Examining the Impact of Neutral Theory on Genetic Algorithm Population Evolution

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Keywords: Neutral Theory, Genetic Drift, Neutrality, Genotype, Phenotype, Genetic Algorithms.

Abstract: This paper examines the introduction of neutrality as proposed by Kimura (Kimura, 1968) into the genotype-phenotype mapping of a Genetic Algorithm (GA). The paper looks at the evolution of both a simple GA (SGA) and a multi-layered GA (MGA) incorporating a layered genotype-phenotype mapping based on the biological concepts of Transcription and Translation. Previous research in comparing GAs often use performance statistics; in this paper an analysis of population dynamics is used for comparison. Results illustrate that the MGA population’s evolution trajectory is quite different to that of the SGA population over dynamic landscapes and that the introduction of neutrality implicitly maintains genetic diversity within the population primarily through genetic drift in association with selection.

1 INTRODUCTION

Neutral theory as proposed by Kimura (Kimura, 1968), offered an alternative to the Darwinian view; stating that the mutations involved in the evolutionary process are neither advantageous nor disadvantageous to the survival of an individual and that most mutations are caused not by selection, but rather by random genetic drift. However, in (Kimura, 1983), Kimura pointed out that although natural selection does play a role in adaptive evolution, only a tiny fraction of DNA changes are adaptive. The vast bulk of mutations are phenotypically silent.

By adopting the principal of Darwinism, simple genetic algorithms (SGA), can be viewed as implementing the process of evolution without containing any explicit neutral mutations. In other words, each mutation is either an advantage or a disadvantage to the individual in terms of fitness, with selection then propagating the fitter individuals. As the search progresses, the exploration and exploitation ratio decreases as the population converges. If we are to implement a genetic algorithm (GA) based on the principles of neutral theory then neutrality needs to be introduced. Neutrality can be viewed as a situation where a number of different genotypes can represent the same phenotype. Traditionally, GAs are evaluated and compared in relation to performance measures. In this paper, in addition to considering performance, the authors examine the population dynamics associated with a SGA and a multi-layered GA (MGA). The motivation is to develop a tunable, synonymous, non-trivial GA representation which incorporates neutrality, in order to gain an understanding of the effects of neutrality on population dynamics. The contributions are as follows: an analysis of the impact of neutrality on population evolution; an examination of the impact of neutrality on population variation; and finally an illustration of the impact of neutrality on phenotypic variability.

The paper is laid out as follows: Section 2 gives a brief background to Neutral theory and the use of neutrality in GAs. Section 3 outlines the MGA used in the paper, while Section 4 describes the experiments undertaken. Section 5 outlines and analyses the results, Section 6 concludes and Section 7 outlines future work.

2 BACKGROUND

Neutral Theory as discussed by Kimura (Kimura, 1968), argues that mutation, not selection, is the main force in evolution. He describes how a mutation from one gene to another can be viewed as being neutral if it does not affect the phenotype, as the number of different genotypes which store genetic information is far greater than the number of phenotypes. This implies that the representation from genotype to phenotype must incorporate an element of redundancy.
and neutral mutations are possible. Mutations can be viewed as neutral if they change the genotype but don’t impact on the phenotype.

Generally, neutrality can be viewed as a situation where the size of the search space is increased, without an equivalent increase in the solution space. This results in a situation where a mutated individual, at the genotypic level, can still represent the same phenotype. Neutrality should be beneficial when neutrality changes the search bias in order to improve the probability of locating the global optimum.

Although originally viewed as being anti-Darwinian, Kimura (Kimura, 1983) stated that although natural selection is important in evolution, the number of DNA changes which are adapted in evolution are small, with the vast majority of mutations being phenotypically silent. Following Kimura, work by King and Dukes (King and Dukes, 1969) describes how much of the evolution of proteins is down to neutral mutations and genetic drift. A number of studies focused on neutral theory (Schuster et al., 1994; Huygen et al., 1996; Huyten, 1996; Schuster, 1997) etc. and illustrated that by introducing redundant representation and thus, neutral mutation, the connectivity in fitness landscapes can be altered. In other words, when a number of genotypes represent the same phenotype, they can be viewed as a neutral set and in turn alter the way in which a population explore the search space.

Previous work on GA genotype-phenotype mappings which introduce neutrality, has produced results indicating the neutrality may prove useful in changing environments and over more difficult landscapes. Ebner et al. (Ebner et al., 2001) outlined how high levels of mutation could be sustained by having neutral networks present. They also identified that neutral networks assist in maintaining diversity in the population, which may be advantageous in a changing environment. Similar findings were found in (Grefenstette and Cobb, 1993). Toussaint and Igel (Toussaint and Igel, 2002) argued that approaches to self-adaptation in evolutionary algorithms can be viewed as an example of the benefits of neutrality, because with non-trivial neutrality, different genotypes which are part of the same neutral set may have different phenotypic distributions.

3 MULTI-LAYERED GENETIC ALGORITHM (MGA)

The concepts of Variation and Variability need to be differentiated. Variation can be described as the difference between individuals in a population and can be seen as relating to a collection. Variability, on the other hand, can be described as the leaning to vary and the “variability of a phenotypic trait describes the way in which it changes in response to environmental and genetic influences” (Wagner and Altenberg, 1996). When exploring the phenotypic space, it is critical to gain an understanding of the variational topology in trying to determine the shape of the landscape (Toussaint, 2003b). Many evolutionary algorithms are created using a fixed variation topology, in other words you don’t need to track the neutrality to explain the evolution trajectory. However, in nature, phenotypic variation landscapes are not fixed. These non-fixed phenotypic variation landscapes can be referred to as non-trivial in terms of their genotype-phenotype map (Toussaint, 2003b). A non-trivial genotype-phenotype map can be viewed as having the following characteristics: firstly, a phenotype can be encoded by many genotypes and secondly, the phenotypic variability of a number of phenotypes will depend on their genotypes (Toussaint, 2003a).

The primary inspiration for the multi-layered GA can be found in the biological processes of transcription and translation. At a very basic level, the biological process of transcription involves the copying of information stored in DNA into an RNA molecule, which is complementary to one strand of the DNA. The process of translation then converts the RNA, using a predefined translation table, to manufacture proteins by joining amino acids. These proteins can be viewed as a manifestation of the genetic code contained within DNA and act as organic catalysts in anatomy. The MGA includes a layered genotype-phenotype map which adopts a basic interpretation of the transcription and translation processes and allows for the implementation of a missense mutation operator. The genotype search space is represented by $\Phi_g$ where $\Phi_g = \{0, 1\}^l$ and $l$ is the genotype length. The transcription phase of the MGA maps the binary genotype to the DNA search space $\Phi_d$, where $\Phi_d = \{A, C, G, T\}^{1/2}$, with the following mappings: $00 \rightarrow A; 01 \rightarrow C; 10 \rightarrow G$ and $11 \rightarrow T$. Following this, a bijective mapping takes place, mapping the DNA space to an RNA space $\Phi_r$, where $\Phi_r = \{A, C, G, U\}^{1/2}$. $U$ is included for biological plausibility and has no impact on the evolution unless we include operators at this level. Following transcription, the translation phase takes place, mapping $\Phi_r \rightarrow \Phi_p$, where $\Phi_p$ represents the phenotype space and $\Phi_p = \{0, 1\}^{1/c}$, where $c$ is the cardinality chosen at initialisation to create a translation table. The level of redundancy is determined by $c$ and in this paper $c = 6$ (see Figure 1), and implies $|\Phi_g| > |\Phi_p|$ where...
Missense mutation in nature is carried out at the RNA level. In relation to the MGA, the Missense mutation mapping is as follows: \(A \rightarrow U, C \rightarrow G, G \rightarrow A \) and \(U \rightarrow C\). To summarise the variation operators, one-point crossover and single-point mutation occur at the genotype level prior to transcription and missense mutation takes place before translation.

The MGA introduces a tunable multi-layered GP-map, which allows a haploid GA to exhibit some of the characteristics normally associated with a diploid. That is a mechanism for allowing alleles or combinations of alleles which proved useful in previous generations (Goldberg and Smith, 1987) and thus, maintaining a form of long term memory without the need to develop a dominance scheme. The MGA population consists of a population of haploid individuals, which allows for the use of traditional crossover and mutation variation operators on the genotype. This differs from the approach used by diploid GAs (DGAs) i.e. (Yang, 2006), where each individual has two chromosomes and crossover is divided into two steps and mutation is viewed as being neutral. Another difference between the MGA mapping and that of a DGA, is that in the DGA, a phenotype allele is made up from a single genotype allele which is expressed. In the MGA, a single phenotype allele is made from the cardinality incorporated in the genotype, in this paper we use 6-bits. Although the MGA’s GP-map is non-deterministic, the approach differs from that of real-coded binary representation, which incorporate a gene-strength adjustment mechanism (Kubalik, 2005). Real-coded binary representations can use standard crossover operators, but mutation is implicit due to the gene-strength adjustment mechanism (Kubalik 2005).

Deception is often used in testing GAs and implies that the search strategy can be misled (Whitley, 1991a). As noted in (Morrison and DeJong, 2002), diversity is critical for GAs, particularly when the landscape is evolving as recombining a homogeneous population will not enable the GA to locate the new optimum. Hamming difference is used as a measure of diversity both for the genotypic and phenotypic diversity. In order to examine the population evolution for both the SGA and the MGA, experiments were conducted over a 4-bit fully deceptive landscape (Whitley, 1991b) which is reversed after generation 50, allowing the local optimum to become the global optimum.

4 EXPERIMENTATION

Deception is often used in testing GAs and implies that the search strategy can be misled (Whitley, 1991a). As noted in (Morrison and DeJong, 2002), diversity is critical for GAs, particularly when the landscape is evolving as recombining a homogeneous population will not enable the GA to locate the new optimum. Hamming difference is used as a measure of diversity both for the genotypic and phenotypic diversity. In order to examine the population evolution for both the SGA and the MGA, experiments were conducted over a 4-bit fully deceptive landscape (Whitley, 1991b) which is reversed after generation 50, allowing the local optimum to become the global optimum.

5 RESULTS

The analysis that follows is broken into three parts: the impact of neutrality on population evolution; the impact of neutrality on variation and the impact of neutrality on phenotypic variability. However, the results begin by comparing both GAs in a conventional manner based on performance. Figure 4, illustrates the off-line (averaged best fitness) and on-line (averaged fitness) performance for both the SGA and the MGA. The results indicate that the changing 4-bit deceptive landscape initially proved equally easy for both the SGA and the MGA. However, after the landscape changes, the SGA becomes trapped on the local optimum, while the MGA succeeds in locating
the global optimum. A Wilcoxon Rank sum test indicates that the results shown in Figure 4, that is both the off-line and on-line comparison between the SGA and MGA, were statistically significant. The remaining analysis examines the evolution of both populations, in an attempt to gain a better understanding of the impact on neutrality on population dynamics over the course of an evolutionary time period and to illustrate the performance of both population in a dynamic environment.

5.1 Neutrality & Population Evolution

5.1.1 Analysis Before the Landscape Change

In relation to the evolution of the SGA’s population, Figure 5 gives an overview of the population distribution over the landscape at generation 0, with the initial population of 20 individuals randomly spread over the landscape. Figure 6 shows the MGA population distribution over the problem landscape. The initial randomly generated population distribution for the MGA is quite similar to that of the SGA.

Examining the populations for both GAs at generation 50, which is the last generation before the landscape changes, we see that the SGA’s population has converged, apart from the impact of mutation (Figure 7). The MGA’s population has also located the global optimum. However, due to the genotype-phenotype mapping, the population doesn’t converge as much as the SGA. Figure 8, shows the many-to-one representation present in the population, with different genotypes having the same fitness represented by different colours and shapes.

The MGA population’s evolutionary trajectory differs considerably by not converging on the global optimum. Therefore the population consists of a number of neutral networks, which is a result of gene flow due to the presence of neutrality.

5.1.2 Analysis After the Landscape Change

Figure 9, illustrates the SGA population distribution when the landscape changes at generation 51 and shows the population, which now converges on the local optimum as the landscape has reversed in relation to the fitness function. It also indicates all but one member of the population are located on the local optimum.

The MGA population can be seen distributed on
the problem landscape in Figure 10, with the bulk of the population located on the local optimum. The figure also indicates that due to the presence of neutrality in the representation, the population is dispersed over a wider number of fitness plateaus.

Examining the population evolution through to generation 200 for both GAs. The SGA population remains trapped on the local optimum (see Figure 11), while the MGA population remains clustered around the global optimum, see Figure 12. This appears to indicate that the MGA, through the genotype-phenotype mapping, implicitly maintains a level of genetic diversity within the population and is resistant to convergence, thereby offering the ability to adapt in a dynamic environment. The impact of neutrality on population evolution is described in Sub-section 5.1 and illustrated the population distribution for the SGA and MGA, both before and after the landscape changed.

5.2 Neutrality & Variation

As a traditional SGA maps directly from the genotype to the phenotype, both the genotypic search space and the phenotypic search space are identical. With the MGA mapping, neutrality increases the genotypic search space in comparison to the phenotypic search space. Using normalised Hamming distances between individuals, Figure 13 and Figure 14, illustrates the population diversity for both the SGA search spaces and the MGA genotypic search spaces, respectively, at generation 0. From the figures, it appears that at generation 0, there is quite a large level of diversity present in both populations. This can be explained as evolution has not yet begun and the populations have been randomly generated. Also, as neutrality is introduced the MGA's genotypic search space increases, while the MGA's phenotypic space (Figure 15) is quite similar to that of the SGA.

As the populations evolve to generation 50, convergence has occurred in the SGA (apart from the influence of mutation) and the population is shown in
To examine the effect of single-bit mutation and missense mutation, we randomly selected an individual from both of the population being part of other neutral networks.

One genotype-phenotype mapping and to individuals phenotypic diversity present, relates to the many-to-

The level of variation is maintained within the genotypic search space, see Figure 17. The MGA phenotypic search space (Figure 18) illustrates the diversity at a phenotypic level.

At generation 200, the SGA population remains on the local optimum and contains little diversity to allow it to escape. This situation is shown in Figure 19, reflecting the lack of diversity within the population when viewed as a function of Hamming distance.

The MGA genotypic population diversity at generation 200, is shown in Figure 20 and the phenotypic diversity is illustrated in Figure 21. The level of phenotypic diversity present, relates to the many-to-one genotype-phenotype mapping and to individuals of the population being part of other neutral networks.

5.3 Neutrality & Phenotypic Variability

The final examination of the effects of neutrality on the evolutionary trajectory of the MGA population relates to the impact of mutation. In order to examine the effect of single-bit mutation and missense mutation, we randomly selected an individual from both
the SGA and MGA populations from various generations. We then flipped all of the bits, one at a time, in sequence and measured the impact on fitness. The aim of this approach is to examine how the presence of neutrality impacts on mutation in GAs which have synonymous representations. A representation is viewed as synonymously redundant if the genotypes representing the same phenotype have the same properties and are next to one another in the mutation space. With the MGA population, a genotype, when mutated, can produce either a silent or an adaptive single-bit mutation and a silent or adaptive missense mutation.

Figure 22 shows the impact of mutation in an SGA population. Figure 23 visualises the impact of single-bit mutation on an individual from the MGA population. The phenotypic distribution for both GAs is similar as the neutrality associated with the MGA representation is synonymous.

The MGA representation includes missense mutation which operates within the layers of the genotype-phenotype mapping and allows the phenotypic variability to differ for individuals having the same level of fitness. Figure 24 illustrates the phenotypic distribution for individual 0100001100001000011000, showing that the phenotypic distribution for the MGA is greater than that of the SGA, as individuals are occupying more fitness plateaus. Figure 25 illustrates the phenotypic distribution for individual 100010011100100000001010, which resides on the same neutral network with a fitness level of 30. They show that the MGA population allows individuals residing on the same fitness plateau, have different phenotypic distributions. This section highlighted the effect of mutation, with results illustrating that the SGA can only access local plateaus, while the MGA, which can be phenotypically silent, has greater variability.

6 CONCLUSION

A population’s ability to survive in dynamic environments often depends on a level of diversity to be maintained within the population. As a GA search involves a mapping between the genotype and the phenotype, a SGA, through it’s one-to-one genotype-phenotype mapping, quickly eliminates diversity from the population through its selection policy and low mutation rates. The results presented, illustrate that through the implementation of Neutral theory, as proposed by Kimura (Kimura, 1968), the genotype-phenotype mapping of the MGA allows for a tunable, non-trivial, many-to-one relationship. The contribution of this form of mapping is the implicit maintenance of related genetic diversity within the population, which allows the occupation by the population, of a greater number of fitness plateaus. By adopting this approach, convergence at a phenotypic level can be achieved, but genetic diversity is maintained at a genotypic level. Neutral theory (Kimura, 1968), would suggest that where genetic changes spread across a population, changes may or may not alter the phenotype and are a result of genetic drift. The results indicated that neutrality, as introduced by the MGA mapping,
impacts on the search space by increasing its size and population variation. Finally, the results showed that adaptive mutations operate in a similar manner to SGA mutations, but allow a greater number of fitness plateaus to be reached. Silent mutations, on the other hand, offer the ability to search the landscape without impacting on fitness. This increases the size of the genetic pool and impacts on gene flow.

7 FUTURE WORK

Future work includes comparing the performance of the MGA with that of other diversity maintenance techniques over a number of problem landscapes.

REFERENCES


