A Structure based Approach for Accurate Prediction of Protein Interactions Networks

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Keywords: Protein Interactions, Protein Structure, 3D Templates, Protein Interaction Network, Protein Binding Sites.

Abstract: In the recent days, extraordinary revolution in genome sequencing technologies have produced an overwhelming amount of genes that code for proteins, resulting in deluge of proteomics data. Since proteins are involved in almost every biological activity, therefore due to this rapid uncovering of biological “facts”, the field of System Biology now stands on the doorstep of considerable theoretical and practical advancements. Precise understanding of proteins, specially their functional associations or interactions are inevitable to explicate how complex biological processes occur at molecular level, as well as to understand how these processes are controlled and modified in different disease states. In this paper, we present a novel protein structure based method to precisely predict the interactions of two putative protein pairs. We also utilize the interspecies relationship of proteins i.e., the sequence homology, which is crucial in cases of limited information from other sources of biological data. We further enhance our model to account for protein binding sites by linking individual residues in structural templates which bind to other residues. Finally, we evaluate our model by combining different sources of information using Naive Bayes classification. The proposed model provides substantial improvements in terms of accuracy, precision, recall when compared with previous approaches. We report an accuracy of 90% when tested for a protein interaction network of yeast proteome.

1 INTRODUCTION

Proteins are the most essential macromolecules that are involved in almost every biological activity. Our knowledge of new proteins is increasing with a rapid pace as next generation sequencing technologies are uncovering new genomes. The knowledge of proteins alone, is not sufficient since proteins rarely act in isolation. The overall complexity of biological systems at different levels primarily arise due to the combinatorial interactions caused by the proteins in the cells. One of the crucial step for understanding biological cells as engineered systems is to map networks of DNA-protein, RNA-protein and protein-protein interactions (PPIs) of a species as completely and accurately as possible. Precise knowledge of protein interactions is also a precondition for fulfilling the promise of preventive as well as personalized medicines that which means more rational development of antibacterial compounds, drugs, and vaccines.

The conventional wet lab experiments e.g., Yeast two-Hybrid (Y2H) (Ito et al., 2001) screening, Protein-fragment Complementation Assays (PCA) (N. Pelletier et al., 1999), or co complex interaction maps (that are attained by high-throughput Co-affinity Purification followed by Mass Spectrometry (AP/MS) to identify protein-protein (bait) interactions) (Rigaut et al., 1999; A. Shoemaker and R. Panchenko, 2007a) etc., are either slow, costly or prone to noise because of the nature of these experiments. Moreover, the existing noise in protein interaction databases resulted by these experiments, plus the deluge of protein data produced by next generation sequencing technologies motivates the need to make accurate computational techniques that can precisely map the interactions of proteins on genome wide scale.

Several computational techniques have been proposed in the past that incorporate a wide variety of data e.g., phylogenetic profiles, sequence homology, and co-expression of genes etc., to accurately infer genome-wide protein-protein interactions (A. Shoemaker and R. Panchenko, 2007b; Salwinski and Eisenberg, 2003). However, comparative studies advocate that the development of noise free protein in-
interaction repertoires of different genomes, is still in its early stages (Braun and et al., 2009; Deane et al., 2002). The most prominent computational methods that produce high confidence interactions utilize protein’s structural information e.g., (C. Zhang et al., 2010; Wass et al., 2011). But unfortunately, there is a huge difference between the number of known protein sequences and their relative known structures; even for the well studied organism such as Saccharomyces Cerevisiae, the known structural information is sparse i.e. less than 10% proteins are with known structure (Zhang et al., 2012). Moreover, the protein complex information of known PPIs is even sparser.

Fortunately, homology models (see Figure 1) as well as known protein complexes (across species) in well-known databases e.g. PDB (Protein Data Bank) (M. Berman et al., 2000), present the opportunity to relate unknown structure sequences with known structures using geometrical features of the individual templates. Approaches incorporating this type of information have shown great success; in such cases protein structure have multiple clues that associate the geometric features of individual templates. However, these methods exhibit much less success on proteins with inconsistent homolog templates (i.e. the homolog templates whose geometrical features are much variant; hence they result in effecting the overall accuracy of the prediction schemes).

In this paper we proposed and evaluated a novel approach that combines heterogeneous structural information of proteins and determine their potency for interaction in the form of a probability score. The fundamental conceptual innovation of our method is to connect geometrical features of proteins with protein binding sites and to enhance the algorithms power as well as applicability for heterogeneous homolog templates. Our new approach relies on scores (features) obtained by combining diverse sources of biological information which includes: sequence similarity, protein homology, protein binding sites, and geometrical features like, no of interacting residues, no of surface residues etc. These scores are combined using Bayes classifier and an overall confidence score is calculated that determines the binding potential of two proteins as interacting pairs.

The remaining part of the paper is organized as follows: In Section 2, we first give an overview of the closely related approaches used for the prediction of protein-protein interactions; with the explanation of why structure based approaches stand out from other techniques. We then introduce, in Section 3, a heterogeneous information based Bayesian network model that combines different types of information (i.e., sequence similarity, protein homology, protein binding sites, and geometrical features) to predict protein-protein interactions. Section 4 demonstrates the effectiveness of the proposed model when applied to cross validate, a subset of interacting as well as non interacting proteins in the yeast network. We lastly discuss the results of our scheme and also compare the performance of most recent related state-of-the-art structure based schemes with our scheme. In Section 5 we present conclusion of our study with possible future considerations.

2 RELATED WORK

Protein-protein interactions are key to most of the biological processes. These interactions orchestrated by molecular mechanisms that have yet not been clearly understood. Understanding protein-protein interactions would also provide us crucial clues about intercellular signalling pathways. Numerous experiments have been devised by researchers in the labs including yeast two-hybrid systems, mass spectrometry, protein microarrays and others. Unfortunately, experimental techniques have not been able to characterize the proteins to a great extent. Thus, our knowledge of protein functions as well as their interactions is very limited. This low contribution by experimental techniques and lesser knowledge about protein interactions is being complemented by the advancement of computational methods.

Since, protein sequence is the most basic as well as most easily available type of information about proteins; therefore, many methods devised in the beginning focused on use of sequence information to see the mutual evolution of proteins. One such method, focused on evolutionary information related to structure and function was proposed by (Valencia and Pazos, 2003). This method constructs and utilized evolutionary relationship among proteins to infer PPI as such proteins co-evolve. Another approach was a multiple classifier based system harnessing sequence of proteins (F. Xia et al., 2010). They utilized two
classifiers rotation forest and autocorelation descriptor. This group tested their system on *Saccharomyces cerevisiae* and *Helicobacter pylori* data. Sequence based approach for PPI prediction has been used by another group but with slight variations. They predicted PPIs more precisely from sequence alignments of proteins by using a Bayesian classifier (Burger and V. Nimwegen, 2008). A similar and more recent set of techniques utilized only sequence information for PPI prediction e.g., (Shen et al., 2006; You et al., 2015).

Mathematical probabilistic models were adopted by some researcher for the prediction of protein-protein interactions. In one such case Probabilistic analysis predicted nearly 40,000 interactions in humans (R. Rhodes et al., 2005). This probabilistic model combined interaction data, functional annotation data, protein domain data and genome-wide gene expression data. Probabilistic models have also provided a motivation for research to model more protein-protein interactions. A work was done using Generative Probabilistic Models with bi clique perspective to model the interaction network of *Saccharomyces cerevisiae*(Schweiger et al., 2011). This method concluded that nave unmodified DD (duplications-divergence) model is much more effective than Preferential Attachment model at capturing key aspects of PPI prediction. Another work employed the use of distant conservation of patterns in protein sequences, also called motifs and their structural relationships in proteins (Espadaler et al., 2005).

Most recent approaches that integrate structural and non-structural type of information into computational models and use machine learning algorithms e.g., Bayesian classifier or Support Vector Machines etc., to infer interaction of putative proteins. One such work is done in the recent past by (Zhang et al., 2012), that utilizes structural as well as non-structural type of features with a blend of Bayesian Classifier for prediction of PPI on a genome wide scale. The authors of this study presented their results for *Saccharomyces cerevisiae*, and reported that structural features outperform non structural features with great margin in terms of statistical performance measures i.e., precision, recall, accuracy, false positive rate etc.,. The major contribution in this work was the use of structural features and evaluation of their impact on the prediction accuracy. Thus structural information of proteins plays a key role in deciphering the underlying mechanism of protein interactions. Therefore, in our work we also mainly integrate, structural information of proteins along with protein binding sites to predict their associations.

### 3 METHODS

In our work, we employ the idea of integrating heterogeneous biological information associated with two queried proteins and determine their strength for interaction, by combining this information in the form of scores using Bayesian statistics. The distinctiveness of our technique comes from the fact that potential interaction information e.g., protein binding sites (which are strongly associated to molecular interaction), can be combined with geometrical features present in the structural templates of two interacting proteins to decide if they interact or not. This combination also increases the power of our algorithm to include structural templates that are varied in geometry but contain sites that can bind to other proteins. Our proposed approach relies on scores (features) obtained by combining diverse sources of biological information which includes: sequence similarity, protein homology, protein binding sites, and geometrical features like, no of interacting residues, no of surface residues etc.

The prediction of protein interactions is more challenging for proteins which are not well annotated or whose molecular details are limited. To enhance the predictive power of our automated PPI prediction algorithm, we combine very powerful associative sources of information namely: protein homolog & sequence similarity, as a baseline to capture proteins which are most similar. This is particularly important as each type of data typically captures distinct aspects of associative activity. The overall process of our technique for PPI prediction is divided into seven steps (as shown in Figure 02):

#### Step 1: Selection of Homolog Sequences

To predict the interactions for sparsely annotated proteins, the first useful type of information that can associate them is the protein homology information. Evolutionary relationships between species advocate that the homolog (specifically orthologous) proteins of different species, whose functions have been established before speciation event and which share high sequence similarity are likely to interact for similar functional activities.

Two proteins are said to be homologous if they share a common ancestor. To detect homology, sequence information is often used to deduce if proteins are homologous or not. If two proteins share high sequence similarity i.e., above 25 % sequence similarity (Benso et al., 2013; Mitrofanova et al., 2011; Benso et al., 2012), they are very likely to be homologous and have similar structures and in many cases part of
The input of our algorithm is a pair of proteins (also called query proteins) say $P_1$ and $P_2$ (in our implementation we used Uniprot IDs (The UniProt Consortium, 2015)), whose interaction information we want to find or predict. In the first step, since these proteins can possibly be sparsely annotated so, we need to associate them through homology to other proteins. To capture ortholog based homolog similarity we run a single iteration BLAST (Altschul et al., 1990) search for each query protein $P_i$ against the protein NR database with an E-value cutoff of 0.0001. We selected protein structures (namely, $S_1$ and $S_2$; also called Model structures) that are highly similar to our query, with the additional constraint that matching PDB structures should have at least 90% or higher sequence identity. It is pertinent to note that this similarity is only in sequences not in structure. The obtained structures as a result of sequence similarity are then queried to PDB (M. Berman et al., 2000), to obtain their structural details (i.e. atomic coordinates, residues information etc.).

**Step 2: Finding Structural Neighbors**

In the second step, structural representatives of each model structure i.e. $S_1$ and $S_2$, were taken directly by querying each model structure to VAST+ (Vector Alignment Search Tool Plus) Server (Madej et al., 2013). VAST+ is a tool designed by NCBI (National Center for Biotechnology Information) and utilizes Molecular Modeling Database (MMDB), for 3-dimensional structures, with the need of finding those structures that have similar macromolecular complexes. The macromolecular similarities are evaluated using purely molecule’s geometric criteria, without considering sequence similarity, thus it is able to identify even distant homologs structures. We queried VAST+ with default parameters and with a threshold of ten templates i.e. we select top ten neighboring templates of each model structure. The structural neighbors are named as $SA_i$ for model template $S_1$ and $SB_i$ for model template $S_2$, (where, $i = 1, 2, ... , 10$).

**Step 3: Formation of Templates Pairs**

At this stage, we have 10 structural neighbors for each query protein $P_i$. To check the overall binding potential for interaction, of individual template pairs, we construct pairs of each structural neighbor $SA_i$ with $SB_j$ (where $i = 1, 2, ... , 10$) i.e., $SA_1$ pairs with $SB_1$, $SB_2$, ... and so on up to $SB_{10}$, likewise we repeat pairing for $SA_2$, $SA_3$ ... up to $SA_{10}$. This step results in a total of 100 template pairs.

**Step 4: Identification of Interacting Residues and Binding Sites**

As a first step, to evaluate the propensity for interaction, of individual template pairs, we first identify the # of interacting residues in the template pairs. For this purpose, we use a tool called Multiprot in a protocol known as PRISM (PRotein Interactions by Structural Matching) (Tuncbag et al., 2011; Shatsky et al., 2004). The Multiprot rationale is based on the fact
that globally different protein structures can interact via chains of architecturally similar residues called motifs. Thus Multiprot predicts binding residues by utilizing structural similarity as well as evolutionary conservation of putative binding residue also called hot spots. For each template pair Multiprot calculates the \# of interacting residues.

To further strengthen the PPI prediction of our technique we also utilize the PDBeMotif (Golovin and Henrick, 2008). PDBeMotif is an incredibly fast and powerful search tool that facilitates the exploration of binding sites of single proteins or classes of proteins e.g., Pepsin, and locates the conserved structural features of individual residues both within the same specie as well as in different species. We employ PDBeMotif to locate residues that are binding sites in our template pairs.

Step 5: Modeling Structural Templates using Homolog Pairs

In this step, we build an interaction model $Mod_{ij}$ by superposing the template pairs $SA_1$ and $SB_1$ over the model template $S_1$ and $S_2$. Overall 100 models are built for (10x10) template pairs. Each model $Mod_{ij}$ is used to calculate four structure based scores.

Step 6: Calculating Interaction Scores from Interaction Models

From the 100 interaction models we prepared in the previous step, we evaluate and combine associated information to calculate four scores for each interaction model $Mod_{ij}$. The scores are based on the criterion that make use of interacting residues, binding sites as well as sequence information. We name our first score as $\xi_{Mod_{ij}}^{(1)}$ where $Mod_{ij}$ denotes the interaction model for which this score is calculated. $\xi_{Mod_{ij}}^{(1)}$ is calculated by taking into account the number of interacting residues in the template (calculated using Multiprot) that are preserved in the homolog models $S_1$ and $S_2$, i.e. both template and model share those residue pairs. Templates have different variations in their amino acid sequence, this score captures the strength of interaction model in terms of \# of interacting residues preserved, when compared with homolog template pair.

The second score of our model is called $\xi_{Mod_{ij}}^{(2)}$ and is estimated by taking fraction of total interacting residues preserved i.e., $\xi_{Mod_{ij}}^{(1)}$ divided by the average of total number of residues in both homolog templates i.e., $S_1$ and $S_2$, as shown in equation 1.

$$\xi_{Mod_{ij}}^{(2)} = \frac{\xi_{Mod_{ij}}^{(1)}}{Average(S_1, S_2)}$$ (1)

The third score $\xi_{Mod_{ij}}^{(3)}$ is the same as the first score, with the additional check that the interacting residues, both in template and model are also shared by the binding sites retrieved using PDBeMotif service, and is calculated as shown in the equation 2.

$$\xi_{Mod_{ij}}^{(3)} = [\xi_{Mod_{ij}}^{(1)} \cap Binding\_Sites(Mod_{ij})]$$ (2)

Lastly, the final score $\xi_{Mod_{ij}}^{(4)}$ of our technique is calculated by taking shared binding sites in the superimposed template and model pairs as shown in equation 3. $\xi_{Mod_{ij}}^{(4)}$ is the number of binding sites in the template that align to the number of binding sites in the model.

$$\xi_{Mod_{ij}}^{(4)} = [Binding\_Sites(S_1, S_2) \cap Binding\_Sites(Mod_{ij})]$$ (3)

Step 7: PPI Prediction using Bayesian Networks

Once all scores are calculated for hundred interaction models, we then combine their effect into one score by taking the mean and standard deviation of individual scores as shown in equation 4 and 5.

$$\varphi_{l}^{(k)} = \frac{\sum_{i=1}^{10} \sum_{j=1}^{10} \xi_{Mod_{ij}}^{(k)}}{100} \quad \text{...For, } k = \{1, 2, 3, 4\}$$ (4)

$$\varphi_{l}^{(i)} = \frac{\left(\sum_{i=1}^{10} \sum_{j=1}^{10} \left(\xi_{Mod_{ij}}^{(k)} - \varphi_{l}^{(k)}\right)^2\right)}{100} \quad \text{...For, } k = \{1, 2, 3, 4\} \text{ and } l = \{5, 6, 7, 8\}$$ (5)

The Standard deviation of scores captures the fact that, whether the templates that our method finds are different from each other or not, because when differences among homologs are spread out the standard deviation will be high.

Lastly we use Bayesian classification to combine the mean values as well as the standard deviations of our scores captured in eight variables $\varphi^{(k)}$, where $k=\{1,2,\ldots,8\}$. Let $P_i$ and $P_j$ be the query proteins whose interaction we want to predict.
and $\varphi(1), \varphi(2), \varphi(2), \ldots, \varphi(8)$ be the random variable that capture different aspects of structural association. The conditional probability that $P_i$ and $P_j$ interact given the distribution of random variables $\varphi(1), \varphi(2), \varphi(2), \ldots, \varphi(8)$ is given by:

$$P(C_{ij} = 1 / \varphi(1), \varphi(2), \varphi(2), \ldots, \varphi(8)) =$$

$$= \left( \prod_{k=1}^{8} P(\varphi(k)/C_{ij} = 1) \cdot P(C_{ij} = 1) \right) / \left( \prod_{k=1}^{8} P(\varphi(k)/C_{ij} = 1) \cdot P(C_{ij} = 1) \right) + \left( \prod_{k=1}^{8} P(\varphi(k)/C_{ij} = 0) \cdot P(C_{ij} = 0) \right)$$

where $P(C_{ij} = 1)$ is the prior probability that $P_i$ and $P_j$ interact, $P(\varphi(1), \varphi(2), \varphi(2), \ldots, \varphi(8))$ is the probability that $P_i$ and $P_j$ has $\varphi(1), \varphi(2), \varphi(2), \ldots, \varphi(8)$ features and $P(\varphi(1), \varphi(2), \varphi(2), \ldots, \varphi(8)/C_{ij} = 1)$ is the probability that $P_i$ and $P_j$ has $\varphi(1), \varphi(2), \varphi(2), \ldots, \varphi(8)$ features given that $P_i$ and $P_j$ interact.

All feature values $\varphi(1), \varphi(2), \varphi(2), \ldots, \varphi(8)$ are normalized and we used binning of feature values so that values of features lie in known ranges. As many machine learning algorithms specially Bayes classification produce better results when continuous attributes are made discrete. Finally, we calculate the value of $P(C_{ij} = 1 / \varphi(1), \varphi(2), \varphi(2), \ldots, \varphi(8))$ for each protein pair $P_i$ and $P_j$.

4 EXPERIMENTAL SETUP AND RESULTS

The integration technique described in the Methods section is evaluated on the task of predicting protein-protein interactions for an interaction network of Saccharomyces cerevisiae species proteins. We tested our algorithm on a data set of Yeast species proteins obtained from IntAct database [Results-01]. The algorithm fuses probabilities derived from diverse data sources including sequence similarity, protein homology, protein binding sites used in combination with other geometrical features. A well known powerful classification scheme i.e. Bayes classification, was used to combine mutually independent features (scores).

In this work, we present results of our scheme for a portion of Saccharomyces cerevisiae species interaction network. We chose the interaction network of HSP75_YEAST protein (Uniprot ID: P11484) for our experiment and tried to reproduce its interaction network using our proposed algorithm. The HSP75_YEAST protein was chosen firstly because it is involved in heterogeneous molecular activities and secondly, because the interaction networks of this protein contains many experimentally validated interactions. Thus, to better evaluate the prediction performance of our algorithm we chose this network.

The HSP75_YEAST protein’s interaction network in IntAct database contain 4,449 interactions as of August, 2015. The protein interaction network databases contain false positive interactions that are a bottleneck to predict the overall performance of an algorithm as well as to judge the statistical significance of experiments conducted. In order to deal with this limitation, we filtered interaction network to include interactions that are of high confidence with the criteria that each interaction in the network must be supported by at least two experimental methods. After filtering our network reduced to 1770 interactions.

We call these interactions as high confidence interactions because each interaction is supported and validated by at least two experimental methods. The interaction network contains proteins from the same (Saccharomyces cerevisiae) as well as other species namely: Arabidopsis thaliana, Rattus norvegicus, Arabidopsis thaliana, and Dictyostelium discoideum.

4.1 Performance Evaluation

For evaluating prediction performance we use cross validation approach to estimate the prediction potency of our proposed scheme i.e., for each protein pair $P_i$ and $P_j$ in the interaction data set, we assumed the interaction of $P_i$ and $P_j$ were unknown and then attempted to predict the interaction by means of our algorithm. Lastly, we compare the predicted interactions with the true interaction set. For assessment of our methodology, we computed performance measures, such as: precision, recall, accuracy and F1 which are estimated using the following formulas:

\[
\text{accuracy} = \frac{TP + TN}{TP + FP + TN + FN}
\]

\[
\text{precision} = \frac{TP}{TP + FP}
\]

\[
\text{recall} = \frac{TP}{TP + FN}
\]
\[ F1 = \frac{2 \times \text{precision} \times \text{recall}}{\text{precision} + \text{recall}} \]

### 4.2 Cross Validation Analysis of Prediction Accuracy

For the interaction network described earlier we first attempted to predict protein-protein interactions by 10-fold cross validation. For each protein pair \( P_i \) and \( P_j \) the probability that protein \( P_i \) interacts with \( P_j \) is calculated using equation 6. Predicted protein interactions having a probability estimate of greater than 0.5 were considered as positive interactions otherwise we conclude that proteins don’t interact. By applying our algorithm on high confidence interaction network retrieved from IntAct, we obtained an overall accuracy of 90\%, recall of 95.2\%, precision of 94.11 and an F1 score of 94.49\%.

### 4.3 Comparison with other Approaches

In this section, we broadly compare our method to the most widely used group of techniques, such as Pre-PPI algorithm proposed by Q. C. Zhang et al. (Zhang et al., 2012), which combines structural as well as non-structural type of information to predict protein-protein interactions. In such methodologies, interactions among proteins are predicted by combining structural clues with non-structural clues using some machine learning algorithm such as, Support Vector Machines (SVM), Bayesian framework etc., which consequently assign a probability score to a protein pair of interest as positively or negatively interacting. Fundamentals of Bayesian techniques are at the heart of the overwhelming majority of methods currently used to combine heterogeneous sources information for PPI prediction. Since this scheme (Zhang et al., 2012), uses Bayesian technique as well as utilizes structural information to predict PPI therefore, we compare our algorithm against this computational technique.

To obtain the most correct comparative results, we use the same species proteins i.e., *Saccharomyces cerevisiae* and compare results in a 10 fold cross-validation setting. The results in figure 03 clearly signify that our method performs better than the Q. C. Zhang’s Pre-PPI method (Zhang et al., 2012) across all measures reported i.e., precision, recall, accuracy and F1 scores. We observed that for almost the same accuracy values, Pre-PPI method produced higher number false positive as well as false negatives predictions, which resulted in lower values of precision and recall, respectively. The improved performance of our algorithm can be attributed to the most important functional clue called protein binding sites, which was further improved by combining with other structural information to precisely model the interaction activity.

### 5 CONCLUSIONS

In this work, we presented a novel approach that uses heterogeneous biological information associated with two queried proteins and determine their strength for interaction, by combining this information in the form of scores using Bayesian statistics. The distinctiveness of our technique comes from the fact that potential interaction information i.e., protein binding sites, can be combined with other geometrical features present in the structural templates of two interacting proteins to decide if they interact or not. This combination also increases the power of our algorithm to include structural templates that are varied in geometry but contain sites that can bind to other proteins. The proposed model provides substantial improvements in terms of accuracy, precision, recall when compared with previous approaches. The proposed scheme may additionally be used in combination with non-structural features to enhance the prediction confidence.

### ACKNOWLEDGEMENTS

We would like to show our gratitude to Dr. Omar Usman, Assistant Professor at National University of Computer & Emerging Sciences for his worthy comments that greatly improved the manuscript.
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