Keywords: Protein coevolution, Multiple sequence alignments, Mutual information.

Abstract: Protein coevolution has emerged as an important research topic. Several methods and scoring systems were developed to quantify coevolution, though the quality of the results usually depends on the completeness of the biological data. To simplify the computation of coevolution indicators from the data, we have implemented a fully integrated and automated workflow which enables efficient analysis of protein coevolution, using the Python scripting language. Pycoevol automates access to remote or local databases and third-party applications, including also data processing functions. For a given protein complex under study, Pycoevol retrieves and processes all the information needed to undergo the analysis, namely homologous sequence search, multiple sequence alignment computation and coevolution analysis, using a Mutual Information indicator. In addition, friendly output results are created, namely histograms and heatmaps of inter-protein mutual information scores, as well as lists of significant coevolving residue pairs. An illustrative example is presented. Pycoevol is platform independent, and is available under the general public license from http://code.google.com/p/pycoevol.

1 INTRODUCTION

Protein coevolution has emerged as an important research topic, being applied successfully to predict the structure of RNA (Freyhult et al., 2005) and proteins (Yeang and Haussler, 2007); to predict intermolecular interactions (Pazos et al., 1997); to identify functionally important regions of molecules (Saraf et al., 2003); and to identify energetic pathways through molecules (Süel et al., 2003). Overall, protein coevolution corresponds to the accumulation of structural/functional changes through evolutionary lineages, which are compensated by changes in other regions of the same protein or in another protein (Pazos and Valencia, 2008). Since many proteins have evolved performing mutual interactions and consequently forming specific molecular complexes (Pazos and Valencia, 2008), inter-protein coevolution corresponds to mutual evolutionary constraints imposed by each protein on the other partner and accordingly, protein sequences must reflect this evolutionary process (Pazos et al., 1997).

Coevolving residues are detected in a three-step process: 1) search for homologue sequences; 2) computation of a multiple sequence alignment (MSA) for each protein; 3) calculation of a coevolution score for each pair of sites in the MSAs. The first step involves the selection of orthologues and the matching of the correct protein pairs along organism lineages. One approach can be a PSI-BLAST search (Altschul et al., 1997), which is a reliable source for distant relatives and favours orthologues over paralogues, reducing one source of errors. The second step involves the computation of MSAs for each protein. The MSA is a rich source of sequence-function relationships and attempts to represent the evolutionary relations between the homologous sequences by aligning them under the assumption that mutations are independent. Although the MSA relies in computationally complex algorithms (Elias, 2006), considering the number and the variability of a set of homologous sequences, supplemented with the assumed independence of mutations, this often leads to poor alignments, and becomes an important problem for identifying coevolution. Finally, a coevolution score is calculated for each pair of sites in the MSAs.

Coevolution analysis depends on the completeness of the biological data and, given the complexity of MSA computations, sometimes made worse by insufficient evolutionary divergence and
the presence of too many indels (gaps), a large number of methods and scoring functions have been proposed in the literature to estimate protein coevolution, including phylogenetic independent and phylogenetic dependent methods (see (Halperin et al., 2006) and (Caporaso et al., 2008) for extended reviews). It is likely that different applications would require different methods and it can be difficult to choose from them, as they exhibit subtle yet significant differences. Unfortunately, there isn’t any survey or benchmark assessing the accuracy of each approach.

Mutual Information (MI) (Martin et al., 2005) is a standard measure to identify sites of correlated and compensatory mutations in a set of homologous sequences and can be used to identify correlated positions between two interacting proteins. MI is a measure based on Information Theory, which quantifies the mutual dependence between two random variables, and is a “tree-ignorant” method (Caporaso et al., 2008), since it does not account for likelihoods or shared ancestral correlations. In a MSA, the MI between two columns (positions) reflects the extent to which the existence of one specific amino acid residue at one position allows us to predict the identity of the residue at the other position. MI scores are high if substitutions at the two positions show positive correlation.

Since protein-protein coevolution analysis involves the execution of the specified steps, and for each step there is a multitude of options, we have implemented a fully integrated and automated workflow which combines these steps and enables efficient analysis of coevolution among proteins, using the Python scripting language. Pycoevol aims at automating the computation of coevolution indicators, speeding up data-mining and improving the accuracy of the results. Pycoevol automates access to remote or local databases and third-party applications and includes data processing functions, thus enabling a flexible use of the workflow.

As a proof-of-concept we present the complete analysis of coevolution in a protein complex formed by transforming growth factor beta 3 (TGF-β3) and extracellular domain of TGF-β receptor type II (TGF-β receptor) (Hart et al., 2002). TGF-β3 is a protein that controls cellular proliferation and differentiation by signalling through kinase receptors, namely serine/threonine receptors as TGF-β receptor. The execution of the Pycoevol workflow pinpointed several coevolving pairs of residues. Most residues identified were at the surface of the protein complex, and 13% of them were located at the complex interface. This example further illustrates how computing inter-protein coevolution can improve the accuracy of constrained docking algorithms (e.g. BiGGGER (Palma et al., 2000)) assisting the demanding task of protein docking.

2 METHODS

As described in the previous section, protein coevolution analysis involves the execution of a series of steps, and for each step there is a multitude of options. To congregate these steps in a system which enables an efficient analysis of protein coevolution, we developed a Python workflow consisting of a set of scripts, which includes connectors to local or remote databases, enabling also the execution of third party applications through the command line, for both PSI-Blast search and computation of MSAs. Furthermore, we have used the Biopython module (Cock et al., 2009), for general manipulation of biological data.

The analysis starts with the input of Protein Data Bank accession numbers (PDB ID), for each protein partner. Alternatively, accession numbers for NCBI reference sequence identifiers (GI) or UniProt primary (citable) accession number can be also used, as in the case of proteins without available 3D structures. For each protein a collection of orthologous sequences is searched. This is done by a PSI-BLAST search (Altschul et al., 1997) against NCBI Reference Proteins database. The reason for using PSI-BLAST instead of a simple BLAST search is that we need to start with a large number of orthologous sequences and PSI-BLAST allows us to find more distant relatives. PSI-blast uses the default configuration, but alternative configurations can be also specified. Protein sequences of both partners are then matched by comparing the source organisms for each sequence. The assumption is that, if the proteins are homologous and interact in one organism, they should also interact in the other organisms. This is a crucial step because proteins will only coevolve within the same lineage, and without matching the correct organisms the data obtained would be meaningless. A refined set of sequences for each interacting partner is obtained and three different MSAs are computed, using ClustalW (Chenna et al., 2003) and Muscle (Edgar, 2004) in the default configuration, and Mafft (Katoh et al., 2002) with linsi (L-INS-i), the most accurate configuration. In order to compare the performance of the MSAs computed, we develop two scores: SP score, which scores each MSA (GOP 4.0, GEP 1.0
and the BLOSUM62 scoring matrix (Henikoff and
Henikoff, 1992)); and a column score (CS), which
compares the MSAs column by column. These
scoring systems are implemented in Python and are
based on the ones developed for BaliBASE
(Thompson et al., 1999). Instead of comparing the
SP scores against a reference MSA, as in the case of
BaliBASE approach, our implementation compares
the scores obtained for each MSA computed with
different MSA programs. For the MSAs
excluded surfaces of molecules, using the MSMS
program (Sanner et al., 1996). In any case, for each
residue at the interface of the other protein. We
implemented a measure of solvent accessible surface area
(ASA) based on the surface calculations
implemented in Hollow (Ho and Gruswitz, 2008).
Alternatively, we implemented a measure of solvent
residues on the core of the protein are not
susceptible to perform or sense the influence of
residues in the MSAs gives a matrix of scores and, to improve the
estimation of MI (1) for all pairs of columns between two
MSAs, by Mutual Information (MI), which is
defined as follows (Martin et al., 2005):

\[
MI(X,Y) = H(X) + H(Y) - H(X,Y)
\] (1)

The estimation is done summing the entropies H(X)
and H(Y), corresponding to amino acid frequencies
for each residue belonging to the columns in
analysis, minus the joint entropy H(X,Y) for that
pair of columns. The higher the estimation is, the
higher the indication that compensatory mutations
arose that mitigated the deleterious effects of
mutations interfering with the stability of the
interaction between that specific pair of residues.
Estimation of MI (1) for all pairs of columns in both
MSAs gives a matrix of scores and, to improve the
detection of significant positions, the analysis is
constrained to include only the residues belonging to
the surface of the proteins. The assumption is that
residues on the core of the protein are not
susceptible to perform or sense the influence of
residues at the interface of the other protein. We
implemented a measure of accessible surface area
(ASA) based on the surface calculations
implemented in Hollow (Ho and Gruswitz, 2008).
Alternatively, we implemented a measure of solvent
excluded surfaces of molecules, using the MSMS
program (Sanner et al., 1996). In any case, for each
position in the MSAs there are a multitude of
contacts and the results of this estimations show that
for each residue in one protein the possible mutual
propensity contacts between positions are usually
variable.

For each complex, the map of potential interactions is calculated using a MI calculator, and
friendly output results are created, namely histograms and heatmaps of inter-protein mutual
information scores, as well as lists of significant coevolving residue pairs. From the collection of MI
scores (surface positions), only the best 20% scores are selected as significant coevolving residues, and
are prone to further analysis.

3 RESULTS AND DISCUSSION

Pycoevol detects inter-protein coevolution, being
therefore suitable to the study of protein complexes.
Furthermore, this workflow is optimized to predict
intermolecular interactions and to constraint the
search space in protein docking. It can be also used
to complement studies concerning the identification
of functionally and structurally important regions of
molecules as well as to predict the structure of
proteins. It offers an easy implementation of the
protein-protein coevolution analysis workflow
(Figure 1), which congregates several tools and
tasks, enabling the researcher to focus on biological
problems, rather than repetitive execution or
implementation of self-made codes. Only if special
tools or specific tasks are needed, the user may need
to edit or complement the Pycoevol source code. For
the general user, Pycoevol runs like any other
application or any other python script, called from
the command line. The simplest usage is to type
python pycoevol.py at the prompt of the operating
system’s command line and select from the available
options. The execution of the workflow takes from
minutes to hours, depending on the extension of the
data being processed. To analyse the traces of
coevolution between the proteins in the complex, the
user only have to specify the accession numbers of
the protein sequences. After PSI-BLAST search,
MSA computation and coevolution analysis, easy
readable output results are generated.

As we noticed before, several methods and
scoring systems were developed to detect traces of
coevolution, though the quality of the results also
depends on the quality of the source data.
Accordingly, the detection of inter-protein
coevolution relies on two main aspects. One is the
computation of coevolution indicators and, to
improve our application, we plan to include other
coevolution indicators as well as normalizations, increasing therefore the sensibility and allowing the cross-validation of the most significant results.

Figure 1: Main steps implemented in the Pycoevol workflow.

The other important factor is the quality of the data and MSA being processed, so we plan to include other MSA programs and a refining tool that accounts for the dependence of mutations, thus improving the quality of the MSAs. Beyond the advantages to the user, these improvements will eventually let us perform a survey assessing the accuracy of some coevolution indicators, as well as evaluate which MSA program may favour the detection of coevolution for the specific test case under study, accounting on the principle that an MSA with high SP score is better suited to MI analysis. This can be misleading, since the MSA algorithm can misplace coevolving sites in the alignment, while attempting to maximize a scoring function (as the SP score).

Pycoevol was tested on the protein complex TGF-β3/TGF-β receptor. Figure 2A shows a histogram of MI score frequencies computed for all the pairs of positions on the MSAs computed for each protein. In this case, coevolution results were processed using MSAs computed by Mafft, as they scored best. Along with histograms, heatmaps were also generated (Figure 2B and 2C). These give a general view on the relative positions of highly scoring residues belonging to each protein. By selecting only the highest MI scores, the heatmap gives a clearer view on the positions of those residues. The structural analysis of the protein complex shows the location of interface residues for both protein partners (Figure 2D). Most residues presenting higher MI scores were located at the surface (Figure 2E bottom), and 13% of them (3 out of 23) were located at the interface (Figure 2E top). The interacting map obtained for the TGF-β3/TGF-β receptor complex (Figure 2F), i.e. the network of pairings relatives to the highest scoring positions, shows that TGF-β3 has 2 residues on the interface (2 out of 8) and TGF-β receptor has 1 residue on the interface (1 out of 15). This finding is very interesting; given the complexity of protein-protein docking, finding even only one positive interface contact can help constraint the search space and improve the accuracy of constrained docking algorithms.

To test the application of our coevolution measure-
Figure 2: Protein coevolution analysis of complex TGF-β3/TGF-β receptor with mutual information. Every pair of positions on the MSAs was examined for coevolution using an analysis of MI. (A) Histogram of inter-protein mutual information scores. (B) The matrix of scores for each pair of positions in the alignment is plotted as a heatmap, according to the colour legend shown. (C) The matrix of scores for positions with highest MI scores (greater than 80% of the best MI score) is plotted as a heatmap. (D) Illustration of complex TGF-β3/TGF-β receptor (PDB ID 1KTZ) showing interface residues of TGF-β3 as blue spheres (top) and interface residues of TGF-β receptor as red spheres (bottom). (E) Illustration of coevolving residues of TGF-β3 (blue spheres) and TGF-β receptor (red spheres), located at the interface (top). Previous representation with remaining coevolving residues of TGF-β3 (light blue spheres) and TGF-β receptor (orange spheres), located at the surface (bottom). (F) Network of the pairings identified by MI, using the same colour scheme as in the previous panel (E).

ments on protein docking, we employed the coevolving residues identified on the complex TGF-β3/TGF-β receptor, as constraints in BiGGER. This is a difficult complex to model because of the low contact surface. Using unbound structures of both TGF-β3 and TGF-β receptor (PDB structures 1TGK and 1MZ9, respectively), to simulate a real-life application, BiGGER could not retain, within the 5000 highest scoring surface contacts, any model that placed the TGF-β receptor at the correct position (Figure 3A). This was no longer the case when constraining the docking simulation using coevolution data. From TGF-β3 we considered 8 residues with higher MI score, in our coevolution criteria, two of which were truly at the interface. From TGF-β receptor there were 15 residues that fulfilled our selection criteria, with only one at the interface. One approach was to use both sets of residues, but imposing the constraint that there must be at least one contact between the 8 residues of one partner and the 15 of the other. Contact was defined as having the alpha Carbons at most 7Å apart. Panel B of Figure 3 shows one model obtained as a result, with TGF-β receptor placed at the correct point relative to TGF-β3, though not quite at the right orientation. This experiment shows that even without being able to identify exactly which are the correct contacts, the constraint requiring any one contact, at least, reduces the search space enough so that correct models are not lost during the filtering stage of docking. In Figure 3C we show one model obtained by forcing the specific contact between an interface residue of TGF-β3 (A93) and one interface residue of TGF-β receptor (R52). Since both residues are at the interface, all models are approximately at the right position. The interesting aspect of this experiment is that, with this constraint, the search space is so reduced that a docking takes less than five minutes, as opposed to nearly two hours for an unconstrained docking run. This means that it is feasible to test, individually, all potential residue contacts given by the coevolution measure-
Figure 3: Summary of the docking results. (A) Correct structure of the complex TGF-β3/TGF-β receptor (PDB ID 1TGK and 1M9Z, respectively), surrounded by spheres representing the geometric centre of TGF-β receptor (red), where it was predicted in the 5000 models generated in the docking run. No model was found that places TGF-β receptor at the right position. (B) One of the models obtained by requiring an unspecified contact between the two groups of 8 and 15 candidate interface residues. In both cases, the resulting model was not very accurate, given the incorrect orientation of TGF-β receptor (red), but even so this was a significant improvement over the unconstrained docking in the modelling of this complex. (C) One of the models obtained by restricting the distance between residue A93 of TGF-β3 (blue) and residue R52 of TGF-β receptor (red), which run took less than five minutes.

4 CONCLUSIONS

Pycoevol source code (version 1.0) will be made freely available for downloaded from http://code.google.com/p/pycoevol.

Additional information on the third-party dependencies, as well as how to install and run the program can be check at the same location. The workflow is fully written in Python 2.7, platform independent, and is available under the general public license. User requests and contributions may be implemented and included in future versions of the software.

Pycoevol is a fully integrated and automated system which enables efficient analysis of coevolution among proteins. In order to improve the workflow and its capabilities, we plan to include other coevolution indicators as well as normalizations. Alongside, the inclusion of new MSA programs and a refining tool is also planned. The integration with molecular viewers, such as RasMol (Bernstein, 2000) and UCSF-Chimera (Pettersen et al., 2004), which allows the automatic selection and display of the coevolving residues, will enable further analysis and usage possibilities.

Finally, the natural extension of the Pycoevol workflow aims at include also protein docking and consequently, Pycoevol will be included and integrated in the Open Chmera Library (Krippahl, 2011), an open source library, which includes among several features, BiGGER, the constrained docking algorithm. This system will become a useful tool to study protein coevolution and interaction, and will hopefully be the basis for several studies concerning protein interactions.

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