## **Robust Template Identification of Scanned Documents**

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Abstract: Identification of low-quality scanned documents is not trivial in real-world settings. Existing research mainly

focusing on similarity-based approaches rely on perfect string data from a document. Also, studies using image processing techniques for document identification rely on clean data and large differences among templates. Both these approaches fail to maintain accuracy in the context of noisy data or when document templates are too similar to each other. In this paper, a probabilistic approach is proposed to identify the document template of scanned documents. The proposed algorithm works on imperfect OCR output and document collections containing very similar templates. Through experiment and analysis, this novel probabilistic approach is shown to achieve high accuracy on different data sets.

### 1 INTRODUCTION

Although electronic documents have become prevalent, governments and enterprises still possess a large volume of paper documents. A major task is to digitize, label, and extract information from these paper documents. Many documents used in enterprises and governments are typically derived from templates, especially forms completed by users, e.g., tax forms, medical forms, job application forms, etc. Given a set of templates and a scanned paper document, an open problem is to quickly and accurately identify which template this scanned document was originally derived from (Esser et al., 2011). To solve this problem, a number of systems based on labeled information have been proposed and developed (Cunningham et al., 2002; T. S. Jayram et al., 2006) The labeled information is usually manually generated, making document identification a time-consuming and expensive process. Studies have been performed to use image features to match a scanned document to its template (Hu et al., 2000). Some of these studies still require labeled information (Esser et al., 2011), while others require consistent high-quality data in order to function properly.

Identifying documents in a repository of scanned documents via manual labeling is somewhat inefficient and expensive. Most automatic image processing techniques require clean data making these techniques ineffective in the presence of noise. Another

drawback of those techniques is that they cannot correctly correlate a document to a template when the templates are too similar to each other, which is a serious problem because many form templates in governments and enterprises are near identical. As such, a robust system to automatically identify the originating template of a scanned document is necessary. Once the template has been correctly identified, existing techniques can be utilized to retrieve specific information.

Now, suppose that a scanned document has been successfully matched to its template. To extract information from the scanned document, one of the first steps commonly applied is Optical Character Recognition (OCR). Even though state-of-the-art OCR techniques are highly accurate in recognizing printed words and characters in clean simple-formatted documents, these techniques still are error-prone when the input is noisy or the document-format is complicated. The accuracy of an OCR engine becomes less reliable for documents that have become distorted under scanning, aging, or folding. Furthermore, OCR output tends to be inaccurate when the document contains multiple columns and text of different font types and font sizes.

This paper introduces an efficient method to identify a document to its originating template by utilizing the results generated by OCR. First, the text contained in the templates is retrieved. Then a scanned document image is OCRed. This result is compared

to all the templates' text using a probabilistic model, and the most likely template is selected. The proposed approach works well on noisy documents and does not require manual intervention or labeling. It also works well on both document templates which are significantly different from each other and on document templates which are nearly identical to each other. The approach can be easily incorporated into other OCR techniques to reduce document processing time.

### 2 RELATED WORKS

Document template identification has been studied extensively. In this section we summarize the related work. A survey of the literature quickly reveals that existing approaches fall into two categories: Information Retrieval approaches, and Image Feature based approaches.

### 2.1 Information Retrieval Approaches

To identify the template of a scanned document with information retrieval techniques, the textual information of the document is treated as a query against a database of template documents (Salton, 1986). The template document which has the highest rank is taken as the identification result.

Cosine similarity is a common similarity measurement used in document query or identification. (Press et al., 2007; Tan et al., 2005; Salton et al., 1975). Given two documents represented as term-frequency vectors  $v_1$  and  $v_2$ , their cosine similarity is defined as:

$$similarity\{v_1, v_2\} = \cos(\theta) = \frac{v_1 v_2}{\|v_1\| \|v_2\|}$$
 (1)

These term-frequency vectors can be applied with local and global functions to improve the results in different scenarios.

Singular Value Decomposition (SVD) is another well developed technique that is widely used in document query or identification. There are variations of this technique, namely latent semantic indexing (LSI) (Deerwester, ), probabilistic latent semantic indexing (pLSI) (Hofmann, 1999), and latent dirichlet allocation (LDA) (Blei et al., 2003). SVD based techniques sometimes achieve better results than just using terms for retrieval. Taking a lower rank of SVD can help filter out the noise in the document-term matrix. OCR may recognize some terms incorrectly. These terms tend to appear together within a set of same terms for the documents generated from the same template. SVD can be explored as the fill-in data that do not frequently occur can be filtered out as noise with SVD.

### 2.2 Image Feature Approaches

Image-feature based approaches have also been extensively studied for document template identification. To identify the template of a certain document, different features of the image have been selected, (Lu and Tan, 2004; Hu et al., 2000; Zheng et al., 2005; Jinhui Liu, 2000; Shin et al., 2001). Based on different features in use, different similarity measurements have been proposed. In (Jinhui Liu, 2000) and (Zheng et al., 2005), the image is classified with geometric line information. These methods require image data to be clean and noise-free, and do not work on forms containing free-size cells. Free-size cells are those cells whose sizes will adjust with the filled-in data. Image based approaches cannot work on forms generated with the same form structure but having different contents. The ZoneSeg method used by (Esser et al., 2011) is chosen as representative of image feature approach to compare against our approach. In (Esser et al., 2011), this method has been claimed to have over 98% accuracy.

### 3 PROBLEM FORMULATION

In this section, we formulate the problem of scanned document identification, describe the intuitive approaches, and identify shortcomings in those approaches.

#### 3.1 Problem Definition

A modified bag-of-words representation is used for the document. Each document is treated as a set of strings. This modified bag-of-words representation maintains the frequency of each string occurrence and does not disregard grammar. For example, unlike the traditional bag-of-words representation, this modified representation does not use stemming and does not disregard punctuation.

Let  $N_T$  denote the size of the document-templates set. Each template is denoted as  $T_i$ , with  $i \in [1, N_T]$ . Each template  $T_i$  can be represented as a set  $\overline{T}_i$ :

$$\overline{T}_i = \{s_1^i, s_2^i, \dots, s_m^i\}$$

where  $s_1^i, s_2^i, \ldots, s_m^i$  are the strings that appear in the template  $T_i$ . If a string appears multiple times in  $T_i$ , it is represented once in  $\overline{T}_i$ , and its frequency is recorded. The frequency (or count) of appearance for the strings in template  $T_i$  is denoted by

$$C_i = \{c_1^i, c_2^i, \dots, c_m^i\}$$

Similarly, an unlabeled query document E, i.e., the document needing to be identified, is represented as a set  $\overline{E}$ :

$$\overline{E} = \{e_1, e_2, \dots, e_n\}$$

where the  $e_j$  are the strings that appear in E, and the frequencies of these strings in E are

$$C_E = \{c_1^e, c_2^e, \dots, c_n^e\}$$

The goal is to find the template  $T_k$  that the input document E was derived from, where  $T_k \in \{T_1, T_2, \dots, T_{N_T}\}$ .

**Lemma 3.1.** Suppose the OCR result of E is errorfree. In this case,  $\overline{T}_k \subseteq \overline{E}$ .

We have the case that  $\overline{T}_k \subset \overline{E}$  when the input document E was filled-out by a user or annotated by a fax machine (e.g., adding the timestamp and the fax number). Since E was derived from the template  $T_k$ , all the strings in  $T_k$  will also be in E given that the OCR result is error-free. We can also have the case that  $E = T_k$  in the event the input document E was just  $T_k$  scanned in, without any additional strings added by a user or a fax machine.

In this particular situation, common information retrieval techniques (e.g., cosine similarity) can produce decent results. However, many scanned and faxed documents cannot be OCRed error-free.

**Observation 3.1.** Suppose E is derived from  $T_k$ . It may be the case that  $\overline{E} \cap \overline{T}_{j \neq k} \neq \emptyset$ . Let  $\overline{E} = A \cup B$ ,  $A \subseteq \overline{T}_k$ ,  $B \cap \overline{T}_k = \emptyset$ . One or more of the following cases may hold true:

- 1.  $A \cap \overline{T}_{j \neq k} \neq \emptyset$
- 2.  $B \cap \overline{T}_{j \neq k} \neq \emptyset$
- 3.  $(A \cup B) \cap \overline{T}_{i \neq k} \neq \emptyset$

The first case stems from the fact that the strings which appear in input E may also appear in templates other than  $T_k$  (due to the overlap of strings between templates). The second case stems from strings appearing in E and not appearing in  $T_k$  but appearing in other templates in the set, as a result of filled-in data. The third case can occur when both the first and second cases occur simultaneously.

The challenges of this problem are due to the imperfect output from OCR and the user fill-in data. Our goal is to be able to find the correct template  $T_k$  for E not only when E does not include all strings of  $T_k$ , but also when E contains information appearing on other templates  $T_{j\neq k}$ ,  $j \in [1,N_t]$ , given that templates themselves can be very similar to each other.

Note that a document represented with the traditional bag-of-words model is not desired in this situation. Stemming removes grammatical information, which is useful in our setting. For example, a term

appearing on a template in *singular* form should be treated differently from a term appearing in *plural* form. Comparing documents represented as a sequence of strings or as a sequence of words involves searching a space that is exponentially larger than our representation. Furthermore, for the current problem context, representation considering the order of the words (e.g., *n*-grams) is unsuitable for comparing documents since the OCR output will have errors, and word-order is not guaranteed in complicated document formats.

### 3.2 Intuitive Approaches

Given the problem formulation, there are a few intuitive solutions, which we discuss in this section.

The very direct and intuitive solution for this problem is as follows:

Given  $N_T$  different templates, if every template  $T_i$  has a subset of strings unique to  $T_i$ , i.e., occurring in  $T_i$  and in no other template, then these subsets of strings can be used as signatures. We denote the signature of template  $T_i$  with  $S_i$ . Since  $\forall s \in S_i$ ,  $s \in T_i$  and  $s \notin S_j$ ,  $\forall j \neq i$ , if any of the strings of the signature can be found in the OCR result of E, we can identify the template. This approach is problematic, however.

Depending on the similarities among the templates in the set, the number  $|S_i|$  of uniquely appearing strings differs across templates. For some template sets, we will be able to find many strings that uniquely identify each template. But for other template sets, we might have degenerate cases with no strings to uniquely identify some of the templates. In addition, as the number of templates grows in the set, the size of the signatures tend to become smaller. More importantly, the success of this approach relies on perfect OCR, with all strings from a query document E being extracted correctly. If all the strings in the signature  $S_i$  have been incorrectly recognized, it would not be possible to find the originating template. Furthermore, realistically speaking, there is no control over the information that will be filled-in in the query document E. Thus, we could have the case where E contains strings that are a part of signatures of multiple templates.

Another intuitive solution would be to use cosinesimilarity. If E was derived from the template  $T_k$ , its vector should be close to  $T_k$ 's vector. However, we have two caveats here: First, with OCR errors and user filled-in data, the vector representation of Emight be dramatically different from  $T_k$ , resulting in a large distance between E and  $T_k$ . This may result in a false match when E's vector is closer to another template's vector. Second, if two templates  $T_k$  and  $T_j$  are very similar (i.e., the vector space distance between  $T_k$  and  $T_j$  is very small), we will have the case where we are not able to determine whether E was derived from  $T_k$  or  $T_j$ .

# 4 A PROBABILISTIC METHOD FOR DOCUMENT IDENTIFICATION

In this section, we will discuss how to solve the document identification using a probabilistic approach in detail.

The basic idea of our probabilistic approach is to explore the difference in the feature space of similar templates. To identify the template of an unlabeled document E, both the similarity and the dissimilarity between E and a template  $T_i$  should be considered. The similarity serves as a filter to exclude the templates which E cannot belong to, while the dissimilarity is used to enlarge the differences between similar templates.

#### 4.1 The Probabilistic Method

For a query document E, we first use OCR to extract all the strings and build the set  $C_E$ . If E was derived from the template  $T_k$ , there may be instances where  $E \cap T_k \neq \emptyset$  and  $\overline{E} \cap \overline{T}_j \neq \emptyset$ , for some j and k where  $j \neq k$ . These instances result from two situations (or a combination of these situations, as defined in Observation 3.1). First, the templates may share common strings among themselves, that is,  $\overline{T}_k \cap \overline{T}_j \neq \emptyset$ ,  $k \neq j$ . Second, the input may have been filled with information that was correctly or incorrectly recognized as a string occurring in another template  $T_i$ ,  $(\overline{E} \setminus \overline{T}_k) \cap \overline{T}_i \neq \emptyset$ . For a string s appearing in input E and template  $T_k$ , it is possible that E was derived from  $T_k$ . It is also possible that E was derived from another template  $T_i$ , but the filled-in data in E contained s. To handle this uncertainty, we will use maximum a posteriori (MAP) estimation to estimate the most likely template from which E was derived.

From the set of templates  $\{T_1, T_2, \dots, T_{N_T}\}$ , a union of the set of strings can be obtained, as  $U_T = \bigcup_{i=1}^{N_T} \overline{T_i}$ . Any string that is in E but not in  $U_T$  is ignored. Identifying which template  $T_i$ ,  $i \in [1, N_T]$ , the input E was generated from is equivalent to deciding which template that the  $E' = \overline{E} \cap U_T$  is most likely to follow.

For any string  $e_i \in E'$ ,  $e_i \in U_T$ , the number of times  $e_i$  appears in E' is  $c_i^e$ . Suppose  $e_i$  appears in template  $T_i$ , with its count of occurrence in  $T_i$  being  $c_i^i$ .

The case where  $c_j^i \ge c_i^e$  may be a result of OCR errors with  $e_i$  being incorrectly recognized as other string(s). The case could also be that some of the  $e_i$  in E have been incorrectly identified, as well as some fill-in data containing  $e_i$  have been correctly recognized, but the total number of occurrence is still less than  $c_j^i$ . In the case of  $c_j^i < c_i^e$ , it is possible that all the strings  $e_i$  from template  $T_i$  have been correctly recognized by OCR, and fill-in data containing exact  $c_i^e - c_j^i$  of  $e_i$ , it is also possible that not all  $c_j^i$  occurrences of  $e_i$  are correctly recognized, but the fill-in data containing more than  $c_i^e - c_j^i$  occurrences of  $e_i$  are recognized.

To handle these uncertain situations, two probabilities are defined. In general, we can state that the OCR success in recognizing a string  $e_i$  follows a Bernoulli distribution with probability p. For the template  $T_i$  with  $e_i$  appearing  $c_j^i$  times, while  $e_i$  appears in E for  $c_i^e \leq c_j^i$ , the probability follows a Binomial distribution  $(c_j^i, p)$ . A string  $e_i$  which appears in  $U_T$  follows a Bernoulli distribution with a probability of q that it actually comes from the fill-in data.

Given the input E as an observation and a set of templates  $T_1, T_2, \ldots, T_{N_T}$ , the template that maximizes the posterior probability will be selected as the template that E was derived from. The posterior probability is computed as:

$$\hat{i}_{MAP}(C_E) = \arg\max_{i} p(T_i|C_E)$$

$$= \arg\max_{i} \frac{p(C_E|T_i)p(T_i)}{p(C_E)}$$

$$\propto \arg\max_{i} p(C_E|T_i)p(T_i)$$
(2)

where  $p(T_i)$  is the prior probability distribution of the template  $T_i$ . Based on the particular application, if knowledge regarding which template is more frequent is known, this probability can be assigned. In the case that there is no such prior knowledge,  $p(T_i)$  can be assigned with the Uniform distribution, with  $p(T_i) = 1/N_T$ . This results in the MAP estimator being the Maximum likelihood estimator (MLE).

Now, we discuss how to compute  $p(C_E|T_i)$ . The recognition result of each string in the template  $T_i$  from which E has been derived can be taken as a random variable following a Binomial distribution of  $(c_j^i, p_i)$ . The recognition results of all strings in template  $T_i$  are assumed to be independent identically distributed. The probability of having any string from  $U_T \setminus T_i$ , which is the probability of filled-in data is the same as strings occurring in other templates is q. Then the probability  $p(C_E|T_i)$  can be precisely computed as the combination of these two distributions, which is too complicated. Under the assumptions p >> q,  $p(c_i^e|T_i)$  can be simplified as: if  $c_i^e \leq c_i^i$ , all strings

are considered as being from the template; if  $c_i^e \ge c_i^i$ ,  $c_i^i$  strings are assumed to be from the template, while  $c_i^e - c_i^i$  are strings accidentally falling in  $U_T$ .

$$p(c_i^e|T_i) = \begin{cases} \binom{c_j^i}{c_i^e} p_i c_i^e (1 - p_i)^{c_j^i - c_i^e} & \text{if } c_i^e \le c_j^i \\ p_i^{c_j^i} q_i^{c_i^e - c_j^i} & \text{if } c_i^e \ge c_j^i \end{cases}$$
(3)

Hence, given a template  $T_i$ , the conditional probability of having an observed data as E with its frequency vector as  $C_E$  can be computed approximately

$$p(C_E|T_i) = \prod_{l=1}^{n} p(c_l^e|T_i)$$
 (4)

With Equation 3 and 4, the MAP estimator of template  $T_i$  can be computed. We use the logarithm of the

$$\hat{i}_{MAP}(E) \propto \arg\max\log p(C_E|T_i)p(T_i)$$
 (5)

 $\hat{i}_{MAP}(E) \propto \arg\max_{i} \log p(C_E|T_i)p(T_i)$  (5)
This can be computed faster and avoid the underflow

### **Considerations**

The probabilistic model allows for situations when an important string is not properly recognized by OCR. At the same time, this model leverages the length of the words. The  $p_i$  used in our experiment is obtained by first OCRing the known templates and comparing with the ground-truth on each template and their OCRing output to obtain an estimation of  $p_i$ . It can be argued that this  $p_i$  does not reflect any particular error rate on different input E. However, it is useful to express the relative error rates among the templates.

## **EXPERIMENTAL** PERFORMANCE EVALUATION

In this section, the proposed algorithm is evaluated on two data sets. Some properties of the data sets are discussed first, followed by a brief introduction to other algorithms we compare against. Then the experiment results are shown, followed by detailed evaluation and discussion.

#### **5.1 Data Sets**

Two data sets are used in the experiments, the first data set is the Special database II from the National Institute of Standards and Technology (NIST). This data set contains 12 different sets of tax forms of IRS 1040 Package X for the year 1988 totaling 5,590

IRS tax documents. This data set will be referred to as the NIST-IRS data set. These documents include Forms 1040, 2106, 2441, 4562, and 6251 together with Schedule A, B, C, D, E, F, and SE. These documents have 20 different form faces and are all binary images of consistent quality. These forms have a small pair-wise similarity as shown in Figure 1(a) and 1(b), in terms of both the image feature and the actual string contents they contain.

The other data set contains 4,576 event report forms from the US Food and Drug Administration (FDA). This document set consists of 12 different form faces, which are the actual event reports. These forms are also binary images scanned in different resolutions, from 199dpi to 300dpi. Documents following the same templates were produced at different times, with various fill-in data. Most of the documents are noisy with various skewing angles and annotation. Some of the templates are very similar in term of image layout and string contents, making these difficult to differentiate. Figure 1(c) and 1(d) illustrates a pair of similar templates. JBLICATIONS

#### 5.2 **Comparison Methods**

The detailed implementation and set up for the comparison methods, Cosine Similarity, SVD, and Zone-Seg are explained as follows.

### 5.2.1 Cosine Similarity

Given two documents templates  $T_i$  and  $T_j$ , all terms (i.e., strings) that occur on the whole collection are first collected to obtain the term-frequency vectors  $C_i$ and  $C_i$ , and their cosine similarity is computed with Equation 1.

As the term frequency cannot be negative, similarity between  $T_i, T_j$  is bounded in the interval [0,1]. When  $T_i$  and  $T_j$  have no common terms,  $similarity\{T_i,T_j\}=0$ , and if  $T_i,T_j$  are exactly the same, then  $similarity\{T_i, T_j\} = 1$ . To use cosinesimilarity to identify the template of a document, each document template is represented as a term-frequency vector  $C_i$  ( $i = 1, 2, ..., N_T$ ). The dimension of these term frequency documents is the total number of distinct terms that appear on the whole set of templates. For each unlabeled test document E, the corresponding term frequency vector  $C_E$  is computed. The similarities between the test document and the templates similarity $\{E, T_i\}$  are computed. The template  $T_i$  with the largest cosine-similarity to the unlabeled test document is taken as the matching template.

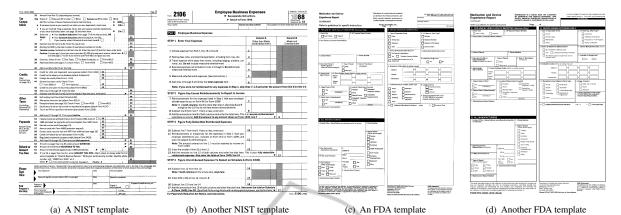


Figure 1: Sample NIST and FDA templates. Notice (a) and (b) are significantly different while (c) and (d) are quite similiar.

#### **5.2.2** Singular Value Decomposition

The Singular Value Decomposition (SVD) approach is implemented as follows. All terms on templates  $T_1, T_2, \dots, T_{N_T}$  are used to generate the term document matrix. We have experimented with several common weighting functions. The two weighting functions which give the best accuracy were used in the experiment. The log weighting function is used as local weighting function. It is defined as: for term iin template  $T_i$ , the weighting  $l_{i,T_i} = \log(c_i^J + 1)$ , with  $c_i^J$  being the count of occurrences of term i in template  $T_i$ . The global weighting used is the Entropy weighting function, which is reported to work well with LSI. A term i's global weighting is computed as  $g_i = 1 + \sum_j \frac{p_{i,T_j} \log p_{i,T_j}}{\log N_T}$ , where  $p_{i,T_j} = \frac{c_i^j}{c_i^{UT}}$ , and  $c_i^{UT}$  is the total count of occurrences of term i in the whole collection UT. All ranks of singular values have been tested, and the half rank and full rank results are reported.

### 5.2.3 Image feature similarity / ZoneSeg

Each template  $T_i$  and the input document E are treated as an image, and grids are superimposed on the images with size  $m \times n$ . For each small patch of the image, if the black pixels on the patch exceed over a threshold  $K_{threshold} = 5\%$ , the patch is represented as 1, and 0 otherwise. Then, according to the same sequence, the image can be represented as a string consisting of 0s and 1s. The similarity between a template  $T_i$  and an input document E is defined with the Levenshtein distance between the two strings. The more visually similar the two images are, the smaller the Levenshtein distance will be. The Levenshtein distance between the test document E and each template  $T_i$  is computed, and the template that minimizes the distance is taken as the identified template. Different

image patch sizes are also experimented with, and the size m=36 pixels, n=24 pixels, which renders the best results, is used in the experiment.

### 5.3 Experiment Design

The experiment was conducted on a set of Intel Core Duo machines, using Python 2.7, and MatLab 2009b. For OCR, we used the open-source Tesseract 3.01 project.

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### 5.4 Results and Analysis

In this section, we compare the performance of our approach with cosine similarity, SVD, and ZoneSeg. The performance is reported in terms of accuracy. We evaluate the accuracy of a document identification algorithm based on two metrics: total accuracy and average accuracy on each template. The total accuracy  $ACC_t$  of an algorithm is defined as the ratio of number of documents which are correctly identified and the total number of documents. The average accuracy on each template  $ACC_a$  is defined as the average accuracy on documents from each template. While the  $ACC_t$  accuracy demonstrate the overall performance of each method on the data sets respectively, the template-wise average accuracy  $ACC_a$  shows the algorithm robustness towards different templates. The corresponding results on NIST-IRS and FDA data set are shown in Fig. 2 and 3 respectively.

From Figures 2 and 3, we make the following observations

- All algorithms achieve good results on the NIST-IRS data set.
- 2. For the NIST-IRS data set, all algorithms achieve 100%  $ACC_t$  accuracy and  $ACC_a$  accuracy, as expected, except for ZoneSeg. However, the result

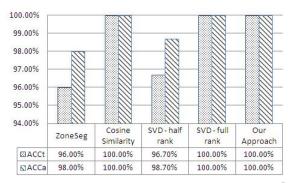


Figure 2: Performance on the NIST-IRS data set.

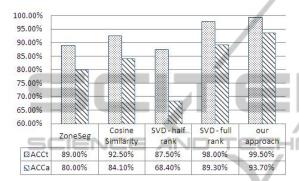


Figure 3: Performance on the FDA data set.

of ZoneSeg algorithm is still consistent with the reported results in (Esser et al., 2011).

- 3. For the FDA data set, our algorithm achieves the best *ACC<sub>t</sub>* accuracy and *ACC<sub>a</sub>* accuracy.
- 4. SVD methods performs better on full rank than on half rank on both data sets.
- 5. For the NIST-IRS data set,  $ACC_a$  result is better than  $ACC_t$  with all algorithms. For FDA data set,  $ACC_t$  result is better than  $ACC_a$  consistently for all algorithms.

The first observation is expected: the accuracy of document identification algorithms depend on the data sets. When the difference of different templates in the data set is significant, it is easier to identify the template. Hence, the accuracy will be high. Since the NIST-IRS data set's templates are significantly different both in image level and contents, high accuracy for most algorithms was expected.

The second observation indicates that the differences between different templates are significant. Both the algorithms based on OCR output and the algorithms based on image level features achieve good results, all being over (98%). However, the algorithms based on OCR output achieve better accuracy than algorithms based on image level features because the difference in string level features is more significant than the difference in image level features. The

NIST-IRS data set also has less fill-in data in common, which makes the test images easier to be identified using image level features. However, the noise on the image, including the scanning skewing and translation, still affects the accuracy.

The third observation indicates that the proposed probability-based algorithm works very well even on the templates that are very similar. Because this approach considers both the reward on the evidence of an unlabeled test document being any of the templates, it also penalizes the dissimilarity with probability. Unlike other algorithms that mainly measure similarity between a query and a template, our model measures both the similarity and the dissimilarity between a query document and a template. The accuracy of cosine similarity and SVD methods is not as good as our algorithm because they do not have a penalty mechanism, and cannot consider the possibility of a match on a string occurring when the fill-in data coincides with the term used in another template. The accuracy of the ZoneSeg is lower on the FDA set, indicating that the performance of ZoneSeg is sensitive to the quality of the document and the similarity between templates.

The fourth observation indicates that full rank SVD works better than smaller ranks. As in most information retrieval task, usually only few ranks are used to approximate the data in feature space, which is accurate enough. However, a fewer rank does not approximate the full rank that well for this task.

The last observation indicates an important result. Since  $ACC_a$  is the average of the accuracy for each template, in the case that an algorithm performs consistently on all templates, the two metrics should give the same result. However, when the number of samples for each template differs, the accuracy of the same algorithm differs across different template detection result; so, the two metrics have different values. For the NIST-IRS data set, the accuracy  $ACC_a$ is consistently higher than the accuracy measurement  $ACC_t$ . This is because the accuracy of several templates, whose sample sizes are smaller, all algorithms still give a high accuracy, most of which is higher than the templates with larger sample size. However, for the FDA data set, there are a few templates with small sample sizes, and the accuracy for these templates are lower. The templates that are harder to identify have a smaller number of test documents. Note that our probabilistic approach has the smallest decrease in accuracy from  $ACC_t$  to  $ACC_a$  among all methods, which indicates that our method is more consistent across different templates.

We also studied the 23 failed cases out of the 4,576 tests in the FDA data set and found that the failed

cases generally fall into two situations: 1. The images are severely malformed (e.g., more than half of the document was not scanned), and only the identical portions of the images are kept and OCRed; 2. For a pair of templates, which share almost the same structure, having 10 or fewer different words, the test was unable to determine the template, given that the scores computed by Equation 5 for the pair were too close. Simply choosing the maximum score results in incorrect classification. To handle these cases, a threshold on the likelihood should be set based on application and similarity among the templates. Any test file whose likelihood is below this threshold should be verified manually.

With respect to speed, the experiments show that our method's speed is comparable to cosine similarity and SVD, and ZoneSeg has a varied speed depending on the size of the patch. In the experiments, the image patch size that gives the best accuracy is significantly slow, since a general test image will be converted into a string having a length greater than 5,000. This results in the Levenshtein distance computation to take a long time to execute.

# 6 CONCLUSIONS AND FUTURE WORK

A probabilistic method of identifying document templates for noisy scanned document has been studied. This method works well with low accuracy OCR results produced from noisy documents. Through experiment and analysis, the proposed method is shown to perform consistently across different template sets, and works well even when document templates are very similar. We recognize that certain documents will contain, in addition to text, non-text content for which our technique does not apply. It is the intent that the technique in this paper will be incorporated into larger application systems that handle both text recognition (our technique) and non-text recognition (image feature-based techniques).

Our future research will focus on incorporating other image features-based techniques with our methods and identifying fill-in data automatically based on the proposed method.

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