Deep Associative Semantic Neural Graphs for Knowledge Representation and Fast Data Exploration

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Keywords: Active Knowledge-based Neural Structures, Semantic Neural Structures, Representation of Complex Entities, Knowledge-based Inference, Deep Neural Network Architectures, Associative Graph Data Structures, Big Data, Associative Database Normalization, Database Transformation, Data Mining, Knowledge Exploration.

Abstract: This paper presents new deep associative neural networks that can semantically associate any data, represent their complex relations of various kinds, and be used for fast information search, data mining, and knowledge exploration. They allow to store various horizontal and vertical relations between data and significantly broaden and accelerate various search operations. Many relations which must be searched in the relational databases are immediately available using the presented associative data model based on a new special kind of associative spiking neurons and sensors used for the construction of these networks. The inference operations are also performed using the reactive abilities of these spiking neurons. The paper describes the transformation of any relational database to this kind of networks. All related data and their combinations representing various objects are contextually connected with different strengths reproducing various similarities, proximities, successions, orders, inclusions, rarities, or frequencies of these data. The computational complexity of the described operations is usually constant and less than operations used in the databases. The theory is illustrated by a few examples and used for inference on this kind of neural networks.

1 INTRODUCTION

Efficient and safe collecting, storage, retrieval, processing, mining, and exploration of big data are the most important tasks of contemporary computer science (Apiletti et al., 2017), (Han and Kamber, 2000), (Piatetsky-Shapiro and Frawley, 1991), (Fayyad, 1996), (Jin et al., 2015), (Linoff and Berry, 2011), (Pääkkönen and Pakkala, 2015). To get benefits from various big data collections, we need to use smart and very fast methods for data search, mining, and knowledge exploration. It is not an easy task because data are typically stored in relational databases which relate data and entities only horizontally. Data must be sorted, indexed, or joined, and vertical relations must often be found and processed in many time-consuming nested loops.

This paper introduces new deep associative semantic neuronal graphs (DASNG) which allow for storing data where the data are automatically horizontally and vertically associated and ordered according to all attributes without any substantial computational or memory costs. Moreover, these relations can be easily supplemented by any further relations or related objects that can be added to this structure or stored in a result of data exploration using extra neurons and connections. Vertical data associations describe many useful relations like similarity, proximity, order, or succession in space or time. They can also easily determine minima, maxima, medians, average numbers, and data ranges. Data mining and knowledge exploration methods usually try to find interesting groups of similar, different, frequent, or infrequent patterns for a given minimum support and minimum confidence to define associative rules, cluster objects or draw some useful conclusions about objects or their groups (Agrawal et al., 1993), (Apiletti et al., 2017). The introduced model of the data representation and storage in the DASNG structure supplies us with an ability to directly or indirectly connect related data. This strategy excludes computationally expensive loops and reduces the computational complexity of operations on the related data. All minima and maxima are available in constant time. All other values of each attribute are organized using the...
introduced aggregated values B-trees which automatically aggregate and count duplicated values and order them linearly during their construction process. This strategy reduces the computational complexity of many operations.

The introduced DASNGs consist of a special kind of spiking neurons introduced in this paper and referring to the earlier models presented in (Horzyk, 2014), (Horzyk et al., 2016), (Horzyk, 2017). Spiking neurons are reactive and use a time approach for computations (Gerstner and Kistler, 2002), so data exploration routines can be triggered in these graphs automatically by stimulation of neurons representing any search context. It is very useful because some frequently performed operations are built-in this neural system and do not need to be implemented in the form of typical algorithmic procedures. The connection network between neurons allows us to quickly find associated data, objects, and patterns according to their frequency, similarity, or vicinity in raw data. Furthermore, all important findings can be almost costlessly converted into new neuronal substructures that will store them in the same graph for any further use and inference.

The way, in which the DASNGs work, classify them as emergent cognitive neuronal systems. They have a few similar features to semantic networks and other emergent cognitive systems (Duch and Dobosz, 2011), (Nuxoll and Laird, 2004), (Parisia et al., 2017), (Starzyk, 2007), (Starzyk, 2015). The semantic networks represent semantic relations between concepts that are linked together (Sowa, 1991), while in the introduced DASNGs, neurons can represent any sets of elementary or complex sub-combinations of input data and directly or indirectly related objects for defining differing contexts affecting the neurons with different strength. Semantic networks are browsed through using various search routines operating on graph structures, while the presented associative graphs are equipped with special reactive spiking neurons that can automatically perform some search operations by stimulating them. It will be shown how neurons process such search operations and how this neural graph works on exemplary data in section 6.

2 RELATIONAL DATABASE MODEL DRAWBACKS

In relational science, we used to store data in relational databases, consisting of tables, which use primary and foreign keys to represent related entities. In relational databases, we use entity-relational model (ER model) that describes interrelated things of interest in a specific domain of knowledge (Bagui and Earp, 2011), (Chen, 2002). The above-mentioned ER model is composed of entity types which classify the things of interests and specifies various horizontal relationships that can exist between instances of those entity types. This model is also an abstract data model that defines a data structure that can be implemented as a relational database. The ER modeling was developed for database design by Peter Chen (Chen, 2002). However, the ER model can also be used in the specification of domain-specific ontologies.

Entities may be characterized not only by relationships but also by additional properties (attributes), which include special identifies called primary keys. In the databases, each row of a table represents one instance of an entity type, and each field represents an attribute type, where a relationship between entities is implemented by storing a primary key of one entity as foreign keys in other entities of other tables (Fig. 1).

![Figure 1: A sample of the small database with typically repeated attribute values and relations to the same objects of another table represented by the primary keys.](image)

In the relational database model, features are grouped in rows defining entities (records, tuples, objects) collected in tables. The rows of different tables can be horizontally linked together using primary and foreign keys. This kind of row linking allows defining more complex objects by other already represented objects in other tables. Keys are unique, sorted, and usually quite quickly available using B-trees, B+trees, hash-tables, or other methods typically in logarithmic time (Cormen et al., 2001), (Hellerstein et al., 2007).

All modern databases use a Cost Based Optimization (CBO) to optimize queries and to create an individual execution plan for each query. Usually, there are many possibilities, which dependently on row numbers and created indices can differ computational cost and complexity of various execution plans. Execution plans can comprise
Many times, heuristic or greedy algorithms are also used to quickly find out a “good” enough execution plan without brute force search (Hellerstein et al., 2007).

Moreover, we distinguish various join operations as nested loop join, hash join, and merge join which can be more efficient in some specific situations. The join operations are frequently executed on every database, so their optimization is crucial. The nested loop join takes $O(N \times M)$ time, the hash join is processed in $O(N + M)$ time, and the merge join in $O(N \log N + M \log M)$ dependently on working on the sorted or unsorted data, where $N$ and $M$ are the numbers of merged records of two joined tables (Hellerstein et al., 2007).

Statistics are also very useful and help to estimate the disk I/O and CPU operations and memory usage to find a “good” enough execution plan, however, there is a certain cost of updating statistics as well. The I/O disk data access for reading and writing operations are bottlenecks of databases, especially when a database is huge and do not fit into memory because disk operations are typically at least hundreds of times slower than operations executed in the RAM.

Despite the many advantages of such a solution, we also come across many difficulties and bottlenecks, where the ER data model is not effective enough (Hellerstein et al., 2007), e.g. the time necessary to update statistics and indices, sorting operations, cope with hundred times slower I/O disk operations, quick finding a good enough execution plan for each query, or the necessity to frequently search for various vertical relations between entities of the same table. One of the main drawbacks of the relational database model, which is addressed in this paper, is in the limited way of binding data and objects vertically. Vertical relations between entities and their defining values stored in columns are not represented (Fig. 1). This lack forces database management systems (DBMS) to search for vertical relations in many loops using SQL operations if the information about such relations is required. The SQL search operations (SELECT) in relational databases are typically the most frequent operations, so inefficiency of them costs a lot of time which is most annoying and very expensive when managing huge data collections.

Moreover, the objects can be naturally ordered only after a single selected attribute in each table. If it is necessary to have data sorted after several attributes simultaneously, indices must be used. The indices typically use B+trees or hash tables to sort and organize data to make them available in logarithmic time. The main drawbacks of using indices are the relevant additional memory cost and the slowdown of addition, updating, and removal operations. In result, it is not recommended to add indices for data attributes which data are not frequently used in search operations. This paper presents how to overcome these drawbacks and organize data in such a way that both horizontal and vertical relations are represented in the proposed associative neuronal graph data structure described in the following sections.

3 AVB-TREES

In this section, a new self-ordering and self-balancing tree structure is proposed to efficiently organize input elements of the further introduced associative neural structures and get a very fast access to all stored features and objects. This structure, called AVB-tree (Aggregated-Values B-tree), is similar to the well-known B-tree structure, but it automatically aggregates and counts all duplicates (Fig. 2). Thus, the AVB-trees store only unique values of each attribute defining stored objects. Despite the aggregation of duplicates, this operation does not diminish the information about the stored objects. The neurons representing these unique attribute values can have many connections to neurons representing objects. Hence, AVB-trees are usually much smaller than B-trees or B+trees constructed for the same data, where duplicates are not aggregated.

The aggregation of the same values also saves the memory and accelerates the access to the stored objects, especially to the related objects which are on the top of interests and usually searched by queries. The counting of duplicates makes possible to remove data from this structure correctly.

![Figure 2: Construction of an exemplary AVB-tree.](image-url)
The insertion of the next key to the AVB-tree is processed as follows (Fig. 3):

1. Start from the root and go recursively down along the edges to the descendants until the leaf is not achieved after the following rules:
   - if one of the keys stored in the node equals to the inserted key, increment the counter of this key, and finish this operation,
   - else go to the left child node if the inserted key is less than the leftmost key in the node,
   - else go to the right child node if the inserted key is greater than the rightmost key in the node,
   - else go to the middle child node.

2. When the leaf is achieved:
   - and if the inserted key is equal to one of the keys in this leaf, increment the counter of this key, and finish this operation,
   - else insert the inserted key to the keys stored in this leaf in the increasing order, initialize its counter to one, and go to step 3.

3. If the number of all keys stored in this leaf is greater than two, divide this leaf into two leaves in the following way:
   - let the divided leaf represent the leftmost (least) key together with its counter;
   - create a new leaf and let it to represent the rightmost (greatest) key together with its counter;
   - the middle key together with its counter and the pointer to the new leaf representing the rightmost key pass to the parent node if it exists and go to step 4;
   - if the parent node does not exist, create it (a new root of the AVB-tree) and let it represent this middle key together with its counter, and create new edges to the divided node representing the leftmost key and to the node pointed by the passed pointer to the new node representing the rightmost key (Fig. 2). Next, finish this operation.

4. Insert the passed key together with its counter to the key(s) stored in this node in the increasing order after the following rules:
   - if the key comes from the left branch, insert it on the left side of the key(s);
   - if the key comes from the right branch, insert it on the right side of the key(s);
   - if the key comes from the middle branch, insert it between the existing keys.

5. Create a new edge to the new leaf or node pointed by the passed pointer and insert this pointer to the child list of pointers immediately after the pointer representing the edge to the divided leaf or node.

6. If the number of all keys stored in this node is greater than two, divide this node into two nodes in the following way:
   - let the existing node represent the leftmost (least) key together with its counter;
   - create a new node and let it represent the rightmost (greatest) key together with its counter;
   - the middle key together with its counter and the pointer to the new node representing the rightmost key pass to the parent node if it exists and go back to step 4 (Fig. 2);
   - if the parent node does not exist, create it (a new root of the AVB-tree) and let it represent this middle key together with its counter, and create new edges to the divided node representing the leftmost key and to the node pointed by the passed pointer to the new node representing the rightmost key (Fig. 2). Next, finish this operation.

The removal of the key from the AVB-tree is processed very similarly as for B-trees with respect to the counters of individual keys that must be gradually decreased to zero for each removed object before removing a given countered key from this structure. During this operation, the AVB-tree is self-balanced in the same way as is proceeded for B-trees (Cormen et al., 2001).

The search operation in the AVB-tree is processed as follows:

1. Start from the root and go recursively down along the edges to the descendants until the searched key or the leaf is not achieved after the following rules:
   - If one of the keys stored in the node equals to the searched key, return the pointer to this key.
   - else go to the left child node if the searched key is less than the leftmost key in this node.
   - else go to the right child node if the searched key is greater than the rightmost key in this node.
   - else go to the middle child node.
2. If the leaf is achieved and no stored key in it equals the searched key, return the null pointer.

The search operation for any key in the above-introduced AVB-trees is very efficient because the maximum number of search steps is equal to the logarithm of the number of unique keys stored in them, i.e. \(O(\log_2 M^{ak})\), where \(M^{ak}\) is the number of the unique keys of the attribute \(a_k\). Considering that the attribute values are typically many times repeated in the database table rows, the number of all entities \(N\) in the table is usually much bigger than the number of unique values \(M^{ak}\) of each attribute \(a_k\) (\(N \gg M^{ak}\)). Hence, the logarithm computed for the usually constant number of unique values \(M^{ak}\) for AVB-trees is usually smaller than the logarithm of the number of all entities (rows) \(N\) used in the search operations using B-trees or B+trees in relational databases, i.e. \(O(\log_2 N) > O(\log_2 M^{ak}) \approx O(1)\).

The computational complexity of the insertion, removal, and update operations in AVB-trees is the same as for the search operation. It is typically constant independently of the size of data tables thanks to the aggregation property of AVB-trees.

Each key element in the AVB-tree structure represents a sensor which is most sensitive to the value represented by the key. The sensors stimulate connected value neurons which can be connected to any number of object neurons representing objects.

### 4 SENSORS AND ASSOCIATIVE SPIKING NEURONS

The presented associative neural graph structures in the next section will use special kinds of sensors and associative spiking neurons (ASN), which enable fast inference using various combinations of stimuli of the network elements. These graphs consist mainly of numerical and symbolic sensors, value neurons, and object neurons to represent tabular data.

In these associative neural graphs, all non-key database table attributes \(a_1, \ldots, a_k\) are transformed into sensory input fields \(F^a_1, \ldots, F^a_k\) and all attribute values are represented by sensors \(S^a_1, \ldots, S^a_k\) which are organized using the introduced AVB-trees. Sensors aggregate all duplicates of each attribute \(a_k\) separately. Each sensor \(S^a_k\) represents all duplicates of the value \(v^a_k\), so for large data collections, we usually achieve high memory savings without any loss of information. It is possible because each value \(v^a_k\) represented by the sensor \(S^a_k\) and subsequently by a connected value neuron \(V^a_k\) can be repeatedly connected to various object neurons that represents various entities which contains this value. While attribute values can define entities in database tables, here sensors together with value neurons representing values can define object neurons representing entities.

Each sensor \(S^a_k\) is connected to a value neuron \(V^a_k\) which is stimulated by this sensor with a constant stimulus \(x^a_{vk}\) computed after:

\[
x^a_{v_k} = \begin{cases} 
1 - \frac{|v^a_k - v^a_{vk}|}{|v^a_k|} & \text{if } r^a_k > 0 \\
\frac{|v^a_k|}{|v^a_k|} & \text{if } r^a_k = 0
\end{cases}
\]

(1)

Value neurons \(V^a_k\) and \(V^a_{vk}\) representing numerical neighbor values \(v^a_k\) and \(v^a_{vk}\) of the same attribute \(a_k\) are additionally mutually connected, and their weights are computed after the formula:

\[
w^a_{vk} = 1 - \frac{|v^a_k - v^a_{vk}|}{r^a_k}
\]

(2)

where \(r^a_k = v^a_{max} - v^a_{min}\) is the range of all already represented values of the attribute \(a_k\), and \(v^a_{min}\) and \(v^a_{max}\) are the minimum and maximum values of this attribute appropriately. The range is automatically updated by each sensory input field \(F^a_k\) when a new minimum \(v^a_{min}\) or maximum \(v^a_{max}\) is introduced.

Each numerical attribute \(a_k\) is additionally equipped with special extreme sensors \(S^a_{min}\) and \(S^a_{max}\) sensitive for existing and new minima and maxima. These sensors compute their output values using the following formulas:

\[
x^a_{min} = \begin{cases} 
\frac{v^a_{max} - v^a_{min}}{r^a_k} & \text{if } r^a_k > 0 \\
v^a_{min} - v^a_{min} + 1 & \text{if } r^a_k = 0
\end{cases}
\]

(3)

\[
x^a_{max} = \begin{cases} 
\frac{v^a_{max} - v^a_{min}}{r^a_k} & \text{if } r^a_k > 0 \\
v^a_{max} - v^a_{min} + 1 & \text{if } r^a_k = 0
\end{cases}
\]

(4)

The output values of sensors define the strength of stimulation of the connected extreme neurons \(V^a_{min}\) and \(V^a_{max}\) which continuously stimulated achieve their spiking thresholds after the certain periods of time:

\[
t_{min}^{a_k} = \begin{cases} 
\frac{1}{x^a_{min}} & \text{if } x^a_{min} > 0 \\
\infty & \text{if } x^a_{min} = 0
\end{cases}
\]

(5)
The extreme sensor $S_{max}^{a_k}$ or $S_{min}^{a_k}$ stimulate the extreme neurons $V_{min}^{a_k}$ and $V_{max}^{a_k}$ with strength equal to one only if the current minimum or maximum value is presented on the $F^{a_k}$. The stimulation $x_{min}^{a_k}$ or $x_{max}^{a_k}$ is stronger than one only if there is presented a new minimum or maximum value which causes the achievement of the spiking threshold of the $V_{min}^{a_k}$ or $V_{max}^{a_k}$ neuron in time $t_{min}^{a_k} < 1$ or $t_{max}^{a_k} < 1$. Such a strong stimulation of the extreme neuron starts a conditional plasticity routine that brakes the existing connection from extreme neuron $V_{min}^{a_k}$ or $V_{max}^{a_k}$ to the connected value neuron $V_{i}^{a_k}$, and a new connection to the new created value neuron representing a new extreme value is established, and its weight is set to one. It updates the minimum value $t_{min}^{a_k}$ or maximum value $t_{max}^{a_k}$ and range $r^{a_k}$ appropriately. In other cases, the extreme sensors stimulate the connected neurons with strength less than one, so the neurons fire later (5) or (6) according to the distance of the presented value to the extreme ones.

Each sensor $S_{i}^{a_k}$ is connected to its value neuron $V_{i}^{a_k}$ which is stimulated and charged by this sensor as long as the input value $v^{a_k}$ is presented on the sensory input field $F^{a_k}$. All value neurons used for the associative transformation of databases into the DASNG neuronal systems have their activation thresholds equal to one ($\theta_{i}^{a_k} = 1$). According to this fact, each stimulated value neuron $V_{i}^{a_k}$ solely by its connected sensor $S_{i}^{a_k}$ achieves its spiking threshold $\theta_{i}^{a_k}$ after the time $t_{i}^{a_k}$ calculated after:

$$t_{i}^{a_k} = \begin{cases} 1 & \text{if } x_{i}^{a_k} > 0 \\ \infty & \text{if } x_{i}^{a_k} = 0 \end{cases}$$ (7)

In the next step of the associative transformation, there are created object neurons $O_{i}^{T_{m}}$, ..., $O_{i}^{T_{n}}$ for each table $T_{n}$ that does not contain foreign keys. These neurons represent entities, so they are connected to the adequate value neurons representing attribute values which define these entities. The weights of the connections from these value neurons to the object neurons should reproduce rarity of the values represented by value neurons in the defining various object neurons, so they are defined as the reciprocal of the numbers of all connections that come from the given value neuron $V_{i}^{a_k}$ to all connected object neurons $O_{j}^{T_{m}}$ representing the entities of the table $T_{n}$:

$$w_{i,j}^{a_k} = \frac{1}{\sum_{l:j}^{w_{i,j}^{a_k}}} \left| l: V_{i}^{a_k} \rightarrow O_{j}^{T_{m}} \right|$$ (8)

These weights can be easily updated when a new entity is added, or an existing one is removed. These weights do not even need to be stored in a neural network structure because they can be locally and very fast calculated before each neuronal spike.

Next, there are created object neurons $O_{i}^{T_{m}}$ for the tables $T_{m}$ which contain not only attributes but also some foreign keys for which the object neurons $O_{j}^{T_{m}}$ representing primary keys have been already created in the previous steps. The connection weights that come from the object neurons $O_{j}^{T_{m}}$ representing primary keys to the object neurons $O_{i}^{T_{m}}$ containing adequate foreign keys are computed as the reciprocal of the numbers of connections that comes from the given object neurons $O_{j}^{T_{m}}$ to all connected object neurons $O_{i}^{T_{m}}$ representing the entities of the table $T_{m}$:

$$w_{i,j}^{T_{m}} = \frac{1}{\sum_{l:j}^{w_{i,j}^{T_{m}}}} \left| l: O_{j}^{T_{m}} \rightarrow O_{i}^{T_{m}} \right|$$ (9)

The weights (8) and (9) allow for the stimulation of the postsynaptic object neurons with the strength reflecting the rarity of the values or the entities represented by the presynaptic neurons. It means that frequent values and entities have a smaller impact on the postsynaptic object neurons, while rare values and entities have a bigger impact and can faster charge postsynaptic neurons to their spiking thresholds. Each unique value and entity which primary key is used only once as a foreign key in another table (representing the relation 1:1) have the biggest possible impact because its connection weight is equal to one, and such a connection can solely charge the postsynaptic object neuron to its spiking threshold. The interpretation is quite intuitive because such features or entities exclusively identify objects that should also be automatically recognized in any natural or artificial cognitive neural system.

The spiking threshold of each object neuron must be achieved ultimately when all defining inputs start to charge it. However, it can be achieved earlier when any sub-combination of enough rare inputs happens. All defining inputs of each object neuron can achieve the following maximum strength of stimulation:

$$t_{max}^{a_k} = \begin{cases} 1 & \text{if } x_{i}^{a_k} > 0 \\ \infty & \text{if } x_{i}^{a_k} = 0 \end{cases}$$
The object neuron's spiking threshold is defined as:

$$\theta_{O_t} = \begin{cases} 1 & \text{if } W^{T_n}_{O_t} \geq 0 \\ W^{T_n}_{O_t} & \text{if } W^{T_n}_{O_t} < 0 \end{cases}$$

The associative spiking neurons used for modeling of the value and objects neurons incorporate the concept of time and implement charging, discharging, relaxation, and absolute and relative refraction processes (Fig. 4) (Kalat, 2012). They can also be in resting state when not stimulated for a longer time. All internal neuronal processes are modeled using linear functions that can be easily added, subtracted, or combined for charging, discharging, or overlapping stimuli (Fig. 4). All external stimuli influence on internal neuronal processes which change states of neurons (Fig. 4-5).

Figure 4: Overlapping charging and discharging external stimuli influencing the state changes and internal neuronal processes of associative spiking neurons.

Figure 5: The illustration of the operation that combines the new stimulus $S_i$ with the processes $P_0$ and $P_1$ in the IPQ created for previous stimuli $S_0$ and $S_1$ where $d_i$ determines the duration of the stimulus $S_i$, and $s_i$ is its strength.

The ASNs work parallel and combine the external input stimuli that can appear at any time. To simulate them on a sequential CPU, they use an internal process queue (IPQ) to manage and switch internal processes $P_i$ and update neuronal states at the right time (Fig. 5), and a global event queue (GEQ) to order and execute these internal processes of all neurons at an appropriate moment and sequence. The GEQ watches out the time when processes finish to start updating neurons at the right time. The expected moments of achievement of spiking thresholds (11) of individual neurons are always calculated in advance and watched out. Different than in the artificial neural networks of the second generation (Haykin, 2009), which answers are produced by various values of the output neurons, ASN answers are produced based on their frequencies of spikes and the elapsed time from a given external stimulation moment to the moments when these neurons start spiking. Hence, the most frequently spiking neurons represent the answer that can be read from connected neurons representing the associated objects and values.

5 DASNG - DEEP ASSOCIATIVE SEMANTIC NEURAL GRAPHS

Brains consist of many complex and very deep graph structures of connected neurons of various kinds (Longstaff, 2011), which use thousands of connections to represent our knowledge and make our intelligence work smartly, quickly, and context-sensitively (Kalat, 2012).

In this section, new deep associative semantic neural graphs (DASNG) will be introduced to demonstrate how relational databases can be transformed into these graphs. Figure 6 illustrates a neuronal DASNG structure that represents all data and their relations from the sample database presented in Fig. 1. This neuronal structure does not reduce any information so that it can always be transformed back into the original database. The DASNG can be constructed for any database storing related records. In any formal database or cognitive model, we can distinguish individual data which are related in different ways. Some groups of related data model objects (represented by e.g. entities) that can also be related between themselves in various ways (e.g. using primary and foreign keys), which describe semantic relations between them. Such relations can reproduce similarity, proximity, inclusion, sequence, actions etc. Such relations can group objects and define their classes based on similar features. Such kinds of tasks should be solved in computational intelligence and knowledge engineering because our intelligence is based on the ability to discover various relations and find interesting groups among other things. To find such relations, the algorithms use various conditions, limitations, search routines, and operations which compare or group objects to satisfy defined requirements or achieve given goals.

The introduced DASNG model can naturally
reproduce data, entities, and all relations that are represented by the primary-foreign key relational model. **Classes of objects** can be defined based on the similarity between objects which some subsets of attribute values are the same or close. In the DASNG model, all the same values are aggregated and all similar attribute values are directly or indirectly connected. Consequently, all related objects are fast accessible thanks to these aggregations and connections between neurons representing similar values. **The similarity between objects** can be defined as any subset of close attribute values (features) that relates the group of objects. Thus, all possible clusters coming from similarity are naturally included in the DASNG model. In consequence, any class of objects can be quickly found in the DASNG network because the stimulation of a subgroup of sensors representing selected features will gradually induce activation of connected neurons representing objects (entities) which the most meet the given limitations defined by these features as will be described in the following section.

The DASNG model can also represent other relations that usually come from object vicinity in time or space. **Vicinity** can be defined as an attribute of time or space where the two compared objects occur in the close time interval, or their coordinates are not too far away. Therefore, the vicinity is a distance in space or time in which objects can interact with each other or can be perceived as being neighboring or subsequent by somebody. Close objects in space or time cannot be similar at all, so we do not include vicinity as an attribute that groups objects into classes, but we talk about object neighborhood or succession. Thus, vicinity can relate objects independently of their similarity or differences. Therefore, we can define any sequence of objects or actions, and elaborate various procedures and algorithms that come from our intelligence and knowledge about objects, their features, and usefulness. Moreover, not only directly subsequent objects but also more distant ones in any sequence or neighborhood can be connected and these connections appropriately weighted to emphasize the right contexts of their occurrences which exclude ambiguity. This feature is very important in view of storing various complex sequences, procedures, or algorithms that can be applied only in some specific situations, contexts, constraints, or circumstances, in which our brains make us undertake a specific strategy or action selected from the portfolio of the possible ones that are available to us.

In the DASNG model, objects represented by neurons are connected to other neurons that represent other objects or specific features. Each connection is appropriately weighted to reproduce the strength of the similarity, vicinity, or defining relations between them. In comparison to the non-weighted primary-foreign key binding mechanism used in databases, we achieve more precise information about the relation strengths of related objects when representing them in the DASNG model, so we can conclude about the represented relations easier and more accurately.

Summarizing, the DASNG model enriches the horizontal relations used in the databases with additional vertical relations between objects thanks to aggregations of the same values and connections between neighbor values. The use of reactive sensors and neurons instead of passive database records allows for fast automatic exploration of information according to the context given by the stimulation of any selected subset of sensors and/or neurons.

In the relational database model, we can distinguish one-to-one, one-to-many, and many-to-many relationships between related entities. The one-to-many relationship is represented by a primary key in one entity (e.g. in table E in Fig. 1) which is related to many foreign keys of other entities (e.g. in table A in Fig. 1). The many-to-many relationship defines multiple relations between various objects from two tables, so we typically use an additional link table which binds together primary keys of these tables (e.g. the table D relates entities of the tables A and C in Fig. 1). The link tables are unnecessary in the DASNG networks because we can directly represent many-to-many relations using direct connections between objects represented by neurons (Fig. 6). This is also true for one-to-many relations where objects are directly connected in the same way. Hence, we do
not need to distinguish between various cardinalities of relations as in relational databases.

Each attribute is represented by a separate sensory input field $F^a_k$ which consists of sensors representing aggregated attribute values, i.e. various features of objects. All sensors of each field $F^a_k$ are organized using a separate AVB-tree (Fig. 2). Such a structure makes all values quickly available, usually in constant time, however, the sub-linear-time access time may also happen for rarely frequent features. Moreover, numerical value neurons connect in order, so there is no need to sort data later (Fig. 2).

In the relational databases, modeled objects are stored in separate or connected table entities (records), while in the DASNG model, each object can be represented by a single neuron connected to other neurons defining features and included objects in it. If more than one database record contains the same set of attribute values and foreign keys, these records can be aggregated and represented by the same object neuron that counts the number of aggregated records. This aggregation does not eliminate diversity because the aggregating neuron can be further connected to various other neurons representing differing features for various aggregated objects. However, during such an aggregation, we lose the unique identity of the aggregated objects represented by the primary keys that diversify such records, e.g. two people with the same first and last name. When the diversity of records (objects) is necessary, the primary key must be treated as an attribute feature that cannot be reduced in the aggregation process. In result, such objects will not be aggregated and do not lose their identity and separateness fixed by their primary keys. On the other hand, the aggregation is many times beneficial, and we do not need to store the separate identities of all objects, e.g. it is usually unimportant to store the information about which exact entities of the same products have been sold by which the seller. It is possible to automatically distinguish between tables that represent objects that cannot lose their identity and other tables where we can do aggregations. The primary keys that are directly used by SQL queries to search for records are non-reducible and should be treated as other attributes that store important data. On the other hand, when the primary keys are used only to join records from the related tables, such keys are reducible and can be converted to connections between neurons. Hence, we need to analyze a possibly large subset of real SQL queries that have been processed on the given database in the past to automatically and correctly distinguish between reducible and non-reducible primary keys. In case, when we get a collection of empirical data records, where some records are identical (e.g. a few samples in the Iris data set from ML Repository), they can also be aggregated and represented by the same neurons.

Concluding, aggregations are very important in view of generalization, knowledge formation, and drawing conclusions about objects, so we should not always trend to store identities of all objects if not necessary.

Another benefit of direct connections between neurons representing objects is that we do not need to browse primary and foreign keys to join records from various tables and waste time. In the DASNG network, we simply go along the connections to associated information in constant time.

Figure 7: Various kinds of sensory stimuli and interactions with sensors in the sensory input fields (SIFs).

During the construction process, there is created a sensory input field $F^a_k$ for each attribute $a_k$ (the grey fields in Figs. 6, 8-10). The sensory input fields (SIFs) can be of various types alike the senses in a human body. These fields constitute input interfaces for the remaining part of the neural structure (Fig. 6). The SIFs contain sensors that are sensitive for some values, their ranges, or subsets (Fig. 7). The sensors can be differently sensitive to various values presented to their SIF. They are not sensitive to the values presented to the other SIFs. The way the sensors work can be described by suitable mathematical functions introduced in section 4.

The structure presented in Fig. 6 represents not only horizontal relations between objects but also vertical relations between data of each attribute. These data are ordered, and all duplicated values of each attribute are removed. Despite this reduction, there is no loss of information because the duplicated values have been replaced by connections to various neurons representing various objects in Fig. 1. Moreover, the aggregation of duplicates and their joined representation allow for very fast access to any data. Databases use B-trees or B+trees to achieve a logarithmic time of search operations while DASNGs use AVB-trees which for a constant set of stored unique attribute values usually work in constant time. Hence, we also do not waste so much time during insertion or delete operations like when using indexes in databases. We do not need to sort data or add indices to this structure because data are always automatically sorted simultaneously for all attributes. Furthermore, the transformation of the table structure to the presented graph structure automatically
extracts additional relations of their order, similarity, minima, maxima, ranges from the data, which are available on demand in constant time. Thanks to the aggregation and joined representation of duplicates we have direct access to all objects (records) that have some given value which we want to explore. We also have indirect but very fast access to all similar objects which are defined by similar attribute values. Thus, we can also define various clusters of similar objects or recognize their defined classes represented by neurons very fast for any criteria. The stimulation of any subset of features, their ranges, or any subset of objects induces gradual activations of the associated objects neurons, which can be clustered on this basis. The object class can be retrieved based on the first or most frequently activated class neuron. Every such stimulation of DASNG takes constant time, so it is fast in comparison to many other methods.

The use of ASNs in the DASNG network makes possible to develop a reactive graph structure that can execute some operations on the represented data fully automatically. Such operations let us draw useful conclusions about objects and their features represented in this neural network.

6 NEURONAL INFERENCE

After the transformation of the database tables into the DASNG neural network presented in Fig. 6, this network can be used for inference about represented objects to find similar objects quickly, various classes of objects, identify shared features, filter or sort objects after various criteria, attributes, or draw some useful conclusions about selected groups of objects. Figures 8, 9, and 10 present exemplary inference processes that can be performed in this DASNG network. To filter out objects including some features or other objects, it is enough to stimulate these features or objects via sensors or neurons representing them in the DASNG network and wait for spikes of neurons representing answers (Fig. 8). In such a network, it works like associative reminding in a human brain when recalled information together with the previous calling context create a new context for recalling of the next memories associated with the information represented by the recently activated neurons. Therefore, the further stimulation of the initial context (here: the sensor representing “science”) induce the gradual activations of the next connected neurons representing associated information about previously recalled objects (Fig. 9). Thus, we can automatically find out what are the names of pupils who like science, what subjects they like at most, and what are their living conditions. We can conclude about them as far as the created structure contains such information and as long as the sensor “science” is stimulated providing subsequent spikes of the directly or indirectly connected neurons. If the network works parallel, then we always get all this information in constant time.

The inference processes in the DASNG neural network are based on measuring the time when the ASN neurons representing the desirable answer(s) start spiking and on counting the numbers of their spikes (Fig. 10). Neurons representing the answer spike most frequently and typically start to spike at first. The less frequently or later spiking neurons usually represent other weaker alternatives, i.e. objects that only partially satisfy the input conditions or the associated features of the objects representing the answer. On this basis, we can conclude that pupils
represented by the most frequently spiking neurons 3 (Jack Brown) and 5 (Luke Hanks) are interested in science and live in the apartments. The other pupil neurons 2, 6, 7, 8, 9, 10, 11, 14, and 16, which spike less frequently, represent the pupils who like science or live in apartments. The pupil neurons 1, 4, 12, 13, and 15, which do not spike at all, represent pupils with the other interests and those, who do not live in apartments. The chronology of activations of individual neurons automatically sorts the objects or features represented by these neurons. These kinds of neuronal structures do not only represent data transformed from the database but also have the built-in inference routines available thanks to associations represented by the connections between ASNs.

Figure 10: Neurons representing the conjunction of the stimulated features spike the most frequently and usually also at first (the violet pupil neurons 3 and 5), while neurons representing the other alternatives spike less frequently and usually start spiking later (the red and blue pupil neurons).

Each database table which represents only a single attribute is transformed into a single SIF, sensors, and value neurons, while database tables containing more attributes and foreign keys are represented by separate layers of object neurons. Hence, such an associative graph can have many appropriately connected layers dependently on the size and complexity of the transformed database.

The construction and inference processes in the DASNG networks are parallel in their nature, so there can be used many processors and many cores of processors to accelerate such computations and make them even faster in comparison to sequential methods often used in many relational DBMS systems.

Today, the main limitation of DASNG networks is in the capacity of RAM memory installed on the server because the efficiency of operations proceeded on these kinds of networks can be significantly reduced by the disc operations. Therefore, it is recommended to keep the whole DASNG network in the RAM memory during its work like the biological neurons in brains which are still ready to use in a human brain (Kalat, 2012). Despite this limitation, thanks to the possible aggregations of duplicates, even large databases can be successfully transformed into the DASNG networks, fit into the RAM, and can benefit from the very fast operations on them and automatic inference about represented objects.

7 CONCLUSIONS

This paper presented new complex deep associative semantic neuronal graph structures consisting of the special kind of spiking neurons which let us associate data and objects in various ways and run fast inference in constant time. It was also investigated that such networks produce answers based on speed and frequency of spikes of neurons which represent the most associated values or objects in the DASNG network. This paper also provides the information about the possible interpretation of how biological and spiking neurons represent information using frequencies of spikes and the time of being activated that had elapsed from the input stimulations that had a real influence on these spikes (Kalat, 2012).

It was presented how this network can represent horizontal and vertical relations between data and objects, expanding possibilities of the relational model used in relational databases (Hellerstein et al., 2007). It was also explained why the most frequent operations of this model are typically processed in constant time thanks to its automatic ordering mechanism which works for all attributes simultaneously. The presented AVB-trees manage attribute data and allow for very fast access to them in comparison to other popular algorithms used in relational databases due to the aggregations of duplicates and connections of successive values. The presented associative spiking neurons can be used to create complex neuronal structures which represent related objects defined by attributes and other objects.

The DASNG abilities were demonstrated on several examples which showed how these networks could be used for inference and searching for related information according to some initial contexts, including filtering, conjunction, and alternative. Due to the aggregation properties of the DASNG networks, they could be used for mining and finding frequent itemsets for Big Data (Apiletti et al., 2017) and be applied to overcome new challenges (Jin et al.,...
2015) thanks to their built-in self-organizing neural network mechanisms (Parisia, 2015).

The future works include further studies on deep architectures consisting of the associative spiking neurons and possible ways of complex inference using various kinds of associations. The presented model will be developed to represent and use sequential patterns, ranges, clusters, and classes to allow for deeper inference, mining, and appropriate generalization during classification. The future studies will strive to create a self-developing graph structure to store and reinforce the gained conclusions and build neural knowledge-based cognitive systems.

However, this paper is not a complete solution for solving all difficulties and inefficiencies of databases, but it has shown how neurons and DASNG networks could help to solve some of the problems mentioned above, and make the computations on big data more efficient in the future. The associative spiking neurons used in the DASNG networks as well as biological neurons do not calculate output values directly but using time-based approaches and frequencies of spikes. They represent and associate various data combinations in many ways to recall these associations in the future when the similar ignition contexts will happen again. They can also generalize about associated data, especially when new input contexts are used. It is planned to construct intelligent associative knowledge-based cognitive systems on their basis in the future. Finally, deep associative spiking neural models can be an interesting alternative to databases not only to store data but also to supply us with conclusions and enable very fast access to various pieces of information that can be drawn from the collected and associated data. The presented neural networks can support the future big data mining and knowledge exploration systems.

ACKNOWLEDGEMENTS

This work was supported by AGH 11.11.120.612 and a grant from the National Science Centre DEC-2016/21/B/ST7/02220.

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