INJECTING SEMANTICS INTO EVENT-DRIVEN ARCHITECTURES

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Abstract: Event-driven architectures (EDA) have been proposed as a new architectural paradigm for event-based systems to process complex event streams. However, EDA have not yet reached the maturity of well-established software architectures because methodologies, models and standards are still missing. Despite the fact that EDA-based systems are essentially built on events, there is a lack of a general event modelling approach. In this paper we put forward a semantic approach to event modelling that is expressive enough to cover a broad variety of domains. Our approach is based on semantically rich event models using ontologies that allow the representation of structural properties of event types and constraints between them. Then, we argue in favour of a declarative approach to complex event processing that draws upon well established rule languages such as JESS and integrates the structural event model. We illustrate the adequacy of our approach with relation to a prototype for an event-based road traffic management system.

1 INTRODUCTION

A wide range of applications is characterized by event-driven business processes. They must deal with a huge amount of different events which continuously arrive as streams (Luckham, 2002), (Babu et al., 2001). Due to the high volume of events and their complex dependencies, no predefined workflow can be specified for business processes. Current software architectures such as service-oriented architectures (SOA) do not target event-based systems, because they are based on a process-oriented control flow, which is not appropriate for event-driven systems.

In recent years, event-driven architectures (EDA) have been proposed as a new architectural paradigm for event-based applications (Luckham, 2002). Processing events is the central architectural concept of EDA: streams of events are analyzed using Complex Event Processing (CEP) to initiate downstream event-driven activities, which are provided by software components and application systems for implementing domain-specific event handling. Event streams generated by sensors, RFID tags or software components contain a large volume of different events, which must be transformed, classified, aggregated and evaluated. Examples for EDA-based systems are logistic applications based on RFID events (Wang et al., 2005), (Dunkel and Bruns, 2008), financial trading (Adi et al., 2006), business activity management (Coy, 2002), click stream analysis in web portals (Coy, 2002) and traffic control systems (Dunkel et al., 2008).

The main goal of CEP is to identify in a huge event cloud those patterns of events which are significant for the business domain. In traffic control systems millions of sensor-emitted events are analyzed to discover event patterns signifying upcoming traffic problems.

Meanwhile, EDA have been used successfully for event-based applications (Wu et al., 2006), (Babcock et al., 2002) and several commercial products supporting EDA are available (Coral8, 2008), (Espertech, 2008).

Unfortunately, event-driven architectures have not yet the maturity of well-established software architectures: there is still a lack of methodologies, models and standards. Despite the fact that EDA-
based systems are essentially built on events, existing architectures does not use any formal event modelling approaches. In this paper, we introduce Semantic Event Models using ontologies to define precisely the hierarchy of event types used in an Event-Driven Architecture. Semantic Event Models reflect the sequence of event processing steps and constitutes the software architecture by identifying the essential systems components and the main event processing steps.

The paper is organized as follows: In the next section the main deficiencies of existing EDA-based systems are discussed. In section 3 we introduce semantic event models based on ontologies and show how they can be used subsequently in event processing. Finally, we summarize the most significant features of our approach and provide an outlook on future lines of research.

2 EDA DEFICIENCIES

One of the main deficiencies of current EDA approaches is the absence of decent software architectures. A software architecture is described by an abstract model defining the essential domain concepts and mapping them on appropriate software components (Evans, 2003), (SEI, 2008).

Obviously, events are the key domain concept of EDA and should therefore be defined precisely by a formal event model. An event model should provide a complete understanding of the different event types, its properties, constraints and dependencies; and is therefore invaluable to derive the software architecture of EDA-based systems.

Defining Events in Event Processing Languages. Surprisingly, existing event-driven architectures do not use any generic and comprehensive event model, e.g. (Adi et al., 2006), (Rozsnyai et al., 2007), (Wang et al., 2005), (Wu et al., 2006).

Instead, event processing languages (EPL) are used, which intermingle the processing with the definition of events. Mostly, proprietary SQL-like event processing languages for continuous queries (CQL) are used in academic approaches (Babu et al., 2001), (Babcock et al., 2002), and available EDA products (Coral8, 2008), (Esper, 2008). Event definitions are hidden in the SQL-like low-level code (Arasu et al., 2002). This approach causes the following drawbacks:

- Because CQL-based system doesn’t provide any dedicated event model, an overview of the given event types is missing, which makes the understanding of event processing difficult.
- Furthermore, there is a lack of explicit business rules in form of event constraints. Due to this deficiency, event processing rules can easily violate inherent.

Benefits of Formal Event Models. A formal event model is a key issue of EDA-based systems allaying the above mentioned problems in providing detailed semantics about the given events. Furthermore, event models yield the basis for the overall system architecture. The event hierarchy corresponds with the sequence of event processing steps: simple technical events are transformed into more abstract and sophisticated application-specific events. Each transformation step is processed by event agents which building blocks of the software architecture (Dunkel et al., 2008).

In summary, current EDA systems lack semantically rich event models which are indispensable for understanding the key concepts of event-driven systems and for deriving appropriate software architectures.

3 SEMANTIC EVENT MODELS

In our approach we distinguish two different layers of Event-Driven Architectures: the Structural Event Model and Complex Event Processing see figure 1.

Figure 1: EDA layers.

The Structural Event Model serves as a formal event model as motivated in section 2. It defines the different types of events and their relations. Furthermore, it specifies general constraints defining more precisely the structure of events and their inter-dependencies.

Note that the Structural Event Model determines the business objects of EDA. Its task is to specify the properties of events but not how they are
processed. In particular, the Structural Event Model should meet the following requirements.

- The Structural Event Model must be formally defined and semantically rich to provide a complete understanding of the given events. It should define all constraints and interdependencies between events by declarative description mechanisms; i.e. by structural rules.
- The specification of the Structural Event Model should be based on an adequate formalism to limit the room of interpretation and to allow model-driven approaches.

**Complex Event Processing** is responsible for processing streams of continuously arriving events. It is based on event processing rules which define correlations between events and are expressed by event processing languages based on event algebras (Schiefer, 2007). The rules consist of two different parts: event patterns specify a certain situation of events; and event actions are executed when the event pattern is fulfilled. In particular, new events can be generated within the event action part. CEP relies completely on the Structural Event Model, where all events used in the event processing rules must be defined.

In summary, the two layers separate domain knowledge: the structure of events is decoupled from operational knowledge, i.e. the event processing rules.

### 3.1 Formalisms for Event Models

Experience with EDA-based systems has led us to the following requirements for formalisms aimed at semantic event models:

- **sufficient expressiveness of the Structural Event Model to describe all aspects and interdependencies of events.**
- **Complex Event Processing should integrate smoothly the knowledge of the Structural Event Model.**
- **compatibility with standards to facilitate tool support.**

**Structural Event Models.** Most current EDA approaches specify only the types of events by using XML and XML Schema, as recently investigated in (Rozsnyai et al., 2007). But XML is not suitable for modelling semantics, as it lacks high-level language constructs that support the declarative specification of event interrelations and constraints.

Some other approaches use simple UML models for defining event types and their relations (Coral8, 2008), (Esper, 2008). Common UML models are not expressive enough, but they can be enriched by OCL (Object Constraint Language) constraints (OMG, 2003) to specify more precise event models. However a drawback of this approach is that OCL cannot be easily integrated in standard rule engines which perform complex event processing.

To comply with the above listed requirements, we decided to apply ontologies for defining semantically rich event models. Ontologies languages such as the Web Ontology Language (OWL) provide sufficient expressiveness (W3C, 2004), and may be easily integrated with classical rule engines for further processing (Dunkel et al., 2006).

Furthermore, OWL is standardized by the W3C and can be viewed as a semantic extension of XML, RDF, and RDFS. We will use the OWL DL sub-language that is based on description logic providing an adequate degree of expressiveness while still allowing automated consistency checking.

**Complex Event Processing** must integrate the Structural Event Model with the event processing rules. For instance, the constraints of the Structural Event Model can be used as consistency rules for checking the validity of incoming event data.

Because SQL-like continuous query languages don’t support the concept of rules, it is much easier to integrate a Structural Event Model with a general rule based system like JESS (Jess, 2008) or DROOLS (Drools, 2008). For instance, in (Dunkel et al., 2006) we have shown how OWL models can be mapped to facts and rules of a general inference engine. In section 3.3 we will show how general rule languages can be used for specifying event processing rules.

### 3.2 Structural Event Models

In this section we show that OWL-DL is an appropriate formalism for specifying Structural Event Models. To illustrate our approach, we refer to the prototype of a Decision Support Systems for traffic management, which has been modelled using an EDA (Dunkel et al., 2008).

In high capacity road networks, as the one of Bilbao in Spain, sensors installed in the roads emit events when cars are passing. The Decision Support System transforms the sensor events into more abstract and sophisticated domain events for evaluating the actual traffic situation and initiating appropriate traffic control actions.

In the following we will derive an ontology-based event model for to illustrate how different aspects of Structural Event Models can be modelled in OWL. Figure 2 shows the simplified OWL event ontology.
**Event Instances and Event Types.** Every situation that may require a reaction of the system forms an Event Instance. An Event Instance is atomic and instantaneous, i.e. bound to a certain point of time. An Event Type classifies the event instances and describes their conceptual features. Each Event Instance belongs to a certain Event Type. The Event Types reflect the event processing steps.

OWL already provides mechanisms for dealing with Event Instances and Event Types: an OWL class provides an abstraction mechanism for classifying individuals. An Event Instance is represented by an OWL instance.

In Figure 2 each rectangle shows an OWL class representing an Event Type, e.g. a CarSensorEvent is emitted by a loop detector when a car passes. The particular situation that a car passes the sensor at a certain time forms an Event Instance. The decision support system transforms the Sensor Events into more meaningful Traffic and Problem Events.

**Event Hierarchies.** Event Types usually constitute a hierarchy – defining an Event Type as a subclass of other types. (Note that OWL allows multiple inheritance.) In Figure 2 the ProblemEvent has two subtypes: a CongestionEvent and an AccidentEvent.

**Event Type Construction.** Furthermore, OWL offers some constructors to build classes out of other classes, which are useful for event type definitions. In particular, in OWL the operators union, intersection and complement are defined, which represent the AND, OR and NOT operators on classes.

**Event Context.** Each Event Instance is characterized by some data: general metadata (event ID, time) is common to all Event Types; event-specific data describes the context, in which the event occurs. Because event data is type-specific, it can be used to infer the Event Type. OWL allows attributes of class instances: OWL data properties describe event data, and OWL object properties specify relationships between event instances.

In Figure 2, a relation between TrafficEvent and SensorEvent is defined by OWL object properties. The TrafficEvent aggregates some SensorEvents: it calculates its attributes density, (average) speed and occupancy using data from the corresponding sensor events. Thus, the TrafficEvent can be considered as a complex event which aggregates correlated (sensor) events.

**Event Constraints.** With the hitherto presented OWL language constructs the basic structure of an event model can be specified. For defining events more precisely, we need to inject further semantics into our models.

The domain and the range of an object property specify which classes are linked. In Figure 2, the property yields has a TrafficEvent as range and a ProblemEvent as domain.

Additionally, logical restrictions can put more semantics to the relations between Event Types. OWL provides the symmetricProperty, inverseOf and transitiveProperty constructs for logical restrictions: dependsOn is a symmetricProperty between ProblemEvents; requires and eliminates are inverse; dependsOn is a transitiveProperty.

Furthermore, OWL allows formulating constraints on Classes by so-called OWL class axioms. For instance, two classes are disjoint if they have no instances in common, such as SensorEvent and ProblemEvent.

**Notation of Time.** Event Instances are (partially) ordered according to their times of occurrence and most event patterns define a certain sequence of events. Therefore, the concept of time is a key issue for event models. However, time is not explicitly defined in OWL. A possible solution is modeling time in a dedicated abstract type, here: AbstractEvent. This class contains meta data which is common to all events types, i.e. the occurrence time and an eventId. All Event Types inherit from this class to provide them with these concepts. Note that recently some work has been proposed extending OWL with temporal aspects (Marwaha et al., 2007).

In summary, OWL ontologies can be used to develop semantically rich event models. Especially OWL constraints can enrich event models with more semantics.
3.3 Complex Event Processing

In this section we show how to use general rule languages for specifying event processing on the basis of the Structural Event Model. Note that the Structural Event Model just represents the knowledge about the event types and their properties, but not how these events are processed.

CEP and Structural Event Model. Complex Event Processing depends heavily on the Structural Event Model: All event types and data used in the event processing rules must be defined in the event ontology as OWL classes or OWL properties.

Note that the expressiveness of OWL is not sufficient for specifying processing rules: OWL lacks the language constructs for formulating complex event patterns and does not allow any data processing as required in the action part.

A key issue of our approach is the smooth integration of the OWL ontology with the event processing rules. In (Dunkel et al., 2006) we have outlined how OWL models can be mapped to facts and rules of a general inference engine. In particular, we used the OWL Inference Engine tool (OWL inference engine, 2008) to load OWL ontologies and OWL instances into a JESS knowledge base.

Event Patterns. In the following, we show how general rule languages like JESS can serve as event rule language. The key issue is their capability of defining event patterns, which can be characterized by the following elements (Zimmer et al., 1999):

- Event Patterns are based on event types, i.e. they define a sequence of event types that must be matched. Events sequences can be defined by some basic operators of an underlying algebra: the sequential operator $E_1; E_2$, a conjunction operator $E_1 \land E_2$, the disjunction operator $E_1 \lor E_2$ and a negation operator $\neg E_1$. The following example shows a pattern that identifies an accident as the cause of a specific congestion.

- Event Patterns contain context conditions, i.e. restrictions on the data context of an event instance. Context conditions are specified by means of relational operators, which depend on the data types of the corresponding event properties. Data context allows the definition of correlation sets, e.g. correlating all sensor events belonging to one road segment. The next rule is used to aggregate the speed measured by the two sensors of a road section.

```lisp
(defrule DataAggregation
  (CarSensorEvent (sensorId ?sId1)(speed ?v1))
  (CarSensorEvent (sensorId ?sId2)(speed ?v2))
  (test (=> ?sId1 ?sId2))
  (sensor (sensorId ?sId1)(location ?sec))
  (sensor (sensorId ?sId2)(location ?sec))
  =>
  (assert (TrafficEvent (eventId (gensym*)) (time (time))
  (speed (/ (+ ?v1 ?v2) 2)) (section ?sec)))
)
```

Finally, the event instance selection must be determined: the event patterns just specify the required event types. In the next example, we need to select the last AlertEvent to show its message property in the information panel. The first conditional pattern matches any alert event, but the second requires the absence alert events with a timestamp higher than the first one. So, the rule only fires for the most recent Alert Event, sending it to the panel.

```lisp
(defrule SelectMessageToShow
  (AlertEvent (time ?ta)(message ?m))
  (not (and (AlertEvent (time ?tpre))
  (test (> ?tpre ?ta))))
  =>
  (assert (sendMessageToPanel ?m))
)
```

Event Handling. If an event pattern is matched, i.e. if a rule fires, a certain action is executed. The event rules should allow defining arbitrary handling code. In particular, the data of those event instances that match the pattern must be processed and new event instances must be created. Furthermore, actions must be able to invoke business-level activities which implement domain-specific event handling.

4 CONCLUSIONS

Though EDA-based systems are essentially built on events, current approaches do not use formal event models. Instead, event processing languages (EPL) are used, which intermingle processing and definition of events. Generally, there is a lack of comprehensive and precise event models.

In this paper, we have put forward a semantic approach to event modelling for EDA-based systems. A Structural Event Model defines all event types with their constraints and interdependencies and can be described by ontology languages. We
showed how to use OWL to express semantically rich event models that can be reused in subsequent event processing steps straightforwardly. Complex Event Processing defines the operational behaviour of EDA on base of the Structural Event Model. For instance, the constraints of the Structural Event Model can be used as consistency rules for checking the validity of incoming event data.

To integrate the structural with the operational model we chose well established rule language as JESS and showed how they can be used for specifying event processing rules. Furthermore, we have illustrated the adequacy of our approach with relation to a prototype for an event-based road traffic management system.

In contrast to other works (Adi et al., 2006), (Rozsnyai et al., 2007), (Wang et al. 2005), (Wu et al., 2006), we used a model-based approach for deriving EDA, which separates the structural (i.e. event types and constraints) from operational knowledge (i.e. event processing rules). The proposed models yield the basis for the software architecture and can be used for model-driven software development approaches.

For the future, we intend to derive explicit architectural guidelines and design patterns from the semantic event models. For this purpose, we also plan to integrate a reference architecture that we have developed for structuring CEP reasoning (Dunkel et al., 2008) into our approach. Furthermore, we intend to explore the potential benefits and drawbacks of combining OWL-based ontologies with SQL-based EPLs. Finally, we want to apply model-driven software development approaches to generate event processing rules from semantic event models and to simplify the development of low-level event processing rules.

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