

PROLONGATION RECOGNITION IN DISORDERED SPEECH USING CWT AND KOHONEN NETWORK

Ireneusz Codello, Wiesława Kuniszyk-Jóźkowiak, Elżbieta Smółka and Adam Kobus
Institute of Computer Science, Maria Curie-Skłodowska University, pl. Marii Curie-Skłodowskiej 1, Lublin, Poland

Keywords: Kohonen network, Automatic prolongation recognition, Waveblaster, Neuron reduction, CWT, Continuous wavelet transform, Bark scale.

Abstract: Automatic disorder recognition in speech can be very helpful for the therapist while monitoring therapy progress of the patients with disordered speech. In this article we focus on prolongations. We analyze the signal using Continuous Wavelet Transform with 22 bark scales, we divide the result into vectors (using windowing) and then we pass such vectors into Kohonen network. We have increased the recognition ratio from 54% to 81% by adding a modification into the network learning process as well as into CWT computation algorithm. All the analysis was performed and the results were obtained using the authors' program – "WaveBlaster". It is very important that the recognition ratio above 80% was obtained by a fully automatic algorithm (without a teacher). The presented problem is part of our research aimed at creating an automatic prolongation recognition system.

1 INTRODUCTION

Speech recognition is a very important branch of informatics nowadays – oral communication with a computer can be helpful in real-time document writing, language translating or simply in using a computer. Therefore the issue has been analyzed for many years by researches, which caused many algorithms to be created such as Fourier transform, Linear Prediction, spectral analysis. Disorder recognition in speech is quite a similar issue – we try to find where speech is not fluent instead of trying to understand the speech, therefore the same algorithms can be used. Automatically generated statistics of disorders can be used as a support for therapists in their attempts at an estimation of the therapy progress.

We have decided to use a relatively new algorithm – Continuous Wavelet Transform (CWT) (Akansu and Haddar 2001, Coddello and Kuniszyk-Jóźkowiak 2007, Nayak 2005), because by using it we can choose scales (frequencies) which are most suitable for us (Fourier transform and Linear Prediction are not so flexible). We have chosen the bark scales set, which is, besides the Mel scales and the ERB scales, considered as a perceptually based approach (Smith and Abel 1999). The CWT result is divided into fixed-length windows, each one is

converted into a vector and such a vector is passed into the Kohonen network. Then we use a simple algorithm on the Kohonen output to determine if this window contains prolongation or not. This way we obtain the list of the windows in which prolongations occurred.

After creating recognition statistics we decided to add a few algorithm improvements which significantly increased the recognition ratio.

2 CWT

2.1 Mother Wavelet

Mother wavelet is the heart of the Continuous Wavelet Transform.

$$CWT_{a,b} = \sum_t x(t) \cdot \psi_{a,b}(t) \quad (1)$$

$$\psi_{a,b}(t) = \frac{1}{\sqrt{a}} \psi\left(\frac{t-b}{a}\right) \quad (2)$$

where $x(t)$ – input signal, $\psi_{a,b}(t)$ – wavelet family, $\psi(t)$ – mother wavelet, a – scale (multiplicity of mother wavelet), b – offset in time.

We used Morlet wavelet of the form (Goupillaud, Grossmann, Morlet, 1984-1985):

$$\psi(t) = e^{-t^2/2} \cdot \cos(2\pi \cdot 20 \cdot t) \quad (3)$$

which has center frequency $F_C=20\text{Hz}$. Mother wavelets have one significant feature: length of the wavelet is connected with F_C which is a restraint for us. Morlet wavelet is different because we can choose its length and then set its F_C by changing the cosines argument.

2.2 Scales

For frequencies of scales we decided to assume a perceptually based approach – because it is considered to be the closest to the human way of hearing. We choose Hartmut scales (Traunmüller 1990):

$$B = \frac{26.81}{1+1960/f} - 0.53, f - \text{freq. in Hz} \quad (4)$$

The frequency of each wavelet scale a was computed from the equation

$$F_a = F_C F_S / a, F_S - \text{sampling frequency} \quad (5)$$

Due to the discrete nature of the algorithm, it was not always possible to match scale a with scale B perfectly (Table 1).

Table 1: 22 scales a (and scale's shift b) with corresponding frequencies f and bark scales B .

a [scale]	f [Hz]	B [bark]	b [samples]
46	9586	21,7	23
57	7736	20,9	29
68	6485	20,1	34
83	5313	19,1	42
100	4410	18	50
119	3705	17	60
140	3150	16	70
163	2705	15	82
190	2321	14	95
220	2004	13	110
256	1722	12	128
297	1484	11	149
347	1270	10	174
408	1080	9	204
479	920	8	240
572	770	7	286
700	630	6	350
864	510	5	432
1102	400	4	551
1470	300	3	735
2205	200	2	1103
4410	100	0,8	2205

2.3 Smoothing Scales

Because CWT values are similarity coefficients between signal and wavelet, we assumed that the sign of its value is irrelevant, therefore in all computations modules are taken – $|CWT_{a,b}|$. We went one step further and we smoothed the $|CWT_{a,b}|$ by creating a contour (see Figure 2)

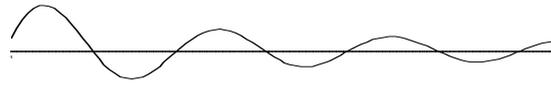


Figure 1: Cross-section of one $CWT_{a,b}$ scale.

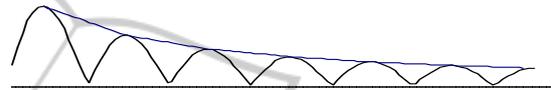


Figure 2: Cross-section of one $|CWT_{a,b}|$ scale and its contour (smoothed version).

2.4 Windowing

Thus now we have spectrogram consisting of 22 smoothed bark scales vectors. Then we cut the spectrogram into 23.2ms frames (512 samples when $F_S=22050\text{Hz}$), with a 50% frame offset. Because every scale has its own offset – one window of fixed width (e.g. 512 samples) will contain different number of amplitudes (CWT similarity coefficients) in each scale (see Figure 3), therefore we take the arithmetic mean of each scale's amplitudes.

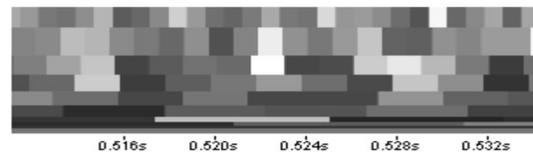


Figure 3: One CWT window (512 samples when $F_S=22050\text{Hz}$).

From one window we obtain the vector V of the form:

$$\vec{V} = \{ \text{mean}(|CWT_{46}|), \text{mean}(|CWT_{57}|), \dots, \text{mean}(|CWT_{2205}|), \text{mean}(|CWT_{4410}|) \} \quad (6)$$

Such consecutive vectors are then passed into the Kohonen network.

3 KOHONEN NETWORK

The Kohonen network (Kohonen T, 2001, Garfield

S. 2001) (or "self-organizing map", or SOM, for short) was developed by Teuvo Kohonen. The basic idea behind the Kohonen network is to establish a structure of interconnected processing units ("neurons") which compete for the signal. While the structure of the map may be quite arbitrary, we use rectangular maps.

Let assume that:

- Kohonen network has K neurons
- n is dimension of each input vector X
- each element $x_i \in X$ is connected to all K neurons, so we have $K \times n$ connections. Every connection is represented by it's weight w_{ij} , $i=1..n$, $j=1..K$ which are adjusted during the training.

We use the Kohonen network to convert 3-dimension CWT spectrogram into 2-dimension winning neuron contour (Szczurowska and Kuniszyk-Józkowiak, 2006, 2007)

3.1 Learning Algorithm

The basic training algorithm is quite simple:

- select the input vector from the training set – we could take consecutive vectors, or take them randomly
- find the neuron which is closest to the given input vector (i.e. the distance between $W_j = \{w_{ij} : i = 1..n\}$ and X is a minimum). The metric can be arbitrary, usually Euclidean, where the distance between the input vector and i -th neuron is defined:

$$d_i = \sqrt{\sum_{j=1}^n (x_j - w_{ij})^2}, \quad (7)$$

- adjust the weight vectors of the closest node and the nodes around it in a way that they move towards the training data:

$$\vec{W}_j = \vec{W}_j + \alpha(\vec{X} - \vec{W}_j) \quad (8)$$

, α is a coefficient factor, usually connected with the distance from the winning neuron

- repeat all steps for a fixed number of repetitions

As a result of such learning, we can say that, in a Kohonen map, neurons located physically next to each other will correspond to classes of input vectors that are likewise next to each other (Figure 4). Therefore such regions are called maps.

3.2 Learning Algorithm Modification

We added one additional step into the learning process (Codello and Kuniszyk-Józkowiak 2010). This step is applied after the network has been trained using the standard algorithm described previously. The purpose is to reduce each map (which contains similar neurons) to only one neuron within one map.

We do the following:

- Find two closest neurons k_A, k_B (the distance between neurons weights are measured using Euclidean metric – equation 7.)
- If the distance is less then some threshold (algorithm's parameter), fill weights of one of the neurons with zeros. This way input vectors that were assigned to k_B neuron, now will be assigned to k_A
- Repeat steps 1. and 2. until there exists a pair of neurons closer then the threshold.

The result of the reducing procedure is shown in Figures 5 and 6. As we can see, such a result is much clearer and therefore more useful than an unmodified result.

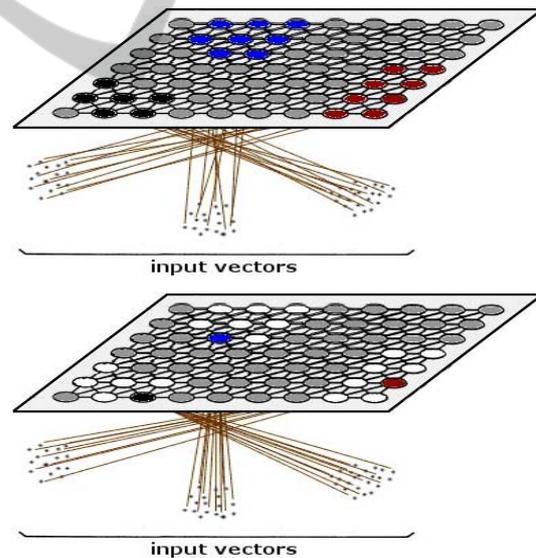


Figure 4: Input vectors with corresponding maps on Kohonen network before (top) and after (bottom) "neuron reduction". Similar vectors are assigned to group of neurons (top) and to only one neuron (bottom). Other neurons (white ones) within the maps are cleared.

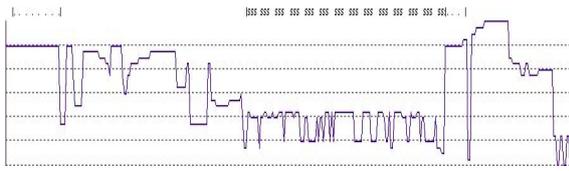


Figure 5: Winning neuron contour of the 2 seconds long utterance with prolongation “sss”. Kohonen network size: 5x5. Vertical axis: winning neuron number, horizontal axis: time. Screenshot from program “WaveBlaster”.



Figure 6: Winning neuron contour from Figure 5 after "neuron reduction". Screenshot from program “WaveBlaster”.

4 AUTOMATIC PROLONGATION RECOGNITION

The procedure of finding prolongations in the file is the following:

- Compute CWT spectrogram for the entire file
- Divide the spectrogram into ‘small’ windows (e.g. 23.2 ms) with a certain offset (e.g. 11.6 ms). By using windowing (see section 2.4 for details) each ‘small’ window is converted into a set of 22 element vectors (each vector’s element corresponds to one bark scale)
- Divide the result into ‘big’ windows (e.g. 2000ms – first parameter on Figure 7) with a certain shift (e.g. 300ms – second parameter on Figure 7)
- Each window, which consists of 22-element vectors, is passed into the Kohonen network. After the learning process we obtain a winning neuron graph (Figure 5)
- Then we can perform the Kohonen neuron reduction (fourth option in Figure 7)
- If a winning neuron contour (Figure 6) contains a section longer then a certain parameter (e.g. 250ms – the third parameter in Figure 7) in which only one neuron wins – then this section is considered as prolongation
- If the section overlaps some other automatically found prolongation, then the sections are combined
- At the end we manually compare the pattern with

the algorithm output and count the number of correctly and incorrectly recognized prolongation (Figure 8)

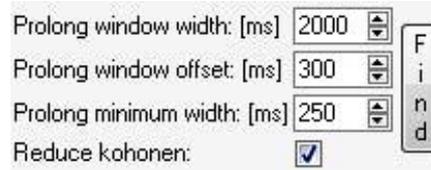


Figure 7: Automatic prolongation options panel. Screenshot from program “WaveBlaster”.

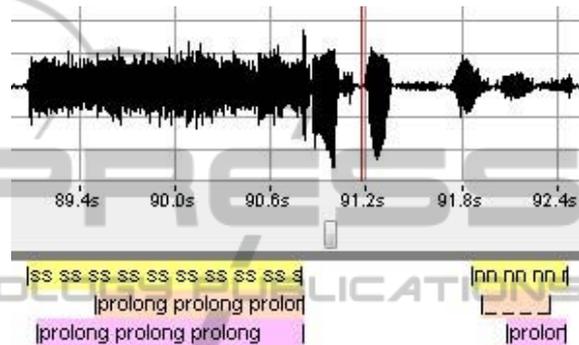


Figure 8: Input signal with three sets of patterns (first one manually created, other two automatically generated by algorithm with different configuration) – screenshot from program WaveBlaster.

5 WAVEBLASTER

The presented way of Kohonen post-learning and CWT smoothing is quite unique, therefore we had to create our own tool for this purpose. The presented problem is only part of our research (an automatic prolongation recognition system) – therefore our program ‘WaveBlaster’ has quite a developed functionality and set of parameters.

The following algorithms are implemented:

- DTF, iDFT, FFT, iFFT
- FFT reduced by 1/3 octave filters
- Linear Prediction (LP)
- Formant tracking (based on LP)
- Vocal tract visualization (based on LP)
- Signal envelope calculation
- DWT, CWT
- Kohonen neural network
- Automatic

The following graphs are displayed:

- DFT, FFT, 1/3 octave FFT, LP, DWT and CWT

- 2D spectrums and 3D spectrograms
- LP parameters and formant paths
- 3D vocal tract visualization
- Kohonen neural network
- Wavelets and wavelet scales

All the modules, despite of the numerous elements, are consistent. The components are flexibly programmed, enabling the user to easily change and visualize the data – which is very useful in research processes during which, when we look for the answers and some regularity, we need to look at the same set of data from different perspectives (enlarging, reducing, shifting, selecting, changing colors, scales, different analysis). The precise system of axis scales and variety of quantity measurement is very helpful in the observation process and finding even small irregularities in data behavior. All graphs are connected to each other (enlarging, reducing, shifting and selecting affects all panels) and therefore for a particular fragment we can observe many coefficients simultaneously (oscillogram, spectrograms, spectrums) – which is also quite helpful while doing research.

Summarizing – all these features make our application a very useful research tool. It is focused only on a particular sort of computation – which is both an advantage and a disadvantage. All this can be done by other tools, like MATLAB, but we would not have been able to do it so quickly and comprehensively (in the context of our needs). Therefore we think that despite the effort made to implement this tool, it was worth it – it will be used in many situations, facilitating and speeding up the research.

6 RECOGNITION EFFICIENCY ANALYSIS

6.1 Input Data

We took Polish disordered speech recordings of 6 persons and Polish fluent speech recordings of 4 persons. In the disordered speech recordings we chose all prolongations with 4 seconds surroundings and from fluent speech we randomly chose several 4 seconds long sections. We merged all the pieces together obtaining 15 min 24 s long recording containing 286 prolongations. The statistics are the following:

Table 2: Prolongations count.

a	5	s	63
e	2	sz	13
f	10	ś	37
g	1	u	2
h	7	w	32
i	7	y	17
j	1	z	43
m	10	ź	6
n	5	ż	17
o	8	all	286

6.2 Algorithm Parameters

In CWT we used Morlet wavelet (equation 3) with 22 Hartmut bark scales (Table 1).

Vectors for the Kohonen network were created from CWT spectrogram frames divided into 23.2ms windows shifted by 50% of frame length (11.6 ms) – for details see paragraph 2.4.

We used a 5x5 Kohonen network with the following learning parameters: 100 epochs, learning coefficient 0.10-0.10, neighbor distance 1.5-0.5, reducing distance 0.30.

An automatic prolongation recognition algorithm was run with the following settings: prolongation window equal 2s, offset equal 300ms and minimum prolongation equal 250ms.

The recognition ratio was calculated using the formulas (Barro and Marin 2002):

$$\begin{aligned} \text{sensitivity} &= \frac{P}{A} \\ \text{predictability} &= \frac{P}{P+B} \end{aligned} \quad (9)$$

where P is the number of correctly recognized prolongations, A is the number of all prolongations and B is the number of fluent sections mistakenly recognized as prolongation.

6.3 Results

We wanted to test the following two issues:

- how the neuron reducing algorithm (see section 3.2 for details) influences the recognition ratio
- how the CWT smoothing algorithm (see section 2.3 for details) influences the recognition ratio

Therefore we performed the following four tests:

- CWT smoothing: NO, Kohonen network neuron reduction: NO
- CWT smoothing: NO, Kohonen network neuron

- reduction: YES
- CWT smoothing: YES, Kohonen network neuron reduction: NO
- CWT smoothing: YES, Kohonen network neuron reduction: YES

The results are presented in Table 3.

Table 3: Automatic prolongation recognition results.

1. CWT smoothing – NO, Kohonen reduction – NO				
A	P	B	sensitivity	predictability
286	154	8	54%	95%
2. CWT smoothing – NO, Kohonen reduction – YES				
A	P	B	sensitivity	predictability
286	179	12	63%	94%
3. CWT smoothing – YES, Kohonen reduction – NO				
A	P	B	sensitivity	predictability
286	213	44	74%	83%
4. CWT smoothing – YES, Kohonen reduction – YES				
A	P	B	sensitivity	predictability
286	231	48	81%	83%

7 CONCLUSIONS

As we can see, the CWT smoothing algorithm increased the recognition ratio from 54% (set 1.) to 74% (set 3.) and from 63% (set 2.) to 81% (set 4.). It gives us 20% and 18% – that is very good. The CWT algorithm is too precise – especially in the hi-frequency scales. For the prolongation finding purpose such precision it is too high – that is why smoothing gives such a good ratio improvement. The disadvantage of this method is that it decreases predictability by 12% (set 1 and 3) and 11% (set 2 and 4), therefore it needs to be improved.

The Kohonen neuron reduction algorithm is a little more difficult to interpret. We used such an algorithm because if a prolongation is long (e.g. 1000ms), then consecutive vectors within that period are similar to each other – they represent one phoneme. We observed that when we want to have only one winning neuron for that phoneme, then other neurons have to compete for other phonemes, therefore

- A) all input vectors representing the prolongation have to be almost identical, then no matter how big the network, only one neuron will win the competition for the prolongation phoneme or
- B) an input signal needs to have a few other pho-

nemes in the window (proportional to the size of the network) – then every neuron in the network will compete for a different phoneme

When a given prolongation is short, then usually there are a few phonemes within the window, therefore condition *B* is met, which is good. But if the prolongation is long, or there is a lot of silence, then there are not many phonemes in the window. The Kohonen neurons start to compete for the same phoneme and they specialize in different variations of one phoneme, which is bad because we want only one neuron to win. That is why the CWT smoothing algorithm works so well – it makes similar vectors even more similar to each other and then condition *A* is met. And that is why the ‘neuron reduction’ algorithm is working – it reduces excessive neurons (condition *B* is met).

As we can see, ‘neuron reduction’ increases the recognition ratio by 9% (set 1 and 2) and by 7% (set 3 and 4), which is significant. What is important is that it does not reduce predictability – it means that the algorithm improves recognition without increasing the number of algorithm mistakes.

The results are promising. Now the main issues are:

- to improve the CWT smoothing algorithm – it decreases predictability ratio too much
- to investigate the Kohonen learning parameters for better prolongation recognition such as: the Kohonen network size, Kohonen network learning and neighbour coefficients, Kohonen network neuron initialization method, wavelet scales and scale shifts, decibel threshold. The research into the parameters is in progress.

REFERENCES

- Akansu A.N, Haddad R. A., 2001, Multiresolution signal decomposition, Academic Press.
- Barro S., Marin R., 2002, Fuzzy Logic in Medicine, Physica-Verlag Heidenberg, New York
- Codello I., Kuniszyk-Józkowiak W., 2007, Wavelet analysis of speech signal, Annales UMCS Informatica, 2007, AI 6, Pages 103-115.
- Codello I., Kuniszyk-Józkowiak W., Kobus A., 2010, Kohonen network application in speech analysis algorithm, Annales UMCS Informatica, (Accepted paper).
- Garfield, S., M. Elshaw, and S. Wermter. 2001, Self-organizing networks for classification learning from normal and aphasic speech. In The 23rd Conference of the Cognitive Science Society. Edinburgh, Scotland
- Gold, B., Morgan, N., 2000. Speech and audio signal

- processing, JOHN WILEY & SONS, INC.
- Goupillaud P., Grossmann A., Morlet J., 1984-1985. "Cycle-octave and related transforms in seismic signal analysis", *Geophysical Journal International*, 23, 85-102
- Huang, X., Acero, A., 2001. *Spoken Language Processing: A Guide to Theory, Algorithm and System Development*, Prentice-Hall Inc.
- Kohonen, T., 2001, *Self-Organizing Maps*, 34:p.2173-2179
- Nayak J., Bhat P. S., Acharya R., Aithal U. V., 2005, Classification and analysis of speech abnormalities, Volume 26, Issues 5-6, Pages 319-327, Elsevier SAS
- Smith J., Abel J., 1999, Bark and ERB Bilinear Transforms, *IEEE Transactions on Speech and Audio Processing*, November, 1999.
- Szczurowska, I, W. Kuniszyk-Józkowiak, and E. Smółka, 2006, The application of Kohonen and Multilayer Perceptron network in the speech nonfluency analysis. *Archives of Acoustics*. 31 (4 (Supplement)): p. 205-210
- Szczurowska, I, W. Kuniszyk-Józkowiak, and E. Smółka, 2007, Application of Artificial Neural Networks In Speech Nonfluency Recognition. *Polish Journal of Environmental Studies*, 2007 16(4A): p. 335-338.
- Trautmüller H., 1990 "Analytical expressions for the tonotopic sensory scale" *J. Acoust. Soc. Am.* 88: 97-100.