Exploring a Sub-optimal Hidden Markov Model Sampling Approach for De Novo Peptide Structure Modeling

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Abstract: Peptides have, in the recent years, become plausible candidate therapeutics. However, their structural characterization at a large scale, necessary for their identification and optimization, still remains an open \textit{in silico} challenge. We introduce a new procedure to the rapid generation of 3D models of peptides. It is based on the concept of Hidden Markov Model derived structural alphabet, a generalization of the secondary structure. Based on this concept we have previously setup an approach to the \textit{de novo} modeling of peptide structure based on a greedy algorithm. Here, we explore a new strategy that relies on the sampling of the sub-optimal sequences of states in the terms of a Hidden Markov Model derived structural alphabet. Our results suggest such procedure is able to identify the native conformation of peptides at a very low algorithmic complexity, while having a performance similar to the former greedy approach. On average peptide models approximate the experimental structure at less than 3\AA RMSD, for a processing cost of only few minutes on a workstation. As a result, peptide \textit{de novo} modeling becomes tractable at a large scale.

1 INTRODUCTION

The recent years have seen a regain of interest in peptides as candidate therapeutics, some of the bottlenecks for the use of peptides as drugs or protein-protein interaction probes being overcome (Vlieghe et al., 2010). However, the assistance of \textit{in silico} approaches for the discovery of new peptides can still largely be improved. Focusing on the structural characterization of peptides, the number of genomes fully sequenced, and experimental efforts to identify natural peptides - bacterial peptides (Hobbs et al., 2011), venom peptides (Vetter et al., 2011), peptides of the central nervous system (Malavolta and Cabral, 2011), to cite some - make available a large amount of information about candidate peptides. The rate of determination of peptide structure by Nuclear Magnetic Resonance (NMR) spectroscopy or X-ray crystallography remains however low.

Unlike proteins, peptides are known to be more flexible, not always adopting a stable tri-dimensional structure (Gellman and Woolfson, 2002), which makes homology modeling techniques more challenging to use, compared to proteins. This is why methods have been developed for the \textit{de novo} or \textit{ab initio} peptide structure prediction. Among these, PEPstr (Kaur et al., 2007), PepLook (Thomas et al., 2009), I-TASSER (Zhang, 2008) Rosetta (Rohl et al., 2004) or PEP-FOLD (Maupetit et al., 2010). These approaches rely on different strategies. PEPstr uses the secondary structure predicted by PSIPRED (Jones, 1999) combined with a $\beta$-turn predictor to predict conformations that are then refined by energy minimization. I-TASSER relies on Lomets (Wu and Zhang, 2007), a meta-threading approach, to identify template fragments from a collection of experimentally determined structures. The most representative fragments are extracted and used for the assembly of the complete peptide structure considering only the alpha carbons and side chain centroids. A Monte Carlo procedure is then applied to refine the final structure. The structures generated are clusterized (Zhang and Skolnick, 2004) and a second pass is made considering fragments taken from the cluster centroids. The all-atom models are finally generated (Li and Zhang, 2009) and are sorted according to the C-score, an intrinsic measure of the quality of the structures. PepLook uses a Boltzmann-Stochastic based algorithm (Thomas et al., 2006), that generates structures by randomly selecting couples of $\phi/\psi$ angles taken from canonical local conformations (Etchebest et al., 2005) to cover the complete pep-
tide. The probabilities of each couple of angles are then iteratively modified depending on the energy of the conformation generated, and cycles of conformation generation - 10^4 conformations per step, energy scoring - using the AMBER-95 force-field (Lins et al., 2006), and probability refinement are performed until convergence. PEP-FOLD is also based on the prediction of the local conformation from an amino acid sequence. Unlike PepLook, the assembly is performed using a greedy algorithm to grow amino acid by amino acid the structure of the complete peptide, using the sOPEP coarse grained force-field (Maupetit et al., 2007) to drive the assembly. The conformations generated are then refined using a Monte Carlo procedure, then clustered and sorted according to sOPEP. On average, these methods have shown efficient. For instance PEP-FOLD, one of the most efficient approach so far, is able to approximate the experimental structure at a RMSD of only 2.8 Å for peptides of size between 9 and 25 amino acids.

So far however, none of these approach is able to cope with the large scale processing of millions of sequences, which is the estimated order of magnitude of the number of venom peptides (Escoubas and King, 2009), or bacterial peptides (Warren et al., 2010). Here, we introduce an improved version of PEP-FOLD, that takes advantage of using the prediction of the local conformations within the Hidden Markov Model framework to efficiently select low energy conformations. This approach reduces the conformational sampling by several orders of magnitude, which result in high speed peptide de novo prediction, not affecting the performance of the approach, and thus offering new perspectives for large scale peptide structure prediction.

2 MATERIALS AND METHODS

2.1 Data Set

To evaluate the accuracy of the algorithms, we have used the PepStr data set used in our previous studies (Maupetit et al., 2009). The PepStr set, originally introduced by Kaur and co-workers (Kaur et al., 2007), consists in 15 peptides of size between 9 and 22 amino acids. Note that PepFold performance has already been assessed on larger sets (Maupetit et al., 2010) (Thévenet et al., 2012). Here, since we are interested in assessing how the new procedure we explore impacts the quality of the models returned, this limited but representative set was found sufficient. The peptides contain only natural amino acids, are linear - do not contain any disulfide bond, and are known to be monomeric in aqueous solution.

2.2 Structural Alphabet

PEP-FOLD relies on the concept of Structural alphabet (SA). SA can be assimilated to a generalization of the secondary structure, with a larger number of canonical conformations (SA states, or letters). Here, we have used a Hidden Markov Model derived Structural Alphabet (HMM-SA) (Camproux et al., 2004). In this model, a protein - or peptide, is considered as a series of fragments of 4 residues overlapping by 3 residues. Hence, a protein of L amino acids, corresponds to a series of L – 3 fragments. The fragments are associated with 4 geometrical descriptors, namely the three distances between the non consecutive alpha carbons of the fragment, and the triple-product defining the signed volume of the fragment. The parameters of the HMM model are the mean values of the descriptors of each state and their co-variance and the transition matrix associated with the first order Markovian process. For the present study, we have used a 27 letter SA we have found to correspond to a statistical optimum.

Given the model and the descriptors associated with a conformation of a protein of size L, it is possible to identify the series of the L – 3 SA letters that optimally describe the conformation using the Viterbi algorithm (Viterbi, 1967). It is also possible to identify the probability that each letter emits each of the 4 amino acid fragment of the protein using the forward-backward algorithm (Rabiner, 1989).

2.3 3D Model Generation from Sequence

A flowchart of the complete model generation procedure is depicted Figure 1. It consists in three steps. The first is the prediction of a SA profile from the amino acid sequence. The SA profile describes for each of the L – 3 fragments of 4 amino acids in the sequence, the probability that it is associated with each of the 27 SA letter. In a second step, the SA profile can be processed to select, for each position in the sequence, a limited number of SA letters. Since each SA letter is associated with a limited number of protein fragments depending on its conformational variability, this corresponds to a fragment selection step. In this study, we use two different selection strategies. Finally, the fragments associated with the selected SA letters are assembled to produce full structure models. We describe more in detail each step in the following sections.
2.3.1 Structural Alphabet Prediction from Sequence

The estimation of the probabilities of the states from the amino acid sequence is a prediction problem. Given an amino acid sequence, we have trained a SVM to predict the probabilities of each state given a sequence of 4 amino acids enlarged by two amino acids each side (Maupetit et al., 2010), i.e., using a window of 8 amino acids centered on the 4 amino acids of interest. In practice, the SVM takes as input a matrix of $20 \times 8$ values, where each series of 20 values corresponds to the probabilities of the 20 amino acids at the corresponding positions, obtained using PSI blast (Altschul et al., 1997) against the Uniprot collection filtered at 90% sequence identity (Suzek et al., 2007). We perform the prediction for each fragment of 4 amino acids of the sequence, in turn. The output of the prediction is thus, given a sequence of size $L$ amino acids, a profile of dimension $L - 3 \times 27$.

2.3.2 Fragment Assembly to Generate a Full Structure Model

We do not use a continuous space to generate the 3D models. Each SA state is associated with a limited number of representative fragments - or prototypes - that have been chosen to sample the conformational variability of the letter. The number of prototypes associated with the letters depends on their conformational variability. In practice, we limit this number to a maximum of three except for one letter particularly fuzzy for which we allow up to eight prototypes.

The selection of the SA letters considered at each position - see next section - and their prototypes defines a finite ensemble of conformations of the complete peptide. The size of this space can be measured in terms of complexity. According to the convention set by Park and Levitt (Park and Levitt, 1995), the complexity - the average number of states per residue - for a peptide of size $L$, i.e., consisting of $L - 3$ fragments of 4 residue length, can be expressed as:

$$\sqrt[4]{\prod_{i=1}^{L-3} n_i},$$

with $n_i$ the possible conformations at each position $i$.

Despite we use a limited number of prototypes for each fragment, and despite we prune the number of SA letters using a fragment selection strategy, the combinatorial to sample is yet too large to be sampled using brute force strategy. We use the stochastic greedy approach considered in our previous studies (Tuffery et al., 2005). We use a rigid assembly procedure in which the three first alpha carbon of the next fragment are superimposed onto the last three of the previous one using a best fit RMSD procedure - see (Tuffery et al., 2005). Given a set of conformations generated for fragments of size $L - 3 - x - 1$ amino acids, where $L - 3$ stands for the $L - 3$ letters necessary to describe the conformation of the $L$ amino acids of the peptide, the procedure generates all the conformations of size $L - 3 - x$ by adding all the prototypes of the SA letters accepted to grow the peptide by one amino acid. Since this number can be large, we limit the number of conformations to a maximal number - heap size - of conformations that correspond to a combination of the best scored conformations and conformations randomly selected using the Metropolis criterion. Since the approach has some stochastic aspects, we perform series of runs.

2.3.3 Fragment Selection Strategies

**Best Ranked SA Letters (8BR).** In our previous studies, we have considered the assembly of the fragments associated with the eight best ranked SA letters, based on the predicted probabilities. Based on this selection, we have performed series of one hundred runs per peptide (see previous section). This approach has shown successful to the de novo prediction of the structure of peptide of size up to 25 amino acids (Maupetit et al., 2010).
Sampling the Sub-optimal Sequences of State (S4).

Another selection strategy can be specified using HMM formalism. Given the prior observations of the sequence, one can derive the probabilities that each letter is associated with each fragment along the peptide sequence (see upper), independently. Such probabilities can be assimilated to the initial laws of the HMM model, and can be used to infer the most probable series of letters associated with the amino acid sequence using the Viterbi algorithm or the Forward-Backward algorithm to select the most probable state at each position. Unfortunately, the uncertainty and error associated with the prediction from the amino acid sequence make unlikely that the optimal series of letters derived using either the Viterbi or the Forward-Backward algorithm can describe the native conformation (see (Maupetit et al., 2010)). Ways to explore sub-optimal sequences of states are thus desirable. The generalized Viterbi algorithm (Foreman, 1992) that precisely determines the k best sequences of states is confronted to the limit of a possibly very large number of sequences to explore to reach the native conformation, most of them being associated with small conformational changes, making its computational cost prohibitive and not efficient. For this reason, we have chosen to explore an alternative procedure using a Sampling of the Sub-optimal Sequences of States (S4 procedure). We note $S_{\text{opt}}$ and $S_{\text{subopt}}$ the optimal sequence and the sub optimal sequences of states, respectively. These are identified using in a iterated manner the Viterbi algorithm starting from the initial laws $P_{1:L-3}$ using the following procedure:

\begin{verbatim}
input initial laws $P_{1:L-3}$
identify $S_{\text{opt}}_{1:L-3}$ (Viterbi)
for a suboptimal sequences do:
randomly select position $k$ in sequence
randomly select state $s$ not already present in a previous sequence of states
set $P[k][x]=$ 0, then $P[k][s]=$ 1.
identify $S_{\text{subopt}}_{1:L-3}$ (Viterbi)
restore $P[k]$ to its initial values
enddo
\end{verbatim}

We have found such procedure allows a fast sampling of the sub-optimal conformations, while ensuring a diversity of the conformational sampling. For each sequence of states, we then apply the greedy algorithm. Since only one state is accepted at each position, the complexity of the search is reduced to the use of the prototypes of the letters. In the present study, we have considered up to 400 sub-optimal sequences of states.

2.3.4 Force Field

To drive the generation of the model during the assembly, we use the sOPEP force field (Maupetit et al., 2007). sOPEP is a coarse grained force field that allows a fast, yet accurate evaluation of the energies. It has been adapted from the OPEP3.2 force field designed for molecular dynamics in cartesian coordinates. Like OPEP, sOPEP makes use of a six bead representation per residue. Five are for the backbone - one for each atom of the backbone but the alpha carbon hydrogen, and one for the side chain. sOPEP specific terms are related to side chain-side chain interactions. Since PEP-FOLD is based on the rigid assembly of a limited number of prototype fragments sampling the conformational variability of each SA letter, the OPEP formulation using a 6-12 potential was found too sharp and has been adapted (see (Maupetit et al., 2007)). sOPEP has been optimized for soluble peptides, at pH 7 and for the 20 standards amino acids. Ions are presently not considered.

2.3.5 Clustering

To clusterize the ensembles of models generated we use a procedure using the TMscore to score the similarity, similarly to our previous work (Maupetit et al., 2010). The clusters are sorted by increasing energy according to sOPEP. The centroid of the cluster is the conformation associated with the lowest energy.

2.4 PepStr and PepLook Models

Results presented for PepStr (Kaur et al., 2007) and PepLook (Thomas et al., 2009) are based on the models returned by the servers available at http://www.imtech.res.in/raghava/pepstr/ and http://peplook.gembloux.ulg.ac.be/, respectively. Note that the PepStr and PepLook server identify only one best preferred conformation.

3 RESULTS AND DISCUSSION

We first discuss the ability of the S4 approach to identify native like conformations. Table 1 reports the results obtained for the peptides of the PepStr set. The BestEne5 section reports the results reached when considering the cluster of lowest energy for each series of runs, i.e. corresponding to the solution of lowest energy. These values can be compared with those obtained using PepStr of PepLook. The BestRMSD5 section reports the best results that could be reached considering the five clusters of lowest energy, i.e. the
Table 1: Results obtained with the S4 procedure for the peptides of the PepStr set. L: peptide size (amino acids), C\textsubscript{S}: complexity of the assembly using the S4 procedure, C\textsubscript{S4}: complexity of the assembly using the S4 procedure (average number of conformations per position), \(\mu\) and \(\sigma\) correspond to the mean and standard deviation of the RMSD (full structure) to the experimental conformation over 4 series of 100 runs. \(\Delta\) denotes if the RMSD is smaller (-) or greater (+) compared to the results obtained with the 8BR procedure. Number in parentheses correspond to the values obtained using the 8BR procedure, taken from (Maupetit et al., 2010). BestEn5 results are related to the conformation of lowest energy. BestRMSD5 results are related to the centroid of the 5 best clusters approximating at best the experimental conformation. PepStr and PepLook: RMSD to the experimental conformation of the models returned by the servers.

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<th>RMSD (\sigma)</th>
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<th>BestEn5 (\sigma)</th>
<th>(\Delta)</th>
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Looking at the efficiency of the two strategies, it is striking that the S4 performance is reached considering a very low number of sub-optimal sequences of states. Indeed, the part of the conformational space sampled by the S4 procedure is several order of magnitudes smaller than that sampled by the best ranks procedure. As shown Table 1, the gain in terms of complexity is important, the difference being close to 13 on average. Note that the values of the complexity can be misleading since for instance considering 3 conformation at each position results, for a peptide of twenty amino acids in a complexity of 2.5. It also depends on the size. The corresponding number for 100 amino acids would be of 2.9. However, on average, for a peptide of size 20 amino acids, the difference in complexity results in decreasing the number of conformations sampled during the assembly process from over 6 \(10^{19}\) down to only 5.4 \(10^{4}\), i.e. a gain of 15 orders of magnitude. Considering why such dramatic decrease in the conformational sampling can still lead to the effective identification of native conformations, it seems obvious it necessarily implies that the initial laws resulting from the SVM prediction are already biased towards the correct local conformations of the fragments along the complete sequence. It appears sufficient to efficiently sample the low conformations of low energy resulting form the SVM prediction. However, the efficiency of the modeling also relies on the effectiveness of the force field. Actually,
as illustrated in Figure 2, the S4 procedure does not solve the poor modeling obtained for the 2bta target using the best ranks approach. Indeed, for this target, the SVM prediction makes likely non helical conformations that are not identified. The same behavior is observed for 1du1 (not shown). Accepting the current limits of the coarse grained force field it remains the S4 procedure appears much more efficient than the 8BR strategy.

An important outcome of S4 is in terms of computational cost. As illustrated in Figure 3, the execution times to generate the models of peptides up to 20 amino acids are of only a few seconds per simulation, compared to several minutes using the 8 best ranks strategy. On average, execution times are on the order of 10 times faster using S4, and close to 14 seconds for a peptide of 20 amino acids. On the opposite to the best ranks approach, it is also noteworthy that the S4 procedure can be easily paralleled, since it consists in series of independent simulations. This makes the simulation of peptide conformation given the SA prediction profile easily tractable on a desktop machine. For instance using a 8 cores machines, a series of 100 simulations for the modeling of a peptide of 20 amino acids would require on the order of only 3 minutes. This clearly opens the door to the large scale de novo modeling of peptides since the complete processing from sequence can be as low as five minutes. On a medium size computational resource of 400 cores, it would become possible to process as many as 24 000 peptide sequence of 20 amino acids per day, and 2 400 000 in 100 days. Such order of magnitude is compatible with estimates of the number of candidate peptides in the complete set of prokaryotic genomes (Kastenmayer et al., 2006).

4 CONCLUSIONS

In the present study, we have explored a new procedure for the de novo modeling of peptide structure. It is based on the sampling of the sub optimal sequence of states using a Hidden Markov Model. Using a test set of 15 peptides of size between 9 and 20 amino acids, our results show that it is able to identify the native conformation of the peptides at a success rate comparable to a much more resource consuming procedure previously benchmarked. The complexity of this procedure is much lower, and it requires the generation of as few as only one hundred models, which makes possible the de novo generation of models in only a few minutes on a desktop computer. Having addressed an important issue in terms of our ability to model large quantities of peptide structure, we still remain confronted with other limits of the de novo prediction of structures, such as the effectiveness of the force field, or the exactness of the prediction of the lo-
cal structure underlying the approach. It remains that such procedure now makes tractable the processing of peptide sequence at a scale compatible with the outcome of the complete genome sequencing projects, which should open new opportunities in terms of the discovery of bioactive peptides.

REFERENCES


