

Detection and Prediction of Primary Productivity in Coastal Environment Using Ensemble Models

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Abstract: Prediction on marine productivity in the ecosystem is a challenging task nowadays. Fault prediction in marine ecosystem occurs due to the climate change, waste water infusion in the marine environment which leads to the harmful primary production in the marine ecosystem. In traditional method it was a struggle to focus on the complexity and the changes in the variation metrics. To overcome those complexity deep learning acts as a powerful tool to predict modelling methods in various domains. Deep learning algorithm mainly has an ability to differentiate patterns from huge dataset. This study empirically analyses the effectiveness of various deep learning algorithm used to analyse prediction in primary productivity mainly focusing on algae bloom. General key performance metrics like accuracy, recall, precision and F1 score are analysed. The algorithms like Convolutional Neural Network (CNN) and Hybrid Convolutional Neural Network (HCNN) are the superior models in predicting accuracy when compared to traditional methods. Overall, this study focuses on the use of various deep learning algorithm which can be implemented to analyse the algae bloom in marine ecosystem. This concept will be helpful for the readers focusing on Algae Bloom.

1 INTRODUCTION

Primary productivity is the rate at which photosynthetic organisms such as plants and algae convert energy into organic molecules through the photosynthesis process. Using sunlight, this process transforms carbon dioxide and water into glucose and creates oxygen. The generated organic substances supply nutrition to rest of the ecosystems.

1.1 Environmental Value of Main Productivity

In marine ecosystems, primary production constitutes the base of the food chain. Where the Producers or autotrophic organisms changes the solar energy into chemical form which is later passed on to herbivores and predators within the ecosystem.

During Photosynthesis Primary producers combines nutrients like carbon, nitrogen, and phosphorus into their tissues. These nutrients are

returned into the environment when these nutrients are consumed and broken down by other species or by natural processes, hence encouraging nutrient cycling in ecosystems.

Production of Oxygen: The major function of photosynthesis is oxygen creation. Most living organisms depends on atmospheric oxygen levels, which plants and algae considerably contribute in releasing oxygen as a byproduct while they make glucose for their energy level.

Carbon dioxide from the atmosphere is taken by the Primary producers during photosynthesis, hence changes occurs in the global carbon cycle. This absorption influences atmospheric carbon dioxide levels, consequently impacting the Earth's temperature and global climate patterns.

Main production is also incredibly vital for human civilizations since it produces food, fiber, fuel, and pharmaceuticals among other requirements. Direct or indirectly dependant on productive ecosystems include fishing, agriculture, forestry, and ecotourism.

1.2 Field dimensions

Direct monitoring of oxygen production by primary producers (e.g., aquatic plants, phytoplankton) employing techniques including light and dark bottle tests. This requires monitoring fluctuations in dissolved oxygen concentrations in under control situations.

Direct monitoring of biomass building and growth rates of key producers are done across time. This generally requires measuring biomass using growth chambers or harvesting and weighing plant materials. The figure 1 shows Algal Bloom process.

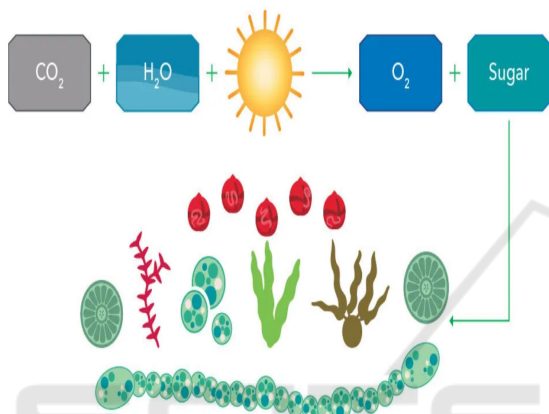


Figure 1: Algal Bloom process.

2 RELATED SURVEYS

This survey focusses on the application and methodologies that were implemented by various researchers in marine environment.

Deep learning for marine species recognition was proposed by Lian Xu et al focus on deep learning techniques that are used to identify automatically the species in marine environment. The author implements CNN to overcome the challenges that are faced by the traditional methods. With the help of CNN, the author analysed underwater imagery and acoustic data. With this analysis he classified the data according to their characteristics.

Deep learning and transfer learning features for plankton classification, Alessandra Lumni et al uses deep learning techniques to differentiate plankton. Author uses transfer learning, pre-tuning and fine-tuning models to train the model. Ensemble model is proposed by the author to improve the performance. CNN method is implemented for identification of plankton.

Defining a procedure for integrating multiple oceanographic variables in ensemble models of marine species distribution, D. Panzeri et al focus five different modelling approaches. For each approach different spatial data and test data set is used to enhance performance. Depth, spatiotemporal variables are used as input for simple model and Oceanographic variables are used for complex model. The author focusses on space and time on European lake.

Species distribution modelling for machine learning practitioners, Sara Beery et al here in his work the author implemented SDM Species Distribution Modelling to focus where the huge number species were found in the marine ecosystem. This modelling used to predict the spatial and temporal patterns of species.

There are lot of work are done in the filed of marine environment focusing on Algal Bloom and however there are lot of limitations too.

2.1 Preprocessing and Data Gathering

2.1.1 Data Gathering

There are several sources from which primary productivity data can be measured and monitored. Some of the common sources are listed for obtaining primary productivity data.

2.1.2 Satellite Imagery

Measuring vegetation indicators like Normalized Difference Vegetation Index (NDVI) and Enhanced Vegetation Index (EVI) are done with the help of Moderate Resolution Imaging Spectroradiometer (MODIS) which provides global coverage.

$$NDVI = (NIR - VIS) / (NIR + VIS) \quad [13]$$

$$EVI = G * ((NIR - R) / (NIR + C1 * R - C2 * B + L)) \quad [14]$$

Another method is Landsat which gives higher spatial resolution than MODIS, suitable for complete land cover and vegetation dynamic monitoring.

2.1.3 Satellites in Ocean Colour

Measuring ocean colour to estimate concentration of chlorophyll-a is monitored using Sea-Viewing Wide Field-of- View Sensor (SeaWiFS). Hence phytoplankton biomass and marine algal bloom can be measured. The figure 2 shows Satellite image by SeaWiFs for Algal detection

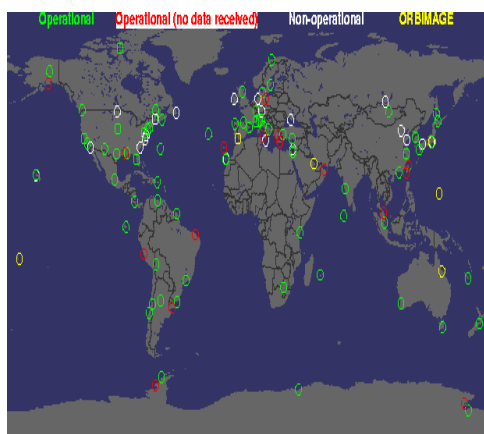


Figure 2: Satellite image by SeaWiFs for Algal detection.

2.1.4 Field Measurements

Chamber-based methods allow to analyse photosynthesis rates of plants or algae. Often employing gas exchange measurements to estimate carbon dioxide absorption and oxygen production, Gathering plant or algal samples to measure biomass growth over time is the biomass harvesting method. Tracks carbon absorption and integration into organic matter using isotopically labelled carbon dioxide (e.g., ^{14}C).

2.1.5 Environmental and Climate Data

Recording information on temperature, precipitation, solar radiation, and other environmental conditions impacting major production are analysed with the help of meteorological stations.

Soil Measurements is used to identify the soil characteristics including nutrient content, pH, and moisture levels that impact plant growth and production effects. The figure 3 shows Environmental and climate change image.



Figure 3: Environmental and climate change image.

2.2 Remote Sensing Products and Database

To access a wide range of satellite data products, including MODIS, Landsat, and other remote sensing datasets NASA Earth Observing System Data and Information System (EOSDIS) provides large dataset in real time.

European Space Agency (ESA) Earth Observation Data offer satellite data for monitoring land and ocean conditions essential to primary production.

2.2.1 Data Preprocessing

Getting major productivity data available for deep learning models relies crucially on data preparation. Typical cleaning, preprocessing, and data preparation techniques are discussed.

2.2.2 Data Cleansing

Managing Missing Values: Find and fix missing data points. Strategies like imputation using mean, median, or mode or deletion of incomplete records may be utilized dependent on the dataset and nature of missing information.

Look for outliers that might alter the data distribution or impair model performance. Statistical tools (e.g., z-score) or domain-specific knowledge may assist one to locate outliers.

To boost model training convergence, normalization /standardization is used to size numerical features to a similar range. Common strategies include standardizing (scaling to zero mean and unit variance) or min-max scaling (scaling to $[0, 1]$).

2.2.3 Data Translation

Feature engineering extract new features from present ones maybe enhancing model performance. Regarding major productivity, this can involve aggregating meteorological variables (e.g., monthly averages) or calculating vegetation indices from satellite data (e.g., NDVI, EVI).

To minimize noise and capture long-term trends, temporal aggregation is used to aggregate daily measurements which converts into meaningful intervals either monthly or seasonal averages.

Using interpolation methods (e.g., bilinear interpolation) aligns spatial resolutions of various datasets (e.g., satellite pictures, climate data) to a same grid or resolution.

2.2.4 Information Integration

Integrate various datasets e.g., satellite photos, temperature data, ground measurements into a cohesive dataset appropriate for deep learning models. Throughout merging, maintain uniformity in timestamps, geographical locations, and data formats.

While lowering dimensionality and computational complexity, pick important qualities that most assist to forecast major production. Feature selection may benefit from approaches including feature significance from machine learning models or correlation analysis from statistical models.

2.2.5 Split Data

Creates various set of data for training, validation, and testing from the given dataset. The deep learning model is trained using the training set; the validation set sets hyperparameters and records model performance; the test set analyses the final model performance on unprocessed data.

For time-dependent data that instance, seasonal swings in primary productivity ensure that training and testing datasets are split in a method that respects temporal dependencies and mimics real-world deployment conditions.

2.2.6 Getting Model Training Input Data

Transpose data into representations suited for deep learning models (like tensors for neural networks). Make that input features suit the specified deep learning framework (e.g., TensorFlow, PyTorch) and are correctly ordered.

Considering hardware restrictions (e.g., GPU RAM), partition the training data into batches to facilitate efficient model training and optimization.

Following these preprocessing strategies enables to ensure correct cleaning, transformation, and integration of essential productivity data for training deep learning models. Appropriately produced data boosts the generalizability, accuracy, and reliability of models used to predict primary output in ecosystems.

3 FEATURE REVIEW

When anticipating primary production, feature engineering is particularly crucial in increasing the performance of deep learning models. Several other

variables or qualities acquired from the data can potentially boost model performance.

3.1 Vegetational Indices

Calculated using satellite photographs to assess green vegetation, Normalized Difference Vegetation Index are sensitive to differences in canopy structure and chlorophyll content, NDVI is a robust indication of photosynthetic activity and primary production.

Designed to limit atmospheric influences and soil background changes, Enhanced Vegetation Index (EVI) like NDVI but delivers a more accurate assessment of vegetation density.

3.2 Variables of Climate and Weather

Over various periods e.g., the growth season average, maximum, or lowest temperatures impact photosynthetic rates and plant development.

Rainfall frequency and quantity affects soil moisture levels and nutrient availability, consequently influencing plant yield.

Incoming light energy effects photosynthetic rate as well as overall plant growth.

3.3 Land Surface Features

Using satellite data or land use maps enables one to identify land cover types (e.g., woodlands, grasslands, croplands) in respect to key productivity variations.

Terrain characteristics like height, slope, and aspect effect microclimatic conditions and water availability, consequently impacting plant growth.

3.4 Attributes of Soil

Soil Moisture- The quantity of moisture in the soil impacts plant water stress and nutrient absorption, consequently impacting major production.

Plant growth and biomass building are regulated by differences in nitrogen, phosphorus, potassium, and other important nutrients.

3.5 Phenological Measurements

The length of the growth season is, the duration of favourable conditions for plant development affects output patterns.

Satellite data enables one to calculate time of leaf emergence and senescence, hence revealing seasonal variations in vegetation activity.

3.6 Metrics Derived from Satellite Data

Patterns and variability in vegetation indicators across time for example, seasonal patterns, anomalies to capture changes in primary output.

Spatial heterogeneity in vegetation indices or climatic factors allows comprehension of landscape-scale processes and ecosystem productivity gradients.

4 DEEP LEARNING ALGORITHMS

Several aspects including data type (e.g., satellite imagery, time series data), computational resources, and unique research purposes impact the choice of deep learning architectures for assessing key productivity. These are several common deep learning architectures that might fit.

4.1 Convolutional Neural Networks (CNN)

CNNs are ideal for analysing spatial data like land cover maps or satellite photos. Usually containing convolutional layers for feature extraction, pooling layers for spatial down sampling, and fully connected layers for classification or regression, architecture. Effective capture of spatial dependencies and patterns makes one robust to spatial transformations and fluctuations.

Accepts input data usually satellite pictures or other spatial data shown as multi-channel tensors (e.g., RGB channels for imaging). Convolutional layers enable you capture spatial patterns by means of feature extraction utilizing convolutional filters. Every layer employs a set of filters then activates using functions. ReLU (Rectified Linear Unit) is commonly employed because of its efficiency and aptitude to handle sparse gradients. Down sample feature maps to smaller spatial dimensions while still keeping considerable information using pooling layers. For usage in fully connected layers, flattening layer turns 2D feature maps into a 1D vector.

Fully Connected (Dense) Layers: Handle the flattened features for either classification or regression operations. Usually employing a softmax activation for classification or a linear activation for regression, Layer creates predictions.

Randomly marks a fraction of input units to zero during training to avoid overfitting and increase

generalization. The figure 4 shows convolutional Neural Network.

Normalizing input data throughout the mini-batch, batch normalisation stabilises and speeds up the training process. Penalizes large weights to prevent overfitting and model complexity.

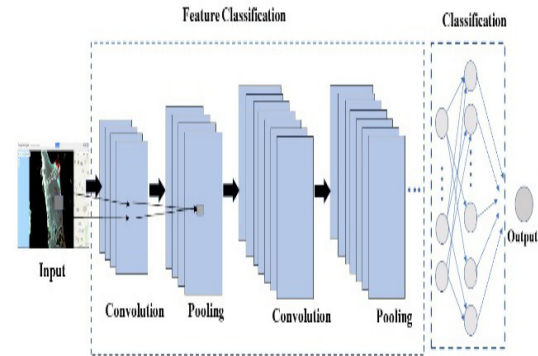


Figure 4: Convolutional Neural Network.

4.2 Long Short-Term Memory (LSTM)

Appropriate for time series data includes primary production temporal patterns, phenological metrics, or climatic influences. RNNs and LSTMs handle sequential input by way of recurrent connections, hence capturing temporal relationships and patterns across time. Suitable for prediction and anomaly detection in time series data, advantages include managing variable-length sequences and keeping remembrance of earlier inputs.

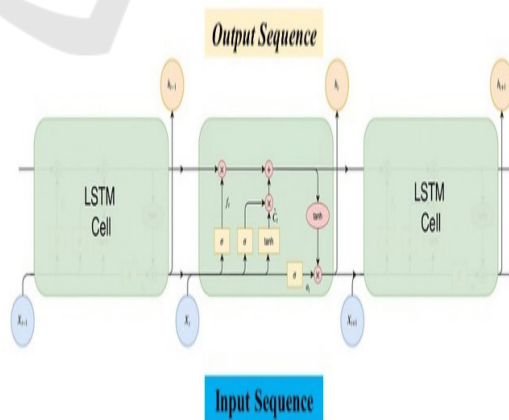


Figure 5: LSTM.

Accepts sequential data containing temporal trends in key productivity or climatic variable time

series. Process sequential input data in LSTM (or RNN) Layers retaining a memory state to capture temporal dependencies. Often utilized tanh or sigmoid activations inside LSTM cells to modulate information flow. Based on the studied sequence data it generates predictions.

Applied to LSTM (figure 5) cell input and recurrent connections, Dropout helps to decrease overfitting and boost model generalization. L2 Regularization: Possibly employed to penalize network's large weights.

4.3 Convolutional-LSTM

Ideal for spatiotemporal data analysis, application blends spatial and temporal linkages. Combining CNNs with LSTM cells lets the model learn spatial patterns via convolutional operations and temporal dynamics via recurrent connections. Effective for evaluating key production trends considering both geographical and temporal interactions, it also aids satellite-derived data with both spatial and temporal dimensions.

Like in a normal CNN, convolutional layers extract spatial information from incoming data. Replace standard pooling layers with LSTM cells to incorporate temporal dependencies and enable the model continuously record spatial and temporal trends. ReLU for convolutional layers and tanh or sigmoid within LSTM cells comprise activation function. Based on the unique building design, optional pooling layers.

Applied for regularity both convolutional and LSTM layers is Dropout. During training, batch normalisation enhances stability and convergence speed. The figure 6 shows Convolutional- LSTM Architecture.

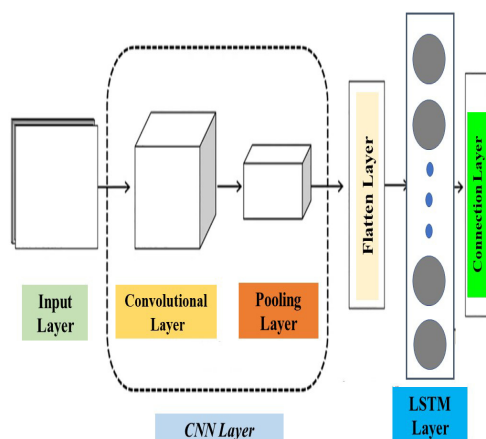


Figure 6: Convolutional- LSTM Architecture.

4.4 Architectures Based on Transformers

Recently updated for sequential data with intricate relationships, such as satellite time series or meteorological data, such application. Transformer models like the well-known BERT (Bidirectional Encoder Representations from Transformers) use self-attention approaches to discover global dependencies and links in input sequences. Scalable to enormous datasets, able to capture long-range associations, and efficient in operations employing context knowledge and pattern identification in time series data. Useful for analysing intricate time series or satellite data, attention mechanism employs self-attention layers to represent global dependency across input sequences. Comprising multiple layers of multi-head attention and feedforward neural networks, Transformer Blocks aid to allow data context and relationship learning. Usually incorporates ReLU in feedforward networks and, if necessary, softmax for classification duties. Applied to feedforward networks and attention layers, dropout helps to prevent overfitting. Applied separately across the features of every sample, Layer Normalisation is analogous to batch normalisation.

5 TRAINING PROCESS FOR PARAMETER VALIDATION

Setting up the training process, modifying hyperparameters, and assessing model performance encompass three essential stages in constructing deep learning models for analysis of primary production. Here is a broad overview of how this training technique normally proceeds.

5.1 Data Preparation

Create training, validation, and test sets out from the dataset. The model is trained using the training set; hyperparameter tweaking and performance monitoring during training are conducted using the validation set; the test set analyzes the performance of the final model on unprocessed data. Apply adjustments including rotation, scaling, or flipping to offer additional training data by decreasing overfitting and hence boosting model generalization.

5.2 Model Choosing

Based on the sort of the primary production data either spatial, temporal, or spatiotemporal. select an appropriate deep learning architecture (such as CNN, LSTM, ConvLSTM, Transformer).

5.3 Hyperparameter for Learning Rate

Change the model's weight update rate during training. While too low could result from delayed convergence, too high might generate instability.

Find out the sample count handled prior to weight update for the model. Though they may demand more memory, greater batch sizes may boost computer efficiency.

Specify the total number of times the full dataset is passed through the model during training.

Choose an optimizer (such as Adam, SGD) that updates the weights of the model based on the loss function's gradient.

To stop overfitting, alter dropout rates, L2 regularization strength, or batch normalizing parameters.

5.4 Training Models

Table 1: Sample Water Quality Parameters.

Water Quality Parameters	Summer 2024				
		Jan	Feb	Mar	Apr
Salinity	Min	30	29	30	30
	Max	33	31	31	36
Temperature	Min	30	29	31	32
	Max	31	32	36	35
pH	Min	6	7.2	7.5	7.8
	Max	8	8.3	8.1	8.5
Dissolved Oxygen	Min	3.1	2.6	2.8	2.5
	Max	3.6	3.5	4.2	3.4
Nitrite	Min	0.172	0.13	0.546	0.526
	Max	0.394	0.36	0.881	0.914
Nitrate	Min	0.89	0.80	1.12	2.18
	Max	1.1	1.11	1.9	1.76
Phosphate	Min	0.31	0.39	0.74	0.52
	Max	0.61	0.58	1.1	1.18
Silicate	Min	6.6	10.6	23.7	23.6
	Max	25.5	20.8	75.4	79.53

Feed batches of training data into the model then execute predictions.

Using a suitable loss function for e.g., mean squared error for regression, categorical cross-entropy for classification to calculate the loss (error) between anticipated outputs and actual objectives. The table 1 shows Sample Water Quality Parameters.

Using automated differentiation, construct gradients of the loss with relation to model parameters Backward Pass (Backpropagation). Update model weights using the specified optimizer to decrease the loss function is called gradient descent.

In the assessment of water nutrients, water samples were collected on a monthly basis. Samples of water were taken from the near channels and

examined for nutrient levels that include nitrite, nitrate, phosphate and silicate.

5.5 Proof

Periodically check the model on the validation set during training to monitor performance parameters (e.g., accuracy, RMSE) and detect overfitting.

Stop training if, after a defined period of epochs, performance on the validation set does not rise to prevent overfitting.

6 RESULTS AND DISCUSSIONS

Depending on the individual task the classification, regression, or time series forecasting is done with the help of certain metrics. Variety of evaluation criteria may be employed to measure the

effectiveness of deep learning models for assessing primary production. These are some significant evaluation criteria widely used in numerous contexts.

6.1 Classification Measurements

6.1.1 Confusion Matrix

Table 2: Correct and Inaccurate Predictions.

	Predicted Algae A	Predicted Algae B	Predicted Algae C
Actual Algae A	20 (TP)	5 (FN)	1 (FN)
Actual Algae B	3 (FP)	15 (TP)	2 (FN)
Actual Algae C	0 (FP)	2 (FP)	18 (TP)

Table 2 displaying below is divided down by each class, the number of correct and inaccurate predictions given by a classifier. The figure 7 shows Classification Metrics.

- **True Positive (TP):** Specific class anticipated accurately.
- **False Positive (FP):** Said to be a specific class but in reality, it belongs to another class.
- **False Negative (FN):** is not anticipated as a given class while it truly belongs to that class.
- **True Negative (TN):** Designed to be not a certain class, predicted precisely.

The model failed predicting Algae A five times (FN), but accurately predicted Algae A twenty times (TP).

When Algae A was missing, the model mistakenly predicted Algae A three times (FP).

By using these variables, one may create accuracy, recall, and other metrics to analyze the performance of the model for every class.

6.2 Accuracy

computes among all the model's predictions the proportion of correct forecasts. The table 3 shows Comparative study between Standard Technique and Deep learning.

$Acc(A) = \text{sum of all estimated predictions} / \text{Total no of overall predictions}$

Here:

Correct guesses aggregated across all classes: $20 + 15 + 18 = 53$.

Total number of predictions $53 + 5 + 3 + 1 + 2 + 2 = 66$

$Acc(A) = \text{about } 0.80$.

6.3 Precision

Calculates among all the positive forecasts the proportion of true positive predictions, sometimes known as properly expected positives.

$Precision(P) = TP / (TP + FP)$

$Precision(P \text{ for Algae A}) = 0.87$ approximately.

$Precision(P \text{ for Algae B}) = 0.75$

$Precision(P \text{ for Algae C}) \approx 0.86$

6.4 Recall

Calculates, from all the actual positives in the dataset, the proportion of real positive predictions.

$Recall(R \text{ for Algae A}) = TP / (TP + FN)$

$Recall(R \text{ for Algae A}) = 0.80$ precisely.

$Recall(R \text{ for Algae B}) = 0.88$ approximately.

$Recall(R \text{ for Algae C}) = 0.90$ approximately.

6.5 F1-SCORE

Harmonic mean of accuracy and recall delivers a reasonable evaluation of the two metrics.

$F1 \text{ Score} = 2 * (Precision * recall) / (Precision + Recall)$

Algae A's F1 score Roughly 0.83

Algae B's F1 score equally 0.81

Algae C's F1 score Roughly 0.88

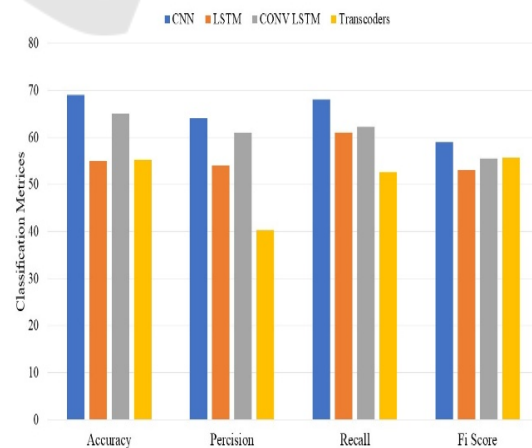


Figure 7: Classification Metrics.

Table 3: Comparative study between Standard Technique and Deep learning.

Categories	Deep learning models	Traditional models
Precision & Predictive range	Usually displays outstanding accuracy when taught on huge sets. Can handle intricate interactions in the data and nonlinear linkages.	Useful only on a tiny quantity of data. They often may be tested against theoretical frameworks and gives insights on causal links.
Openness & Interoperability	Though they are advancing in interpretability methodologies, deep learning models may still lack the direct causal insights afforded by mechanistic models.	In ecological research, where verifying model assumptions and grasping model outputs hinges on enhanced interpretability and transparency, classical methodologies give precisely these traits.
Scalability & Data requirement	Although they are resource-intensive, deep learning models gain from scalability with enormous datasets.	Smaller datasets and preserve interpretability make conventional techniques more practical; consequently, they match studies with constrained data availability or when clear ecological theories lead modelling.

7 CONCLUSIONS

Marine environment prediction is a challenging task. This work provides a detailed empirical analysis on various deep learning algorithms used for forecasting primary productivity in marine environment. Various classification metrics were also studied. Although deep learning models has been applied successfully in various application areas, building a appropriate model is essential based on their variations and dynamic nature for the real world problems. High level data representation and large amount of raw data can be produced with deep learning. A successful technique should provide accurate data driven modelling based on the nature of raw data. Deep learning has proved to be useful in analysing various range of applications.

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