

# Evaluating the Generalizability of Machine Learning Models for Seismic Data Prediction Across Different Regions

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**Keywords:** Machine Learning, Earthquakes, Prediction, Generalizability.

**Abstract:** Earthquake prediction is a critical challenge, requiring advanced methods with strong generalization capabilities. This paper investigates the generalization of traditional machine learning models—Linear Regression (LR), Support Vector Regression (SVR), Random Forest (RF), K-Nearest Neighbors (KNN), and Decision Tree (DT)—in predicting earthquake magnitudes across different geographic distributions. Using seismic data from the United States Geological Survey (USGS), the study trains models on data from the Eastern Hemisphere and tests them on the Western Hemisphere, evaluating their performance and ability to migrate across regions. The RF model showed superior generalization with the lowest mean squared error (MSE) and the highest  $R^2$  value, indicating robust performance across different distributions. In contrast, the KNN model struggled, reflecting its limitations in handling diverse data. The study's findings demonstrate the reliability of RF in generalizing across distributions and the significance of model selection when working with information from various geographic areas. More comprehensive knowledge of model migration and its adaptability to various datasets is facilitated by this work, opening the door for more trustworthy earthquake prediction models.


## 1 INTRODUCTION

Natural disasters have always posed significant threats to human life, infrastructure, and the environment. Among these disasters, earthquakes are among the most destructive due to their sudden occurrence and devastating impacts. An earthquake is typically caused by the rapid release of energy in the Earth's crust, usually due to tectonic activities like fault slips. Earthquakes can trigger secondary hazards such as tsunamis, landslides, and building collapses, which amplify the risks to human populations (Duan, 2021; Mavrouli, 2023). Given the frequency and severity of seismic events, the ability to predict earthquake magnitudes is crucial for early warning systems and risk mitigation strategies.

However, traditional earthquake prediction methods, primarily based on seismological data analysis and empirical models, have significant limitations. These methods often struggle with accurately predicting the timing, location, and magnitude of seismic events due to the highly complex nature of geological processes (Wald, 2020;

Mignan, 2020). With advancements in computational technology, there is increasing interest in using Artificial Intelligence (AI) techniques to improve prediction accuracy and address these challenges. AI models, leveraging large datasets and sophisticated algorithms, have shown promise in capturing non-linear patterns. Combining AI with seismological data could enhance earthquake prediction capabilities, making this field an essential area of exploration (Banna, 2020; Bhatia, 2023).

AI has rapidly evolved over the past few decades and has been successfully applied in various domains, ranging from healthcare and finance to environmental monitoring and disaster management (Secinaro, 2021; Goodell, 2021; Ullo, 2020; Sun, 2020). Representative machine learning algorithms have demonstrated impressive performance in complex tasks, including pattern recognition, time-series forecasting, and anomaly detection (Pisner, 2020; Aguilar, 2023; Patil, 2020). In the field of geosciences, AI has been increasingly used for natural disaster predictions. For instance, Makinoshima et al. proposed a deep learning model

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using Convolutional Neural Networks (CNNs) that integrates geodetic observation data and oceanographic data to predict tsunami events along the Pacific coast of Japan (Makinoshima, 2021). Similarly, Ruttgers et al. used Generative Adversarial Networks (GAN) to predict the trajectory and intensity of typhoons in the Northwest Pacific based on historical meteorological data (Ruttgers, 2022). In earthquake prediction, Cui et al. (2021) employed a stacking-based ensemble learning model for earthquake casualty prediction. The model employs XGBoost, Bagged Decision Trees, and Gradient Boosting Decision Trees (GBDT) as first-level base learners and GBDT as a second-level meta-learner. Popular machine learning techniques including SVM, RF, and Classification and Regression Trees (CART) were surpassed by the suggested approach (Cui, 2021). Additionally, Iaccarino et al. (2023) utilized a Gradient Boosting Regressor (GBR) and achieved reliable results in predicting the seismic ground motion intensity (Iaccarino, 2023).

Despite these advances, current approaches often fail to consider variations in geographical distributions, such as the differences between seismic activities in the Eastern and Western Hemispheres. This limitation could affect the generalizability of models when applied to regions with distinct geological characteristics. In order to close this gap, the present work uses seismic data from various hemisphere distributions to assess how well various machine learning models predict earthquake magnitudes. By systematically comparing the generalization capabilities of models trained on Eastern Hemisphere data and tested on Western Hemisphere data, the study aims to provide insights into the robustness and adaptability of popular AI models for seismic prediction.

The technical approach of this research involves dividing the seismic data into two classes: Eastern Hemisphere and Western Hemisphere. The models under consideration include LR, SVR, RF, KNN, and DTs. The methodology is structured as follows: (1) preprocessing and feature extraction from the seismic dataset, (2) training models using Eastern Hemisphere data, (3) evaluating model performance on Western Hemisphere data, and (4) examining and contrasting the models' generalizability using different assessment metrics, including Mean Absolute Error (MAE), MSE, Root Mean Squared Error (RMSE), and  $R^2$ . The study also explores the implications of these findings for improving seismic prediction models and enhancing their practical applicability in disaster management.

## 2 METHOD

This section outlines the dataset preparation, the specific machine learning models utilized, and the evaluation metrics adopted in this study. The aim is to assess the generalizability of various machine learning models in predicting earthquake magnitudes based on seismic data from different hemispheres (i.e. training on Eastern Hemisphere and testing on Western Hemisphere).

### 2.1 Dataset Preparation

The seismic dataset used in this study was sourced from USGS, which provides a comprehensive collection of earthquake data worldwide (USGS, 2024). The data covers seismic events from the Eastern Hemisphere and the Western Hemisphere. Specifically, the data range from records of earthquakes with magnitudes greater than 4.5 since 2020, with 19,671 records collected in the Eastern Hemisphere and 14,075 records in the Western Hemisphere, providing a robust basis for model training and testing. The dataset consists of 22 features in total such as time and latitude.

Given the scope and nature of this study, which focuses on predicting earthquake magnitudes, the primary target variable is "Magnitude(ergs)." The task is thus framed as a regression problem. The dataset underwent feature selection and index conversion as part of preprocessing to improve model performance and lower complexity. The "time" feature was converted into an index to simplify chronological ordering, while the number of features was reduced to eight essential predictors: "Latitude(deg)," "Longitude(deg)," "Depth(km)," "Magnitude(ergs)," "Magnitude\_type," "No\_of\_Stations," "horizontalError," and "depthError." Notably, the dataset did not contain missing values, obviating the need for imputation.

In this study, the models use six features for prediction: "Latitude(deg)," "Longitude(deg)," "Depth(km)," "No\_of\_Stations," "horizontalError," and "depthError." The training and testing datasets are divided based on hemispheres: the Eastern Hemisphere dataset is used for training, while the Western Hemisphere dataset is used for testing. This division is critical in evaluating the generalizability of the models across different geographic distributions.

## 2.2 Machine Learning Models-Basesd Prediction

The study employs five distinct machine learning models: LR, SVR, RF Regression, KNN Regression, and DT Regression. All models were implemented using the scikit-learn (sklearn) library in Python. To verify each model's generalizability, it was first trained using data from the Eastern Hemisphere and then tested using data from the Western Hemisphere. These metrics were used to assess each model's performance:  $R^2$ , MAE, MSE, and RMSE.

### 2.2.1 Linear Regression

Regression analysis's most basic and widely applied algorithm is LR. It explains the relationship between a dependent variable and one or more independent variables by fitting a linear equation to observable data. The formula for a simple LR is given as:

$$y = \beta_0 + \beta_1 x + \epsilon \quad (1)$$

Where  $y$  stands for the predicted value,  $\beta_0$  for the intercept,  $\beta_1$  for the slope of the line,  $x$  for the input variable, and  $\epsilon$  for the error term (Maulud, 2020). By minimizing the sum of squared residuals—the variations between observed and anticipated values—the least squares method was used in this study to fit the model. More intricate models can be compared to the LR model as a baseline.

### 2.2.2 Support Vector Regression

SVR extends the principles of SVM to regression tasks. The primary objective of SVR is to find a hyperplane that best fits the data points within a predefined margin of tolerance (Bansal, 2022). SVR uses a kernel trick to transform data into a higher-dimensional space, making it easier to perform LR in this transformed space. The Radial Basis Function (RBF) kernel is widely used in SVR due to its flexibility in handling non-linear data patterns. The RBF kernel function is defined as (Montesinos, 2022):

$$K(x_i, x_j) = \exp(-\gamma \|x_i - x_j\|^c) \quad (2)$$

The SVR model used in this work has the following hyperparameters set:  $\gamma = 0.1$ ,  $C = 1$ , and kernel = 'rbf'. The influence of individual data points is defined by the parameter "gamma," while the trade-off between obtaining a narrow error margin and preserving a smooth decision border is managed

by the parameter "C." When there is a non-linear relationship between characteristics, SVR is especially helpful, which makes it a good fit for complex seismic data.

### 2.2.3 Random Forest Regression

RF is an ensemble learning technique that lessens overfitting and increases accuracy by combining the predictions of several Decision Trees. In regression tasks, RF averages the outputs of individual trees to produce a final prediction. To ensure diversity across the trees, each tree is trained on a random portion of the data and only takes into account a random subset of features for splitting at each node (Genuer, 2020).

The hyperparameters for the RF Regressor used in this study were set as 'n\_estimators=1000', where 'n\_estimators' represents the number of Decision Trees in the forest. The model is an effective tool for estimating earthquake magnitudes because of its resilience to noise and capacity to manage high-dimensional data, particularly in situations where the data distribution is intricate and has non-linear correlations.

### 2.2.4 K-Nearest Neighbors Regression

A non-parametric, instance-based learning approach called KNN Regression uses the values of a data point's k-nearest neighbors to predict the value of a new data point. The target point and every other point in the training set are measured using the Euclidean distance technique. The prediction is then determined by averaging the values of the k-nearest neighbors (Bansal, 2022).

In this study, the value of k was set to 5 ('n\_neighbors=5'), which balances bias and variance. Even while KNN is easy to use and understand, when working with big datasets, it can be computationally demanding and sensitive to the size of the features. Despite these limitations, KNN was included in this study for its effectiveness in capturing local data patterns and trends.

### 2.2.5 Decision Tree Regression

A non-linear predictive model called DT Regression divides the dataset recursively at decision nodes until a leaf node is reached. It does this by dividing the data into subsets according to feature values. The final prediction is contained in the leaf node, while each decision node represents a feature and each branch a potential result. The DT algorithm selects the feature that results in the highest information gain or lowest mean squared error at each split (Bansal, 2022).

Although DTs are prone to overfitting, they are easy to visualize and interpret, making them a valuable tool for exploring feature importance and model behavior (Charbuty, 2021). In this study, a standard DT Regressor was employed with default settings.

### 3 RESULTS AND DISCUSSION

This section presents the findings of the study and offers a critical analysis of the results obtained from applying five machine learning models—LR, SVR, RF, KNN, and DT—to earthquake magnitude prediction. In the subsequent analysis, the strengths, weaknesses, and insights gained from the experiments are discussed in detail, alongside a reflection on the limitations and suggestions for future improvements.

#### 3.1 The Performance of Models

The results of the experiment are provided in Table 1, where the performance metrics for each model are summarized.

The RF model consistently outperformed the other models in terms of predictive performance; it had the lowest MAE (0.2331), MSE (0.1057), RMSE (0.3251), and positive  $R^2$  value (0.2230). These measures show that when it comes to predicting earthquake magnitudes across various geographies, the RF model has a more favorable balance between bias and variance, which leads to improved generalizability. On the other hand, the KNN model performed the worst, as evidenced by large error rates and a markedly negative  $R^2$  value (-0.6002), indicating inadequate dataset adaption.

To better visualize the performance of each model, scatter plots depicting actual versus predicted values were generated for each model:

The scatter plot shown in Figure 1 reveals that the model tends to underestimate earthquake magnitudes, particularly for magnitudes exceeding 5. The alignment of points close to the perfect prediction line is mostly observed for lower magnitudes, where linearity assumptions hold.

The SVR model shown in Figure 2 shows a highly clustered set of predictions with limited variance, indicating that the model struggles to capture the dynamic range of the data. This results in consistently inaccurate predictions.

The scatter plot shown in Figure 3 shows the RF model's predictions are closely aligned with actual values, with most prediction errors within a 1 to 1.5 unit range. This suggests that the ensemble approach effectively captures complex relationships.

The KNN's in Figure 4 predictions are concentrated between 4.5 and 5.5, leading to significant inaccuracies for larger earthquake magnitudes. The pattern highlights the model's inability to generalize beyond local data points.

The DT model shown in Figure 5 demonstrates considerable prediction errors, with points scattered away from the perfect prediction line, particularly in the lower left corner. This reflects the model's tendency toward high variance and overfitting.

Additionally, two key plots provide further insights:

A feature importance plot shown in Figure 6 for the RF model highlights the relative importance of each input feature. Notably, the features "No. of Stations" and "Depth Error" stand out as the most influential factors in predicting earthquake magnitudes.

A line plot shown in Figure 7 showing the first 100 actual and predicted values in the test dataset for the RF model illustrates that while the model follows the general trend, there are noticeable deviations, particularly at higher magnitudes. This indicates some limitations in fully capturing the non-linear relationships in seismic data.

Table 1: Performance Metrics of Each Model.

Model Name	MAE	MSE	RMSE	$R^2$
Linear Regression	0.241816	0.131785	0.363022	0.031435
SVR	0.277640	0.137359	0.370620	-0.009529
Random Forest	0.233067	0.105717	0.325141	0.223026
KNN	0.373962	0.217721	0.466606	-0.600158
Decision Tree	0.302034	0.199197	0.446315	-0.464016

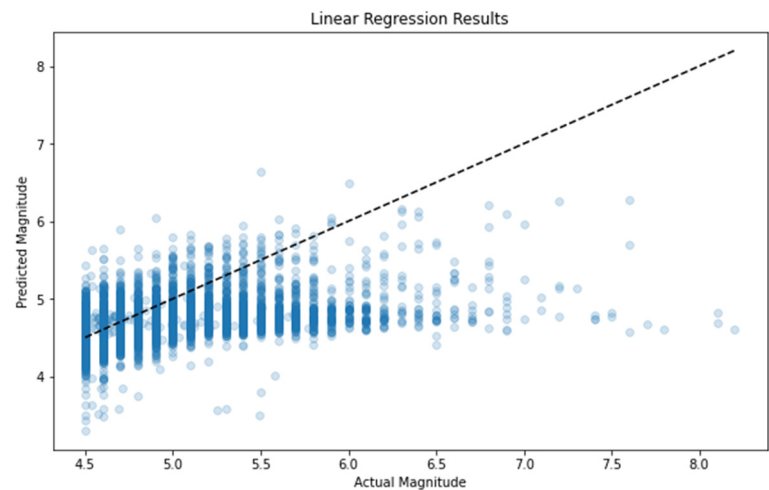


Figure 1: Linear Regression Result (Photo/Picture credit: Original).

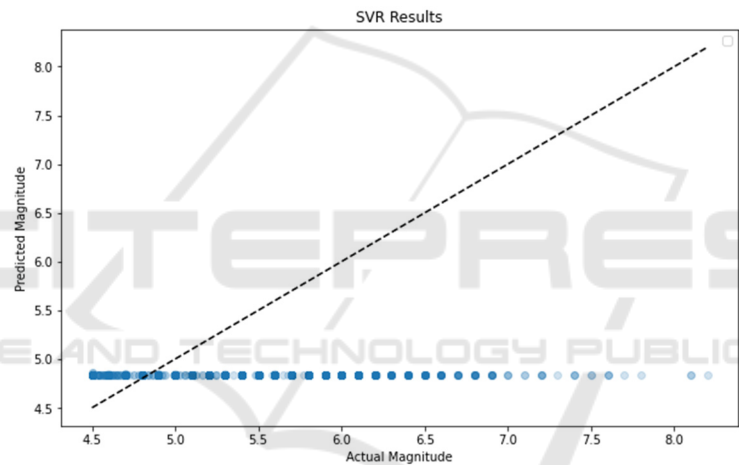


Figure 2: SVR Result (Photo/Picture credit: Original).

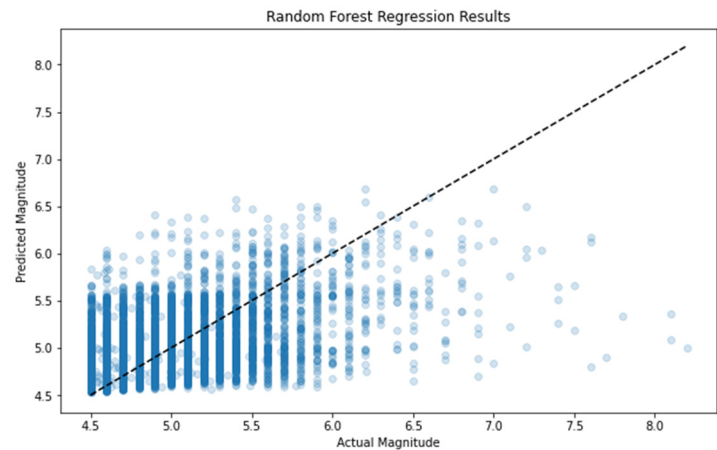


Figure 3: Random Forest Result (Photo/Picture credit: Original).



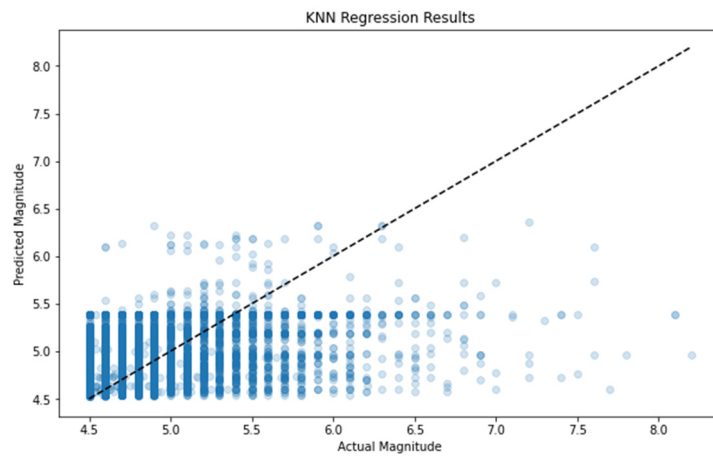


Figure 4: KNN Result (Photo/Picture credit: Original).

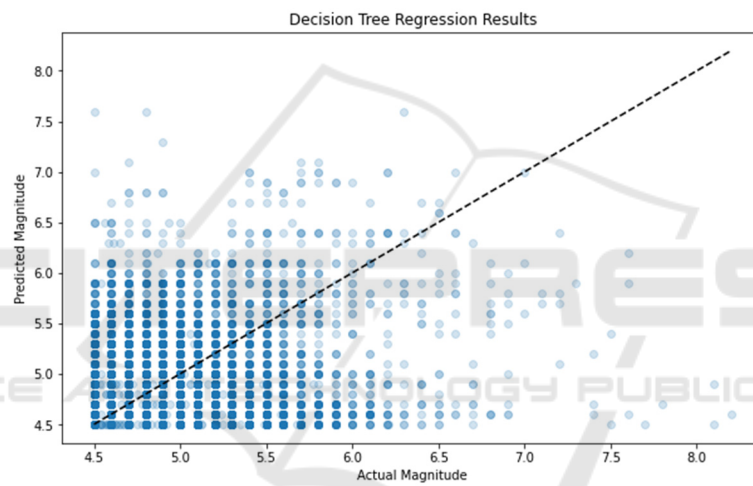


Figure 5: Decision Tree Result (Photo/Picture credit: Original).

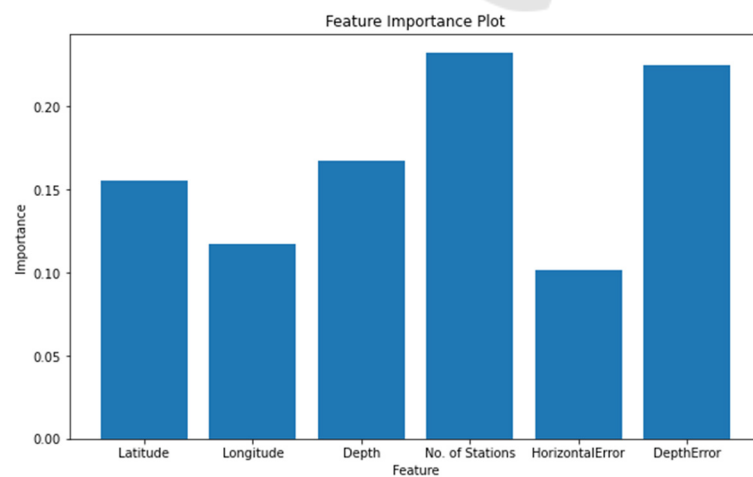


Figure 6: Feature Importance Plot (Photo/Picture credit: Original).

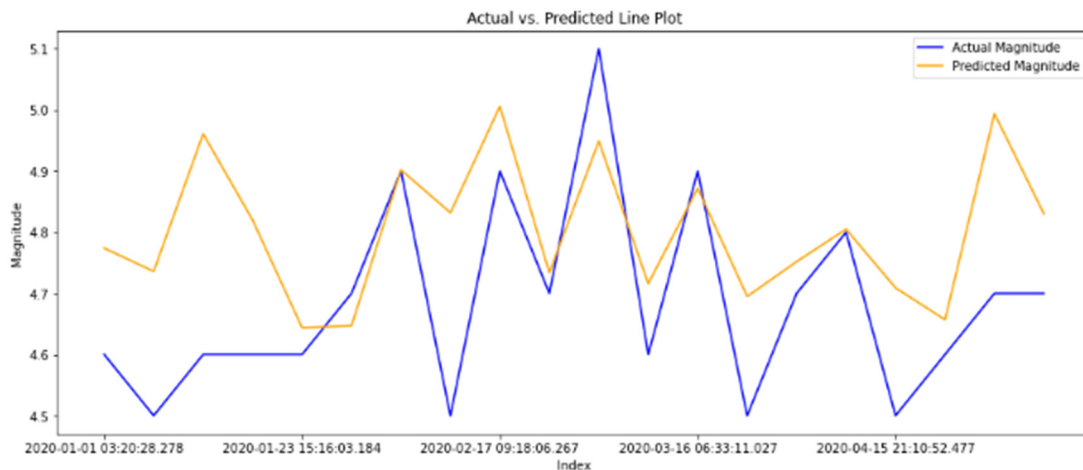


Figure 7: Actual vs. Predicted Line Plot (Photo/Picture credit: Original).

### 3.2 Analysis and Discussion

The study's conclusions offer significant new understandings into the applicability of different machine learning methods for assessing the size of earthquakes in diverse geographic locations. The ensemble aspect of the RF model, which combines several Decision Trees to average out mistakes and lower the risk of overfitting, is responsible for its better performance. For a complicated task like earthquake prediction, this method is very useful in capturing non-linear correlations and interactions among the characteristics. Large feature spaces and reduced variance were advantages of the RF model in this investigation, which led to more accurate predictions.

In contrast, the KNN model's poor performance is largely due to its sensitivity to noisy data and its reliance on localized patterns. The model tends to perform well when data is uniformly distributed; however, in this case, the geographic and seismological variations across different regions introduce significant challenges. The high-dimensional feature space further exacerbates the model's limitations, leading to suboptimal predictions clustered within a narrow range.

The LR model, while simple and interpretable, failed to capture the complex relationships inherent in the data. The model works well for linear trends, as seen in its reasonably good predictions for magnitudes below 5, but struggles with non-linear patterns, leading to consistent underestimations for higher magnitudes.

The SVR model, using an RBF kernel, did better at capturing some non-linearities, but its performance

was hindered by the challenge of tuning hyperparameters like the penalty parameter ( $C$ ) and kernel coefficient ( $\gamma$ ). The model's tendency to produce similar predictions regardless of input variations suggests it did not generalize well to the unseen test set.

The DT model, despite being interpretable and fast, showed high variance, leading to overfitting. The model's lack of regularization resulted in large prediction errors, as seen in the widely scattered points on the scatter plot. This behavior is typical of DTs when they fail to generalize beyond the training data.

Several important findings emerge from this study. First, models trained solely on Eastern Hemisphere data struggled to generalize effectively to Western Hemisphere data, emphasizing the importance of considering regional heterogeneity in seismic modeling. This result points to a potential limitation in some existing predictive models that are typically trained on data from one geographic area. It also underscores the necessity of employing transfer learning techniques or training region-specific models when dealing with the task of global earthquake prediction.

Second, the study emphasizes how crucial feature selection is and how it affects model performance. The RF's ability to identify the importance of features like "No. of Stations" and "Depth Error" provides valuable guidance for future research, suggesting that integrating additional features related to seismic activity, geological composition, and real-time monitoring could further enhance prediction accuracy.

## 4 CONCLUSIONS

This paper investigates the generalizability of five machine learning models—LR, SVR, RF, KNN, and DT—in predicting earthquake magnitudes across different geographical distributions. By using seismic data from the Eastern Hemisphere for training and testing on data from the Western Hemisphere, the study highlights the varying effectiveness of these models in handling data distribution shifts. Among the models, RF demonstrated the best predictive performance, while KNN showed the least accuracy. The experimental results underscore the importance of model selection when dealing with datasets from different regions.

The study's conclusions advance the knowledge of model migration and adaptability, particularly in applying machine learning models to datasets with diverse distributions. This exploration is crucial for improving the robustness of predictive models in seismology, potentially aiding in better disaster preparedness and risk mitigation.

However, the study is not without limitations, such as the exclusion of more granular regional data and the lack of temporal dynamics consideration. Future work should address these limitations by incorporating localized geophysical factors and evolving seismic patterns to enhance model generalization further.

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