempt, the tutor may present additional information in various possible forms (e.g. hints, additional instructions, colored squares and arrows on the chessboard, etc.) to aid the student.

The student's solution to the problem, or a solution step, is received through the user interface. This information is validated on the fly in real-time by the search engine, to verify whether the student's move leads to the achievement of the given goal. If not, the tutor warns the student about the error, and the student can restart the problem or investigate why her solution is inappropriate. The search engine also plays an important role in the selection of a goal to be achieved next. The rules from the domain model are used to identify the candidate goals, and the search engine then evaluates which of these goals are achievable. Based on so-called *malrules* in the domain model, it may also detect possible misconceptions in the student's knowledge.

The output of the search engine represents the basis for the selection of the next tutorial action, and for an update of the student model. The tutor's representation of the student is available to her in a form of a *skill meter*, which represents an estimate of the student's mastery of particular skills (or goals). The skill meter is updated, and the tutor goes to the next cycle.

Fig. 3 displays the user interface of the tutor. On the top of the screen there is the navigation panel that enables switching between *tutor mode* and *play mode* (see Section 2.3 for explanations), access to instructions and example games, and information about the time spent. On the left-hand side there is a large chess board, with navigation buttons and last few moves played below. On the right-hand side there is a space for tutorial actions and the skill meter.

## 2.2 Domain Model

Chess endgames are a *well-defined problem-solving* domain. Even elementary chess endgames can be sufficiently complex and thus interesting to learn. In an endgame of king, bishop, and knight versus a lone king (also known as KBNK), for example, even optimal play in a checkmating procedure may take as many as 33 moves. There are many recorded cases when strong players, including grandmasters, failed to win this endgame.

We use a rule-based domain model. This type

of domain models is typical for *cognitive tutors* that proved to be successful in improving student learning in a range of learning domains (Anderson et al., 1995; Koedinger et al., 1997; Koedinger and Corbett, 2006). The domain model was obtained semi-automatically as a result of *domain conceptualization*, as presented in (Možina et al., 2012) and (Guid et al., 2009).

### 2.2.1 Conceptualization of Domain Knowledge

Conceptualization of learning domains can be viewed as one of the key components in the construction of intelligent tutoring systems. The role of domain conceptualization is as follows. In complex domains, the connection between the basic domain theory (axioms, laws, formulas, rules of the game, etc.) and problem solutions is usually rather complex and hard for a human to execute. Therefore, there is typically a need for an intermediate theory, *conceptualized domain theory*, which serves as a bridge between the basic declarative domain theory and procedural knowledge for concrete problem solving.

In terms of a derivation chain, the basic domain theory (axioms, etc.) logically entails a "conceptualized domain theory," which in turn entails problem solutions. Logically, the basic domain theory also entails problems solutions, but at much higher problem-solving effort. The basic theory is typically "non-operational" for a human (requires excessive computation, or it may be too complex to memorize), whereas the conceptualized theory is "human-assimilable." These relations are illustrated in Fig. 2.



Figure 2: The result of a domain conceptualization. Arrows indicate derivation, and the length of an arrow indicates the complexity of the derivation.

A conceptualized domain is a problem-solving tool for a human, and therefore should be simple and compact, so that it can be understood, memorized, and executed by the student.

Fig. 4 shows a problem state space in a typical problem-solving setting. The circles represent problem states, and arrows represent available actions. In domains of any interest the solution path requires too excessive computation, or it is too difficult to memorize for a student. To alleviate the student's task, we learn intermediate goals that can lead the student reliably towards the solution of the problem (see Fig. 5).

Our rule-based model consists of no more than 11 *production rules*, i.e., if-then statements suggesting goals to be achieved when some conditions are met. They are slightly adapted from (Guid et al., 2009).



Figure 3: The chess-endgame tutor user interface.

Each production rule contains one goal, achievable in  $d$  plies (i.e. half-moves). This *depth* parameter is fixed and is set prior to conceptualization of domain knowledge. It enables to adapt the level of conceptualization to the skill level of a targeted group of students, since it determines to some extent the complexity of learned rules (Mozina et al., 2010).

The goals are achievable in up to  $d$  plies, typically in several possible ways and move orders. The search engine verifies on the fly whether the student's move is correct or incorrect in the sense of achieving the given goal. Moreover, the search engine can also evaluate whether the move is acceptable (in terms of approaching to checkmate) even in cases when it actually fails to achieve of the goal – in such a case the student will receive a different type of feedback as if the move was entirely bad.

### 2.3 Tutoring Model

The cognitive theory underlying our chess-endgame tutor is compatible with the ACT-R learning theory

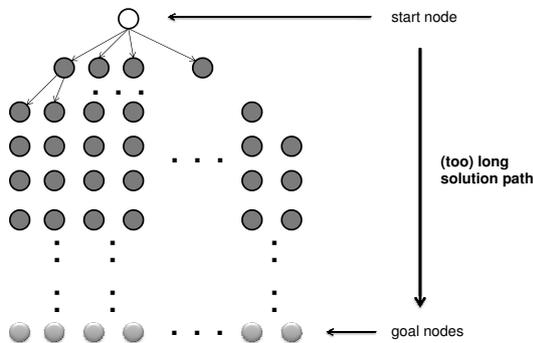


Figure 4: Problem state space in interesting domains.

(Anderson and Lebiere, 1998). The *model-tracing* approach to intelligent tutoring is used: the tutor assesses and interprets students' solution steps by comparing what the student does in any given situation against the appropriate rule in the domain model (Anderson et al., 1995). The production rules guide a student reliably towards the final goal of achieving checkmate within the allowed 50 moves, even with a slowest possible realization of strategic goals (Guid et al., 2009).

The tutor operates in two different modes:

**Tutor Mode.** represents the main learning environment and thus the most important part of the tutor. It enables the student to practice her skills in a problem-solving context, executing suggested goals and receiving feedback by the tutor.

**Play Mode.** enables the student to test or practice her skills in playing the endgame against the computer, without any interventions by the tutor. The student only has basic hints on disposal, given on demand only. No move retracts are possible.

Beside text-based explanations the tutor also has an

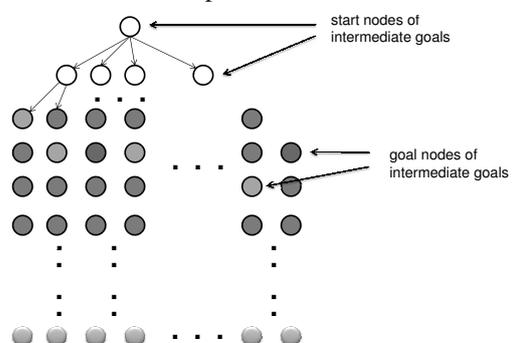


Figure 5: The role of intermediate goals.

option to use colors and arrows on the chessboard display when giving feedback to the student. For example, to mark the squares that limit the area available to the opponent's king.

## 2.4 Student Model

In our chess-endgame tutor, the role of the student model is primarily to help correct "incomplete" student knowledge, and to help diagnose bugs in the student's knowledge. The knowledge is represented in a form of a skill meter (see Fig. 3 on the right side), aiming to show the level of student's understanding of particular skills. Each of the skills corresponds to one production rule in the domain model. We use one of the most popular methods for estimating students' knowledge, that is *Bayesian Knowledge Tracing model* (Corbett and Anderson, 1995). The model uses four parameters per skill, which were in our case tuned arbitrarily with the help from a chess expert and will be continuously updated using student performance data, to relate performance to learning as well as possible. We use an *open student model* to support students in evaluating their own learning (Bull and Kay, 2007). The skill meter may assist the student in making the choice of which skill to focus on: the tutor allows the student to pick a random position featuring the goal associated with particular skill.

## 3 CONCLUSIONS AND FUTURE WORK

We followed some commonly accepted guidelines for building intelligent tutoring systems and applied them to the domain of chess endgames. The tutor is based on a rule-based domain model that represents the result of using our methods for semi-automatic domain conceptualization (Možina et al., 2012).

The main line of the future work is to evaluate the proposed system. This includes both:

- *Summative Evaluation*: to examine the overall educational impact of the tutor,
- *Formative Evaluation*: to assess the effectiveness of the evolving design, in particular with respect to usability of our semi-automatically derived domain model.

One of the features of our web-based application is an ability to record students' actions and times spent on executing them. These data will represent the basis for an assessment of student acquisition of skills and understandings. As another aspect of the evaluation,

we intend to evaluate the applications' usefulness and its pedagogical abilities (Giannakos, 2010).

We also plan to extend the domain model to include several additional chess endgames.

## REFERENCES

- Anderson, J., Corbett, A., Koedinger, K., and Pelletier, R. (1995). Cognitive tutors: Lessons learned. *The Journal of the Learning Sciences*, 4(2):167–207.
- Anderson, J. R. and Lebiere, C. (1998). *The atomic components of thought*. Lawrence Erlbaum Associates, Mahwah.
- Bull, S. and Kay, J. (2007). Student models that invite the learner in: The smili open learner modelling framework. *International Journal of Artificial Intelligence in Education*, 17(2):89–120.
- Corbett, A. and Anderson, J. (1995). Knowledge tracing: Modeling the acquisition of procedural knowledge. *User Modeling and User-Adapted Interaction*, 4(4):253–278.
- Giannakos, M. N. (2010). The evaluation of an e-learning web-based platform. In *Proceedings of the 2nd International Conference on Computer Supported Education*, pages 433–438. SciTePress.
- Guid, M., Možina, M., Sadikov, A., and Bratko, I. (2009). Deriving concepts and strategies from chess tablebases. In *ACG*, pages 195–207.
- Kazemi, F., Yektayar, M., and Abad, A. M. B. (2012). Investigation the impact of chess play on developing meta-cognitive ability and math problem-solving power of students at different levels of education. *Procedia - Social and Behavioral Sciences*, 32:372 – 379.
- Koedinger, K., Anderson, J., Hadley, W., and Mark, M. (1997). Intelligent tutoring goes to school in the big city. *International Journal of Artificial Intelligence in Education*, 8(1):30–43.
- Koedinger, K. and Corbett, A. (2006). Cognitive tutors: Technology bringing learning sciences to the classroom. In Sawyer, R., editor, *The Cambridge handbook of the learning sciences*, pages 61–78. Cambridge University Press, New York.
- Možina, M., Guid, M., Sadikov, A., Groznic, V., and Bratko, I. (2012). Goal-oriented conceptualization of procedural knowledge. In *Lecture Notes in Computer Science*, volume 7315, pages 286–291.
- Mozina, M., Guid, M., Sadikov, A., Groznic, V., Krivec, J., and Bratko, I. (2010). Conceptualizing procedural knowledge targeted at students with different skill levels. In de Baker, R. S. J., Merceron, A., and Jr., P. I. P., editors, *EDM*, pages 309–310.