Performance-optimized Indexes for Inequality Searches on Encrypted Data in Practice

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Abstract: For information systems in which the server must operate on encrypted data (which may be necessary because the service provider cannot be trusted) solutions need to be found that enable fast searches on that data. In this paper we present an approach for encrypted database indexes that enable fast inequality, i.e., range searches, such that also prefix searches on lexicographically ordered but encrypted data are possible. Unlike common techniques that address this issue as well, like hardware-based solutions or order-preserving encryption schemes, our indexes do not require specialized, expensive hardware and use only well-accredited software components; they also do not reveal any information about the encrypted data besides their order. Moreover, when implementing the indexing approach in a commercial software product, multiple application-centric optimization opportunities of the index’s performance did emerge, which are also presented in this paper. They include basic performance-increasing measures, pipelined index scans and updates and caching strategies. We further present performance test results proving that our indexing approach shows good performance on substantial amounts of data.

1 INTRODUCTION

Along with the risen popularity of cloud-based informations systems (IS), the need increases as well for such systems that store highly sensitive data, like, e.g., medical data. For instance, software companies developing a cloud-based ambulatory information system for medical data have to comply with strict legal obligations considering data confidentiality, meaning all data on the server need to be encrypted, and the encryption keys need to reside outside of the scope of all entities (especially server entities) without a need-to-know for that data. On the other hand, requirements regarding flexibility and performance still have to be fulfilled.

In order to enable good performance for inequality searches (i.e., range searches) on encrypted data values that constitute a linear order, this paper focuses on design, usage and especially optimization of encrypted indexes for such searches. Similar to order-preserving encryption (OPE) schemes, our indexes disclose the values’ order, so the server can use that information for fast data access. The order is stored in the index in a binary tree representation as well as simultaneously in a linear list representation. During searches, the binary tree is used for fast determination of the boundary values of a range search interval, and the linear list for fast collection and sorting of all values lying between the boundary values.

The work that has to be done for such a search is split between client and server under the paradigm of letting the server do as much work as possible. However, unlike most OPE schemes (see (Popa et al., 2013)), our indexes do not reveal further plaintext bits of the indexed data. Furthermore, by a slight modification the index can be used to perform prefix searches on lexicographically ordered data.

The index is designed in such a way that it can easily be implemented using only standard SQL DDL components of the underlying DBMS; i.e., no DBMS or even hardware components have to be changed in order to use the index.

A further advantage of the index is that its functionality and security do not rely on a specific encryption scheme like, e.g., OPE or homomorphic encryption (HOM). Instead, the index can be implemented using an arbitrary, well-accredited encryption scheme; at the time we use the Advanced Encryption Standard (AES) encryption scheme in
Galois-Counter Mode (GCM) and 256 bits key length. Nevertheless, the encryption scheme can easily be replaced by another scheme if necessary.

We also present, from an application-centric point of view, several extensions of the basic index concept that significantly enhance its performance and applicability in a real-life software product. These extensions include performance-enhancing measures by standard “on-board” DBMS means, pipelined index scans and updates and caching strategies on both client and server for faster data retrieval during read as well as write operations.

The remainder of the paper is organized as follows. After giving an overview of previous and related work in section 2 we introduce the index in section 3, covering its basic idea, implementation details and cryptographic considerations. In section 4, a set of basic performance-enhancing measures is introduced before caching strategies are presented in section 5. In section 6 performance test results are presented and discussed. The paper is concluded with summary and future considerations in section 6.

2 RELATED WORK

Many publications exist that target fast access to encrypted data. E.g., in an early stage, (Hacigümüş et. al., 2002) defined a paradigm of letting the server do as much data processing as possible though dealing only with encrypted data, and hence presented a “coarse index” approach by labeling all encrypted data on the attribute level with their respective value domain partition.

More recent contributions have been made in the HOM, e.g., in (Gentry, 2009), and the OPE sector, e.g in (Agrawal et al., 2004), (Boldyreva et al., 2009) and (Liu and Wang, 2013). However, both classes of encryption schemes still lack performance; moreover, (Popa et al., 2013) shows that a whole list of OPE schemes leak a substantial amount of plaintext bits.

Another approach to the topic is the use of specialized hardware. Two examples of publications using that approach are (Ramanamurthy et. al., 2013) and (Bajaj and Sion, 2011). Their basic idea is a server component that uses a common CPU to process all non-sensitive data, while all sensitive data is transferred to a trusted hardware component in which data enter and leave only in encrypted form. The authors claim that their solution may be less performant than plaintext systems, but orders of magnitude faster than software-only solutions, i.e., OPE and HOM schemes. Nevertheless, such systems relying on specialized hardware are probably expensive and difficult to administer, apart from the fact that decryption keys reside on the server, albeit in a secure hardware module.

The focus of (Popa et. al., 2012) lies on the design of IS with an encrypted database backend. The authors present their system “CryptDB”, which makes use of random, deterministic, homomorphic and order-preserving encryption schemes in a “SQL-aware” way, so that native SQL queries can be executed on the encrypted data. The system also allows for dynamically adjusting the encryption layer on the DBMS server via a concept of “onions of encryption”. The generic approach of CryptDB that enables to process (almost) all kinds of SQL queries is impressive. However, in this publication performance-enhancing measures like caching and pipelined index updates are neither considered nor discussed; so our work provides a contribution to the topic that is orthogonal to CryptDB’s approach.

The same holds for (Tu et al., 2013): The authors present MONOMI, a system optimized for processing analytical queries over sensitive, encrypted data. It encompasses a designer and a planner component responsible for an optimized physical layout of the data at design time, respectively for the specification of optimized query execution plans at runtime. MONOMI’s expressive power is demonstrated on the TPC-H benchmark, where it shows impressive performance. MONOMI focuses on analytical queries, which means it is optimized for DRL operations, i.e., SELECT statements. But again, in this publication the performance enhancements we do present in this paper are not considered. Furthermore, when considering range searches, MONOMI also relies on order-preserving encryption schemes, which we chose to avoid.

Like mentioned before, the authors of (Popa et. al., 2013) show that current OPE schemes leak information besides the items’ order; they propose an alternative “order-preserving encoding scheme” claimed to reveal no information apart from the linear order of the encrypted elements. They follow a similar approach to ours by encrypting the index items with an arbitrary encryption scheme and providing the items’ order by organizing them in a binary tree. Yet we believe our indexes to have a performance advantage, for it needs fewer maintenance operations during normal DML operations, and especially because of our performance-enhancing measures presented in sections 4 and 5.
3 THE INDEX

In this section the basic idea of our index will be briefly described, after it has been introduced and described with greater detail in a previous publication of ours, (Lehnhardt et al., 2014).

3.1 Basic Idea

The basic idea of our index evolves around a data structure holding the encrypted contents of all index items. It is persisted in and processed by a common DBMS, although we consider a complete in-memory solution as a next step. Each index item’s content has been encrypted on the client such that the server is not able to view the content’s plaintext. Furthermore, the linear order constituted by the index items is expressed in the index data structure by two representations: first, a binary tree representation and second, a representation as a linear list (when referring to the index’s binary tree representation, we will sometimes refer to the index items als nodes; both terms are used synonymously).

Figure 1 shows an example of the index structure; note that the index item contents are only shown in plaintext for better understanding. Note further that the values of the linear list representation of the item’s linear order are not related to the respective item values. They are rather arbitrary numbers chosen in such a way that they constitute the same linear order as the index item values.

![Index structure](image)

Figure 1: Index structure containing item contents, binary tree organization and linear list numbers.

As the index items have a common structure, they are well suited for being stored in a common database relation, in which node ids, encrypted contents, parent and child node references of the binary tree representation and linear list numbers are stored in separate attributes.

3.2 Write Access

When a new item is added to an index of binary tree height \( H \) containing up to \( 2^H - 1 \) items, the index’s binary tree is traversed, starting at its root, until the right position for the insert is found, or it turns out that the value of the new item is already in the index. In this case the insert operation is skipped, because the index contains only unique items.

Since the decision for a node during tree traversal whether to proceed to its left or right child must be made on the node’s plaintext content, that content needs to be sent to the client, where it can be decrypted. The decision of the next item to be fetched from the index is sent back to the server. Hence, every node of the traversal path to the new node’s insert position must be transferred to the client, meaning \( H \) roundtrips between client and server, because new items are inserted at the binary tree’s leaf level.

3.3 Read Access

The main application of the index are range searches, i.e., all values lying in an interval \([a, b]\) (the interval can also be open or semi-open).

Another index application are prefix searches on lexicographic data, e.g., all persons’ last names starting with “sch”. Since lexicographically ordered data also establish a linear order, this type of search can easily transformed in a range search on that data: The search for items matching the regular expression \( sch\Sigma^+ \) can be transformed in an equivalent range search for items lying to the interval \([sch, increment(sch)] = [sch, scI]\).

When processing a range search with \([a, b]\) being the search interval, the index’s binary tree is first traversed looking for the appropriate index item value \( x \) being the closest match for the lower interval boundary \( a: x = \min\{k \in \text{index} \mid k \geq a\} \). The closest match \( y \) for the upper interval boundary \( b \) is accordingly: \( y = \max\{k \in \text{index} \mid k \leq b\} \).

Both values are found by tree traversal, similar as described in 3.2; however, here the client keeps track during traversal of the closest candidate so far for a lower or upper boundary value match.

Having found \( x \) and \( y \), a simple selection query is submitted to the DBMS, requesting all index items whose linear list number lies in the interval \([l_x, l_y]\), i.e., between the linear list numbers of \( x \)’s
and y’s index item. The DBMS can use the linear list numbers also to sort the query’s result set.

3.4 Further Aspects

3.4.1 Division of Labor

We would like to point out that the presented indexing approach implements a division of labor between client and server under the paradigm of letting the server do as much work as possible and making the client do only those steps that are not permitted for the server, i.e., accessing decrypted index values.

3.4.2 Security

As mentioned before, in (Popa et al., 2013) it is shown that most OPE schemes leak a substantial amount of plaintext information. An “order-preserving encoding scheme” is proposed that, like we do, uses an arbitrary, non-order-preserving encryption scheme like, e.g., AES, and expresses the items’ linear order through additional structures. The authors further show that this scheme does not leak any plaintext information about the encrypted values besides their order. Since the approach of the “order-preserving encoding scheme” is very similar to our range index data structure, the proof of (Popa et al., 2013) is also transferable, meaning that our index does not leak any plaintext information either, besides the values’ order.

A further advantage of our index is not having to rely on the security of a particular encryption scheme. We have the liberty of choosing a fast, well-accredited and widely accepted symmetric encryption scheme like AES-256 in GCM mode. And even if that scheme should be broken one day, it can easily be replaced by a new, still secure successor.

4 OPTIMIZATIONS

In this section a set of performance-enhancing measures is presented that can be added to the index’s basic idea given in section 3. Some of them are quite obvious, but should nevertheless be mentioned before the more sophisticated measures like pipelining and caching strategies (in section 5) are presented.

Regular Database Indexes. In order to perform fast operations on the database relation holding our index, a regular database index should be defined on the index item id in order to find items fast; since only punctual searches are performed on id, the index should preferably be a hash index. Another index should be defined on the linear list number attribute, since it is part of the data access path during read accesses (see 3.3). Because value ranges are requested here, a B+-tree index is preferable.

Redundancy. In order to accelerate binary tree operations, several information that is contained implicitly in the index’s binary tree representation should be made explicit:

- The reference to a node’s parent node refParent for fast server-sided subtree retrieval, preferably with a (hash) database index defined on it. At the same time, the database relation should contain refLeft / refRight child reference attributes which enable fast subtree traversal on the client.
- The height attribute of an index item holds the height of the subtree the item constitutes in the index’s binary tree representation, such that the value for height of item “Barton” in Figure 1 equals 2 and the height of “Elwood” equals 4. This helps accelerating tree balancing.
- isLeftChild tells whether the current index item is the left child of its parent node. This is helpful during determination of the change paths (see 5.3).

Subtree Retrieval. To reduce the number of server roundtrips, whole portions of the tree can be transferred to the client instead of single nodes, i.e., binary subtrees of a defined height limit \( h < H \) containing up to \( 2^h - 1 \) nodes. This way only \( \lceil H/h \rceil \) roundtrips are necessary. The subtree is then traversed in the client, until its leaf level is reached and the next subtree is requested or the entire tree’s leaf level is reached and traversal terminates. Note that only the \( h \) nodes of a subtree’s traversal path need to be decrypted instead of all up to \( 2^h - 1 \) nodes in the subtree.

AVL Tree. We chose an AVL tree for the index’s binary tree representation, for it is easy to implement and administer while still showing good performance. Furthermore, the subtree height can easily be varied in order to adapt roundtrip numbers and data volumes being transferred from server to client flexibly because of differing environmental circumstances like network latency and bandwidth.

Deterministic Encryption. When choosing a deterministic encryption function \( E \) such that the following equivalence holds:

\[
a = b \iff E(a) = E(b),
\]
then the step of adding a new item to the index can be improved the following way: If the population of the indexed data values is expected to contain many recurring values, i.e., that often a new index value \( x \) is to be inserted that is already in the index, then the client can encrypt \( x \) to \( x' = E(x) \) and let the server check whether \( x' \) is already in the encrypted index value attribute of the index’s database relation. This is obviously much faster than the tree traversal described in 3.1. A database index defined on the encrypted index value attribute is then recommended.

**Pipelining during Read Access.** When processing an interval search, every interval border requires a separate tree traversal (see 3.3), so when a query contains \( n \) interval conditions, up to \( 2n \) tree traversals are necessary, each requiring \(|H/h|\) server roundtrips, which would turn out to be expensive when all \( 2n \cdot |H/h| \) subtree retrievals were executed consecutively.

Instead, all \( 2n \) traversals can be processed in parallel by the client, while the database server performs all subtree retrievals in a single worker thread; hence, this procedure is rather a pipelined subtree retrieval instead of a parallel one.

Nevertheless, because the database server is by far not the bottleneck in our system architecture, it can easily serve all the requests with little additional latency for the entire query response time. Hence, a query containing many range conditions does not take substantially longer than a query with only a single one.

**Pipelining during Write Access.** Pipelining is also applicable for write accesses. Consider \( n > 1 \) items to be added to the index by the same client and have to be added as new nodes to the binary tree representation. Then the step of determining each node’s designated parent node described in 3.2 can be executed in parallel, for it consists solely of read-only tree accesses.

When all parent nodes are determined, insertion of the new index node with possibly necessary subsequent tree re-balancing (see also 5.3) can be performed. This has to be done by the database in a pipelined instead of parallel mode in order to avoid tree inconsistencies.

If all new nodes have different designated parent nodes this is easy; a simple sequence of nodes is sent to the server, which are all added to the tree one after another. However, when the determined insert position for \( m > 1 \) of the \( n \) new nodes is the same child position of the same parent node (see Figure 2), a slight modification has to be made to the basic usage of AVL trees: A new node designated as the left child of a determined parent node is then
- either inserted exactly like that, if that place is currently not taken by another node,
- or inserted as the right child of the greatest item in the designated parent’s left subtree.

All other AVL usage steps can remain the same, including tree rebalancing. If the client now inserts all \( m \) conflicting new nodes in an ordered fashion, starting with the smallest value proceeding to the greatest, the AVL tree’s consistency will not be affected by the set of insertions.

![Figure 2: New nodes competing for the same insert position.](image)

Note that for the symmetric case, i.e., new nodes competing for being the right child of the same parent node, the above steps are simply turned to their opposites: all new nodes are sorted from greatest to smallest, and a new node is either inserted as the right child of its parent node, or, if that place is taken, as the left child of the smallest value in the parent node’s right subtree.

5 CACHING

Caching plays a big part in our set of performance-enhancing measures, which is why we devote an entire section to this topic. We distinguish between caching for read and for write access as well as between client and server caching.
5.1 Server Caching

A first naïve caching approach is to store temporary range search results on the server. For instance, consider one client having submitted a range search for all values of index \(Ix\) lying in \([a, b]\), which initiates according to 3.3 two tree traversals with the result of a pair of closest match candidates \(x\) and \(y\) for \(a\) and \(b\). This is followed by a selection of all index items whose linear list number lies between the linear list numbers of \(x\) and \(y\):

\[
\sigma_{value([a, b])}(Ix) = \sigma_{value([lx, ly])}(Ix) = rs
\]

The resulting tuple set \(rs\) could be stored on the server, in case another client issues the exact same query for index values lying in \([a, b]\). However, since storing the result sets for many search intervals \([a, b]\) might occupy too much space, a more compact caching method is preferable.

We therefore chose to cache for \([a, b]\) instead of \(rs\) a triple for each interval border value: \((E(a), lower, l_x)\) and \((E(b), upper, l_y)\), with:

- \(E(a)\) and \(E(b)\) being the encrypted border value, which is used as an identifier,
- \(lower\) and \(upper\) being the border type (also used as part of an identifier)
- \(l_x\) and \(l_y\) being the linear list value of the closest match in the current tree extension for the given interval border, \(a\) and \(b\).

When a client submits a range search request for \([a, b]\), it first encrypts \(a\) and \(b\) and sends \((E(a), lower)\) and \((E(b), upper)\) to the server, where the cache is scanned for possible hits. If one cache hit occurs or both, the according triple’s linear list number is fetched for the final selection of the range search operation. If not, tree traversal starts as described in 3.3.

A cached triple can be outdated when the index is changed, e.g., when an index item value is inserted whose value is a closer match for the triple’s encrypted interval border. In that case the triple needs to be erased from the cache. At the moment we simply erase the server cache every time the index changes, but as of now we develop a more sophisticated cache-erasing algorithm soon.

5.2 Client Caching

In order to avoid as many redundant subtree retrievals as possible, subtrees that have been retrieved during previous searches can be stored on the client for later use. The “root subtree” for instance, i.e., the highest subtree below the entire tree’s root node, is always needed, because every traversal starts there. Other cached subtrees can be useful as well if the client searches for nodes or intends to insert nodes within close distance of previous tree accesses. Note that the same kind of subtrees is retrieved for both read and write accesses.

So, after its retrieval, the subtree below the node with id \(i\) is stored on the client as a cache entry. It contains the subtree’s \(k \leq 2^h - 1\) nodes and uses its root node’s id \(i\) as an identifier. It is also useful to flag a cache entry as being the root subtree \(\tau_{root}\), such that a cache entry \(\tau_i\) is of the following structure:

\[
\tau_i = (i, \{(id_i, left_i, right_i, cData_i), \ldots, (id_{i, k}, left_{i, k}, right_{i, k}, cData_{i, k}), isRoot\})
\]

So when a subtree with root node id \(i\) is needed during tree traversal, the client first checks its cache whether it contains an entry \(\tau_i\); if it does not, a server call \(\text{getSubtree}(i)\) is submitted.

5.3 Erasing Client Caches

Erasing the cache is obviously necessary when the index has been modified such that the cached subtrees are no longer consistent with their counterparts in the index’s current extension in the database, i.e., when a new item is inserted into or deleted from the index. Without restriction to generality we consider only index insertions in the following of this subsection; nevertheless, the presented concepts apply as well to indexes that allow deletions.

Following a naïve approach, cache erasure can be done upon every index modification; whenever an item is inserted into the index, all currently connected clients are notified to erase all their cache entries. However, although it produces correct results, this is not a favorable approach, for it causes many unnecessary erasures, as will be shown in the following.

When a new item is inserted into the index, the binary tree representation of the index items’ linear order, which is implemented using an AVL tree, may need to be rebalanced. The server does this by re-traversing the new node’s traversal path back to the tree root, checking the balance of each node along the path.

In case of an imbalance, depending on its type, an appropriate rebalancing operation (“rotation”) is performed on the node (that node is referred to as the “rotation point” in the following). It changes the positions, child-parent relations and subtree heights.
of several nodes around the rotation point. At most one such rotation can occur during rebalancing, so if a rotation has occurred, the entire AVL tree is rebalanced, and the re-traversal is aborted. The balance of all nodes lying outside of the traversal path is not affected by the entire insert and rebalancing operation.

Combining the rotation on the re-traversal path with cached subtrees is best illustrated by an example. Figure 3 shows a set of cache entries identified by their respective root node id, and a traversal path of a new node inserted at the leaf level of \( \tau_{916} \). Since the traversal path crosses only \( \tau_{916}, \tau_{2824}, \) and \( \tau_{1741} \), the other three cache entries \( \tau_{1053}, \tau_{2549} \), and \( \tau_{10} \) are not affected by the insertion. Moreover, supposing \( \nu_x \)'s insertion has caused a rotation in \( \tau_{2824} \), this affects merely \( \tau_{2824} \) itself, while the other cache entries hosting the traversal path, \( \tau_{1741} \) and \( \tau_{916} \), remain unchanged.

![Figure 3: Traversal path after index item insertion, with a rotation in \( \tau_{2824} \).](image)

Hence, in theory only that cache entry in which the rebalancing operation happens needs to be erased (\( \tau_{2824} \) in our example), and all others can remain. Yet, from a practical perspective it is advisable to erase more cache entries for the following reason:

A rotation that occurs in a subtree may not change balances and heights of the nodes in the subtree’s child subtrees, but it does change the tree levels of some of those nodes. Because subtrees are retrieved with a defined height, this would render a subtree’s cached child subtrees useless, and in special cases even erroneous.

In our example, supposing a subtree height \( h = 5 \), the root nodes \( \nu_{1053} \) and \( \nu_{916} \) of \( \tau_{1053} \) and \( \tau_{916} \) are both located at tree level 11 before the rotation. After the rotation these tree levels may have changed to 10 and 12 or vice versa. Yet during all tree traversals, only subtrees with root nodes at tree level 1, 6, 11, 16 etc are requested, and \( \tau_{1053} \) and \( \tau_{916} \) would remain in the client cache as dead entries.

Hence, in our practical implementation we chose to erase the cache entry with the subtree containing the rotation point and all cache entries with that subtree’s transitive child subtrees as well, i.e., in our example, cache entries \( \tau_{2824}, \tau_{1053} \) and \( \tau_{916} \). All other subtrees, and especially all subtrees along the traversal path above the subtree containing the rotation point can remain in the cache.

6. PERFORMANCE TESTS

We benchmarked insert operations and interval searches on a publicly available database of 19,000 first and last names. The order of first and last names were randomized to avoid insert patterns with uncommon rebalance and re-caching operations.

The test environment consists of an Intel E5-2640 server with 16 GB RAM, which hosts a Wildfly 8.1 and a Postgresql 9.3 server.

A Macbook Pro i7-4850HQ running Chrome 37 32-bit accesses the server via a 30 Mbit cable connection with a roundtrip time (RTT) of approximately 25 ms. The best performance was achieved with a maximum subtree depth of four, which may vary depending on index size, RTT and bandwidth.

6.1 Bulk Insert

We benchmarked a bulk insert of 19,000 patient records with our index defined on both the first and last name attribute (First 19k US/Spanish names from https://github.com/enorvelle/Name Databases).

Caching and pipelining optimizations were applied independently. See Table 1 for the results.

<table>
<thead>
<tr>
<th></th>
<th>Single</th>
<th>Pipelined (8)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Not Cached</td>
<td>~290</td>
<td>~38</td>
</tr>
<tr>
<td>Cached</td>
<td>~230</td>
<td>~35</td>
</tr>
</tbody>
</table>

For single tuple inserts the performance mainly depends on the number of client-server roundtrips. The graph in Figure 4 illustrates that caching keeps the average roundtrips for an insert low.

Still there are at least 3 roundtrips, which make insertion of single tuples expensive. Here pipelining improves the performance for bulk insert operations. The performance improves nearly linear up to eight pipelined patient inserts. The best performance is
achieved with a combination of caching and pipelining.

![Figure 4: Average number of client-server round trips per pipelined insert. The x-axis is inserts in thousands, the blue line represents uncached, the red line cached inserts.](image)

Caching further results in much lower server load and transfers. Table 2 illustrates the improvement achieved by caching.

<table>
<thead>
<tr>
<th></th>
<th>Not Cached</th>
<th>Cached</th>
</tr>
</thead>
<tbody>
<tr>
<td>Server Calls</td>
<td>161,095</td>
<td>89,077</td>
</tr>
<tr>
<td>Transfer (MB)</td>
<td>45</td>
<td>15</td>
</tr>
</tbody>
</table>

### 6.2 Queries

Caching and pipelining have a similar effect on range queries. A prefix search on the first name attribute results in two pipelined index traversals, the lookups of two interval borders. The query times on the 19,000 unique first/last names patients, ordered and with a limit of 20 are summarized in the Single Range column of Table 3.

<table>
<thead>
<tr>
<th></th>
<th>Single Range</th>
<th>Four Ranges</th>
</tr>
</thead>
<tbody>
<tr>
<td>Not Cached</td>
<td>221</td>
<td>233</td>
</tr>
<tr>
<td>Root Cached</td>
<td>179</td>
<td>191</td>
</tr>
<tr>
<td>Two Cached</td>
<td>138</td>
<td>149</td>
</tr>
<tr>
<td>Full Cached</td>
<td>43</td>
<td>49</td>
</tr>
</tbody>
</table>

Complex queries benefit further from pipelining. Consider a query for the two prefixes “No” and “So” on both first and last names:

```sql
prefix(“No”, firstName) && prefix(“So”, lastName) || prefix(“So”, firstName) && prefix(“No”, lastName)
```

The query matches e.g. “Sophia Nordes” and “Nouzha Soldeo”.

The query contains four independent range searches. Pipelining keeps the overhead for the additional searches low, see column Four Ranges in Table 3. Again the results were ordered by first and last name and are queried with a limit of at most 20 tuples per result set.

### 7 SUMMARY

We presented an index structure enabling fast range searches on encrypted data that is used and maintained collaboratively on client and server. We further introduced multiple performance-enhancing measures for that index, including basic measures like redundancy and regular indexes on database relations as well as pipelined processing of read and write accesses, and caching strategies. We further showed the performance-enhanced index approach’s good performance on a substantial set of data.

Future development includes further performance optimizations, like a refinement for client cache erasure in order to intelligently enforce a size limit for client caches, a more sophisticated erasing strategy for server caches, and an optimization of the serialization method of subtrees being transferred to the client using Google’s protocol buffer technology. Some of our target devices, mobile and web clients, are often unreliable and connected via high latency links. For this reason classic transactions are not a good choice for all concurrency scenarios, since often used resources, like the presented index structures, are locked for a long time. Therefore we developed an optimistic transaction management model aligned with our 3-tier architecture, which will be a topic of a later publication.

Our long-term goal is to provide “Secure SQL”, an extension of the SQL language: It comprises the encrypted index operations described in this paper along with other index operations on encrypted data, while client operations would be encapsulated in extensions of database access libraries like JDBC. In Secure SQL, the creation of an index for range searches on an attribute `attr` in a relation `rel` would simply be achieved by the adapted SQL statement:

```sql
CREATE RANGE INDEX ON rel(attr);
```

### REFERENCES


