

ADDRESSING THE HARDWARE RESOURCE REQUIREMENTS OF NETWORK-ON-CHIP BASED NEURAL ARCHITECTURES

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Abstract: Network on Chip (NoC) based Spiking Neural Network (SNN) hardware architectures have been proposed as embedded computing systems for data/pattern classification and control applications. As the NoC communication infrastructure is fully reconfigurable, scaling of these systems requires large amounts of distributed on-chip memory for storage of the SNN synaptic connectivity (topology) information. This large memory requirement poses a serious bottleneck for compact embedded hardware SNN implementations. The goal of this work is to reduce the topology memory requirement of embedded hardware SNNs by exploring the combination of fixed and configurable interconnect through the use of fixed sized clusters of neurons and NoC communication infrastructure. This paper proposes a novel two-layered SNN structure as a neural computing element within each neural tile. This architectural arrangement reduces the SNN topology memory requirement by 50%, compared to a non-clustered (single neuron per neural tile) SNN implementation. The paper also proposes sharing of the SNN topology memory between neural cluster outputs within each neural tile, for utilising the on-chip memory efficiently. The paper presents hardware resource requirements of the proposed architecture by mapping SNN topologies with random and irregular connectivity patterns (typical of practical SNNs). The architectural scheme of sharing the SNN topology memory between neural cluster outputs, results in efficient utilisation of the SNN topology memory and helps accommodate larger SNN applications on the proposed architecture. Results illustrate up to a 66% reduction in the required silicon area of the proposed clustered neural tile SNN architecture using shared topology memory compared to the non-clustered, non-shared memory architecture.

1 INTRODUCTION

Biologically-inspired computing paradigms such as evolutionary computing and neural networks provide promising solutions for designing complex and intelligent embedded systems (Marrow, 2000). The organic central nervous system includes a dense and complex interconnection of neurons and synapses, where each neuron connects to thousands of other neurons through synaptic connections. Computing systems based on Spiking Neural Networks (SNNs) emulate real biological neural networks, conveying information through the communication of short transient pulses (spikes) between neurons via their synaptic connections. Each neuron maintains a

membrane potential, which is a function of incoming spikes, synaptic weights, membrane potential, and membrane potential leakage coefficient (Maass, 1997); (Gerstner and Kistler, 2002). A neuron fires (emits a spike to all connected synapses/neurons) when its membrane potential exceeds the neuron's firing threshold value. Brain-inspired computing paradigms such as SNNs offer the potential for elegant, low-power and scalable methods of embedded computing, with rich non-linear dynamics, ideally suited to applications including data/pattern classification, dynamic control and signal processing. The efficient implementation of SNN-based hardware architectures for real-time embedded systems is primarily influenced by neuron design, scalable on-chip interconnect architecture,

and SNN training/learning algorithms (Maguire et al., 2007).

The authors have proposed and investigated EMBRACE as an embedded computing element for implementation of large scale SNNs (Jim Harkin et al., 2009). The proposed EMBRACE mixed-signal architecture incorporates compact, low power, high-resolution CMOS-compatible analogue neuron cells, interconnected using a packet switched Network on Chip (NoC) architecture.

Directly connecting neuron circuits within large scale hardware SNN is not viable in VLSI architectures because of high fan-out and interconnection requirements. The NoC approach exploited within EMBRACE provides flexible, packet-switched inter-neuron communication channels, scalable interconnect and connection reconfigurability (Benini and De Micheli, 2002); (Vainbrand and Ginosar, 2010); (F. Morgan et al., 2009).

For hardware SNN implementations, the SNN topology information includes neural circuit connectivity data for each synapse in the system. Scaling of NoC-based hardware SNN systems requires large amounts of distributed on-chip memory for storage of the SNN synaptic connectivity (SNN topology) information. This large memory requirement poses a serious bottleneck for compact embedded hardware SNN implementation.

This paper proposes clustering of neurons within neural tiles in order to reduce the overall SNN topology memory requirement by 50% compared to the previously reported single neuron per NoC router SNN architecture (Jim Harkin et al., 2009). Each clustered neural tile comprises a fully connected feed-forward SNN structure. Fixed connections between the neurons in the neural cluster remove the requirement for storage of connection topology memory. The paper describes the architecture of the neural cluster element (made-up of a two layer fully connected feed-forward SNN structure) and the neural tile. The use of fixed sized SNN structure as a neural element can result in constrain mapping of certain SNN application topology, which can be addressed by using additional neural clusters as spike repeaters.

The paper also proposes a further architectural enhancement, which involves sharing the SNN topology memory (within each neural tile) between neural cluster outputs. The paper describes the shared SNN topology memory partitioning and operation. SNN topology memory blocks are allocated to each active cluster output based on its synaptic connectivity requirements. The scheme

offers flexible synaptic connectivity for SNN application topologies. The proposed clustered neural tile, and shared topology memory hardware SNN architecture is analysed with a range of SNN application topologies exhibiting irregular connectivity typically seen in real-life SNN application topologies (Kohl and Miikkulainen, 2008). Hardware resource requirements for each element of the proposed clustered neural tile SNN architecture using shared topology memory are compared to the single neuron per NoC router EMBRACE hardware SNN architecture reported in (Fearghal Morgan et al., 2009) (using recently reported 32nm CMOS VLSI technology). Results illustrate up to a 66% reduction in the required silicon area of the proposed clustered neural tile SNN architecture using shared topology memory compared to the reported single neuron per router EMBRACE hardware SNN.

The structure of the paper is as follows: Section 2 summarises the current research in hardware SNN architectures, and SNN topology memory resource requirements. The previously reported EMBRACE NoC-based hardware SNN reference architecture and its hardware resource requirements is described in section 3. The proposed neuron clustering and shared SNN topology memory architecture are presented in Section 4. Section 5 presents significance of the shared SNN topology memory scheme by mapping SNN applications representing practical connectivity patterns to the proposed architecture. Section 6 concludes the paper and proposes future work.

2 STATE-OF-THE-ART HARDWARE SNN ARCHITECTURES

Inspired by biology, researchers aim to implement reconfigurable and highly interconnected arrays of neural network elements in hardware to produce powerful signal processing units (Jim Harkin et al., 2009); (Yajie Chen et al., 2006); (Furber and Brown, 2009); (Upegui et al., 2005); (Pearson et al., 2007); (Ros et al., 2006); (R. J. Vogelstein et al., 2007); (Ehrlich et al., 2007); (B. Glackin et al., 2005); (Schemmel et al., 2008). For large scale hardware implementation of SNNs, the neuron interconnect imposes problems due to high levels of inter-neuron connectivity and often the number of neurons that can be realised in hardware is limited by high fan in/out requirements (L. P. Maguire et al., 2007).

Direct neuron-to-neuron interconnection exhibits switching requirements that grow non-linearly with the network size. Efficient, low area and low power implementations of neuron interconnect and synaptic junctions are key to scalable hardware SNN implementations (L. P. Maguire et al., 2007).

(Ros et al., 2006) present an FPGA-based hybrid computing platform. The neuron model is implemented in hardware and the network model and learning are implemented in software. (B. Glackin et al., 2005) uses a time multiplexing technique to implement large SNN models (with >1.9M synapses and 4.2K neurons), implemented in software, where speed-acceleration is the key motivation, and the parallel capability of SNNs is not exploited. Clustered connections based neural network architecture using NoC and method for mapping of SNNs to the architecture has been proposed in (Emery et al., 2009).

Analogue spiking neuron design approaches can benefit from a compact area implementation due to their inherent similarity with the way electrical charge flows in the brain (Yajie Chen et al., 2006); (Yajie Chen et al., 2008); (R. J. Vogelstein et al., 2007). These architectures rely on digital components for a flexible communication infrastructure. (Ehrlich et al., 2007) and (Schemmel et al., 2008) present FACETS, a configurable wafer-scale mixed-signal neural ASIC system. The work proposes a hierarchical neural network and the use of analogue floating gate memory for synaptic weights. (R. J. Vogelstein et al., 2007) presents a mixed-signal SNN architecture of 2,400 analogue neurons, implemented using switched capacitor technology and communicating via an asynchronous event-driven bus. The chip area is reported to be 3mm x 3mm using 0.5 μ m CMOS VLSI technology.

Practical SNN systems are characterised by large numbers of neurons and high interconnectivity through inter-neuron synaptic connections. Each of the SNN execution architectures presented in (Ehrlich et al., 2007); (Schemmel et al., 2008); (Furber and Brown, 2009); (Ros et al., 2006); (Upegui et al., 2005); (Pearson et al., 2007); (B. Glackin et al., 2005); (Vogelstein et al., 2007) aim for thousands of neurons and millions of synapses. Due to the high neuron interconnectivity, synaptic connectivity information is stored in off-chip DRAMs and is accessed using memory controllers. The neural computing kernel must be supplied with this connectivity information for calculation of spike generation and transfer events in the system; this synaptic connectivity information storage strategy results in high memory traffic and increased power

consumption, unsuitable for embedded system implementation.

The NoC design paradigm provides a promising solution for the flexible interconnection of large SNNs (Vainbrand and Ginosar, 2010). The SpiNNaker project (Furber and Brown, 2009) aims to develop a massively parallel computer capable of simulating SNNs of various sizes, topology and with programmable neuron models. The SpiNNaker architecture uses ARM-968 processor-based nodes for computation and an off-chip NoC communication infrastructure. Each NoC tile in the SpiNNaker system models 1000 Leaky-Integrate-Fire neurons, each having 1000 synapse inputs. Each SpiNNaker node requires approximately 4MBytes of memory for storing synaptic connectivity information (Furber et al., 2006). Hence, the SpiNNaker architecture stores the synaptic connection data in off-chip SDRAM. Due to low-power and area requirements of embedded systems targeted by EMBRACE NoC-based SNN architecture, use of off-chip SDRAM and associated memory controllers is not feasible.

3 EMBRACE: HARDWARE SNN ARCHITECTURE

This section describes the previously reported EMBRACE NoC-based hardware SNN architecture and its hardware resource requirements. EMBRACE (Jim Harkin et al., 2009) uses a single neuron per neural tile (non-clustered) SNN implementation and provides a reference for the work of this paper.

The EMBRACE mixed-signal architecture (currently prototyped digitally, Figure 1) ultimately aims to incorporate low-power CMOS-compatible analogue neural cell circuits, and a digital NoC-based packet switching interconnect, to realise a scalable SNN execution architecture suitable for embedded systems. This architectural scheme has potential to offer high synaptic densities while maintaining compact silicon implementation area and low power consumption.

The EMBRACE NoC-based SNN architecture (Figure 1) is a two-dimensional mesh topology array of neural elements (N) and NoC Routers (R). The architecture comprises a single neuron per NoC router, where each neuron within the NoC tile supports 64 input synapses and its output can connect to maximum 64 synaptic connections. (This architecture is referred as non-clustered EMBRACE architecture in the rest of the paper).

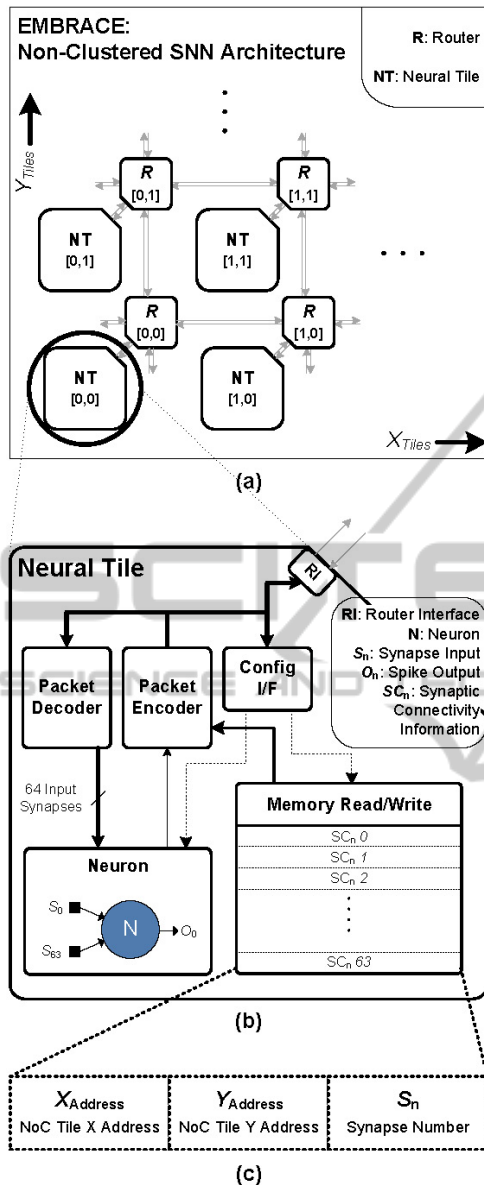


Figure 1: (a) EMBRACE NoC-based SNN Architecture, (b) Neural Tile Comprising Single Neuron, Packet Encoder/Decoder and SNN Topology Memory and (c) Synaptic Connection Information.

The SNN topology memory within EMBRACE architecture defines each inter-neuron synaptic connection. The EMBRACE architecture template (Figure 1) requires 11MB of SNN topology memory to support 64K neuron/4M synapse hardware SNN.

NoC router is connected in North (N), East (E), South (S) and West (W) directions, forming a Manhattan-style, two-dimensional mesh topology NoC architecture. An application specific SNN is realised on the EMBRACE architecture by programming neuron configuration parameters

(SNN synaptic weights and neuron firing threshold potential) and SNN connection topology. Spike communication within the SNN is achieved by routing spike information within spike data packets over the network of routers. The authors have implemented and reported EMBRACE-FPGA (Morgan et al., 2009c), an FPGA prototype implementation of the EMBRACE architecture. The EMBRACE-FPGA prototype has been successfully applied to benchmark SNN control and classifier applications (such as pole balancer, two-input XOR and Wisconsin cancer dataset classifier). EMBRACE-SysC, a SystemC-based, clock cycle accurate simulation and performance measurement platform for simulation and analysis of EMBRACE architecture has been reported (Sandeep Pande et al., 2010). EMBRACE-SysC enables rapid NoC architectural exploration and analysis of the EMBRACE architecture.

3.1 Hardware Resource Requirements

Compact hardware implementation of SNN architectures is essential for their use in portable embedded systems. This section estimates the hardware resource requirements of the non-clustered EMBRACE architecture. The transistor count and chip area is estimated for the non-clustered EMBRACE architecture in recent CMOS VLSI implementation technology to understand the practicality of realising EMBRACE SoC in silicon.

The silicon area required for implementation of the non-clustered EMBRACE architectural template (depicted in Figure 1) is estimated using recently reported 32nm CMOS VLSI technology. Figure 2 presents the estimated silicon die area (in mm²) by scaling the non-clustered EMBRACE architecture.

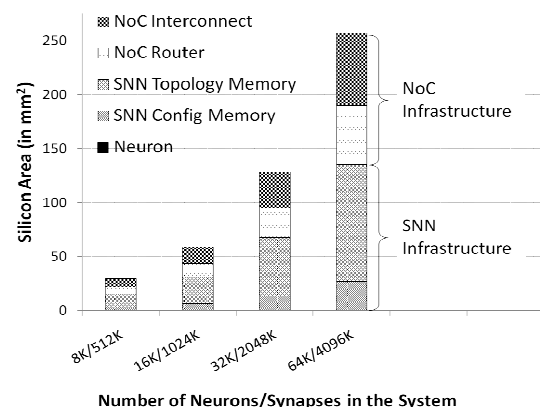


Figure 2: Silicon Area Estimate (using 32nm CMOS technology) for the EMBRACE non-clustered architecture.

The x-axis indicates the number of neurons and synapses (Neuron/Synapse). The stacked columns in the histogram denote the silicon area for each architectural entity described below:

- **NoC Infrastructure:** The NoC infrastructure comprises NoC routers, packet buffers, NoC interconnect and associated control circuits. The total number of bits in all the storage elements within digital components is summed and the required number of transistor estimated based on the standard SRAM cell design. The transistor count for control circuitry within the digital components is proportional to the transistor count of the storage elements. The NoC interconnect (point-to-point bus links between NoC routers) area is estimated based on the bus width and the metal layer routing offered by the VLSI implementation technology. The analytical estimates indicate that complete NoC infrastructure requires 47.27% of the total chip area.

- **SNN Infrastructure:** The silicon area for the EMBRACE analogue neural elements (including synapses, synaptic weight summing and membrane potential threshold device), is calculated using the design and characterisation data reported in (Yajie Chen et al., 2006a); (Yajie Chen et al., 2008); (Yajie Chen et al., 2006b). Due to its compact implementation, the silicon area occupied by neural elements is negligible in comparison to rest of the SNN support infrastructure. The SNN support infrastructure is made-up of SNN configuration memory (for storing synaptic weights of 5 bits each and threshold values of 16 bits each) and the SNN topology memory (for storing synaptic connectivity information) (Seamus Cawley et al., 2011). Silicon area of the SNN infrastructure is estimated using the above mentioned estimation technique and requires 52.74% of the total chip area. Figure 3 further enumerates the silicon area of the SNN components for the 64K Neuron non-clustered EMBRACE architecture.

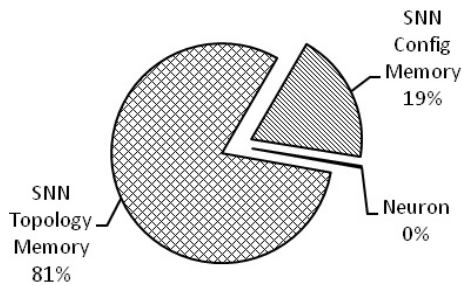


Figure 3: Estimated Silicon Area Proportion for the SNN Infrastructure Entities for 64K Neurons/4M Synapses Non-Clustered EMBRACE Architecture Configuration.

Figure 3 illustrates that the SNN topology memory accounts for 81% and the SNN configuration memory accounts for 19% of the area required by the SNN components.

4 NOVEL CLUSTERED NEURAL TILE HARDWARE SNN ARCHITECTURE

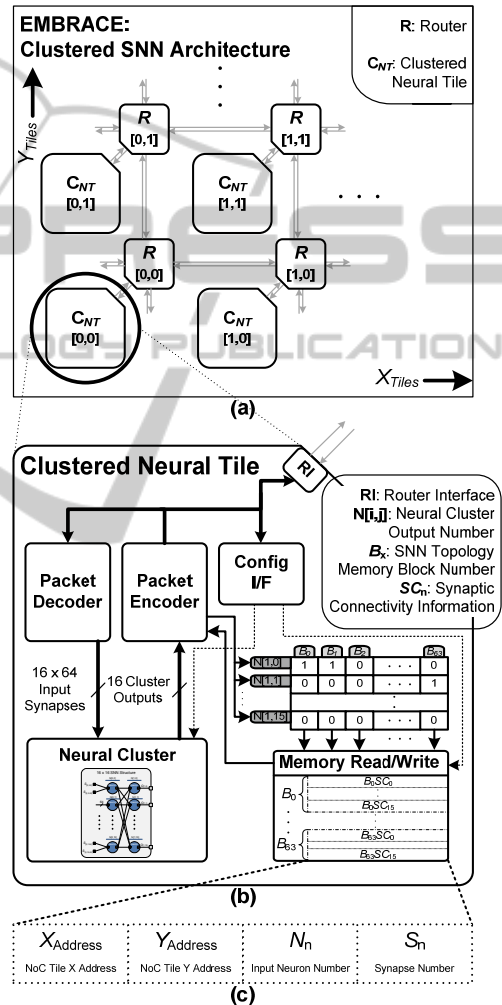


Figure 4: The Proposed EMBRACE Clustered SNN Architecture, (b) Clustered Neural Tile Comprising Neural Cluster, Packet Encoder/Decoder, Shared SNN Topology Memory and Look-up Table, and (c) Synaptic Connection Entry.

Architectural techniques for reducing the SNN topology and configuration memory are vital for compact silicon implementation of hardware SNN architectures suitable for embedded computing. This section presents clustering of neurons in the NoC tile

and architectural scheme for sharing of the SNN topology memory within the NoC tile for compact implementation of the proposed EMBRACE architecture. Silicon area requirements for the proposed clustered neural tile NoC architecture are compared with those of the non-clustered EMBRACE architecture.

Figure 4 illustrates the proposed clustered SNN architecture, clustered neural tile architecture and synaptic connection entry details.

4.1 Neural Cluster

Permanent interconnection between neurons within the neural cluster removes the need to store synaptic connectivity information within the cluster. For hardware implementations, size of the SNN structure formed using the direct connections can be extended based on the permitted fan-out of individual neuron circuits. Also, the metal layer routing in the VLSI architectures cannot efficiently accommodate large sized interconnect crossbars without increasing the inter-metal capacitance and crosstalk. A two-layered 16:16 fully connected feed-forward SNN structure (shown in Figure 5) is proposed as the neural computing element inside each NoC tile.

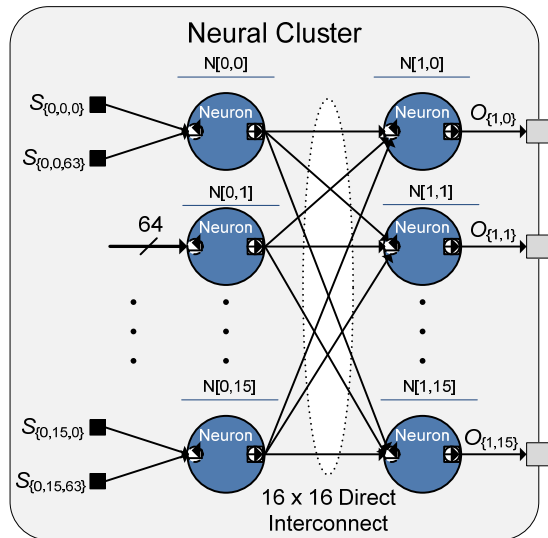


Figure 5: Two layered 16:16 Fully Connected SNN Structure as the Proposed Neural Cluster.

The input and output layer of the neural cluster comprises 16 Leaky-Integrate-and-Fire neurons. The input layer neurons have 64 input synapses each, which receive spikes from synaptic connections external to the NoC tile. Each of the 16 input layer neurons connects directly to each of the 16 output

layer neurons, to form a fully connected feed-forward SNN structure. Each output layer neuron has 16 input synapses, which individually receive spikes from the corresponding input layer neurons. The neural cluster has 16 outputs each corresponding to the 16 output layer neurons.

4.2 Shared SNN Topology Memory Architecture

Figure 6 illustrates the internal organisation of the clustered neural tile comprising the fixed-sized neural cluster, SNN topology memory and the associated look-up table.

The synaptic connection information for the neural cluster outputs is stored in the SNN topology memory. The synaptic connection information entry comprises destination tile address ($[X,Y]$ address of the NoC tile), destination neuron (N_n) and synapse number (S_n) (see Figure 4). The SNN topology memory is partitioned into 64 blocks (B_0 to B_{63}), where each block is made-up of 16 synaptic connection information entries (B_xSC_0 to B_xSC_{15}). This block-wise partitioning arrangement helps flexible allocation of the SNN topology memory blocks to different neural cluster outputs on need basis.

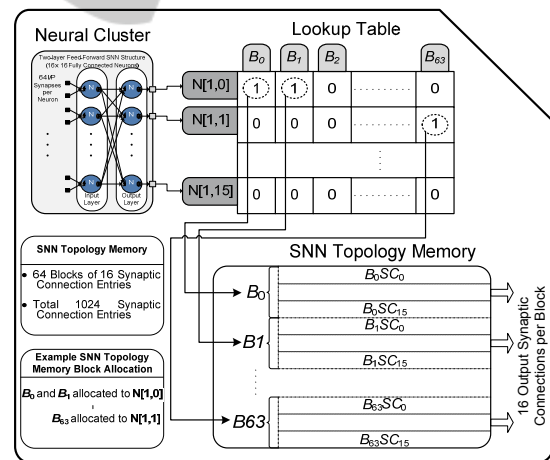


Figure 6: The Clustered Neural Tile Internal Organisation, Comprising Neural Cluster, SNN Topology Memory and the Associated Look-up Table.

The synaptic connection information for the neural cluster outputs is stored in the SNN topology memory. The synaptic connection information entry comprises destination tile address ($[X,Y]$ address of the NoC tile), destination neuron (N_n) and synapse number (S_n) (see Figure 4). The SNN topology memory is partitioned into 64 blocks (B_0 to B_{63}),

where each block is made-up of 16 synaptic connection information entries ($B_x SC_0$ to $B_x SC_{15}$). This block-wise partitioning arrangement helps flexible allocation of the SNN topology memory blocks to different neural cluster outputs on need basis.

The lookup table maintains the SNN topology memory block allocation information for each neural cluster output. Each neural cluster output has a designated row in the lookup-table. Each bit in the 64-bit lookup table row allocates the corresponding memory block from the SNN topology memory to the neural cluster output. For example, bit number B_x of the row number $N[1,0]$ allocates block number X in the SNN topology memory to the neural cluster output $N[1,0]$. (i.e. For the row number $N[1,0]$, setting the bit value $B_x = 1$, allocates the SNN topology memory block X to cluster output $N[1,0]$; whereas Bit value $B_x = 0$ dissociates the SNN topology memory block X from cluster output $N[1,0]$). The packet encoder generates spike packets for the cluster output based on the allocated SNN topology memory blocks for the cluster output. The process of mapping the SNN application topology onto the proposed clustered neural tile, shared memory architecture involves populating the lookup table and SNN topology memory entries, such that the correct synaptic connections are established between the neural clusters. If the synaptic connectivity for a neural cluster cannot be accommodated in the given SNN topology memory available in the NoC tile, additional neural cluster and NoC tiles are use as spike repeaters.

4.3 Architectural and SNN Application Significance

This section compares the proposed clustered neural tile architecture with the non-clustered EMBRACE architecture for silicon area requirements and number of synapses supported.

4.3.1 Silicon Area Requirements

The silicon area for implementation of the proposed clustered neural tile NoC architectural template (shown in Figure 4) is estimated using 32nm CMOS VLSI technology. Figure 7 illustrates the comparison of silicon area by scaling the non-clustered EMBRACE and the proposed clustered neural tile NoC architecture.

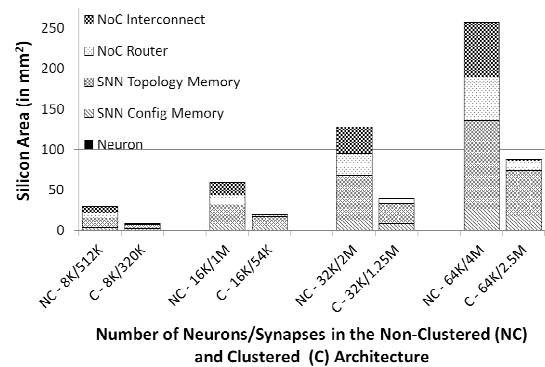


Figure 7: Silicon Area Estimate Comparison for the Non-Clustered EMBRACE Architecture and the proposed Clustered Neural Tile SNN Architecture.

Each NoC tile in the clustered architecture comprises 32 neurons served by a NoC router as compared to the non-clustered architecture (which has a single neuron for each NoC router). Thus, the total number of NoC routers in the system are decreased by a factor of 32 (i.e. the number of neurons in the neural cluster) as compared to the non-clustered architecture. In the proposed clustered neural tile NoC architecture, the packet buffers inside each NoC router are increased by a factor of 16 to accommodate higher spike packet traffic density in the NoC. Due to the reduced number of NoC routers, the area occupied by the NoC infrastructure in the proposed clustered neural tile NoC architecture is decreased by 89% as compared to the previously reported non-clustered architecture.

The fixed interconnection within the neural cluster removes the need for storing the output synaptic connectivity information for the input layer neurons within the neural cluster. The regularly structured interconnect requires much less area than the SRAM-based synaptic connectivity storage and the associated control circuitry. Hence, the SNN topology memory for the proposed clustered neural tile NoC architecture is reduced by 54.05%. The size of the complete chip is approximately 33% of the previously reported non-clustered EMBRACE chip area estimation.

4.3.2 Number of Synapses Supported

The input layer neurons in the proposed neural cluster can have maximum 16 output synaptic connections (each connecting to an output layer neuron within the same cluster). Also within the neural cluster, the input layer neurons cannot directly connect to synapses external to the tile and the output layer neurons cannot receive spikes

directly from the synapses external to the tile. These constraints affect the maximum number of synapses that can be supported by the proposed architectural scheme.

Figure 8 compares the maximum number of synapses that can be supported by the proposed clustered neural NoC architecture with the previously reported EMBRACE architecture.

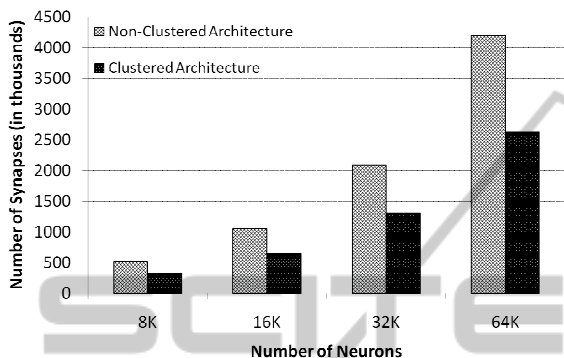


Figure 8: Number of Synapses Supported by the Non-Clustered and Clustered EMBRACE Architecture.

The proposed clustered neural tile NoC architecture supports 37.5% less synapses as compared to the previously reported EMBRACE architecture for the same number of neurons in the system. As the proposed architecture requires approximately 1/3rd area as compared the non-clustered architecture, the number of neural tiles in the architecture can be increased to achieve the synaptic density required by the SNN application. In other words, the proposed clustered neural tile SNN architecture offers 200% increase in number of neurons and 87.5% increase in number of synapses compared to single neuron NoC architecture, for the same silicon area.

5 PRACTICAL SNN TOPOLOGY IMPLEMENTATION RESULTS

Practical SNN application topologies exhibit a variety of connectivity patterns. Through clustering of neurons and flexible sharing of the SNN topology memory within the neural cluster outputs, the proposed architecture addresses diverse connectivity requirements of the practical SNN application topologies while maintaining compact silicon area.

This section presents and compares hardware resource requirements for the proposed clustered neural tile architecture with shared and non-shared SNN topology memory scheme for SNN application

topologies with irregular and random connectivity patterns (Kohl and Miikkulainen, 2008). (The non-shared SNN topology memory scheme uses fixed allocation of 4 blocks to each neural cluster output.) Additional clustered neural tiles are used for relaying spikes, if the synaptic connectivity requirement of the cluster cannot be accommodated in the SNN topology memory in the NoC tile.

A large SNN application topology made-up of 64, individual SNN clusters (of 16:16 neurons) is mapped to the proposed clustered neural tile NoC architecture. The proposed architecture is tested under non-shared and shared SNN topology memory configuration. (The non-shared SNN topology memory scheme uses fixed allocation of 4 blocks to each neural cluster output).

The neural clusters in the example SNN application topology are configured such that 8 neural outputs from each individual neural cluster (within the 64 cluster application topology) are kept inactive by configuring zero synaptic connections. The number of required NoC tiles and the size of the NoC is measured by varying the synaptic connection density of the remaining 8 active neural cluster outputs. Figure 9 illustrates the NoC tile requirement for the clustered neural NoC architecture under non-shared and shared topology memory architecture executing the SNN application topology with irregular synaptic connectivity pattern.

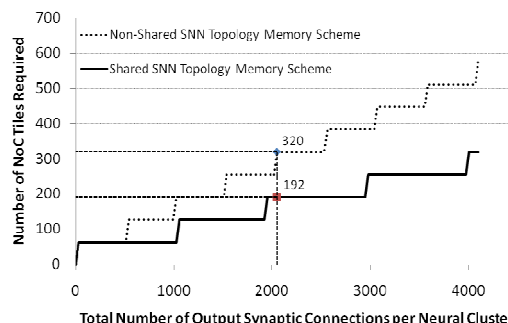


Figure 9: NoC Tile Requirements for Non-Shared and Shared SNN Topology Memory Schemes for the Irregularly Connected Example SNN Topology.

For 2048 connections from each of the 8 active neural cluster outputs in the proposed example SNN topology, the non-shared topology memory scheme requires 320 NoC tiles, whereas the shared topology memory scheme requires 192 NoC tiles (see Figure 9). The SNN topology memory in the NoC tile can hold 1K synaptic connection entries. When the synaptic connectivity requirement of each cluster increases by a fold of 1k, additional set of tiles are used for relaying spike packets. This can be seen in

the step wise ascending graph in Figure 9.

The SNN topologies evolved using Genetic Algorithm (GA) based search methods often exhibit random connectivity patterns (Kohl and Miikkulainen, 2008). The SNN application topology described above is configured for random number of output synaptic connections from each of the 64 individual neural clusters. This SNN application representing random synaptic connectivity pattern is mapped to the proposed clustered neural tile NoC architecture and tested under non-shared and shared SNN topology memory configuration. Figure 10 illustrates the NoC tile requirement for the clustered SNN NoC architecture under non-shared and shared topology memory architecture executing the SNN application topology with random synaptic connectivity pattern.

The proposed shared SNN topology memory architecture facilitates allocation of the SNN topology memory blocks to the neural cluster outputs based on the synaptic connectivity requirement. The look-up table based shared SNN topology memory architecture offers a flexible number of synaptic connections from the neural cluster outputs resulting in efficient usage of each NoC tile. As seen in the Figure 9 and Figure 10, the shared SNN topology memory scheme requires less number of NoC tiles for SNNs with irregular and random synaptic connectivity patterns (observed in practical SNN application topologies). This facilitates accommodation of larger SNN application topologies in the given architectural configuration.

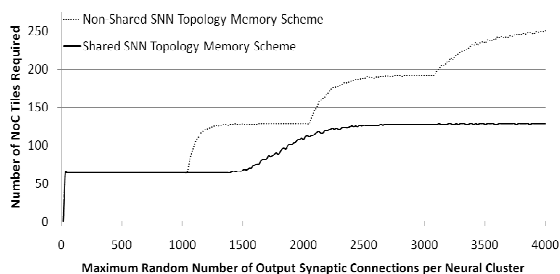


Figure 10: NoC Tile Requirements for Non-Shared and Shared Topology Memory Schemes for the Randomly Connected Example SNN Topology.

6 CONCLUSIONS AND FUTURE WORK

This paper presents the clustered neural tile NoC architecture for compact hardware implementation of practical SNN applications for embedded systems. The proposed architectural scheme for

clustering of neurons within the NoC tiles reduces the SNN topology memory requirement of the system by approximately 50% compared to the single neuron per NoC router SNN architecture. A look-up table based SNN topology memory sharing scheme is presented that allows efficient utilisation of the SNN topology memory for practical SNN application topologies with irregular and random synaptic connectivity patterns. The silicon area of the proposed clustered neural tile, shared topology memory SNN architecture is nearly 33% of the previously reported non-clustered EMBRACE architecture. This paper presents a new approach to addressing the hardware resource challenges of SNN architectures using a combination of fixed-sized cluster of neurons and NoC-based reconfigurable interconnect.

Future work includes realisation of the proposed clustered neural tile NoC architecture in silicon and performance evaluation using benchmark and large practical SNN applications.

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