Retrieving the Topology from the Knowledge Frame System for Composition of the Topological Functioning Model

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Abstract: Model-driven software development considers models as a core artefact for generation of software source code. This requires models to be formal and complete enough for further transformations and code generation. It requires clear understanding of such knowledge as functionality, objects and dependencies in the problem domain. In our approach, this knowledge is kept in the frame-based system. The completeness and consistency of the knowledge can be verified by generating and validating the topological functioning model (TFM). The TFM is a model, which elements are linked by the topology, i.e. by cause and effect relations among the functional characteristics of the domain. Automated composition of the TFM requires retrieving appropriate conditions on cause and effect functional characteristics of the system from the knowledge base. The proposed algorithm reads data of functional characteristics kept in the knowledge base, relates those of them, where a cause condition corresponds to an effect condition, and generates data for the corresponding cause-and-effect relation. The difficulty is that conditions can be combined using logical operators AND, OR, XOR, as well as can use negation NOT. The benefit is that any inconsistency in the retrieved topology could be discovered and marked for further analysis. This should force careful analysis of the problem domain before generation of the design model. That could lead to decreasing a number of errors made due to uncertainty in the analysis.

1 INTRODUCTION

Knowledge about the problem domain (a business organization, a mechanical system etc.) can be found in official documents, technical specifications, descriptions, instructions, statistics etc., as well as got from domain experts by means of interviews, surveys, research and so on.

As Elstermann and Heuser pointed out (Elstermann and Heuser, 2016), there is not a big problem to create a complete description of the problem domain in the natural language, but it requires time, human and financial resources. If this work will not be used further with clear and satisfactory results, then all the resources will be just wasted. Knowledge extraction from the information sources can be manual, automated and automatic. The last one is very difficult due to particularities of natural languages such as errors, ambiguities as well as due inconsistencies and incompleteness in text documents. However, manual extraction also has its negative sides, i.e. the process is slow and error prone. Thus, automation software tool support based on natural language processing (NLP) could be used to improve processing of multiple information sources.

Since the topological functioning modelling is based on analysis of the exhaustive verbal information about the system, the analysed information must be kept in some form. Since we want to integrate possibilities of natural language processing and knowledge inferring, the core element should be a knowledge base. There are several formats for knowledge representation such as frame networks, ontology, concept networks, product rules etc., and even artificial natural languages, e.g., Esperanto, Conlang, Lingvata (Roux, 2013). Discussion on positive and negative properties of knowledge representation formats (Nazaruks and Osis, 2017a) leads to the choosing the knowledge frames. The knowledge frames allows keeping both structural and procedural knowledge in the way similar to the object-oriented one. We believe that a knowledge frame-based system can serve as a storage of domain knowledge in the consistent and computer-understandable format. Knowledge frame systems can be standalone, but it is more valuable in integration with other representation formats such as...
ontology and product rules (Nazaruks and Osis, 2017a). However, at the present this aspect is out of scope of the given research.

Modelling of behaviour and structure of the problem domain is based on the knowledge acquired from experts and extracted from documents. Models can be informal, semi-formal and formal. Usually, formal models are considered as “heavyweight”, informal are too inaccurate, the gold middle are semi-formal models, but they may contain ambiguities due to their incompleteness.

For modelling the problem domain, we suggest using advantages provided by the Topological Functioning Model – formal but “light-weight” model that can be transformed to most-used UML (Unified Modelling Language) diagrams (Donins et al., 2011, 2012; Donins, 2012b).

The construction of the TFM requires analysis of domain information and extraction of both (procedural and declarative) knowledge, but the functional view on the system is the primary one. And it must be assigned to the structural view on the system.

These principles are to be incorporated into the knowledge frame system (Figure 1). The frame system contains generable and manually added knowledge (Nazaruks and Osis, 2017b). The next step after adding knowledge is to generate the TFM and to validate it. Validation of the TFM includes also generation and validation of the topological space and allows discovering incompleteness and contradictions in the available knowledge.

The goal of this research is to implement generation of the TFM. The main difficulty is in discovering cause-and-effect relations between functional features without explicitly indicated sequence. We assume that mandatory identification of all pre- and post- conditions of all functional characteristics of the system is a way to discover this causal sequence.

The paper is organized as follows. Section 2 describes the background on the TFM and the initial scheme of the knowledge frame system. Section 3 illustrates the developed algorithm and examples. Section 4 provides an overview of related work. And Section 5 concludes the paper.

2 THE KNOWLEDGE SYSTEM

2.1 Topological Functioning Model

The TFM is a formal model which describes the functioning of a system. Its fundamentals are published by Janis Osis (Osis, 1969). The TFM can be specified as a topological space \((X, \Theta)\), where \(X\) is a finite set of functional features of the system under consideration, and \(\Theta\) is a topology on \(X\).

A functional feature is “a characteristic of the system (in its general sense) that is designed [for] and necessary to achieve some system’s goal” (Osis, Asnina and Grave, 2008; Osis and Asnina, 2011). It can be specified by a unique tuple \((1)\), where:

- \(A\) is an action linked with object \(O\),
- \(R\) is a result of the action \(A\),
- \(O\) is an object (objects) that gets the result of the action or an object (objects) that is used in this action,
- \(PrCond\) is a set of preconditions or atomic business rules,
- \(PostCond\) is a set of postconditions or atomic business rules,
- \(Pr\) is a set of responsible entities (systems or subsystems) that provide or suggest action \(A\) with a set of certain objects \(O\),
- \(Ex\) is a set of responsible entities (systems or subsystems) that enact a concrete action \(A\) (Osis and Asnina, 2011; Nazaruka et al., 2016).
- \(S\) is a label that indicates belonging of the functional feature to the system for which the TFM will be composed, namely, \(inner\) if belongs and \(external\) if does not.

\[
(A, R, O, PrCond, PostCond, Pr, Ex, S) \quad (1)
\]

The topology \(\Theta\) is expressed by cause-and-effect relations. A cause-and-effect relation is a causal implication (dependency) between two functional features. It is a binary relationship, where a cause triggers an effect without any middle functional feature (Asnina and Osis, 2011).

There are several formal specifications of cause-and-effect relations (Donins, 2012a; Asnina and Ovchinnikova, 2015), but the common is that they are focused on assessment of the completeness of incoming and outgoing conditions.
In the research on automated determination of the topology, it is more convenient to use the specification presented by Uldis Donins (Donins, 2012a).

A cause-and-effect relation (2) is a topological relation $T_{id}$ between a cause functional feature $X_c$ and an effect functional feature $X_e$, where at least one condition of $L_{out}$ that is a set of $X_i$ postconditions is equal to the at least one condition of $L_{in}$ that is $X_e$ preconditions.

$$T_{id} = (id, X_c, X_e, L_{out}, L_{in})$$ (2)

The TFM is valid when it satisfies topological and functioning properties (Osis and Asnina, 2011). The topological properties are: connectedness, neighbourhood, closure and continuous mapping. The functioning properties are: cause-and-effect relations, cycle structure, inputs and outputs. The possibility of validation of the TFM using execution model simulation is discussed by Ovchinnikova and Nazaruka (Ovchinnikova and Nazaruka, 2016), where decision making is based on results presented by the same authors in (Asnina and Ovchinnikova, 2015).

There are three approaches for complex system modelling that apply the TFM, namely TFM4MDA, the Topological UML and IDM. The Topological Functioning Modelling for Model Driven Architecture (TFM4MDA) approach (Osis and Asnina, 2008) is intended for problem domain analysis and modelling in the context of MDA, where the TFM acts as a Computation Independent Model (CIM). The Topological UML approach (Asnina and Osis, 2010; Donins, 2012b) integrates the TFM and its formalism with elements and diagrams of the Unified Modelling Language (UML). The Integrated Domain Modelling (IDM) approach “suggests using common system analysis and artificial intelligence practices to capture the domain knowledge and then transform these into a corresponding domain model” (Slihte, 2015).

### 2.2 The Initial Scheme of the Frame System Based on the TFM

Based on the comparison of metamodels of TFM4MDA, IDM and Topological UML, the initial scheme of the frame system was developed (Nazaruka and Osis, 2017b). There are three types of frame classes: with manually filled in slots, with partially generated knowledge in slots, and with completely generated knowledge of frame instances. The structure of frames is based on TFM elements. Generation of the TFM from frames and its further validation allows assessing completeness of acquired knowledge. However, in most cases assessment of semantical correctness is left to a human – the expert in the field.

In this research, the focus is on two frame classes, namely, CauseAndEffectRelation and FunctionalFeature (Figure 2).

![Figure 2: Frame classes CauseAndEffectRelation and FunctionalFeature.](image)
All slots of FunctionalFeature are filled in manually, while all slots of CauseAndEffectRelation are to be generated (Section 3).

3 COMPOSITION OF THE TFM

3.1 Determination of the Topology

Till now, determination of the topology over the set of functional features in the TFM has been done in two ways. The first one is manual. It was proposed in the TFM4MDA approach and requires human participation in text analysis (Asnina and Osis, 2011). The second one is automated, but it is performed on the structured textual descriptions (Osis, Asnina and Grave, 2008; Osi and Sliht, 2010; Sliht, Osi and Donins, 2011; Sliht, 2015), i.e. on the specifications of use cases. The important characteristic of the use case specification is that all steps are ordered in the logical sequence with all the possible branches. Preconditions as events are to be added manually and serve as guards on alternative scenarios. A reference to the corresponding step (event) of the next use case must be added manually as well.

The idea of retrieving the topology by analysis of pre- and post-conditions has been proposed in Topological UML (Osis and Donins, 2010; Donins, 2012a). There it has been applied for identification of logical relations among cause-and-effect relations (Donins, 2012a).

This approach also requires human participation, since postcondition and precondition sets may be not indicated, thus semantics of logical conditions must be analysed properly.

In this research we develop this idea but assume that frame instances should have all the preconditions and postconditions defined and indicated during manual filling of the knowledge into instances of frame class FunctionalFeature.

3.2 Implementation of the Algorithm

The general idea is illustrated in Figure 3. Data of frame instances is kept in XML file with the extension “tfm”. In order to generate the cause-and-effect relations this file is parsed to get all structures named FunctionalFeature. For each instance its preconditions as well as conditions are tokenized using Polish notation, i.e. the simple conditions are extracted from complex combinations keeping negations when they are (Figure 4 and Figure 5).

Then the check whether a condition in a set of preconditions is met in a set of postconditions in other functional features is performed. If it is met, then the cause-and-effect relation is established between those two functional features, the corresponding structure is generated and added to the collection of cause-and-effect relations in the TFM file. The result is a *.tfm file with instances of functional features and cause-and-effect relations.

Figure 3: General idea of retrieving cause-and-effect relations from instances of frame class FunctionalFeature.
3.3 Illustrative Examples

Let us test the developed algorithm on the example of investigation of a criminal case (Nazaruks and Osis, 2017b) with several modifications.

The original TFM is shown in Figure 6. Cause-and-effect relations among functional features are created also manually based on specification of pre- and post-conditions (Figure 8). After generation of the cause-and-effect relations according to the algorithm (Figure 7), we have found out that a few relations have not been created, namely, 7-16 and 7-14, but relation 12-10 that is absent in the original TFM has been created (Figure 9). After investigation, we have found that in first case the reason is a mistake in the condition’s text – “(a criminal case is sent to prosecutor)” in functional feature 7 and “(a criminal case is sent to a prosecutor)” in functional features 14 and 16. But the relation 12-10 is based on the condition “(a criminal case is terminated)” that was missed during manual work.
Figure 6: The manually created TFM with preconditions and postconditions.

Figure 7: The generated TFM with errors in causal dependencies.
In the second experiment we have removed the postcondition of functional features 1 and 16 (Figure 10). The cause-and-effect relations 1-6, 2-3, 3-4 and 16-1 where not generated. After investigation it was found out that the value of precondition of functional feature 3 is set for the wrong slot.

Summarizing, the implemented algorithm works correctly to the current style of recording condition sets. Certainly, it must be additionally tested for other cases. However, inconsistencies in the generated TFM such as isolated vertices or wrong cause-and-effect relations may indicate several cases:
• Errors in specifications of functional features that could be either grammatical or due to a use of wrong slots;
• Undefined preconditions or postconditions that means that not all facts and states of the system are discovered;
• Misunderstood causal implications due to fragmentary nature of the analysis.

Without doubts, manual discovering and specification of all preconditions and postconditions of functional characteristics is resource-consuming tasks and would get accepted only in case of software tool automated support and control as well as in case of automation of model transformation.

4 RELATED WORK

In the UML (Unified Modelling Language) and BPMN (Business Process Model and Notation) causality is expressed through control flows, data flows, and transitions. Determination of causality is important not only during analysis and design, but also for testing purposes, when a tool creates state machines to check coverage criteria of tests.

Some authors (Briand, Labiche and Lin, 2010) put their attention on identification of data flows from OCL (Object Constraint Language) guard conditions and operation contracts. The authors report that data flow information can be used for determination of the “best transition tree”. The preconditions of TFM functional features after their transformation to elements of UML diagrams become also guard conditions. Thus, analysis of preconditions has a sense in determination of causality.

Other authors illustrate control and data flow transformation to transition flows of Petri Nets as a part of analysis of system’s functionality (Lin et al., 2005). Control flow graphs are important for automation of many software engineering task, their composition is not straightforward even from UML sequence diagrams (Kundu, Samanta and Mall, 2012), since this knowledge is expressed in different elements and sometimes even in nested fragments with arbitrary nesting depth. Integration of multiple control flows may lead for creation of non-appropriate paths (Arora, Bhatia and Singh, 2017).

Control flows in BPMN diagrams may form conflicts and deadlocks, since they may include different constructs, e.g., several types of events, activities, and getaways. Usually, for analysis of BPMN control flows transformations to formal models (El Hichami et al., 2015) or model simulation (Todoran and Mitrea, 2015) are suggested. However, in most cases modelling of control flows is not automated and can be done at three levels of details – from business to executable one (Stiehl, 2014). In the field of automatic generation of BPMN we want to note an approach presented by Kluza and Nalepa (Kluza and Nalepa, 2017) and similar to the our one, where a BPMN model is generated from manually created requirements descriptions and business rules declarations. The authors apply Attribute Relationship Diagram (a structured specification of the system description) and generate a process model integrated with rule-based structures, i.e. decision tables. Rules are discovered previously by business analysts. After refining, the integrated model is suitable for simulation. The similarity with our approach is the focus on the “rule-based task”.

Another interesting approach is generation of a business process model from business rule descriptions in SBVR (Semantic Business Vocabulary and Rules) language (Steen, Pires and Jacob, 2010). The authors apply the same idea that preconditions and consequences form control flows between activities.

Causality is also the very important concept in conditional logic, in artificial intelligence, e.g. for planning tasks (Wobcke, 1994; Giunchiglia et al., 2004), and in the framework of action systems (Giordano and Schwind, 2004). Giordano and Schwind (2004) indicate that causal implication can exist between two types of assertions:

• An action can cause a fact to become true, or
• A fact can cause another fact.

In the first case, the causal implication relates also to a state transition, so the caused fact “belongs” to the “next state”. In the second case, the causal implication does not touch any state, the modifications occur in the same state. As Giordano and Schwind (2004) formulate: “caused facts are regarded as indirect effects of actions”. The authors also formulate several restrictions: a causal implication cannot itself cause other facts, causality is not reflexive, causal implication is not monotonic, material implication is excluded, and that a domain constraint must hold in all states of the world. Giving these restrictions, the authors have formulated “the causal action logic AC”. This logic is introduced into a new approach for reasoning about actions and causation. The main idea presented in this logic is similar to the reasoning applied in the topological functioning modelling.
5 CONCLUSIONS

Understanding causal dependencies is very important for modelling system behaviour and structure. Causal implications relate as to facts and system states as to transitions between states. The TFM is a formal model where discovering causal implications (named cause-and-effect relations) is one of the key principles. Incorrect cause-and-effect relations leads to incorrect control and data flows in design models and code.

In the context of our research we assume that cause-and-effect relations could be retrieved from specifications of system functional characteristics, i.e. functional features. Certainly, we see three bottlenecks here:

- Correctness and completeness of conditions before and after execution of a functional feature;
- Automated support for determination of those conditions (facts, states, domain constraints);
- Syntactical correctness of descriptions of combinations of the conditions.

The last one can be controlled by the software tool used for system analysis. The first two depends on quality of processing textual descriptions of the system functionality.

The resulting generated topological space and the TFM can be used, first, as a supporting model for computation independent models: Bridging problem and solution domains, in Proceedings of the 2nd International Workshop on Model-Driven Architecture and Modelling Theory-Driven Development, MDA and MTDD 2010, in Conjunction with ENASE 2010. SCITEPRESS - Science and Technology Publications, pp. 23–32.

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