# Suppression of Background Noise in Speech Signals with Artificial Neural Networks, Exemplarily Applied to Keyboard Sounds

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- Keywords: Artificial Neural Networks, Convolutional Neural Networks, Speech Enhancement, Noise Suppression, Image Processing.
- Abstract: The importance of remote voice communication has greatly increased during the COVID-19 pandemic. With that comes the problem of degraded speech quality because of background noise. While there can be many unwanted background sounds, this work focuses on dynamically suppressing keyboard sounds in speech signals by utilizing artificial neural networks. Based on the Mel spectrograms as inputs, the neural networks are trained to predict how much power of a frequency inside a time window has to be removed to suppress the keyboard sound. For that goal, we have generated audio signals combined from samples of two publicly available datasets with speaker and keyboard noise recordings. Additionally, we compare three network architectures with different parameter settings as well as an open-source tool RNNoise. The results from the experiments described in this paper show that artificial neural networks can be successfully applied to remove complex background noise from speech signals.

## 1 INTRODUCTION AND RELATED WORK

Recently, due to the COVID-19 pandemic, the role of remote communication using audio and visual transmission has significantly increased. However, the quality of speech usually remains not perfect, sometimes reasoned by limited speed of the network connection, but also by various background noises: keyboard sounds, another person speaking, street noise, etc. The suppression of complex background noise (like keyboard noise) is related to the topic of speech enhancement. Traditional methods can handle stationary background noise, for example white noise. Commonly applied algorithms are the Wiener-Filtering, the MMSE Estimator, or the Bayesian Estimator (Loizou, 2013). They all provide different techniques to estimate the components of the clean short-time Fourier transform from a noisy input signal. The techniques above all assume that the noise signal is a stationary stochastic process that is predicted and then removed from the signal. This is not the case for keyboard typing sounds, because their frequency curve is more complex. Furthermore, different models of keyboards can sound entirely different, and also the speed and intensity of typing

can vary significantly. For suppressing complex background noise in speech signals, there exist projects that utilize artificial neural networks. Krisp (Krisp, 2021) and NVIDIA RTX Voice (NVIDIA, 2018) are both closed-source tools that work with neural networks using GPU acceleration to suppress keyboard noise in real time. These projects do not offer details about what network architectures are used and how they are trained. A similar open-source project is RNNoise (Valin, 2021), which uses a small recurrent neural network designed to run in embedded systems with low computational power and no GPU acceleration. Because of the low network complexity, RNNoise is expected to underperform the neural networks that will be proposed in this work. However, it can be trained on a custom dataset which allows for a direct comparison with the results of this work.

In the following, we start with some backgrounds on audio signal processing (Section 2). Then, the used datasets and implemented network architectures are presented in Section 3. The results of several studies which compare the proposed networks and also apply *RNNoise* are discussed in Section 4. The most important findings are summarized in Section 5, and several ideas for future work are proposed in Section 6.

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### 2 AUDIO SIGNAL PROCESSING

#### 2.1 Signal Representation

In order to process a speech signal and separate it from the background noise, a Short-Time Fourier Transform (STFT) is applied. It converts the audio signal into a representation where the power of different frequencies over time can be displayed (Loizou, 2013). A processed STFT spectrogram can be easily inverted to output the original signal. In this work, a STFT based on time frames of 512 samples with a step size of 256 samples is used. With a sample rate of 11025 Hz, this results in a window size of approximately 23.22 ms. The spectrogram is then projected to 128 Mel scale components, to take the non-linearity in human frequency recognition (Kathania et al., 2019) into account.

To allow for potential real time application, the neural network only works on a small portion of the input Mel spectrogram. The current time window is selected together with the preceding 7 windows. This leads to a network input size of  $8 \times 128$  (see Figure 1). The network input is normalized using a logarithmic transform and then rescaled to a range of [0,1].



### 2.2 Signal Separation

The neural network has to output the clean spectrogram without background noise. While it is possible to directly output the Mel spectrogram values, we will use a mask to modify the magnitudes in the spectrogram. The magnitude mask is defined on the magnitudes of clean and noisy speech (Wang and Chen, 2018):

$$MM(t,k) = \frac{|S(t,k)|}{|N(t,k)|}$$
(1)

S is defined as the spectrogram matrix of clean speech and N is the matrix overlaid with the background noise. The indices t and k are the time and frequency containers in these matrices. This magnitude mask is used as a target in the training process. After the network predicts the mask, it can be element-wise multiplied with the current time window of the input spectrogram to recover the clean speech signal. The values can be bounded between 0 and 1, because any values > 1 would only introduce an unnecessary error. For |N(t,k)| = 0, we can set this value to 1, because there would be no background noise in that container.

### **3 EXPERIMENT SETUP**

#### 3.1 Datasets

For the training process, a suitable dataset of both speech and keyboard sound is needed. The speech signals should come from different speakers and the background noise should include multiple different keyboard sounds to train a network with a good general performance. The TIMIT Speech-Corpus (Garofolo et al., 1993) was selected for the speech data. It consists of 6300 spoken sentences by 630 different speakers of varying gender and origin. Roughly 10% of the total speech data (624 sentences by 24 speakers) were selected as the test set for the final evaluation. From the remaining sentences, 80% were used to train and 20% to validate the neural networks. The speakers from the test set were not part of the training set. For the background noise, a dataset from DCASE 2016 (Lafay, Benetos and Lagrange, 2017) (Mesaros et al., 2018) was used. It contains multiple types of background noise, in particular typing sounds from 20 different keyboards. All audio data was sampled at a rate of 11025 Hz. To generate the noisy speech signals, every sentence in the TIMIT dataset was overlaid with typing noise from a random keyboard from the DCASE dataset. Every keyboard noise was scaled with respect to loudness using factors of {1.0, 1.5, 2.0, 2.5} and every sentence with  $\{1.0, 1.5, 2.0, 2.5, 3.0, 3.5, 4.0\}.$ This further increased the amount of available training data and introduces a higher variance in volumes.

#### 3.2 Neural Networks

We have tested three different network architectures. First, a fully connected network consists of two hidden layers with 500 units each with ReLU activation and batch normalization. The output layer has 128 units and sigmoid activation to ensure that the mask values are between 0 and 1. This neural network is denoted below as *NN500*.

Because the network input has a shape of  $8 \times 128$ , a Convolutional Neural Network (CNN) might perform better on two-dimensional data (Skansi, 2018). The used network has 4 convolutional layers that each reduce the time dimensionality. In the frequency dimension, a kernel size of 10 is combined with a stride of 1 in all layers. In the time dimension, the kernel sizes are set to (8, 4, 2, 2) and the strides to (1, 2, 2, 2). The kernel count is (32, 32, 16, 16) per layer. Combined with zero-padding, this reduces the shape to  $1 \times 128$  during the convolutions. After the convolution layers, the flattened activations are fed through a fully connected hidden layer with ReLU activation that is tested with different numbers of neurons. The output layer again has 128 units and sigmoid activation. The fully connected hidden layer is tested with  $\{128, 250, 500, 750\}$  neurons. These architectures are denoted as *CNN128*, ..., *CNN750*.

Third, a Redundant Convolutional Neural Network (RCNN) is proposed, because it was shown in (Park and Lee, 2017) that it can achieve comparable results in speech enhancement with a smaller network size. The network is built using 5 redundant blocks that each has 3 convolution layers (Park and Lee, 2017). Each block has (18, 30, 8) kernels at a kernel size of (9, 5, 9). With a stride of 1 and zero-padding, there is no dimension reduction between the blocks. The redundant convolutions reduce the time dimension of the input in the first block and thus have significantly less parameters than the CNNs. Just like in the traditional CNNs, the flattened activations are fed through a fully connected hidden layer with ReLU activation that is tested with {128, 250, 500} neurons. The magnitude mask is output using a layer with 128 units and sigmoid activation. The RCNN architectures are denoted as RCNN128, ..., RCNN500. Additionally, we test a RCNN without a fully connected hidden layer, denoted as RCNN.

All neural networks are trained using an ADAM Optimizer (Bock and Weiß, 2019) with a learning rate of 0.0001 and a batch size of 128 for 100 epochs. For the loss function, the mean squared error of the magnitude masks is used.

## 4 EVALUATION OF EXPERIMENTS

#### 4.1 Initial Training

Table 1 presents the overview of several evaluation measures estimated for the test set. Columns 2 and 3 show the Mean Squared Errors (MSE) for the generated masks (Eq. 2) and the respective spectrograms (Eq. 3). The best results with respect to  $MSE_{mask}$  and  $MSE_{spec}$  are achieved by CNN750. The remaining CNN architectures all perform marginally better than the redundant convolution networks.

*RCNN250* reaches the lowest error out of the tested RCNNs. To show the differences between the examined network models, their output can be visually compared.

$$MSE_{mask} = \frac{1}{TK} \sum_{t=0}^{T} \sum_{k=0}^{K} \left( MM(t,k) - \widehat{MM}(t,k) \right)^2$$
(2)

$$MSE_{spec} = \frac{1}{TK} \sum_{t=0}^{T} \sum_{k=0}^{K} (|N(t,k)| - |S(t,k)|)^2$$
(3)

 $\widehat{MM}$  represents the magnitude mask of the clean target signal. In Figures 2 to 5, example Mel spectrograms generated by the best and worst network are displayed. Figure 2 presents the spectrogram of the mixed signal, and Figure 3 the target output (speech without keyboard noise). When comparing the outputs to the target outputs, we can see that the simple network in Figure 4 only partially removes the keyboard noise. The best network so far, *CNN750* shows better visual results in Figure 5. In the output spectrogram, there is only a little keyboard sound left. Even though it is still hearable in the signal, the volume of the typing noise has significantly decreased.

Because even the best network in the initial experiments did not fully remove the keyboard noise, further investigation of the network error was necessary. The assumption was used that the human perception of errors in spectrograms is not symmetric. As it was proposed in (Loizou, 2005), a positive error (|N(t,k)| - S(t,k)| > 0) has a larger effect on perception than a negative error (|N(t,k)| - S(t,k)| < 0). A positive error means that there is background noise remaining in the signal and a negative error means that the speech signal has lost power in that frequency container. To analyze these errors, the metrics  $MSE_{noise}$  (positive error) and  $MSE_{speech}$  (negative error) are introduced:

$$MSE_{noise} = \frac{1}{TK} \sum_{t=0}^{T} \sum_{k=0}^{K} \max\{0, (|N(t,k)| - |S(t,k)|)^2\}$$
(4)

$$MSE_{speech} = \frac{1}{TK} \sum_{t=0}^{T} \sum_{k=0}^{K} \min\{0, (|N(t,k)| - |S(t,k)|)^2\}$$
(5)

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Network	<b>MSE</b> mask	<b>MSE</b> <sub>spec</sub>	<b>MSE</b> noise	<b>MSE</b> speech	MIS
NN500	0.071	$1.855 \cdot 10^{-5}$	$1.267 \cdot 10^{-5}$	$5.885 \cdot 10^{-6}$	$9.245 \cdot 10^{-6}$
CNN128	0.031	$7.039 \cdot 10^{-6}$	$2.076 \cdot 10^{-6}$	$4.963 \cdot 10^{-6}$	$3.539 \cdot 10^{-6}$
CNN250	0.028	6.629 · 10 <sup>-6</sup>	$1.915 \cdot 10^{-6}$	$4.713 \cdot 10^{-6}$	$3.331 \cdot 10^{-6}$
CNN500	0.026	$6.127 \cdot 10^{-6}$	$1.745 \cdot 10^{-6}$	$4.382 \cdot 10^{-6}$	$3.078 \cdot 10^{-6}$
CNN750	0.025	5.798 · 10 <sup>-6</sup>	1.656 · 10 <sup>-6</sup>	4.143 · 10 <sup>-6</sup>	2.913 · 10 <sup>-6</sup>
RCNN	0.080	$1.830 \cdot 10^{-5}$	$1.129 \cdot 10^{-5}$	$7.014 \cdot 10^{-6}$	9.146 · 10 <sup>-6</sup>
RCNN128	0.045	$1.324 \cdot 10^{-5}$	$8.040 \cdot 10^{-6}$	$5.201 \cdot 10^{-6}$	$6.595 \cdot 10^{-6}$
RCNN250	0.033	7.316 · 10 <sup>-6</sup>	2.707 · 10 <sup>-6</sup>	<b>4.609</b> · 10 <sup>-6</sup>	<b>3.669</b> · 10 <sup>-6</sup>
RCNN500	0.035	9.242 · 10 <sup>-6</sup>	$2.926 \cdot 10^{-6}$	6.315 · 10 <sup>-6</sup>	$4.646 \cdot 10^{-6}$

10

-60

-80

Table 1: Evaluation of different networks on the test set. The best values for CNNs and RCNNs are highlighted.



Figure 2: Example input spectrogram.



Figure 3: Example target output spectrogram.

As listed in columns 4 and 5 in Table 1, these errors show similar results as before. CNN750 is still the best performing CNN network and RCNN250 is the best RCNN network which is marginally worse than the CNNs. For all neural networks, the  $MSE_{noise}$  is lower than the *MSE*<sub>speech</sub>.



Figure 4: Example output spectrogram of NN500.



Figure 5: Example output spectrogram of CNN500.

The different perceptual meaning of these errors can also be expressed by another evaluation measure, the modified Itakura-Saito Divergence (MIS) (Loizou, 2005). It was designed to represent this effect using an additional exponential term:

$$MIS = \frac{1}{TK} \sum_{t=0}^{T} \sum_{k=0}^{K} \exp(|N(t,k)| - |S(t,k)|) - (|N(t,k)| - |S(t,k)|)$$

$$= 1$$
(6)

Table 1, column 6 shows that the *MIS* of the trained network models validated on the test set also shows similar results compared to other evaluation measures.

#### 4.2 Adapting the Loss Function

In the following, the different effects of  $MSE_{noise}$  and  $MSE_{speech}$  were applied to the loss function to further improve the results. In Equation 7, the MSE of the magnitude masks is separated and the positive part is weighted with a hyperparameter  $\alpha$ :

$$L = \frac{1}{K} \sum_{k=0}^{K} \max \left\{ 0, (MM(k) - \widehat{MM}(k))^{2} \right\} \\ \cdot \alpha$$
(7)  
+ min \{0, (MM(k))^{2} \} (7)

Based on the preliminary experiments, the adapted loss function was used with values 4.0 and 8.0 for  $\alpha$ . Besides the new loss, the neural networks were trained using the same setup as before. In Table 2, the evaluation measures for the networks trained with the new loss function with  $\alpha = 8.0$  are shown. It can be observed that the values for  $MSE_{noise}$  are much lower than with the original loss function reported in Table 1. Now, CNN500 achieves the best error with respect to  $MSE_{noise}$ . On the other hand,  $MSE_{speech}$  is higher for all networks, which indicates a tradeoff in speech quality. But because this error is less important for the perceived speech quality (Loizou, 2005), the decreased MSE<sub>noise</sub> might have the advantage of almost complete removal of the background noise. The modified Itakura-Saito Divergence slightly increases for most networks which can be explained by the overall higher error  $MSE_{speech}$ . The network CNN500 which had the lowest value of MSEnoise also reaches the best value in MIS. The visualized example output in Figure 6 shows the improvement compared to the initial loss function. There is almost no keyboard noise visible in the output spectrogram. It is noticeable that the areas in the spectrogram where no speech is present are displayed much darker.

Table 2: Evaluation measures estimated for the test set using the adapted loss function ( $\alpha = 8.0$ ). The best values are highlighted.

Network	<b>MSE</b> <sub>noise</sub>	<b>MSE</b> <sub>speech</sub>	MIS
NN500	$2.788\cdot10^{-6}$	$3.841 \cdot 10^{-5}$	$2.130 \cdot 10^{-5}$
CNN128	$4.140 \cdot 10^{-7}$	$1.149 \cdot 10^{-5}$	$6.017 \cdot 10^{-6}$
CNN250	$3.675 \cdot 10^{-7}$	$1.102\cdot10^{-5}$	$5.758 \cdot 10^{-6}$
CNN500	2.594 · 10 <sup>-7</sup>	$1.164 \cdot 10^{-5}$	2.164 · 10 <sup>-6</sup>
CNN750	$3.123 \cdot 10^{-7}$	9.723 · 10 <sup>-6</sup>	$5.072 \cdot 10^{-6}$
RCNN	$1.050 \cdot 10^{-6}$	$1.021 \cdot 10^{-5}$	$5.686 \cdot 10^{-6}$
RCNN128	4.408 · 10 <sup>-7</sup>	$1.442\cdot 10^{-5}$	$7.512 \cdot 10^{-6}$
RCNN250	$6.649 \cdot 10^{-7}$	$1.079 \cdot 10^{-5}$	$5.784 \cdot 10^{-6}$
RCNN500	$6.420 \cdot 10^{-7}$	9.354 · 10 <sup>-6</sup>	5.040 · 10 <sup>-6</sup>

As this is just normal noise from the recording, the significant parts of the speech signal remain. The newly trained networks remove that part from the spectrogram, which increases the error of speech  $MSE_{speech}$ . Even though the error is increased, the visualization shows that the speech signal is still preserved in the output.



Figure 6: Example output spectrogram of *CNN500* trained with the adapted loss function ( $\alpha = 8.0$ ).

### 4.3 Combination of Different Noise Types

In the experiments so far, the neural networks were only trained to suppress keyboard noise. To test whether the proposed network architectures can also work on multiple background noise types, a new training dataset was created. This dataset was generated using the same procedure as described in Section 3.1, but instead of keyboard noise, 20 different door knocking sounds from the *DCASE* 2016 (Lafay, Benetos and Lagrange, 2017) (Mesaros et al., 2018) dataset were selected. The resulting door knock dataset has the same size as the keyboard training, validation, and test sets together. They were randomly mixed to create a combined dataset. In these experiments, only the three traditional convolutional neural networks were trained on the combined training dataset using the adapted loss function  $\alpha = 8.0$ . In Table 3, the trained networks are evaluated on the keyboard validation set and in Table 4 on the door knock validation set.

Table 3: Evaluation measures of the combined networks estimated for the test set for keyboard noise.

Network	<b>MSE</b> <sub>noise</sub>	MSE <sub>speech</sub>	MIS
CNN128	$4.986 \cdot 10^{-7}$	$1.177 \cdot 10^{-5}$	$6.202 \cdot 10^{-5}$
CNN250	$3.790 \cdot 10^{-7}$	$1.157 \cdot 10^{-5}$	5.041 · 10 <sup>-6</sup>
CNN500	3.350 · 10 <sup>-7</sup>	$1.090 \cdot 10^{-5}$	$5.685 \cdot 10^{-6}$

Table 4: Evaluation measures of the combined networks estimated for the test set for door knock noise.

Network	<b>MSE</b> <sub>noise</sub>	MSE <sub>speech</sub>	MIS
CNN128	$2.254 \cdot 10^{-6}$	$6.800 \cdot 10^{-5}$	$3.663 \cdot 10^{-5}$
CNN250	$1.402 \cdot 10^{-6}$	$6.729 \cdot 10^{-5}$	$3.581 \cdot 10^{-5}$
CNN500	1.382 · 10 <sup>-6</sup>	6.188 · 10 <sup>-5</sup>	3.297 · 10 <sup>-5</sup>

In general, it can be observed that the keyboard noise has a lower error than door knocking. Compared to the previous training on keyboard noise with the adapted loss function, the  $MSE_{noise}$  slightly increases while the  $MSE_{speech}$  slightly decreases. All in all, the combination of two different noise types does work. It delivers comparable validation errors while using the same neural network for two different background sounds.

#### 4.4 Comparison with *RNNoise*

In a further experiment, we have compared the previous results to the open-source software RNNoise (Valin, 2021). RNNoise uses a smaller recurrent neural network running on different features, as explained in (Valin, 2018). The software comes with a pre-trained network, but to get a better comparison of the architectures, RNNoise was trained on the dataset with keyboard noise from Section 3.1 using the method from (Valin, 2018). The resulting network was evaluated on the test set for keyboard noise and compared to the network CNN500 trained with the adapted loss function ( $\alpha = 8.0$ ). The evaluation measures are listed in Table 5. Note that RNNoise only consists of 88,007 parameters while the CNN500 has 1,149,992. RNNoise reaches higher errors than the convolutional neural network in all measures. It must be stated that RNNoise uses a much smaller

network which justifies the worse performance. A noticeable result is that RNNoise has a significantly lower  $MSE_{noise}$  compared to the other measures. The error is smaller than the error of the networks that were trained using the MSE loss function in the initial training.

Table 5: Evaluation measures of *RNNoise* and *CNN500* ( $\alpha = 8.0$ ) estimated for the test set for keyboard noise.

	RNNoise	CNN500
MSE <sub>spec</sub>	$2.196 \cdot 10^{-4}$	1.190 · 10 <sup>-5</sup>
<b>MSE</b> <sub>noise</sub>	$9.154 \cdot 10^{-7}$	2.594 · 10 <sup>-7</sup>
MSE <sub>speech</sub>	$2.187\cdot 10^{-4}$	1.164 · 10 <sup>-5</sup>
MIS	$1.166 \cdot 10^{-4}$	2.164 · 10 <sup>-6</sup>

The results of *RNNoise* were also visually compared to the network *CNN500*, as exemplarily shown in Figures 7 and 8. *RNNoise* manages to only partially remove the keyboard sound. The neural network from this work can outperform *RNNoise*, as there is almost no keyboard sound visible in the Mel spectrogram.



Figure 7: Example output spectrogram of RNNoise.



Figure 8: Example output spectrogram of *CNN500* trained with the adapted loss function ( $\alpha = 8.0$ ).

### 5 CONCLUSIONS

In this work, keyboard sounds were dynamically suppressed in speech signals using artificial neural networks. The inputs to the networks were small time frames of the Mel spectrograms, and the target was to predict a magnitude mask that can remove the background noise from the input signal. In the first experiments, the background signal was only partially suppressed and remained in the output signal at a much lower volume. The best results were achieved using convolutional neural networks.

The adaptation of the loss function, in order to reach a better suppression of the keyboard noise, led to a significantly better removal of the background noise. Especially in the visual comparison of the output spectrograms with the results from the initial experiments, the improvement was recognized. Further, we explored whether the proposed neural networks can work on multiple different background noise types. A combined dataset was created with keyboard and door knocking sounds mixed together. The networks trained on the combined training set showed only marginally higher errors than the previous experiments.

Finally, the results achieved in this work were compared to the open-source tool *RNNoise*. It was determined that the convolutional neural network from the experiments outperforms *RNNoise*. This might be justified because *RNNoise* uses a much smaller network.

In conclusion, this topic is not new and has been researched for some time. The problem in academic research is that algorithms and procedures which are already established in the commercial software are not freely accessible. For this reason, own algorithms and procedures have to be researched and developed in the academic field. This paper presents a system for removing complex background noises from speech signals using the example of computer keyboard noise. Thus, it is possible to develop a non-cost software in a short time adapted to own background noises. To assess the quality of our solution, further experiments and different background noises are necessary.

### **6** FUTURE WORK

Some of the network hyperparameters were not varied in the experiments. It can be further investigated whether the number of the Mel frequency containers can be reduced without a significant impact on the quality of the output. A lower number of containers per time window would also drastically decrease the network size and computation time. Further, the network architectures can be even automatically learned using neural architecture search (Elsken, Metzen and Hutter, 2019). It is expected that the error values as well as the network size can be decreased by systematically exploring new architectures. Also, different loss functions can be used. The adapted loss from this work has to be tested with more fine-grained values of  $\alpha$ , but there might be more suitable loss functions.

For an application of such a system, more noise types must be taken into account. It was shown that two different types can be combined, but the training data could be extended, for example, with fan noise, baby screaming, or traffic sounds. When transferring speech signals over the Internet in real time, a packet loss can occur. The proposed system could be trained to predict the missing time windows from the previous ones. As an extension of the work, run time measurements of the presented method can be carried out. Thus, various comparisons can be made with other NN-based or traditional methods.

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