# A METHOD TO IMPROVE THE ACCURACY OF PROTEIN TORSION ANGLES

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Abstract: Protein structure prediction (PSP) is an open problem with many useful applications in disciplines such as Medicine, Biology and Biochemistry. As this problem presents a vast search space where the analysis of each protein structure requires a significant amount of computing time, it is necessary to propose efficient search procedures in this very large space of possible protein conformations. Thus, an important issue is to add vital information (such as rotamers) to the process to decrease its active search space –rotamers give statistical information about torsional angles and conformations. In this paper, we propose a new method to refine the torsional angles of a protein to remake/reconstruct its structures with more resemblance to its original structure. This approach could be used to improve the accuracy of the rotamer libraries and/or to extract information from the Protein Data Bank to facilitate solution of the PSP problem.

### **1 INTRODUCTION**

Proteins have important biological functions such as the enzymatic activity of the cell, attacking diseases, transport and biological signal transduction, among others. They are chains of amino acids whose sequences determine their 3D structure after a folding process. Moreover, as in almost all cases, the functionality of proteins is exclusively determined by their corresponding 3D structure, there is a high interest in knowing a reasonably accurate 3D structure for any given protein.

The experimental determination of the 3D structure of a protein using methods such as X-ray crystallography and nuclear magnetic resonance (NMR) is usually complex and costly. As a result, less than a 0.6% of the protein sequences included in UniProt (UniProt, 2008) have a known structure in the PDB (Protein Data Bank) (Zhang and Skolnick, 2005; RCSB, 2009). Toward solving this problem, an alternative approach, called Protein Structure Prediction (PSP), is used to take advantage of present computing capabilities to determine/predict the 3D structure of a protein given its sequence of amino acids (Lesk, 2002). There are 20 different amino acids. Each amino acid can be divided into two main areas: backbone and side-chain. All amino acids have the same backbone, but different side-chains to individualize them. A protein is a chain of amino acids where the junction between amino acids is provided by their backbones. Figure 1 shows a sample protein with its amino acids' backbones and side-chains.



Figure 1: Torsion angles in a sample amino acid.

To store attributes and characteristics of proteins, it is necessary for them to be effi-

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Figure 3: (a) A real protein's structure, (b) its PDB structure with noticeable noise in atom positions, (c) torsion angles extracted from the PDB, (d) remade protein with very different structure because of cumulative noises.



Figure 2: Representation of a torsion angle in the bond *b* from two points of view.

ciently/mathematically represented. All-atom 3D coordinates, main-atom 3D coordinates, backbone atoms coordinates and side-chain centroids, and torsion angles are typical approached deployed for this purpose. As a general rule, representations based on 3D coordinates have the common problem of not always being able to reconstruct feasible proteins based on their restored 3D information. In contrast, torsion angles can always represent valid protein conformations when correct bond lengths and static angles are available or assumed. Hence, torsion angles are mainly used to reconstruct and represent proteins. In this case, each amino acid has 3 torsion angles in the backbone ( $\phi$ ,  $\psi$  and  $\omega$ ) and a variable number of torsion angles in the side-chain (0 to 4 depending on the amino acid). Therefore, for a medium-size protein with 60 amino acids, the number of torsion angles can vary between 180 and 420.

The Protein Data Bank contains all known protein structures obtained by traditional procedures such as X-Ray and NMR. Although these methods are assumed to obtain/calculate proteins' structures with RMSD (Root Mean Square Deviation) of around 2 Å –depending on the size of the protein–, PDB files always have some level of noise in their 3D coordinates. Although such noise affects all atoms of a protein, overall shape of the constructed protein is usually fairly similar to the real protein. Figure 2 represents a torsion angle between three atom bonds *a*, *b*, and *c*; and, equation 1 demonstrate how such torsion angle is mathematically calculated. In this equation: *a*, *b* and *c* are vectors in  $\Re^3$ , '×' is the vectorial product, '.' is the dot product, and *atan*2 computes arc tangent with two parameters and returns the principal value of the arc tangent of y/x in radians.

$$\phi = atan2(|b|a \cdot [b \times c], [a \times b] \cdot [b \times c])$$
(1)

Although it seems fairly easy to reconstruct a protein based on its torsion angles, the affecting noises in these torsion angles usually result in constructing a protein with a considerably different 3D structure compared with its real protein. Here, to represent accurate 3D structure of all atoms for an amino acid with more than 20 atoms, 60 real variables –three coordinates per atom– is needed. Therefore, if only value of five torsion angles are used to reconstruct this protein, a large amount of information must be presumed. In this case, reconstructing not only involves the use of protein's torsion angles but also fairly accurate presumptions of its known bond lengths (mostly fixed) and angles.

This work presents a method to minimize the difference between the original and the remade/reconstructed protein by optimizing torsion angles so that they absorb most noises in known angles and lengths. Thus, the optimized torsion angles can be used to extract useful information to facilitate future PSP procedures. To present our work, section 2 describes our procedure, section 3 demonstrate our experimental results followed by conclusions in section 4.

## 2 PROCEDURE FOR TORSION ANGLES REFINEMENT

Whenever torsion angles mathematically obtained/calculated are deployed with known angles and bond lengths, the differences between 3D structure of the original protein and its remade/reconstructed



Figure 4: (a), (b) and (c) correspond to (a), (b) and (c) in Figure 3, (d) optimized torsion angles, (e) remade/reconstructed protein using optimized torsion angles with more resemblance to the original protein.

one is considerably large. For instance, as shown in Figure 3, a small amount of error in one part of the protein can easily cause large errors in other parts. This problem is even worsen –through increment of cumulative noises– when most procedures that use torsion angles assume the ideal value of 180 degrees for their omega torsion angles. Figure 4 shows how optimizing torsion angles to absorb the noise can result in remaking/reconstructing a more similar protein to its original PDB file compare with the one remade using only the mathematically computed torsion angles extracted from the data bank (Figure 3).



Figure 5: Steps of our proposed procedure to optimize torsion angles values.

Figure 5 presents the main steps of our proposed procedure in this work to refine the torsion angles. This procedure (1) uses the PDB file along with the known bond lengths and fixes angles of the protein structure as they are not heavily affected by noise similar to the rest of torsion angles in a PDB file; and then, (2) applies an optimization procedure (either a gradient descent process or an evolutionary strategy) to find the best set of torsion angles. It is also worthwhile mentioning that having torsion angles that can fairly represent a protein plays an important role in extracting its statistical information to summarize its attributes. Therefore, if a protein cannot be fairly remade/reconstructed from its torsion angles, its statistical analysis would also be based on noisy information. and thus not very reliable.

Although 3D shape of a protein from a PDB file could be significantly different from its remade version given its torsion angles, their difference can be overcome sometimes as it is is mainly causes by the accumulative behavior of a large number of small errors. Therefore, initial value of each torsion angle variable must be fairly close to its optimal value, however must be further adjusted to absorb the noise. Therefore, the best strategy to refine torsion angles seems to be based on local searches. In this work, we designed our algorithm based on two local search algorithms: (1) the gradient descent algorithm to benchmark our results, and (2) the CMA-ES (Covariance Matrix Adaptation Evolution Strategy) (Kern et al., 2004; Hansen, 2006) as one of the best local search algorithms reported to date.

### **3 RESULTS**

Proteins 1PLW, 1CRN, 1UTG (RCSB, 2009) and T0513 (CASP8) are used to gauge the performance of our algorithm in this work. The protein 1PLW, also known as enkephalin, has 5 amino acids with 22 torsion angles, 1CRN has 46 amino acids with 194 torsion angles, 1UTG has 72 amino acids with around 342 torsion angles, T0513 has 69 amino acids with 338 torsion angles, and T0496 has 120 amino acids with 674 torsion angles to optimize. To obtain reliable results, each method is deployed for more than 20 times; we observed less than 3% deviation in their results. Table 1 shows that our procedure managed to reduce noises of 1CRN, 1UTG, and T0513 for more than 70%, 80%, and 90%, respectively. Depending on the time and the local search algorithm, different torsion angles qualities were obtained.

Figure 6 shows a very challenging case of T0496

Protein	Original	CMAES	Time (hours)
1PLW	0.908	0.789	0.23
1CRN	1.627	0.474	5.00
1UTG	4.862	0.610	6.70
T0513	7.215	0.715	6.56

Table 1: RMSD between real protein and remade protein, using original torsion angles and optimized torsion angles.

with 120 amino acids from PDB where the cumulative noise managed to result in a significantly different protein structure –i.e., the remade proteins using the original torsion angles result in a completely different protein. Here, using our proposed algorithm, the remade/reconstructed protein is much more similar to the real protein: in both cases of considering and not considering ideal omega angles.



Figure 6: Improvements in remaking the T0496 protein. Each figure is a match of a real protein with a remade protein using: [left] mathematical torsion angles; [right] optimized torsion angles obtained with CMA-ES; [top] considering omega torsion angles; [bottom] ignoring omega torsion angle by setting them to their ideal values of 180 degrees.

In summary, results reveal that the less torsion angles available, the less improvement could be achieved by our procedure. This is mainly because, in short proteins (with less than 20 amino acids) that not many errors exists, remake/reconstructed proteins could fairly resemble the overall structure of the original protein; whereas, in large proteins (more than 100 amino acids) that accumulative errors are dominant, small amounts of correction in one torsion angle can significantly improve the quality of the remade/reconstructed protein to manifest better resemblance.

#### **4** CONCLUSIONS

This work presents a framework to refine torsion angles to remade/reconstruct more resemblant proteins with similar 3D structures with their original proteins from Protein Data Bank (PDB). This method deploys local search algorithms such as gradient descentbased approaches and/or evolutionary strategies to incorporate information in PDB to solve the infamous Protein Structure Prediction (PSP) problem. Simulation results of our algorithms showed that it can effectively reduce the accumulative noise behavior of reconstructing proteins using their stored torsion angles in PDB. Although reconstruction of small proteins could also be improved (around 70%) using our approach, the level of improvement in large proteins was much more significant (more than 90%). This framework can result in significantly more accurate 3D representation of proteins in PDB; and therefore, can have very positive impacts in solving the PSP problem.

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