

FOOD TEXTURE ESTIMATION FROM CHEWING SOUND ANALYSIS

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Abstract: In recent years, an increasing number of people have been suffering from over-weight, indicating the importance of a balanced dietetic lifestyle. Researches in nutrition and oral health have raised the importance of not only calorific consumption, but also eating habits quality such as the regularity of meals, eating speed, and food texture. A new model for the estimation of food texture by analyzing chewing sound collected from a wearable sensor is presented in this paper. The proposed model combining effective sound features extraction and classification methods make it possible to estimate quantitatively detailed texture of food a person is eating. The model has been implemented and shown being efficient (more than 90% accuracy) to estimate three food texture indices at eight detailed levels for each, with little influence of individual chewing differences.

1 INTRODUCTION

Recently, over-weight, which is related to people's lifestyle, is increasing dramatically among all ages groups, and it has been proved to be related to many other diseases such as hypertension (Hoffmans et al., 1989), heart diseases, and diabetes (Abraham et al., 1971). A balanced and appropriate diet leads to a low risk of overweight and obesity. Healthcare specialists identify the regularity of meal times, number of mastication cycles, and types of foods eaten as essential factors in evaluating eating habits. Eating habits are usually examined by meal stability, intake of sweets and soft drinks, intake of fruit and vegetables.

The importance of food texture people eat in daily life was pointed out directly. Food texture does not only affect the appetite of the eater, but is also related to eater's health condition such as dental health. As the teeth function differs from the age to age, and also differs from the people to people, the eating habits related to food texture are important factors of certain health condition such as dental diseases, which also increase the risk of obesity (Hung et al., 2003; Kohyama et al., 2003). Moreover, the texture of food eaten is not only correlated to dental diseases, but directly contributes to obesity. Oka et al. have reported that food texture affects energy metabolism, and so

influence over-weight, since food that is harder for the stomach to break down (hard, crunchy, or crispy food), will cause a slight elevation of body temperature as the stomach churns and burns calories (Oka et al., 2003). Many researches focus on daily monitoring of eating habits using wearable sensors, such as mastication counting and eating sound mapping (Nishimura and Kuroda, 2008), meal-related activities classification (Amft et al., 2005), and so forth. However, the groups of food with other texture properties could not be clearly classified.

In this paper, we report the development of a new model for quantitative estimation of food texture from chewing sound. This paper is organized as follows. In section 2, data analysis methods for model construction are introduced. The model construction is demonstrated in section 3, and the model validation is shown in section 4. Finally, the conclusions are presented in section 5.

2 DATA ANALYSIS METHODS

In this section, the methodology applied to build-up the model is illustrated, and the data analysis methods proposed for model implementation are introduced in

detail.

2.1 Data Analysis Methodology

The data analysis methodology applied to build-up a model for monitoring food texture people eat using chewing sound is proceeded in the following two steps:

- Define food texture indices that can be estimated from sound features
- Build a model to quantitatively estimate defined food texture indices

2.2 Methods

In this sub-section, we present in detail the methods that are composing the chewing sound data analysis model we propose including food texture definition, and food texture estimation model.

2.2.1 Eating Sound Chews' Segmentation

The eating sound is firstly segmented to single chews for the following process. The methods for chews segmentation is demonstrated as follows.

The sound signal is cut into 20ms frames for extracting chew pattern, then the chew patterns are extracted using the amplitude differences accumulation function, which can be expressed as written in formula 1.

$$ADA_n = \sum_{m=(n-1) \times N+1}^{n \times N} |x(m) - x(m-1)|, \quad (1)$$

where x represents the sound signal, n the frame number, and N is the number of sampling points in each 20ms frame.

Then, the signal is smoothed using a butterworth low pass filter with the fixed parameters of 4th order and 2.5Hz cut off frequency, considering the reasonable maximum chewing cycles per second is limited by the physical mechanics of the mandible. Finally, the detecting the local minima allows to separate consecutive chews.

2.2.2 Chew Features Extraction using Wavelets

Wavelets are a mathematical tool that can be used to extract information from many kinds of data, such as those from audio and images. In this study we used a discrete wavelet transform (DWT) (Morlet, 1984).

Two groups of coefficients can be obtained using wavelet decomposition, such as approximate coefficients and detail coefficients. Several statistical quantities of detail coefficients were adopted as features in

this research. Features were extracted for each sound sample from ten levels of wavelet decomposition, using Daubechies basis 5 (db5). Seven statistic properties of detailed coefficients issued from wavelet decomposition were used to finally extract features for each sound samples. The seven statistical properties are summarized in Table 1.

Table 1: Statistical parameters for extracting features from Wavelet transform detailed parameters.

| Serials | Statistic features |
|---------|---|
| 1 | Mean value of coefficients |
| 2 | Standard deviation of coefficients |
| 3 | Ratio of mean values of adjacent sub-band |
| 4 | Power of wavelet coefficients |
| 5 | Max. value of coefficients |
| 6 | Min. value of coefficients |
| 7 | Range of coefficients |

2.2.3 Chew Features Clustering using Self-Organizing Maps (SOM)

Self-organizing maps (SOM) is a type of artificial neural network that is a kind of clustering method. The "feature maps" realized can effectively used for discovering the patterns under high-dimensional data. This method can be used to project and visualize high-dimensional signal spaces on such a two-dimensional display. More detailed explanation can be found in the book (Kohonen, 1997).

2.2.4 Features Set Optimization using mRMR

Feature selection would be helpful to reduce the dimensions of features as well as improve the accuracy of classification as there are redundancies in extracted features (Zhu and Guan, 2004; Unler et al., 2010). The function called mRMR developed by Hanchuan et al. was adopted in this research to select features to enable all wavelet-extracted features to be ranked regarding both their relevance and information content (Peng et al., 2005).

2.2.5 Chew features Pattern Recognition using Hidden Markov Model (HMM)

An hidden Markov model is well known in the application field of temporal pattern recognition such as speech, gesture, and bio-informatics.

HMM parameters can be trained by given sequences using Baum-Walch algorithm, the unknown sequences can be classified by calculating the likelihood that each trained HMM model gives to it.

3 MODEL CONSTRUCTION

In this section, the experiment equipment and data preparation are firstly described. Then the targeted food texture estimation using sound is defined by using SOM, and finally the HMM model for food texture estimation for eating habits monitoring is constructed.

3.1 Wearable Sensing Device for Chewing Sound Recording

A prototype of a wearable sensing system to analyze eating habits using a bone-conduction microphone (Vibraudio EM20 from TEMCO Corp.) shows in Figure 1 was developed in our previous work to record internal body sounds signal (Shuzo et al., 2010). The sound signals used to analyze eating habits using internal body sounds were recorded with an IC recorder (LS-10 from Olympus Corp.).

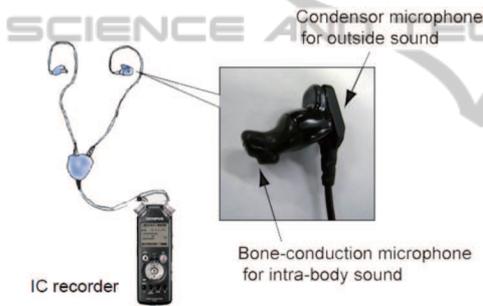


Figure 1: Wearable sensing device developed for eating habits analysis.

3.2 Data Collection

Experiments were conducted to collect data for model construction. The following shows the list describing experimental conditions.

- 15 participants.
- 6 food types: banana, rice ball, salad, rice cracker, fruit jelly, marshmallow.
- The quantity of food intake for one chewing process is not defined, participants can eat according to their will.
- Variety kinds of food with different textures are included in the experiments.
- Participants eat five times for each food type in the experiments.

Through this experiment, we can obtain 450 sound files for establishing the model for food texture estimation. The first three chews are adopted for con-

structing the model, and the whole database are divided into three parts that each part contains five people's data used for defining the targeted food texture, training the HMMs model, and model validation.

3.3 Targeted Food Texture Identification Using SOM

Food texture refers to those qualities of a food that can be felt with tongue, palate, or teeth (e.g. crunchy crackers, crispy salad, soft banana, etc.). It is usually measured by some specific equipments, producing a map defining various food texture indices as shown on Figure 2. In this sub-section, we present how we proceeded to identify the targeted food texture indices that may be estimated using sound.

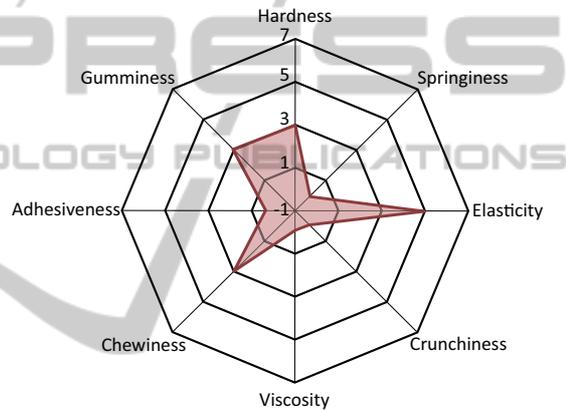


Figure 2: Example of a map conventionally used for food texture measurement by texturometer. Texture definition for cabbage (Yoshikawa and Okabe, 1978).

The targeted food texture is identified using a clustering method called self organizing map (SOM), which is effective to visualize high-dimensional features. We adopted the results from SOM in two aspects, one is the U-matrix to obtain the information of clusters, and the other is the labeled matrix to extract the knowledge about clusters content. The results are illustrated in Figure 3, the information on the U-matrix in this figure is from the the labeled results shown in the right. From this clustering result, we defined the targeted food texture indices that can be analyzed from chewing sound in Table 2.

Table 2: Targeted food texture indices in the estimation model.

| Texture index | Described food textures |
|---------------|----------------------------|
| Hardness | Hard (H) ↔ Soft (S) |
| Elasticity | Elastic (E) ↔ Plastic (P) |
| Crunchiness | Crunchy (Cc) ↔ Crispy (Cp) |

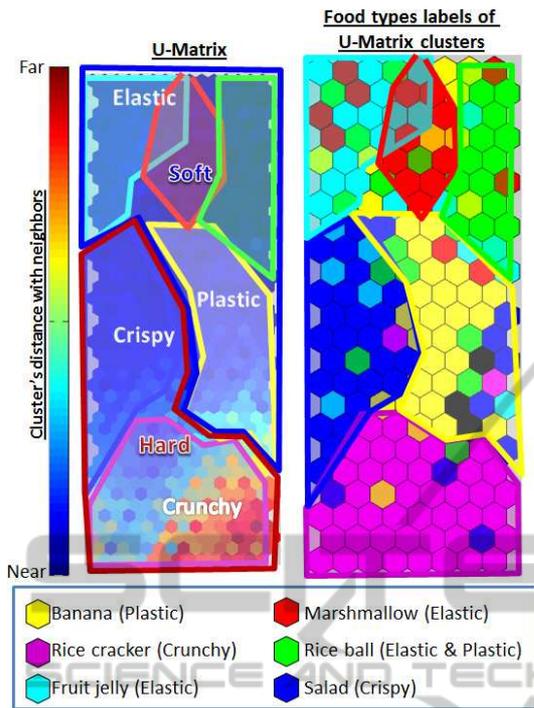


Figure 3: SOM results with U-matrix in the left and labeled information in the right. The distance in N-dimensions of a cell with its neighbors is represented through color gradation from blue for small distance to red for great distance.

3.4 Feature Selection for Model Construction

The features are extracted using five levels wavelet decomposition, and the features are obtained from several statistic parameters shown in Table 1. The features are selected using both SOM and mRMR. First the features are selected based on the results from SOM that has obvious clusters, and then top two features ranked by mRMR are selected according to different food texture indices. The six features set selected based on SOM is {F2.5, F2.6, F2.7, F5.5, F5.6, F5.7}. The features are demonstrated in the following format.

$$F(num1).(num2), \tag{2}$$

where *num1* is the decomposition number and *num2* is the serial number of the statistic parameters for extracting the features in Table 1. The effective features set selected from mRMR is {F2.5, F5.5}.

3.5 Model Construction using HMMs

The model is constructed for estimating the detailed food texture, which reference measurements are extracted from Yoshikawa et al. (Yoshikawa and Okabe,

1978). In each level, the detailed food texture index is estimated into eight levels from 0 to 7. For example, there is eight levels from 0 to 7 equivalent to soft to hard according to hardness index in Table 2. Six kinds of foods with variety food textures were selected for the experiments.

For food texture estimation, we adopt a HMM with 2 states and 25 outputs illustrated in Figure 4. Figure 5 illustrates the output symbols of HMM. The output symbols is fixed by selecting two-dimensional features, the features are extracted using 10ms data in one chew and normalized by using logistic normalization method, and then the symbol is selected by referencing the position shown in Figure 5.

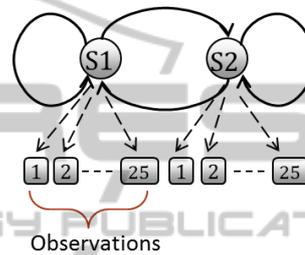


Figure 4: HMM model with 2 states and 25 outputs.

| | | | | |
|----|----|----|----|----|
| 21 | 22 | 23 | 24 | 25 |
| 16 | 17 | 18 | 19 | 20 |
| 11 | 12 | 13 | 14 | 15 |
| 6 | 7 | 8 | 9 | 10 |
| 1 | 2 | 3 | 4 | 5 |

Figure 5: Output symbols of HMM.

The learned HMMs are illustrated in Figure 6. Each level of different textures are trained by the training data. Then the unknown sequences, which are the representation a single chewing sound through features, can be recognized by using this learned HMMs.

4 MODEL VALIDATION

In this section, the model was validated based on the data from the experiment.

4.1 Strategy

According to the situation that the food texture will change during the eating process, the food texture is validated using the first three chews. The HMM

Table 3: Overall accuracy of targeted food texture estimation.

| Food texture index | Hardness | Elasticity | Crunchiness | Overall |
|---------------------|----------|------------|-------------|---------|
| Estimation accuracy | 88% | 95% | 97% | 93% |

Table 4: Detailed accuracy of targeted food texture estimation according to individual differences.

| Subject No. | Accuracy | | | |
|-------------|----------|------------|-------------|---------|
| | Hardness | Elasticity | Crunchiness | Overall |
| 1 | 78% | 80% | 100% | 86% |
| 2 | 84% | 100% | 93% | 92% |
| 3 | 94% | 100% | 100% | 98% |
| 4 | 90% | 93% | 97% | 93% |
| 5 | 92% | 100% | 93% | 95% |

Table 5: Detailed accuracy of targeted food texture indices estimation according to food types differences.

| Food type | Food texture indices accuracy | | | |
|--------------|-------------------------------|------------|-------------|---------|
| | Hardness | Elasticity | Crunchiness | Overall |
| Banana | 76% | 84% | 100% | 90% |
| Rice ball | 92% | 100% | 100% | 97% |
| Salad | 88% | 100% | 84% | 91% |
| Rice cracker | 84% | 100% | 96% | 93% |
| Fruit jelly | 92% | 100% | 100% | 97% |
| Marshmallow | 76% | 100% | 100% | 92% |

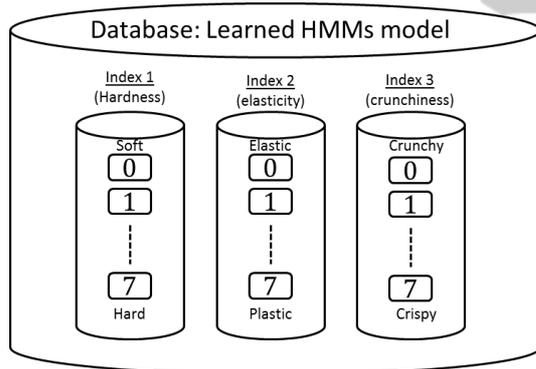


Figure 6: Structure of HMM learning for food texture estimation.

model is trained using 5 persons database, and another 5 persons database is used for validating the learned model. Since for wearable monitoring, eating sound signal is adopted for food texture analysis. But the variation is large using sound since the signal is affected by the strength and direction of the closing mandible when people are chewing, the texture estimated is influenced. However, in order to maintain the meaningfulness of the food texture estimation by using sound for daily life eating habits monitoring, the objective is to measure the food texture with the error less than miss-recognized to the adjacent texture level in the learned database. Concrete validation procedures are demonstrated in the following.

- Train HMMs using the features demonstrate the first three chews in each sound based on 5 persons database
- Calculate the predicted food texture level by round the averaged predicted label of the first three chews of each eating sound
- Calculate the accuracy of food texture estimation by the rule that predicted food texture level should be within the error less than miss-recognized to the adjacent level in the learned database

4.2 Results

The model is validated from the aspect of overall accuracy as well as detailed accuracy for each food type and individual. The overall results of targeted food texture are shown in Table 3. Table 4 and 5 illustrates the detailed accuracy according to individuals and different food types.

4.3 Discussion

From the analysis results, the possibility of using sound as a media to estimate food texture for wearable eating habits monitoring is proved. The method we develop is robust with little variance for different food types and individuals according to the detailed results. The results for hardness estimation is lower than others two, the reason is mostly because of there

are more detailed food textures under it as shown in Figure 3, from the knowledge of the labeled plot, the food texture elasticity is mostly inside the soft part and food texture crunchiness is mostly inside the hard part.

5 CONCLUSIONS

Common ways for food texture measurement is to use equipments that cannot be used for continuous eating habits monitoring. However, it is very important to monitoring eating habits by observing the food texture of foods people eat in daily life.

In this paper, the possibility of estimating food texture in daily life monitoring is explored, and a model of detailed food texture estimation using sound for wearable eating habits monitoring is developed. The proposed model's efficiency has been validated, showing an high accuracy and a good stability for different individuals and different food types with variety of food textures.

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