A GENERIC SERVICE INTERFACE FOR CLOUD NETWORKS

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Abstract: Two major challenges for enabling the vision of cloud computing regard (a) the generic and multi-purpose access to (virtualised) resources, and (b) the flexible, dynamic, and on-demand composition of services vertically from the physical link level, all the way "up" to the application level. Both aspects require a respective flexibility and expressibility from the interfaces in-place, which is missing from the current static socket (and other) interfaces below the application level. In this position paper, we propose, explain and exemplify an alternative generic service interface (GSi) that borrows from object oriented design to enable properties such as polymorphic access, generic service composition, introspection and dynamic reconfigurability, of in-network resources; opening in this way the path for flexible creation of service clouds.

1 INTRODUCTION

For a cloud service user the ability to configure-anduse and then pay-as-you-go a utility-like service, will be of similar importance as will be for the cloud provider the manageability (introspection and customisability) of the resources comprising an offered service. To what extend is this possible today?

An observation regarding Internet related engineering is that, by antithesis to technological progress, little advancement has been made in terms of improving, standardising, and evolving our programming interfaces and design patterns. One has to take a second and ponder how much flexibility and customisability can be attained below the transport level for on-demand or dynamic allocation or federation of flow-resources (flow-based routing schemes, protocol translators, network coding, assign mobility anchors, split/merge flows for distributing processing and caching), expression of service requirements (e.g. relative prioritisation of service flows, per service security level adjustment, data-flow processing), or expression of user policy (e.g. with regard to service path selection to avoid in-transit use of an expensive provider's network, or an episodic path).

In several of these cases, mechanisms to attain such objectives may be available (or might soon emerge), but they cannot be accessed and employed programmaticaly or on-demand, due to the lack of sufficient expressibility in the available programming and user interfaces. At the top-most layer (application) of the OSI model a variety of middleware solutions, which built on top of the socket interface(Stevens et al., 2003), eased application development by aspiring more usable interfaces than the sockets API. Yet, they inevitably cannot offer more expressibility and functionality beyond what sockets provide, and at the same time they are highly proprietary, essentially lacking interoperability. These interface-level issues contribute in two of the most important obstacles for the adoption of cloud computing as pointed in (Armbrust et al., 2009), namely service availability and data lock-in.

To serve the needs of cloud computing, for responding to service demand that varies with time, there will be strong demand for more dynamic, functionally richer and more extensible programming and control interfaces. Such interfaces should (a) leverage

110 Sifalakis M., Tschudin C., Martin S., S. Ferreira L. and M. Correia L.. A GENERIC SERVICE INTERFACE FOR CLOUD NETWORKS. DOI: 10.5220/0003449501100119 In *Proceedings of the 1st International Conference on Cloud Computing and Services Science* (CLOSER-2011), pages 110-119 ISBN: 978-989-8425-52-2 Copyright © 2011 SCITEPRESS (Science and Technology Publications, Lda.) dynamic federation of resources and composition of services (within and across cloud providers), and (b) allow introspection of service state and on-demand customisation of service configuration.

Starting from this tenet we explore the potential of adopting object orientation for describing network functions and services. We present the *Generic Service* abstraction and interface (GSi) as an alternative to the legacy socket API, that provides constructs for describing in-network processing and transportation services on data flows and across (heterogeneous) network(s). We explain how it is possible through this framework, to preserve service modularity, enable abstraction, provide access to the dynamic state in the network (and in doing so effect cross layering), reuse algorithms, and compose network-based services in a structured and accountable way.

In the remaining of this article we first motivate our work (section 2) by sketching the shortcomings of the socket API for the purposes of cloud computing. Then in section 3, we advocate the benefits of object-orientation for the design of cloud services and then we present and exemlify the *Generic Service* framework and interface. In section 4 we provide a use case and early proof-of-concept validation for a service cloud that provides multi-hop Wireless Mesh Network (WMN) paths as services. In section 5 we provide an exploration of the literature and finally in section 6 we conclude this paper.

2 MOTIVATION

TCP/IP was initially intended and served as a least common denominator for heterogeneous networks allowing application inter-operation across them, thus anticipating and necessitating a global deployment everywhere. As a result of this global adoption, the socket interface enabling access and configurability to the services of a TCP/IP stack, became a common denominator and the only de-facto standard API for building network services. However, today's reality is somewhat more complex. Network convergence, resource *virtualisation* and *multi-tenancy* in cloud computing, require more than mere bridging of different link-level transports, with a common overlay. One, cannot factor out the additional diversity and heterogeneity of applications and system resources.

The socket interface appears to be rather restrictive in expressing the dynamism and plasticity necessary for engineering custom services, integrating new methodologies (Akyildiz and Wang, 2008; Chiang et al., 2007) and diverse technologies, and embedding new functions in the network stack. Regarding the last, it is worth noting that most operating systems today provide frameworks for enriching a systems network functionality, but is enabled through proprietary interfaces not programmatically expressed at the socket level. In this section we explore the main limitations of the socket API that need to be addressed in a "modern" API suitable for the purposes of cloud computing and network convergence.

Static coupling of mechanism and function. The first problem we see with the socket interface is that it is tailored to the mechanism (TCP/IP protocol suite) and not the functionality it serves (network communication). This is due to the protocol-centric evolution of the Internet under the domination of TCP/IP, which led to a static interface that cannot be easily extended to accommodate new configuration options and parameters, beyond those that are available for the current TCP/IP stack. This in turn has led to technological dependencies, which are difficult to get rid of, the most probably prominent of which is the locator/identifier coupling: for example separating the location from the endpoint of a communication has not been feasible without re-engineering of the interface.

Lack of modularity. A second problem is the lack of modularity since a socket expresses in a monolithic way the functionality of a complete stack (and therefore a fixed set of functions). However, today it has become more apparent that a full-fledged protocol suite is neither necessary nor suitable everywhere: Grids of very small devices such as sensors and RFIDs may not have the resources to operate a complete TCP/IP stack, or they may not need it (e.g. full mesh networks do not require routing). In other cases the underlying network technologies may already have their own transport level and network level functionality (Howell, ; Joel, 1993). Reinforcing TCP and IP over them for facilitating network-convergence can be far from efficient and complicating for management. At the same time this means that any alternative composition of network functions and federation of network services cannot be expressed.

Opacity. Another important problem is that the sole perspective expressed in the socket interface is an end-to-end transport level view of the network. All other functions and their parameters are indirectly (and insufficiently as it is) represented in transport level options and abstractions. This does not allow deep introspection and fine grained control or configurability of the individual functions in the stack, which is why cross-layer designs rely on additional ad-hocly defined interfaces.

Limited expressibility. As illustrated in Figure 1(b) the layered design of the TCP/IP stack considers, and expresses in the socket interface, the interactions

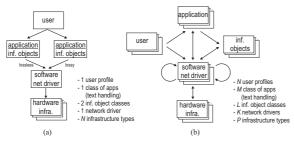


Figure 1: Old versus today's interaction models.

between two entities as communication determinants: (a) the **user application**, which is the user's interface and policy broker towards the network; generating information objects and selecting *how* they should be delivered, and (b) the **hardware infrastructure** over which communication is provided.

The challenge faced today however, is more realistically depicted in Figure 1(b): the number of communication determinants and the possible interactions is larger and the scope of these interactions is more dynamic. Multimedia traffic has introduced a dynamic set of (often mutually interacting) information objects with more diverse delivery requirements than lossy/lossless, including timeliness and spatial synchronisation. Moreover, these information objects often interact with the network beyond the context of mere forwarding (e.g. caching, transcoding or other in-network manipulation functions). The application is not always under explicit user control and interacts with the network in other roles than as a source or sink of information objects (e.g. for handling of mobility). The user (or service initiator), on the other hand, often directly interacts with the network driver (e.g. establishing vpn connections, setting routing rules, performing admission and rate control, selecting interfaces, etc). Finally, new infrastructure technologies permit customisability based on continuous feedback from the network driver for better adapting to service requirements (e.g. soft and cognitive radio, error control, security, etc). And, as a result, the network driver in order to serve effectively this immense diversity necessitates dynamicity beyond routing path selection, in the order to employ appropriate service functions and utilise effectively a physical infrastructure, richer and more diverse than ever before (wired, wireless, multi-hop, ad-hoc, infrastructured, etc).

3 GENERIC SERVICE INTERFACE (GSi)

In this section we try to bash into the aspects discussed so far by considering object orientation as an approach and proposing a modular programming and user interface for dynamically composing and accessing network services.

3.1 Object Orientation in the Design of Network Interfaces

Object orientation provides a generic and structured way for separating functionality from mechanism: a (abstract) class provides the representation and specification of a type of function or service, while its interface represents generic semantics for accessing a mechanism that implements this function. Derived typed class objects then, embody different mechanisms. This distinction allows a clear separation of incentives and roles for a *user* and a *provider* of a network service. A user for example can concentrate on the service provided as opposed to the intrinsics of the service fabric. Encapsulation of mechanism in service classes, in this way, also promotes the invariance of mechanisms (e.g. different providers may offer the same service, that a user can access invariably).

Selective *information hiding*, at the class interface, allows controlled access to the intrinsics of a mechanism and helps the tractability of cross dependencies between different services. Combined with *Polymorphism*, it allows "deep" introspection of state, explicit invocation of service functions across intermediating functions, and provides a consistent methodology for representing and extending the interactions among service functions. This practise enables a consistent way of acquiring "cross-layer" information in an entire composite service and alleviates one of the major concerns currently, against the adoption of many proposed cross-layer optimisations; namely the ad-hoc and intractable nature of interactions that they create.

Function *overloading* can be used to extend the definition and semantics of an operation or service function, in order to group a set of semantically related services under a common usage framework (and interface). It also enables other attractive capabilities that empower cloud services, such as creating new services from existing ones (to leverage composition), encouraging algorithmic and functional reuse at different levels of abstraction (to assist virtualisation), integrating and importing new functional features into services in non-disruptive ways, etc.

Several of these features have been already exploited at and above the application level to improve the usability of application platforms, albeit in proprietary ways and without much intend for standardisation. One only needs to explore the multitude of application level middleware platforms. On the other hand,

less intend has been seen below the socket boundary, living the space inside the network stack rigid and untouchable to any customisability and optimisability.

3.2 Formalising Network Services

The *Generic Service* interface (GSi) opts to express in a universal way network servicing at different levels. In order to account for all types of services however, we first need a network service formalisation, so that a common interface can be applied to them. Fortunately this does not seem to be so difficult.

From a high-level view a network service corresponds to the handling of data as they flow across a network, which typically involves processing $P(\cdot)$ and/or transportation $T(\cdot)$ operations. For example, an Ethernet link implements a service that applies a transportation operation on data, while a VPN service involves two processing operations (encryption and decryption) in combination with a transportation operation (e.g. PPTP (Hamzeh et al., 1999)). We can therefore symbolically represent a network service on data *x* as

$$S(x) = \{P_i(x), T_j(x)\}, \quad i = 1..n \quad j = 1..m$$
 (1)

It draws that every P_i and T_i in this definition may be regarded as another lower-level (or more basic) network service, which immediately allows us to symbolically express the dependency of complex (composed) services in terms of simpler ones as

$$S^{C}(x) = \{S_{i}^{P}(x), S_{j}^{T}(x)\}, \quad i = 1..n, \quad j = 1..m$$
 (2)

or equivalently in a more convenient recursive symbolism (not having to distinguish transportation from processing services)

$$S_k(x) = \{S_{k-1}(x), S_{k-2}(x), ..\}$$
(3)

Finally, to represent service composition in this formalisation, all we need is to specify a composition function $f_c(\cdot)$ that describes how the complex service is provided from its dependants.

$$S_k = f_c(S_{k-1}, S_{k-2}, ..)$$
 (4)

Such a composition function is likely to express the integration of the dependant services in terms of interfacing, ordering, or other criteria, lending to systematic ways of expressing federation (for example in (Sifalakis et al., 2011) f_c is reduced to a declarative description of data flows, while in (Cobbs, 2011) it is expressed by a functional program).

Following this simple high-level formalisation we are now ready to introduce the object oriented *Generic Service* interface (GSi) structure.

3.3 The *Generic Service* Interface

Our aim is to provide programming and control primitives for generic and implicit access to data manipulation and transportation operations, configurable parameters and service state, such as the underlying service mechanisms may permit. Following an object oriented design strategy, service specific functionality is encapsulated in subclasses of an abstract base class that defines the generic interface. Figure 2 shows the structure of the base GSiclass containing a list of elements (*Items*), which may be one of the following:

I/O Points. They represent data inputs/outputs of the service. These may be identifiable protocol endpoints, such as a network address, a port number, a medium access control channel, or a service handler, file descriptor and other system local constructs used to send/receive data. They provide access to the data plane of a service and they can also be used in "plumbing" operations between service functions (dynamic service composition), besides data I/O.

Mediation Point. The data inputs and outputs of generic services that compose higher order services are plumbed together at mediation points. Exposing this construct at the interface level provides a broker interface for (re-)configuring on-demand the composition of a service and the federation of resources. For example if the GSirepresents a routing service or flow aggregation service in the network of a provider, the mediation point would provide a control interface for installing or modifying routing rules/filters. By analogy, if the GSirepresents a network storage service purchased by a user, the mediation point would be an interface to a virtual array of disk slices, where he may release some of them to reduce the cost encountered for the service.

Composing Generic Service List. An optional list of lower order service functions/resources (symbolised as $S^T(\cdot)$ and $S^P(\cdot)$ earlier) on which the generic service depends. The composition function (see $f_c(\cdot)$ earlier) that specifies how these service functions integrate together to provide the higher order service may also need to be known, in which case it can be revealed in the *Attribute List* next.

Generic Service Attributes. A list of configurable parameters and state values related to the service provided. They may be parameters for indirectly modifying or customising the service or state values corresponding to information available e.g. for monitoring the operation or quality of the service. Depending on the type of service or function that the GSiexpresses, they may related to a physical or virtual interface, pro-

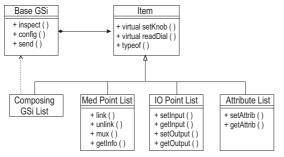


Figure 2: Base GSi class layout.

tocol state, service quality, and so forth.

It is worth noting that while the *I/O points* provide access to the data plane of a service, the *attribute list* on the other hand, exposes the control plane, and a *mediation point* provides management plane access. Therefore, one interface empowers combined operations across all three planes.

A number of interesting capabilities stem from the object oriented design of the GSi.

First, all *Items*, may export a set of *Knobs* and *Dials*¹, as generic configuration and introspection capabilities across the different *Item* types and GSiclasses. By employing *polymorphism* (object oriented design), one can set configuration information or read attributes in a generic service class and recursively to all its composing sub services as one operation. In this manner, a configuration parameter expressed at a high level has a simultaneous effect on a number of other parameters across an entire system. Similarly, monitoring a state value at a high level resolves in deep introspection across the service stack, naturally supporting cross-layer design.

Second, through the virtual function mechanism it becomes possible to dynamically *associate* attributes of a generic service class to respective attributes of its *Items* and sub services without compromising the modularity of the services. For example it is possible to relate a user level qualitative metric of a service (e.g. good, secure, stable, etc) to state information from the underlying infrastructure (e.g. throughput levels, end-to-end encryption, error-rates, etc).

Third, although interoperability and compatibility across services is guaranteed through the unified interface of the abstract generic service class, still at the same time, a provider of a service has the flexibility to decide what level of access will be allowed for the service user (both regarding state information and access for configuration) by offering the service in typed subclasses with reduced attribute lists or reduced functionally interface primitives.

Finally, and very importantly, once we have managed to generalise the interface of services, it becomes possible to also generically express and implement service composition as a set of operations over a set of Generic Service classes (e.q. 1 earlier). This can be done by means of the object-oriented notion of generic operators, which represent algorithms that implement operations on abstract elements (operands). They can be developed agnostically to the nature of their inputs and outputs, which makes highly re-usable mechanisms possible for any set of objects that respect certain interface rules. Generic operators may provide a common framework for expressing data flow manipulations (such as network coding, aggregation, etc), or resource federation operations (e.g. clustering, mirroring, etc) for virtualisation. When combined with meta descriptions that extensively specify the interfacing potential between different types of I/O points, they empower a dynamic and extensible compositional capability for services.

3.4 Compartments and Clouds of Generic Services

According to (Armbrust et al., 2009) the novelty in cloud computing lies in (a) the illusion of an infinite computing resource available on demand, (b) the elimination of an up-front commitment by cloud users that allows one to start small and increase resources following their needs, and (c) the ability to pay-asyou-go for the use of resources on a short-term basis. From these assumptions stem the feature requirements for a *cloud*: it should define and appear as one homogeneous resource/service pool, that has specific policy and account rules, and its own local dynamics and resource management/pooling mechanisms (isolation). These requirements do not undermine the interoperability across clouds; rather they prescribe the self-consistent and dynamic nature of a cloud, which is therefore more than an administrative domain (it includes separation of mechanisms), or an autonomous system (it encompasses more than routing dynamics), or a service layer (it integrates vertically different resources and network functions/services). This means that the cloud concept requires a new contextualisation abstraction and also an interface representation at a resource level that allows to request and access services. Moreover, to leverage interoperability across clouds, this interface must successfully embed the cloud features but should not interfere with the mechanisms that implement them.

The *Compartment* construct and interface in (Bouabene et al., 2010; Randriamasy, 2009) offers a suitable abstraction that captures the essence of a

¹The metaphor of knobs and dials is inspired by (Calvert et al., 2007).

cloud. *Compartments* contextualise communication and information services of different scales or functional complexity (from a single link, a domestic network, an enterprise network, to large federated structures). At the same time they reflect the presence of policy domains for decisions (Paul et al., 2008). On the other hand, how a specific service is implement in a *Compartment* does not impact the service users, nor does it impact decisions on policy, access control and quality of service, in other *Compartments*.

In the context of *Generic Services* and their object oriented design, compartments act as *extended namespaces* for addressing/accessing generic services and control elements that need to be locally identifiable. Moreover, a *Compartment* provides the cloud interface that one may use to request a generic service by means of two primitives: (a) one for registering service points, and (b) another for accessing services at these service points. In this way modularity is preserved at the policy level and the functional level.

In summary, *Generic Services* create a premise for *functional plasticity*, service composition and virtualisation, while *Compartments* provide the context for *virtualisation* and the demarcation of cloud domains. The example that follows will introduce the Compartment interface as a interface for clouds, and will highlight its use with *Generic Services*.

3.5 Programming with the GSi

In the scenario of Figure 3, two applications establish a voice call over a telephony service cloud (*cVoice*), which integrates the underlying services of two candidate technologies (called Skype and GSM); in turn provided by respective clouds providers. Initially, the voice communication between two named entities in the *cVoice* cloud uses a carrier service from the *cSkype* cloud. When the observed quality drops below a threshold level, the carrier service transparently switches from the *cSkype* cloud and to the *cGSM* cloud. Access and configurability of the different service components is effected through the GSiinterface.

A user requests for a cloud service (i.e. creation and initial access to the service) through the Compartment interface as exemplified in the code fragment 4(a). A **publish** call (line 2) requests association with the cloud (registration) of the name sylvain, and is used as the listening end for connection requests. The registration of the name manos (Figure 3) would be performed in a similar way. A **resolve** call (line 3) is used to request a voice connection to manos in *cVoice*. The successful activation of the service returns a GSiobject gM which can be used (line 4,5) for accessing and managing the service resources (in this

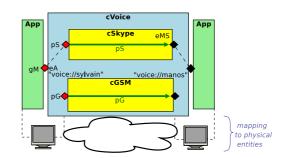
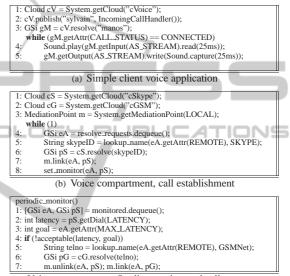


Figure 3: an abstract *cVoice* cloud (compartment), federating *cSkype* and *cGSM* infrastructure clouds (compartments).



(c) Voice compartment: Quality monitor and call management

Figure 4: GSi and compartment API example.

example using the I/O points to send and receive voise samples).

At the provider end (the cVoice cloud) the code that services the user request is shown in Figure 4(b). Upon receiving the service request, a voice connection needs to be established over one of the infrastructure clouds cSkype or cGSM. In line 4, the service request by the user (resolve call in 4(a)) results in preparing up a GSiobject (eA) that will be passed to the user when the service is activated. This is analogous to creating an unconnected socket for communicating with the network stack. Next, the call request to manos is looked-up and recursively resolved in the cSkype cloud (line 5-6). In other words, the cVoice cloud is now requesting (as a user) a service from the cSkype cloud, which results in the instantiation of the *pS* GSiobject when the connection is established. The process is completed (line 7), when the local mediation point is used to link the GSiobject from the cSkype cloud to the GSiobject that will be returned to the user by the *cVoice* cloud. This involves interfacing the I/O points (data-plane plumbing) and linking through any service attributes (control plane set up).

Finally, in Figure 4(c) we show the ease for automating service re-composition through the GSi, in order to satisfy dynamically user requirements for service quality. A call quality monitor function (activated in line 8 of 4(b)) reads the attribute in the GSiobject of the cSkype cloud that holds latency measurements (line 2), and compares them to a quality threshold set by the user (in an attribute of the cVoice GSiobject). When quality drops below the set threshold level, the mediation point is used to transparently replace the cSkype service with a new one (similarly established and accessed by means of the GSi) in the cGSM cloud (line 5-7).

4 A USE-CASE IN WIRELESS MESH NETWORKS

WMNs lay on the evolutionary path of wireless networks, by extending the single-hop access wireless paradigm to multi-hop ad-hoc (backhaul) networks that combine heterogeneous radio access technologies. In this sense, WMNs intend to provide cloud-like services by federating different wireless link resources under a unified dynamic wireless multihop infrastructure. In the achievement of this goal a number of challenges manifest the need for cross-layer design (Akyildiz and Wang, 2008) in order to integrate effectively the diverse wireless network technologies (802.11 (IEEESTD.5307322, 2009), 802.16 (IEEESTD.265774, 2005), LTE (LTE-SAE, 2008)) and radio communication solutions (multiradio/multichannel nodes, directional antennas, etc), in face of heterogeneous QoS constraints, multihop relaying, and variability in link capacity. A second challenge is presented as a requirement for distributed management and dynamic coordination, in order to allow the network to self-configure ("plugand-play" fashion), organise and optimise its servicing capacity, and incorporate self-healing capabilities in case of failures.

A typical example regards the effective allocation and federation of non-interfering radio channels in order to improve mesh node communication and multipath capabilities in a dynamic network topology. A promising research direction considers the use of mesh nodes, equipped with several radio interfaces operating simultaneously on multiple radio channels in combination with a channel allocation strategy that effectively assigns channels/carriers to radio interfaces, in order to maximise channel utilisation and minimise interference. A fixed wireless channel assignment among mesh nodes results in statically enforced topologies, analogous to the wired ones, however, with variable quality or episodic connectivity (due to the susceptibility of the medium to noise and interference). Hybrid and dynamic solutions on the other hand, where some or all radios switch dynamically channels, increase inter-connectedness at the cost of management and algorithmic complexity.

In (Ferreira et al., 2010) a novel distributed cooperation framework is presented, which allows the network to take advantage of the local resources and characteristics of nodes (communication capabilities, surrounding environment, mobility pattern, persistence, energy, computation capacity) in an opportunistic fashion. Each node may assume any network role in the mesh (resource management, network gateway, forwarding, address assignment), contributing in the collective optimisation of the network.

In (Randriamasy, 2009), a hybrid channel assignment strategy is proposed, where every node assigns channels to its interfaces following an interference minimisation model. It enables self-organization and provides stable interconnection by pooling the per-technology channel frequencies (cloud resource) into equivalence classes, and allocating them in a way that minimises a cost function (resource virtualisation/multi-tenancy strategy).

In the following sections we show how the use of the *Generic Service* interface can ease the design of a WMN cloud service which combines the ideas from (Ferreira et al., 2010; Randriamasy, 2009) to provide stable wireless paths as cloud resources.

4.1 Wireless Resource Abstractions and Interfaces

In order to exploit multiple wireless network interfaces simultaneously, we eventually have to address the heterogeneity of the different wireless technologies. Moreover, radio channel resources must be partitioned in the physical dimensions of time, frequency, space and/or code to allow multiple logicallyindependent communications to take place simultaneously (resource pooling and distribution).

This necessitates two steps of composition, one for the federation of different wireless link technologies and a second for the virtualisation (temporal, spatial and frequency multiplexing) and allocation of radio channels over them along a multi-hop wireless path. The modularisation and abstraction of the WMN cloud functionality can be therefore implemented in three levels: (a) at the lowest level a GSiinterface (GSi_{wLLC}) provides access and management of the wireless interfaces, (b) at the middle level another GSiinterface (GSi_{rMAC}) multiples the wireless interfaces and abstract them in virtual channel interfaces, and (c) at the top layer a third GSiinterface (GSi_{WMN}) abstracts the federation of channel links in WMN service paths. The last represents the interface to the service delivered to the cloud user.

As shown in Figure 5 different GSi_{wLLC} class objects (WiFi, LTE, WiMAX, etc) are interchangeably federatable in the list of *Composing Generic Services* of a GSi_{rMAC} class and can be controlled by means of software radio techniques and using internal (in the GSi_{rMAC}) multiplexing strategies. Figure 5 schematically exemplifies also common attributes in all wireless link technologies, which may be exposed in the attributes of the generic GSi_{rMAC} interface.

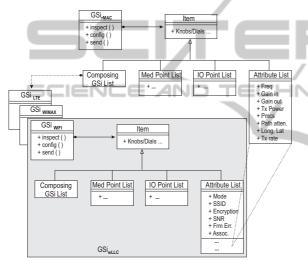


Figure 5: A *GSi_{rMAC}* object providing virtual access to multiple *GSi_{wLLC}* objects.

4.2 Dynamic Channel Allocation and Path Resource Management

Having localised and abstracted the various technology-specific mechanisms (GSi_{wLLC}) and virtualised them as single-channel resources (GSi_{rMAC}), one can then develop flexible, dynamic and technology-agnostic resource management mechanisms for a cloud service. Although in this case study we have concentrated on a channel management strategy, other cloud mechanisms may as well include routing schemes, power/rate control, coding frameworks, QoS frameworks, etc.

The active topology is established through a set of instantiated GSi_{rMAC} service objects that hold the dynamic interconnection state in the cloud. Such dynamic information includes estimates of the

average channel activity and utilisation/contention, queue associations, received power/noise estimates from competing wireless clusters, hop-distances to gateways and respective path attenuation, queue occupancy, and other. Most of this information being estimated relies heavily on information acquired, through the same recursive API, by the active wireless link interfaces, (i.e. *GSi_{wLLC}* objects).

Within the WMN cloud, and for purposes of management and control, an GSi_{rMAC} object and an encapsulated GSi_{wLLC} objects provide access to the same wireless link resource, enabling joint customisation though either of two different but parallel interfaces, each serving a different management objective: On one hand, the GSi_{wLLC} object provides exclusive technology-oriented management of the wireless interface and through it to the link services it provides to different flows. On the other hand, the GSi_{rMAC} object permits customisation of the wireless interface on a per-channel basis and the temporal virtualisation a radio channel across multiple wireless interfaces.

Regarding the user perspective of the cloud service, all mesh nodes along an active WMN path, can be identifiable and accessible in the context of a WMN generic service (not in terms of its physical location, but rather through the GSi_{WMN} object) as a *Mediation point*. They in turn, maintain upto-date dynamic information, which is useful to the cloud provider (and optionally to the cloud user) including the distributed data structures for routing and neighbour tables, channel usage, as well as information about the node locality or operation environment (e.g. geo-position, power decay and shadowing, gaussian noise, and other).

4.3 **Proof-of-Concept**

In an early proof-of-concept validation² of the aforementioned design and the channel management mechanism from (Randriamasy, 2009) we created a mesh topology, where 13 nodes (MAPs) form a backhaul WMN network compartment, and each node lies in the communication range of three others. One of the mesh nodes provides gateway connectivity to the Internet. Each MAP is equipped with 3 wireless interfaces (accessed through GSi_{wLLC} classes): one IEEE 802.11b for providing connectivity to end-users, and two IEEE 802.11a for backhaul interconnection with other MAPs. The two IEEE 802.11a interfaces on every node were thus available to the GSi_{rMAC} classes for channel management. The gateway establishes WMN paths (GSi_{WMN} objects) to each MAP, for sending flows of UDP packets (servicing end users),

²Using the OPNET Modeler simulator

of average size 1500 bytes, and constant rate 12 Mbps for 802.11a interfaces and 11 Mbps for 802.11b.

In the proposed channel assignment strategy, by changing the GSiattribute (in the GSi_{rMAC} objects) for the number of available channels for mesh forwarding, from 3 to 6, improves the observed quality of the service at the GSi_{WMN} service objects. This is shown in Figure 6 for the per-node throughput, where going from from 3 to 5 channels, results in an increase from 1 Mbps to 1.6 Mbps. Using more than 5 channels does not increase further the performance of the network, because of the upper limit of the channel capacity at the gateway.

The maximum theoretical throughput at the gateway node, with its two radios operating at 12 Mbps, and considering an overhead of 15% introduced by the MAC and PHY layers, is 20,4 Mbps. The use of 5 channels in the simulation, serves 12 multiplexed flows of 1.6 Mbps, totaling an effective throughput of 19,2 Mbps. This means that 96% of the theoretical capacity of the WMN is exploited eliminating almost completely channel interference problems on the wireless medium of such a multi-hop network.

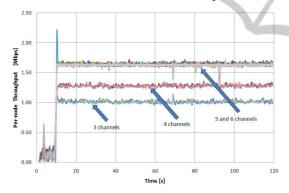


Figure 6: Per-node throughput, for increasing number of channels.

These results, of course do not suggest that virtualisation and dynamic channel management is only possible through the *Generic Service* framework. Nevertheless, they demonstrate how easy it becomes to introduce or remove dynamic functionality without substantial re-engineering effort for adapting the interfaces, in a non-disruptive way.

5 RELATED WORK

A large number of efforts have appeared in the literature that aim to address the lack of dynamicity in the Internet architecture. Many of them provide solutions at the mechanism level within the current architecture, and several focus on interfacing and extensibility within or across certain layers (e.g. cross-layer design literature and active networking). Few other have proposed alternative architectures and communication paradigms as a solution. As a general comment our main difference to those approaches is that we do not advocate a new Internet architecture, or the modification of specific interfaces in order to enable dynamicity for one mechanism or another. Rather, we take a more distanced approach proposing an (additional or alternative) interface for service mechanisms, which is generic everywhere. It will inevitably lead engineers to re-consider the way new services are designed and implemented, but does not necessitate the re-engineering of existing mechanisms.

In the *role-based architecture* (Braden et al., 2002), the authors consider a component-based model founded on service roles as an alternative to the current layer model. Although an important step is being made towards more modular, flexible and extensible model, the authors do not go as far as proposing the adoption of object orientation. A step towards the opposite direction is taken in the NIPCA architecture (Day, 2007), whereby a process-based modelling of network communication is advocated, leading also to a recursive or unified interface across different levels of abstraction, however such a flat procedural-programming style API is not less static than sockets (Stevens et al., 2003).

In i3 (Stoica et al., 2004), the authors adopt indirection as a fundamental construct for on-demand inter-stitching of network services, by means of a publish-subscribe interface. Similarly to the i3 model the earlier work in *Plutarch* (Crowcroft et al., 2003) also promotes indirection and additionally localisation of service functionality in policy domains, whereby global inter-network services can be established across service contexts. Both, propose interfaces that can be useful as an alternative to the Compartment interface we consider in this paper, for requesting and associating the end user to cloud services (as GSi objects). The power of indirection has been also exploited, more intuitively programmatically, in the network pointers model (Tschudin and Gold, 2002), and has been adopted in the ANA architecture (Bouabene et al., 2010). Although, this interface is not object oriented and neither as expressive as GSi, the network pointers model achieves functional polymorphism and dynamic service composition at a very low level.

Another aspect of object orientation, namely abstract services and recursion of protocol functionality is being architecturally explored in the Recursive Network Architecture (Touch et al., 2006), whereby layer functionality is organised and developed in *pro*- *tocol containers*. This work goes beyond the interfacing level to enforce a certain engineering practice in order to be adopted.

6 CONCLUSIONS

We have proposed the adoption of object orientation in the design of a new generic interface (model) for network services, alternative to sockets and all proprietary solutions above the application level. Our approach builds on the generalisation of a network service captured in a simple construct and a set of primitives that promote extensibility and support (at the interface level) dynamic federation/composition of services; for creating higher order services and virtual resources. We presented the most important aspects of the Generic Service model and exemplified its use. In the end we carried out an engineering exercise for the design of a service cloud that provides wireless multi-hop paths as services, which comprise of interlayer resources and rely on distributed resource management and cross-layer information exchange; approaching in this way as close as possible the cloud reality.

Our aim in follow-up work is to experiment more extensively with the *Generic Service* interface model and declarative formalisation, in different cloud service contexts, so as to improve its expressibility and establish its plasticity.

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