Keywords: Speech Recognition, Spectrogram, Fuzzy Logic, STFT, Standard Deviation, Segmentation.

Abstract: The paper presents Bangla word speech recognition using spectral analysis and fuzzy logic. As human speech is imprecise and ambiguous, the fuzzy logic – the base of which is indeed linguistic ambiguity, could serve as a more precise tool for analysing and recognizing human speech. Even though the core source of an uttered word is a voiced signal, our system revolves around the visual representation of voiced signals – the spectrogram. The spectrogram may be perceived as a “visual” entity. The essences of a spectrogram are matrices that include information about properties of a sound, e.g., energy, frequency and time. In this research the spectral analysis has been chosen as opposed to image processing for increased accuracy. The decision making process of our system is based on fuzzy logic. Experimental results demonstrate that our system is 80% accurate compared to a commercial Hidden Markov Model (HMM) based speech recognizer that shows 73% accuracy on an average.

1 INTRODUCTION

Human speech recognition has a broader solution which refers to the technology that can recognize speech. The recognition process is still open because none of the current methods are fast and precise enough compared to human recognition abilities. Research in this area has attracted a great deal of attention over the past five decades. Several technologies are applied and efforts were made to increase the performance up to marketplace standard so that the users will have the benefit in a variety of ways.

During this long research period several key technologies were applied to recognize isolated words such as Hidden Markov Models (Abul et al., 2007), Artificial Neural Networks (ANN), Support Vector Classifiers with HMM, Independent Component Analysis, HMM and Neural-Network Hybrid, the stochastic language model and more (Juang and Rabiner, 2005).

On recognizing Bangla speech, most of the research efforts had been performed using the ANN based classifier. But no research work has been reported that uses the Fuzzy logic, MEL filtering and STFT methods. Therefore, in this research we investigated, proposed and implemented a model that could recognize Bangla isolated words by using fuzzy logic and spectral analysis.

The ambiguity in phonemes in Bengali speech is more intense and varied than that of English speech since Bangla stems from the “Indo-European language family” just as Hindi, Urdu, Persian and numerous languages from South Asia having native speakers of over 3 billion (Weiss, 2006). Therefore our approach for speech recognition considers the “word level” rather than the “phonetic level.” In other words the base or smallest entity of our system is a “word” (in Bangla) rather than a sound (phoneme) that constructs the words. We also want to mention that HMM based speech recognizers work from the phonetic level as opposed to “word level” since most of the HMM based systems are optimized for English speech.

In our Fuzzy Inference System (FIS), we have taken three inputs, i.e., frequency, energy level of the sample, and the energy level of the target or description. Since human ear is more susceptible to lower frequencies of sounds, our FIS rules are made accordingly to put emphasize on the lower frequencies. The output of our FIS is the similarity between two “segments” of a word and the overall evaluation of the FIS has been cumulated to reach the verdict of word recognition.

The organization of the paper is as follows: Section 2 discusses the related works done till date in relevance to speech recognition emphasizing on Bangla speech (phoneme descriptions, vowels and recognition systems) in particular. Section 3 presents...
the detailed descriptions about the strategies that we implement to build our system. In Section 4 we report and analyze the experimental results. Finally, Section 5 concludes giving future directions of our research.

2 RELATED WORKS

Even though Speech Recognition is still an open problem with quite low accuracy, the attempt to recognize speech dates back to the 1950s. The very first speech recognizer only recognized digits that were spoken (Davies et al., 1952). After the first attempt the speech recognition was centered on voice commands in devices and utility services. In 1990 AT&T call centre service devised the first command recognition. When customers called their help lines they could give voice instructions (Juang and Rabiner, 2005). However this attempt was not successful since most dialects could not be recognized.

Since then approaches were revolved around the visual representation of speech. Documentation of the relationship between a given speech spectrum and its acoustic properties were done in 1922 by Fletcher and others at the Bell Laboratories (Fletcher, 1922). Thus Harvey Fletcher became one of the pioneers in recognizing the importance of the spectral analysis in detecting phonetic attributes of sound.

Even though the attempts to recognize human speech properly goes a long period back in time, the speech recognition approaches in Bangla language started only in the 21st century. In a research work (Roy et al., 2002), performed the recognition by ANN using Back propagation Neural Network. A phoneme recognition approach using ANN as a classifier was devised in (Hassan et al., 2003). RMS energy level was calculated by them as feature from the filtered digitized signal. In (Karim et al., 2002) authors presented a technique to recognize Bangla phonemes using Euclidian distance measure. Authors in (Rahman et al., 2003) presented continuous Bangla speech segmentation system using ANN where reflection coefficient and autocorrelations were used as features. They applied Fourier transform based spectral analysis to generate the feature vectors from each isolated words. Authors (Islam et al, 2005) presented a Bangla ASR system that employed a three layer back propagation Neural Network as the classifier. In a research paper Hasnat and others (Abul et al., 2007) presented an HMM based approach in recognizing both isolated and continuous Bangla speech recognition using HMM models and MFCC.

3 METHODOLOGY

The main goal in this research is to create a platform that could translate Bengali speech to Bengali text through proper recognition by spectrogram and fuzzy logic. However to do so, first we need to train the computer-system in a fuzzy learning methodology with original or correct form of utterance of words. Our strategy is divided into two major phases: Learning phase and Recognition phase. Each of the phases consists of multiple steps. Even though the phases are named differently, some of the steps overlap with each other. They are vividly illustrated by the flowchart presented in Figure 1.

3.1 Recording Speech

The first step is self explanatory. We first get input speech in our system. Our system could work on previously recorded “WAV” files or record speech in real time. All sounds that we used and recorded have the following specifications:

- Bit-depth: 8 bit (7 KB/sec)
- Bit-rate: 8.000 KHz

As the bit rate is 8 KHz we represent the “time parameter” axes in “sec/8000” units in figures 2, 3.

Channel: mono (since we recognize speech, the choice of dual-channel/stereo is meaningless as both channels will give the same signal to our system.)

3.2 Segmentation using Noise Approximation

Before analysing further, it is imperative that data speech and the descriptions stored in our database need to be phased in such a way that one can be superimposed onto the other. Simply put, if one speaker starts to speak a word after two seconds whereas the description in our database/dictionary starts the data instantaneously then the two descriptions will not superimpose properly. Therefore, segmentation needs to be done in a way such that both of the descriptions start from the same point of time. This has been implemented with the following way: when a speaker speaks a word, the system will seek for the level where the amplitude of the signal is greater than 0.2 dB/dB (relative threshold amplitude that we approximate is based on
noise of surroundings). A raw and segmented word is presented in Figure 2 and Figure 3 respectively.

It should be mentioned that in the figures we use the unit (dB/dB) to relate the “relative amplitude.” The term “relative amplitude” that we use in this research is the raw value of the energy level and the relation of the “relative amplitude” with the conventional decibel (dB) is expressed by the following equation.

\[ y = 10 \log_{10}(x) \]  

(1)

where, 
\( x \) = the relative amplitude  
\( y \) = amplitude in decibel (dB)

Our system considers the signals that are greater than the threshold value. It will end seeking when the level goes below the threshold level of noise. Thus we will find the interval between which the speech exists and create description/compare with database based on that segment of the word.

**3.3 STFT (Short-time Fourier Transform) the Speech Data/Generating Spectrogram**

Generation of the spectrogram is the core element of this system. The short-term Fourier transform (STFT) is a Fourier-related transform that is simplified but often useful model for determining the frequency and phase content of local sections of a signal as it changes over time (Short-time Fourier Transform, 2010). STFT is defined formally in equation (2).

\[ X(\omega, m) = \text{STFT}(x(n)) = \text{DTFT}(x(n-m)w(n)) \]

(2)

The spectrogram of the signal is the graphical display of the magnitude of the STFT, \( |X(\omega, m)| \) which is used in speech processing. The STFT of a signal is invertible that means that we can recreate the sound from the spectrogram using inverse STFT (Spectrogram, 2010). Now let us take a look at equation (3), where the original Fourier Transform equation for computing the STFT is given:

\[ F(k) = \sum_{n=0}^{N-1} f(nT)e^{-j\frac{2\pi}{N}nk} \]  

(3)

where, \( f(nT) \) corresponds to equally spaced samples of analog time function \( f(t) \). But when the samples of the analog function \( f(t) \) are played through an analog filter, then the frequency response \( H(\omega) \) will be:

\[ H(\omega) = \frac{\sin(\omega T/2)(\omega/2\pi)^2}{(\omega^2 - 2\pi F_s)^2} \]  

(4)

Now for determining a running spectrogram and providing flexibility in terms of the filter characteristic, the function used was:
\[ F_k = \sum_{n=0}^{N-1} w(nT) f(nT + rMT) e^{-j2\pi nk} \]  \hspace{1cm} (5)

which includes \( w(nT) \), a new Hamming window for providing a better spectral characteristic (Spectrogram, 2010).

The sample result from this model (in MATLAB) is shown in Figure 4:

---

3.4 Filtering/Downsampling the Spectrogram Matrix based on Frequency Sensitivity

Since the energy level based Spectrogram of a general Bangla word (based on average length) returns a matrix of size 300 x 1400 (based on length of the sound and the parameters of the spectrogram), it is impractical to work with the magnitude of so many values. Thus we have modelled our system to downsample the spectrogram.

However, by using the word “down-sampling” in our research, we do not refer to downsampling of frequency or time or “dimensionality reduction” techniques (i.e., Principal Component Analysis - PCA, Linear Discriminant Analysis - LDA etc.). Rather we refer to reduction of the dimensions of the large matrix corresponding to energy levels to a smaller and manageable dimension which results in better approximation.

We have divided the frequency domain in 30 equal windows and divided the time domain into 40 equal windows. We have used an algorithm such that this segmentation/creating chunks from a large matrix take place in one step. The algorithm works as follows:

Step 1: The frequency domain is divided into 30 equal parts. Since frequency domain in our system always ends in ~ 5 KHz, each window gives us a 167 Hz window. Let this value be \( x \).

Step 2: The time domain is variable as we need to accommodate words of variable lengths. However, we get the highest value as the end timestamp of a segmented word and divide the time domain into 40 equal parts. Let each window be \( y \).

Step 3: For an \( x \times y \) window we first take the mean of every row/frequency bar (assuming frequency is horizontal) and we select the maximum of the means and we associate that value to that particular chunk/block.

value of a single block = \( \max_{1 \leq i \leq 30} \max_{1 \leq j \leq 40} \text{mean} (S_{i,j}) \)

Figure 5 illustrates the downsampled spectrogram of the same word shown in Figure 4.

Step 4: we continue step 3 for the whole spectrogram which gives us a matrix of size 30x40 where 30 windows are allocated for frequency and 40 windows for time and the values inside the matrix are determined by step 3 of the algorithm.
Since we know that the human ear is more sensitive to lower frequencies and vice versa for higher frequencies, it would be wiser to divide the frequency domain into exponentially growing windows but instead of putting emphasize on the lower frequencies, we decided to put more weight on the overall evaluation on lower frequencies using our Fuzzy Inference System (FIS).

3.5 Storing and/or altering Word Descriptions

By downsampling the matrix is reduced to size 30 x 40. For each word, these matrices are stored in our database along with a “Bengali” string that represents the word speech in text. Altering a word description is vividly described in subsection 3.7.

3.6 Comparison

The comparison is the base or ground of the fuzzy logic implemented in our system. Before providing details of FIS we need to mention the following facts about our Fuzzy Inference System (FIS):

- We have 2 matrices, one for the sample (the word to be recognised) and the other is the target (the description of a word with which it will be compared).
- The similarity of those two will be determined by the closeness of their energy values.
- The similarities will be prioritized by their frequencies.

Next we present the details of the comparison step:

1) The Comparison FIS membership functions: In FIS, we have 3 inputs, i.e., frequency, target and sample. Based on the inputs, the FIS will evaluate the similarity of 2 segments and give us a result ranging in the range [0, 10] where 10 being the perfect match and 0 means no match (Figure 10).

The membership values are illustrated in the following figures (Figure 6-8) and equations (eq. 6-8). In Figure 6 the x axis represents 30 equal and increasing segments of frequencies and the y axis represents the degree of membership. To further illustrate Figure 7 it is necessary to mention that all the elements of the downsampled (subsection 3.4) spectrogram – the 30 x 40 matrix of a word description is normalized (ranging from 0 to 1). And such energy values derived from the STFT/Spectrogram are represented in the x axis of both Figure 7 and Figure 8. In Figure 7, the x axis represents the energy level (every element of the 30 x 40 matrix of a word description) of a particular word in our database (which we are calling “target”).

On the other hand, the x axis of Figure 8 represents the normalized energy level of a word spoken by a user (which we are calling “sample”) which will be compared to “target” as explained above. These energy levels are also merely the elements of the 30 x 40 matrix generated through “downsampling” (subsection 3.4) from the original spectrogram/STFT (subsection 3.3) of the voiced data. In both Figure 7 and Figure 8, the y axis represents the degree of membership.

\[
\mu_{\text{frequency}}(x) = \begin{cases} 
\frac{x}{11} + 1, & 0 \leq x \leq 11 \ (x \ is \ low) \\
\frac{x-6}{4}, & 6 \leq x \leq 15 \ (x \ is \ medium) \\
\frac{(x-22)}{14}, & 15 \leq x \leq 22 \ (x \ is \ medium) \\
\frac{(x-30)}{16} + 1, & 16 \leq x \leq 30 \ (x \ is \ high) 
\end{cases}
\] (6)

Figure 6: Membership Function for Frequency corresponding to equation (6).
The membership functions used in our systems have been based on our sole understanding of the recognition of speech. However the membership function for “frequency” (equation 6 and Figure 6) has been in accordance with the conventional model of MEL spaced filterbanks (IIFP, 2010) even though it has been modified as illustrated in Figure 6. All the other membership functions (sample, target and similarity) were derived from the visual representation of the membership function shapes (modelled by ourselves using MATLAB) based on logical perception.

2) The fuzzy if-then rules: As we have 3 inputs, we slice the three dimensional table into three two dimensional tables (Table 1-3). Since we have 3 input variables, we use 27 or \((2^3)\) fuzzy propositions (fuzzy if/then rules) to model our system. Also two surface plots evaluating the model are presented in Figure 10 and Figure 11.

Table 1: Fuzzy rules when frequency is LOW.

<table>
<thead>
<tr>
<th>Sample</th>
<th>Target</th>
</tr>
</thead>
<tbody>
<tr>
<td>Sample</td>
<td>Target</td>
</tr>
<tr>
<td>Sample</td>
<td>Target</td>
</tr>
</tbody>
</table>

Table 2: Fuzzy rules when frequency is Medium.

<table>
<thead>
<tr>
<th>Sample</th>
<th>Target</th>
</tr>
</thead>
<tbody>
<tr>
<td>Sample</td>
<td>Target</td>
</tr>
</tbody>
</table>

Table 3: Fuzzy rules when frequency is high.

<table>
<thead>
<tr>
<th>Sample</th>
<th>Target</th>
</tr>
</thead>
<tbody>
<tr>
<td>Sample</td>
<td>Target</td>
</tr>
</tbody>
</table>

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The meanings of the terms in tables are given below:

VL = Very Low  
L = Low  
M = Medium  
H = High  
VH = Very High  
P = Perfect

From the rules it can be inferred that the lower frequencies has been given higher priority when evaluating the rules.

To get the complete view of the evaluation of the FIS, Figure 10 and Figure 11 has been generated using MATLAB. These two figures show the evaluation of the aggregate of all the 27 fuzzy propositions (if/then rules presented in Table 1, 2 and 3) and the membership functions shown in Figure 6-8 as a surface plot. Since we have 3 input variables (Frequency, Sample and Target) and 1 output variable (Similarity), the total number of variables is 4 which cannot be accommodated in a single figure (as four dimensions cannot be represented in 3 dimensional form). Thus, we are using 2 figures to illustrate the overall evaluation of the FIS.

In Figure 10, the frequency (ranging from 0 to 30 as defined in the membership function in Figure 6) is represented in the x axis. Here the variable “Sample” is the word description (energy values of the 30 x 40 matrix) that the speaker has spoken which the system identifies. Since it is normalized it is ranging from 0 to 1 (Figure 8 shows the membership function). Finally the similarity (ranging from 0 to 10 – based on our modelling as represented in Fig 9) is represented in the Z axis as output.

Figure 10: Surface illustrating the evaluation of the FIS representing Frequency (X axis), Sample (Y axis) and similarity (Z axis).

But Figure 10 cannot independently shed light on the overall evaluation of the FIS. For that we need to look at Figure 11 as well. Here the X axis and Z axis are same as Figure 10 (frequency and similarity, respectively). However, the Y axis is now “Target” which is the word description (energy values of the 30 x 40 matrix) to which the “Sample” matrix is compared. By “Target” we refer to a particular word description (for a particular comparison) in our data-set in form of a 30 x 40 matrix. Since it is normalized, it is ranging from 0 to 1 (Figure 7 shows the membership function). It is important to note that the “Target” word description changes to the next word in the data-set every time a particular comparison of a word in the dataset (which we are calling “Target”) to “Sample” (the word spoken by a speaker) is computed.

Figure 11: Surface illustrating the evaluation of the FIS representing Frequency (X axis), Target (Y axis) and similarity (Z axis).

Now if we look at the surface plots of Figure 10 and Figure 11 then we notice that both the surfaces are similar. It is because both “Sample” and “Target” are normalized and they are reflected on the similarity fuzzy propositions (Table 1-3). Moreover, for achieving accurate similarity between “Sample” and “Target” the membership functions for both (equation. 7 and equation. 8 respectively) are modelled as identical. In other words, if we picture the two figures together then the similarity will reach towards 10 (Figure 9 for membership function plot) if “Sample” and “Target” have the same or close values (based on the fuzzy if/then rules).

It should be also noted that Figure 10 and Figure 11 conveys the fact that, lower frequencies are getting higher priorities in the FIS than higher frequencies. If we examine and go along the X axis (which represents “Frequency”) then we see that the height of the surface gradually decreases. This tells us that as we move to higher frequencies from lower ones, the similarity found between “Sample” and “Target” are gradually given less weight in “Similarity” which coincides to the fuzzy if/then rules represented in Tables 1-3. For instance, if an energy value of a particular segment (one particular value in the 30 x 40 matrix of Sample) matches completely with the energy value of the segment of the same location of the “Target” (which is another
30 x 40 matrix) then the similarity will not always be 10. According to Figure 10 and Figure 11, if this match is found when frequency value is one (every frequency value corresponds to 167 Hz rising up to 5 KHz as discussed in Subsection 3.4) then the similarity is given as ~ 9.9 on a scale of 10 (paying more priority to lower frequencies), however if this same matching takes place where frequency value is 25 (which corresponds to 25 x 167 Hz = 4175 Hz as mentioned in Subsection 3.4) then the similarity value (defuzzified) is ~ 6.5 (on a scale of 10).

3.7 Training

After we feed our system with 50 words descriptions (in form of 30 x 40 fuzzy sets), the user gets the liberty to alter the description based on his/her particular voice/tone/stress etc. If a particular word – spoken by the user is recognized incorrectly, then the system asks for the correct word from the user (the user then types in which word he/she has just spoken if and only if the system fails to recognize the word itself). After getting the inputs (voiced signal – which, in turn will be converted into a 30 x 40 matrix as discussed in Subsection 3.4, and the correct word string) – the system compares this user’s input (voiced data that has been converted into a 30 x 40 matrix as explained in subsection 3.4) with the description of our database. Based on the difference of the two, the description stored in our database is altered in accordance with the users speaking. Consequently, the incorrect description will shift towards the user’s version of the word.

To clarify the process let us consider that a user has spoken a word that the system has recognized incorrectly (suppose, user said the Bangla word “Ek” but the system recognized it as the Bangla word “Aat”). In that case the user prompts the system that the match was incorrect and this information is stored in a “Boolean” variable to designate if the sample was a match or not. If it was not a match (the system recognized the word incorrectly) then the word description of the original word will be altered as follows:

\[
E_{\text{level(new)}} = (E_{\text{level(original)}} \times \text{original_weight}) + (E_{\text{level(training)}} \times \text{training_weight})
\]  

(10)

Here,

\(E_{\text{level(new)}}\) = the energy level of a particular segment of the spectrogram (every element of the 30 x 40 matrix of the word description and for this example it is the description for the word “Ek”)

\(E_{\text{level(original)}}\) = The energy level that was stored in the database for the word that was spoken (or being trained) by the user (and in this example the word is “Ek”).

\(E_{\text{level(training)}}\) = The energy level that the user had just spoken which was identified incorrectly (and in this example the word is “Ek”).

Original_weight = the weight of the energy level of the original word description stored in the database. We chose it to be \(\frac{1}{2}\).

Training_weight = the weight of the energy level of the word spoken by the user. We chose it to be \(\frac{1}{2}\).

Therefore, we see that the summation of both the weights gives us 1 (and whatever weight we choose for modelling, the summation of the 2 weights has to be 1), and from this we infer that the original word description stored in the database will shift 50% towards the word description of the word that a user has just spoken.

On the other hand, the same system ends up with different word descriptions with different people, making it adaptive to the speaker’s voice. Thus our system becomes user-adaptive with time. Therefore the verdict can be reached that with time our system develops more and more accuracy for a particular user.

4 RESULT ANALYSIS

We have tested our system by categorizing words into 3 categories. They are – mono-syllabic, bi-syllabic and poly-syllabic. The total number of Bangla words we tested for our system was 50 (20 of which were monosyllabic, 20 were bi-syllabic and 10 were polysyllabic).

By “mono-syllabic” we refer to the words that have only one syllable i.e. Ek, dui, tin etc. (in Bangla) or one, good, nice etc. (in English). Mono-syllabic means the words that need only one stretch of breath to pronounce. Then bi-syllabic are words that need two stretches of breaths such as Kori (ko – ri), Kathal (Ka – Thal), Kormo (kor – mo) etc. in Bangla. Finally the polysyllabic words that we refer to are words that have more than two syllables. Example: prottutponnomotitto (prot-tut-pon-no-mot-tito), Kingkortobbobimurho (king-kor-tob-bo-bimur-ho) etc.

These are the criterions that have been kept as constant in 5 different test case scenarios. In the following subsections we analyse the accuracy of
our system as follows: subsection 1 presents the result when the system is trained by a male voice and tested with a male voice and subsection 2 presents the results when the system is trained with female voice and tested against a female voice. Subsection 3, however presents the anomalous (non adaptive) case where a female voice is tested when the system has been trained by a male voice. A similar scenario is presented in subsection 4 where a male speaker was tested on a female-trained system. Finally in subsection 5 we present the results of accuracy when we compared our system against an HMM based speech recognition software. In all the scenarios the 50 Bangla words have been evaluated as the data-set and the results are presented in regard to monosyllabic, bi-syllabic and polysyllabic cases.

1) Male voice trained – Male speaker scenario: The first test case scenario is the first and most general analysis. Here the training was done by a male speaker and the recognizing system was tested by a different male speaker. It can be intuitively derived that in this particular case the system gave one of the most optimal accuracies. The comparison of the first 4 scenarios is presented in graphical form in Figure 12.

2) Female voice trained – Female speaker scenario: This second scenario is similar to the scenario presented in subsection 1. However, it has to be noted that female voices reach higher frequencies for a particular word than that of male speakers. The natural average frequency of a male voice is 120 Hz whereas for female voice it is 210 Hz (Traunmüller and Eriksson, 1995). It will become more vivid in subsection 3. Since in this scenario the training and speaking, both have been done by a female speaker (two different speakers but both female), the accuracy reaches a relatively optimal level.

3) Male voice trained – Female speaker scenario: In this scenario, the importance of training the system becomes precise and illustrious. Intuitively we may concur that if a speech recognition system has been trained and optimized for male voice, it will not perform as well as it would for whom it was trained since the natural frequency range of females are higher (~210Hz) than that of males (~210 Hz) (Traunmüller and Eriksson, 1995). Our result coincides with this fact.

It is self-explanatory that similar results are achieved when the system has been trained using a female voice and speaker happened to be a male. The findings of this particular subsection and the next one are important to realize the importance of “training” and “user-adaptiveness” for speech recognition systems.

4) Female voice trained – Male speaker scenario: This scenario corresponds to the same test case as described in subsection 3. Due to the mismatch of frequencies, the system becomes less “speaker adaptive” and the accuracy deters considerably. The findings are presented in tabular form.

From the Figure 12 we can see that the findings are similar to that of the findings analysed in subsection 3. The aggregation of the findings of subsection 1, 2, 3 and 4 are illustrated in Figure 12.

From the findings of subsection 1, 2, 3, 4 and more appropriately Figure 12, it is clear that the more appropriate training the system gets from the speaker, the more user-adaptive it becomes and the accuracy gets higher through training. The accuracy rates presented in the paper are the accuracy rates at the time of writing the paper; however, with more training the accuracy rates, can, theoretically, get higher (getting closer to 100% by every incrementing training phase) drastically for a particular speaker.

5) Comparison of our system against an HMM based speech recognition system:

We had put our system against an HMM based (phonetic level) speech recognition software – Dragon Naturally Speaking (DNS, 2010) developed by Nuance Communications (NComm, 2010). Since the commercially developed software is phonetic based it was language independent, giving us the liberty to test it against our system but that software gave us transliterations of Bengali words in English rather than UNICODE Bangla text. The accuracy
rates that we found are illustrated below in Figure 13.

It is an interesting finding that the fuzzy logic based recognition recognizes the relatively more difficult words (polysyllabic) better than HMM systems to a greater extent than that of easier or shorter words. It also coincides to our understanding that our system gives better performance in Bangla speech since it has been specifically trained for Bangla word recognition and it works on the “word-level” rather than the “phonetic level.”

![Figure 13: Comparative result of HMM and Fuzzy logic based system.](image)

**5 CONCLUSIONS**

The system developed by us is one of the first speech recognition attempts in Bangla speech using fuzzy logic. However it is not without its limitations. This particular system could be extended to recognize continuous speech. Moreover the overall accuracy of the system could be further improved using the modern technical tools of today (even though fuzzy logic has to be the base for all linguistic ambiguity-related problems). As an end-note it can be said that speech recognition was an “open” problem before our system and it remains the same upon completion of the system – but it is a considerable step in reaching one of the solutions to an “open” problem using spectral analysis and fuzzy logic in Bangla speech.

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