IMPROVING THE PERFORMANCE OF THE SUPPORT VECTOR MACHINE IN INSURANCE RISK CLASSIFICATION A Comparitive Study

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Abstract: The support vector machine is a classification technique used in linear and non-linear complex problems. It was shown that the performance of the technique decreases significantly in the presence of escalating missing data in the insurance domain. Furthermore the resilience of the technique when the quality of the data deteriorates is weak. When dealing with missing data, the support vector machine uses the mean-mode strategy to replace missing values. In this paper, we propose the use of the autoassociative network and the genetic algorithm as alternative strategies to help improve the classification performance as well as increase the resilience of the technique. A comparative study is conducted to see which of the techniques helps the support vector machine improve in performance and sustain resilience. The training data with completely observable data is used to construct the support vector machine and testing data with missing values is used to measuring the accuracy. The results show that both models help increase resilience with the autoassociative network showing better overall performance improvement.

1 INTRODUCTION

Insurance industries have played a crucial role in carrying risks on behalf of clients since their inception in the late seventeenth century. These risks include carrying the cost of a patient admitted to a hospital, vehicle repairs for a client involved in a car accident and many other incidents. However, numerous people today still do not have an insurance cover. The first well-known reason is refusing to get a cover (Crump, 2009); (Howe, 2010). Many people believe that insurance companies are there to make profits rather than helping their clients. Therefore they would rather save their money and incur the risk of paying the cost if any catastrophic event happens to them (Crump, 2009). The second common reason is cancellation. Fraud, failing to pay premiums on time or numerous claims results in client policies being terminated by the insurer (Crump, 2009); (Howe, 2010). The third common reason is affordability (Howe, 2010). The premiums for a cover may be very expensive due to increasing premiums. A client is therefore forced to cancel the cover.

In this paper, a solution to improve the support vector machine (SVM) as a predictive modelling technique in the insurance risk classification is presented. The solution improves the manner in which client risk is predicted using new data. The model is trained using past data (with a large number of features) about clients who are likely to have insurance cover. This information is then used to predict the future behaviour of a new client. The new client data in this case, has attributes with missing values. Missing values are due to clients failing to supply the data, or processing error by the system handling the data (Duma et al., 2010).

Support vector machines struggle with classification performance compared to other supervised algorithms (such as the naïve Bayes, k-

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Nearest Neighbour, and the logical discriminant algorithms) if new data contains missing data (Duma et al., 2010). One of the main reasons is over-fitting of the data. Even though support vector machines are designed to be less prone to over-fitting, in very high dimensional space, this problem cannot be avoided. When training support vector machines, a lot of detail is learned if the client data has many attributes. The result of this is incorrect predictions of new client data, especially if new data is of poor quality as a result of missing values. The model also has little resilience in the presence of increasing missing data. In comparison with other supervised learning models, its classification performance decreased sharply when the quality of the data deteriorated.

We present a comparative study on genetic algorithms and autoassociative networks as effective models to help improve the classification of the support vector machines and increase resilience. Genetic algorithms have been applied successfully as methods for optimising classification algorithms, (Chen et al., 2008); (Minaei-Bidgoli et al., 2004). It has also been applied in fault classification of mechanical systems as a method for estimating missing values (Marwala et al., 2006). The autoassociative networks have been applied successfully in HIV classification (Leke et al., 2006), missing data imputation (Marivate et al., 2007) and assisting in image recognition (Pandit et al., 2011).

We also employ the use of the principal component analysis (PCA) as a feature selection technique to reduce over-fitting and computational cost. Principal component analysis removes those dimensions that are not relevant for classification. The reduced dataset in then passed on to the support vector machine to learn. Principal component analysis has been applied successfully in fault identification and analysis of vibration data (Marwala, 2001). Is has also been used in automatic classification of ultra-sound liver images (Balasubramanian et al., 2007) and in identifying cancer molecular patterns in micro-array data (Han, 2010).

The rest of the paper is organised as follows: Section 2 gives a background discussion on the support vector machine, the principal component analysis, genetic algorithms, autoassociative networks and missing data mechanisms. Section 3 is a discussion on the datasets and pre-processing. A discussion on the AN-SVM structure and the GA-SVM structure is also given. Section 4 is a discussion on the experimental results. Conclusion and future works is discussed in section 5.

2 BACKGROUND

2.1 Support Vector Machine

Support vector machine is a classification method applied to both linear and non-linear complex problems (Steeb, 2008). It makes use of a non-linear mapping to transform data from lower to higher dimensions. In the higher dimension, it searches for an optimal hyper-plane that separates the attributes of one class to another. If the data set is *linearly separable* (i.e. a straight line can be drawn to separate all attributes of a one class from all attributes of another), the support vector machine finds the *maximal marginal hyper-plane*, i.e. the hyper-plane with the greatest margin. The separation satisfies the following equation (Steeb, 2008),

$$log f(x) = \begin{cases} 1, w, x+b \ge 1 \\ -1, w, x+b \le -1 \end{cases}$$

where w is the weight vector and x is the input vector. A larger margin allows classification of new data to be more accurate. If the data set is *linearly inseparable*, the original data is transformed into a new higher dimension. In the new dimension, the support vector machine searches for an optimal hyper-plane that separates the attributes of the classes. The maximal marginal hyper-plane found in the new dimension corresponds to the non-linear surface in the original space. The mapping of input data into higher dimensions is performed by *kernel functions* expressed in the form (Steeb, 2008),

$$K(X_i, X_j) = \varphi(x_i). \varphi(x_j)$$
(2)

where $\varphi(x_i)$ and $\varphi(x_j)$ are nonlinear mapping functions. There are three commonly used kernel functions used to training attributes into higher dimensions, namely the *polynomial*, *Gaussian radial basis* and *sigmoid function* (Steeb, 2008). In this paper, we use the Gaussian radial basis function.

Support vector machines have been applied successfully in the insurance industry and in credit risk analysis. They have been used to help identify and manage credit risk (Chen et al, 2009, Yang et al, 2008). They have also been employed to predict insolvency (Yang et al, 2008).

2.2 Principal Component Analysis

Principal component analysis (PCA) is a popular

feature extraction technique used to find patterns in data with many attributes and reduce the number of attributes (Marwala, 2009).

In most instances, the goal of the principal component analysis is to compress the dimensions of the data whilst preserving as much as possible the representation of the original data. The first step is determining the average of each dimension and then subtract from the values of the data. The covariance matrix of the data set is then calculated. The eigenvalues and the eigen-vectors are determined using the covariance matrix as a basis. At this point, any vector dimension or its average can be expressed as a linear combination of the eigenvectors. The last step is choosing the highest eigen-values that correspond to the largest eigenvectors, or the principal components. The last step is where the concept of data compression comes into effect. The eigen-values that are chosen along with their corresponding eigenvectors are used to reduce the number of dimensions whilst preserving most information (Marwala, 2009). This reduction can be expressed as /

$$[P] = [M] x [N]$$
(3)

where [P] represents the transformed data set, [M] represent the given data set and [N] is the principal component matrix. [P] represents a dataset that expresses the relationships between the data regardless of whether the data has equal or lower dimension. The original data set can be calculated using the following equation

$$[M'] = [P] \times [N^{-1}]$$
(4)

where [M'] represents the re-transformed data set and $[M'] \approx [M]$ if all the data from $[N^{-1}]$ is used from the covariance matrix.

2.3 Genetic Algorithm

Genetic algorithm (GA) is an evolutionary computational model that is used to find global solutions to complex problems (Michalewicz, 1996). Genetic algorithms are inspired by Darwin's theory of natural evolution. They use the concept of survival of the fittest over a number of generations to find the optimal solution to a problem. In a population, the fittest individuals are selected for reproduction. The selection process is based on a probabilistic technique that ensures that the strongest individuals are chosen for reproduction. There are various techniques that can be used for selection, namely the *roulette wheel selection, ranking selector, tournament selection* and *stochastic* *universal sampling* (Michalewicz, 1996). The roulette wheel selection uses a structure where each individual has a roulette wheel slot size that is in proportion to its fitness. The ranking selector orders individuals according to their probability for selection. The tournament selection technique selects a random numbers of individuals, and then assigns the highest probability to the fittest two individuals. The stochastic universal sampling technique is an alternative to the roulette wheel selection. The technique ensures that the selection of each individual is regular with its expected rate of selection. In this paper, we use the roulette wheel selection as it is a commonly used technique for selection (Marwala, 2009).

After the selection process, steps involving *crossover*, *mutation* and *recombination* are performed to generate new individuals (Marwala, 2007, Steeb, 2008).

Crossover involves selecting a crossover point between two parent individuals or chromosomes (This can be a point in a string of bits or an array of features that represent an instance in a dataset). Data from the beginning of a chromosome to the crossover point is exchange with another parent chromosome. The results are two child chromosomes. Mutation involves selecting a random gene to invert it. It usually has a very low probability of occurring than the crossover process (i.e. less than 1%). Recombination involves evaluating the fitness value of the new individual to determine if they can be recombined with the existing population. The weakest individuals are removed from the population (Marwala, 2007, Steeb, 2008).

2.4 Autoassociative Network

Autoassociative networks are specialized neural networks that are designed to recall their inputs. This implies that the input values supplied to the network are the predicted output representing the inputs. The number of hidden inputs in the hidden layer is often less than the number of inputs. The number of hidden layers cannot be too small otherwise the learning results in poor generalisation and prediction accuracy (Leke *et al*, 2006). In a classification problem, the inputs vectors $\mathbf{x} \in \mathbb{R}^m$ include the class value. The predicted values $\mathbf{y} \in \mathbb{R}^m$ are expressed in the following form

$$\mathbf{y} = \mathbf{f}(\mathbf{x}, \mathbf{w}) \tag{5}$$

where w are the mapping weights. The error function e between the input vectors as well as the predicted outputs, can be expressed in the form

$$e = \mathbf{x} - \mathbf{y} \tag{6}$$

By squaring the error function and replaying y with equation (5) (Leke *et al*, 2006), we get

$$e = (\mathbf{x} - \mathbf{f}(\mathbf{x}, \mathbf{w}))^2 \tag{7}$$

we obtain the minimum and non-negative error, which is what is required for the work presented in this paper. Equation (7) can be expressed as a scalar by integrating over the input vectors an the number of training examples as follows

$$\mathbf{E} = \|\boldsymbol{x} - \boldsymbol{f}(\boldsymbol{x}, \boldsymbol{w})\| \tag{8}$$

where || || represents the Euclidean norm. The minimum error is obtained when the outputs are the closest matching to the inputs.

2.5 Missing Data Mechanisms

Information that is gathered from various sources can have missing data. There are various reasons for missing data. Some include people refusing to disclose certain information for privacy or security reasons, faulty processing by system and systems exchanging information that has missing data (Francis, 2005).

The mechanisms for handling missing data are missing at random, missing completely at random, missing not at random and missing by natural design (Little et al, 1987, Marwala, 2009). Missing complete at random infers that the missing data is independent of any other existing data. Missing at random infers that the missing data is not related to the missing variables themselves but to other variables. Missing not at random infers that the missing data depends on itself and not on any other variables. Missing by natural design infers that the data is missing because the variable is naturally deemed un-measurable, even though they are useful for data analysis. Therefore, the missing values are modelled using mathematical techniques (Marwala, 2009).

In this paper, we infer that the data is missing completely at random. The reason is that single and multiple imputations return unbiased estimates.

3 METHODS

3.1 Datasets and Pre-processing

There are two datasets used for conducting the experiment. Both dataset are executed separately and their results are combined. The first dataset is the

Texas insurance dataset used by the Texas government to draw up the *Texas Liability Insurance Closed Claims Report*. The report contains a summary of medical insurance claims for various injuries. The claims are either short form or long form. Short form claims are associated with small injuries that are not expensive for individuals to pay for themselves. Long-term form claims are associated with major injuries that are expensive and require medical insurance. In this dataset, we classify instances based on whether they have medical insurance cover for long form claims as a risk analysis exercise, provided there is missing information.

The Texas Insurance dataset has over 9000 instances, which were reduced manually to 5446 instances by removing all the short form claims. The dataset is separated into training and testing datasets, 1000 and 500 instances respectively (the datasets were reduced to help increase the speed of the training and testing processes. The instances were also randomly chosen). Both sets have missing values initially. We use the testing set to simulate missing data. Each set consists of a total of over 220 attributes initially. The attributes were reduced manually to 118 attributes by manually removing those attributes that were not significant for the experiment such as unique identities, dates etc. The data was also processed to have categorical numerical values for each attribute. The class attribute used also has two values (0 to indicate no medical insurance and 1 to indicate that the claimer has medical insurance).

The second insurance dataset is from the University of California Irvine (UCI) machine learning repository. The dataset is used to predict which customers are likely to have an interest in buying a caravan insurance policy. In this paper, we use it to find out customers who are likely to have a car insurance policy for their motor vehicles, provided there is missing data in the information

The training dataset has over 5400 instances of which 1000 were used for the experiment. The testing dataset consists of only 4000 instances of which 800 instances were randomly chosen and used. Analogous to the Texas Insurance dataset, the subsets of the UCI training and testing datasets are used so that the experiment runs at optimum speed. Each set has a total of 86 attributes with completely observable data, 5 of which are categorical numeric values and 80 are continuous numeric values. Processing was done to make the data consist of categorical numeric values. The class attribute consists of only two values (0 to indicate a customer that is likely not to have insurance or 1 to indicate a customer that is likely to have an insurance cover).

There are five levels of proportions of missingness on the testing datasets that are generated (10%, 25%, 30%, 40% and 50% respectively). At each level, the missingness is arbitrarily generated across the entire datasets, then on half the attributes of the sets. Therefore, in total, 30 testing datasets were created for the experiment.

3.2 AN-SVM Structure

Figure 1 shows the structure for improving the support vector machine using the autoassociative network. We refer to the structure as the AN-SVM structure. The initial step is compressing the data using the principal component technique. The compressed data is used to construct the autoassociative network. Once the network is constructed, it is used to select the best candidate for the support vector machine to classify. A group of candidates is created for each instance that has missing values from the testing data. This is done by randomly replacing missing entries with values for each candidate. We create between 10 and 500 candidates for each instance, depending on the number of missing values. The candidate with the smallest error according to equation (8) is chosen for classification. This is done until all instances that have missing values have a potential candidate.

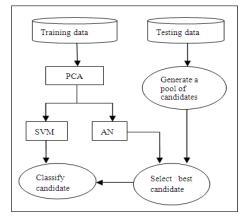


Figure 1: AN-SVM structure.

The autoassociative network is made up of the input, hidden and output layers. There are 20 nodes on hidden layer, determined by trial and error. The Gaussian function is used as an activation function between the input and hidden layer. The linear activation function is used between the hidden and output layer (Leke et al, 2006). The backpropagation technique is used for learning and the number of epochs is 400. The network is written using C# 3.5 programming language, Weka and IKVM libraries. The support vector machine is constructed using Weka 3.6.2 and libSVM 2.91, a library for tool support vector machines. The radial basis function was used as the kernel function. The principal component was also built using the Weka 3.6.2 library.

3.3 GA-SVM Structure

Figure 2 illustrates the genetic algorithm approach to improving the support vector machine classification performance. We refer to the structure as the GA-SVM structure. The initial step is synonymous to the AN-Structure. The only difference is that the genetic algorithm is responsible for creating a population of candidates and selecting the best one for classification. Each candidate represents a potential solution, i.e. it can belong to the 0 class or the 1 class. The maximum number of potential candidates created is 15 for each instance with missing values. Each candidate is represented as follows:

• Each observable entry is ignored, as illustrated by the star (*) in figure 3. The other entries contain generated values used to replace the missing values.

• During the crossover step, only the generated values are exchanged to generate new individual. Similarly, mutation step only occurs on entries with generated values.

Each child candidate's fitness is evaluated using equation (8). The roulette wheel selection is used in the selection step. The genetic algorithm is constructed using the watch-maker framework 0.7.1. The number of epochs is 100 and the mutation probability was 0.0333, as recommended by Leke (Leke et al, 2006) and Marwala (Marwala et al, 2006).

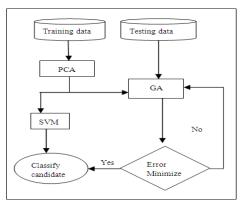


Figure 2: GA-SVM structure.

Xı	X ₂	X ₂	X ₃	X4	X5	X ₆	X7	X ₈	Xo	C1
А	*	*	0.3	В	11	*	*	*	С	0
С	0.5	*	*	E	*	1	*	*	М	1
0	0.9	3	*	*	10	*	*	*	*	0
А	*	5	*	E	*	3	*	*	С	1
С	*	*	*	В	*	*	*	*	С	1

Figure 3: Candidate representation. * means ignored entries. $X_1...X_n$ are attributes and C_1 is the class-label.

4 EXPERIMENT RESULTS

The overall results of the experiment are illustrated in table 1. The AN-SVM and the GA-SVM are compared with MODE-SVM, support vector machine that uses the mean-mode strategy to replace missing values. All the models perform well overall with AN-SVM achieving higher accuracies than the other models by a small margin. The GA-SVM achieves a lower accuracy than the MODE-SVM. The reason being is that the MODE-SVM achieves high accuracies when there is a small percentage of missing data. Furthermore the GA-SVM struggled with performance when data was missing across all attributes compared to other models. This is illustrated in figure 5.

Table 1: Overall Classification Accuracy.

	Accuracy (%)
MODE-SVM	89.94
AN-SVM	90.04
GA-SVM	89.145

The overall performance in figure 4 shows that the AN-SVM and GA-SVM are more resilient to escalating missing data than the MODE-SVM. From figure, the performance of the MODE-SVM decreases sharply as the quality of the data deteriorates. The AN-SVM shows more steadiness in declining performance than the other models. Figure 6 shows the overall performance of the models with half or all attributes with missing data. From the figure, it is clear that all the models perform well and show more resilience when there is half the attributes with missing value. In the case when all or most attributes have missing data, a sharp decline in performance is experienced when the percentage of missingness increase above 30%. The Mode-SVM contributes mostly in the sharp decrease.

5 CONCLUSIONS AND FUTURE WORK

We conducted a study using the autoassociative network and genetic algorithm to help improve the classification performance of support vector machines, in the presence of escalating missing data. Although support vector machines perform well when using the mean mode technique, the performance declines sharply when the quality of the data deteriorates. The autoassociative network showed better performance than the genetic algorithm. It also showed better resilience when the percentage of missing data increased. The genetic algorithm also showed some resilience.

Future work should focus on improving the performance of the genetic algorithm by optimizing the process illustrated in figure 2. The number of candidates currently chosen is a few and a better evaluation function can be used.

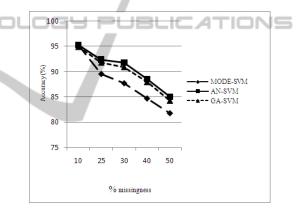


Figure 4: The overall performance of the MODE-SVM, AN-SVM and GA-SVM.

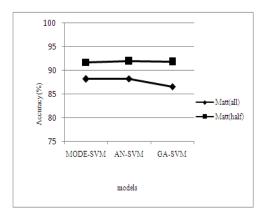


Figure 5: Overall performance per model. Matt(all) is short for most attributes with missing values. Matt(half) is short for half the attributes with missing values.

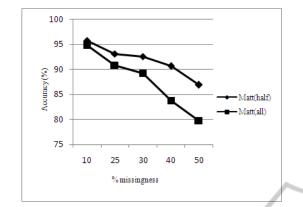


Figure 6: Overall performance with half or all attributes with missing values. Matt(all) is short for most attributes with missing values. Matt(half) is short for half the attributes with missing values.

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