A CHAOS BASED ENCRYPTION METHOD USING DYNAMICAL SYSTEMS WITH STRANGE ATTRACTORS

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Keywords: Lorenz system, Dynamical system, Strange attractor, Dynamical cipher block.

Abstract: In this paper, one approach for using dynamical systems with strange attractors as cipher system is introduced. The necessity of Synchronization for this type of system is discussed in depth and an applicable chaotic encryption-decryption system, some of which is specialized for image cryptography, is developed. The developed system is based on a discrete modification of the Lorenz dynamical system. Synchronization features and spatial and spectral properties of the system are obtained experimentally.

1 INTRODUCTION

Many block cipher encryption methods are in use, among them are: EBC, CBC, NDS, CFB and OFB (Menezes, 1997) and (Beker, 1982); block cipher methods are also common in the field of image and speech cryptography. The method which will be developed in this text uses dynamical systems with strange attractors to map an image in to a ciphertext. Image can be defined in its traditional form.

Definition: Image is defined as a 2-D discrete function $f(x,y)$ with the range of [0-255], where the amplitude of $f$ is the intensity of the pixels of the image (Gonzalez, 2002).

Unpredictable behavior of deterministic systems has been called chaos. The word "Chaos" was introduced by Tien-Yien Li and James A. Yorke in a 1975 paper entitled "Period Three Implies Chaos" (Li, 1975). The term "strange attractors," first appeared in print in a 1971 paper entitled "On the Nature of Turbulence" (Ruelle, 1971). Some people prefer the term "chaotic attractor" (Sprott, 1993).

Many dynamical systems does not have a unique point or set of points as their attractor but rather a complicated geometrical object which according to (Sprott, 1993) is called strange attractor. A more precise definition of strange attractor is included here.

Definition: If an attractor for a dissipative system has a noninteger dimension, then the attractor is a strange attractor of that system.

Among the features of strange attractor with respect to (Hilborn, 2000), is the ability of trajectories to remain within some bounded region by intertwining and wrapping around each other (not intersecting) and without repeating themselves. The geometry associated with these attractors makes them capable of generating pseudo random sequences, the noise like features of which can be used for cryptography. The dependence of the systems with strange attractors to the initial conditions makes them less predictable and therefore more reliable for our purpose. But it increases the need for a precise synchronization between the encryption and decryption systems.

The next section is concerned with the design procedure of the cipher system. Section 3 introduces an applicable cipher system based on the theory of section 2. The applicability of the system is shown through some experiments in section 4.

2 DESIGN STEPS

According to (Menezes, 1997) a block cipher is defined as below.

Definition: An n-bit block cipher is a function $E: V_n \times K \rightarrow V_n$, such that for each key $K \in K$, $E(P,K)$ is an invertible mapping (the encryption function for $K$) from $V_n$ to $V_n$, written $EK(P)$. The inverse mapping is the decryption function, denoted $DK(C)$. $C = EK(P)$ denotes that ciphertext $C$ results from encrypting plaintext $P$ under $K$. 
In this work the blocks are different from the above definition, where blocks are defined as \( n \times m \)-byte matrices instead of \( n \)-bit blocks. A block cipher whose block size \( n \) is too small may be vulnerable to attacks based on statistical analysis (Menezes, 1997), as a consequence of this study we will use large blocks with large keys. Specialization of the system for image cryptography encourages us to take the size of our block as large as the size of normal images.

The overall system scheme can be observed in Figure 1 and Figure 2 where the Encryption/Decryption Dynamical system is a dynamical system with strange attractor which means it is a state space differential/difference equation, that has at least three dimensions (three state variables). (Hilborn, 2000) One of the state variables can be used for developing the Cipher block matrix (Figure 1 and 2), while one other state variable will be updated at every iteration under the influence of the private key (this process will be discussed in detail). For a dynamical system of the form \( u(n + 1) = f(u(n)) \), if \( u_0(n) \) is the variable that chosen to develop the Cipher block matrix and if we start the generation of Cipher block at some time \( N \) then:

\[
Cipher \ block = T_\mathbb{N} \left( u_0(N), u_0(N+p*k), u_0(N+q*k), \cdots, u_0(N+(p+q-1)*k) \right) \tag{1}
\]

Where \( p \times q \) is the size of the block and \( k \) is a time step parameter. Needless to mention that a transformation \( T: \mathbb{R} \rightarrow \mathbb{N}: [0,255] \) is necessary in the process of Cipher block matrix because this matrix should take part in XOR operation.

There are two phases in encryption-decryption process. First the synchronization phase in which the Encryption system generates a synchronization key (sync) and decryption system updates its initial condition in accordance with the synchronization key. The synchronization key can be a dynamical public key or it can be sent out via a secure channel. The second phase is the encryption/decryption under the influence of the private key.

After every execution of the second phase, the initial conditions of the state equations will be changed and therefore the generated Cipher blocks will be completely different from each other using a constant private key.

As introduced by Pecora and Carrol in (Pecora, 1990) two dynamical systems can be synchronized in certain conditions. The aim of synchronization in our work is to enforce two equal dynamical systems (with different initial conditions) to generate the same Cipher block matrices in both of the Encryption/Decryption dynamical systems.

It can be shown that two identical chaotic systems can be synchronized if they are coupled together in an appropriate way (Stavroulakis, 2006), that is to decompose a chaotic system in to two subsystems (Stavroulakis, 2006). An \( n \)-dimensional chaotic system with state-space equation \( \dot{u} = f(u) \) can be decomposed in to two subsystems \( \dot{v} = g(v,w) \) (\( k \)-dimensional) and \( \dot{w} = h(v,w) \) (\( m \)-dimensional) where \( n = m + k \). Now to drive a response system with an equation the same as \( \dot{w}' = h(v,w') \), we calculate the variable \( v \) from \( \dot{v} = g(v,w) \) and substitute it in the response system, taking \( w_\delta = w - w' \)

\[
w_\delta = h(v,w) - h(v,w') = D_w h(v,w) * w_\delta
\]

for small \( w_\delta \) and \( D_w h \) is the Jacobian of \( w \) subsystem. For synchronization to happen \( w_\delta \) need to go toward zero and therefore the lyapunov exponents must be negative. Although the above conditions are derived for continues dynamical systems, experiments and simulations show that they are applied to the discrete modification of Lorenz system which will be introduced in the next section.

Synchronization in our case occurs in an offline form, which is to generate a synchronization key by the Encryption Dynamical system (Sync in Figure 1) and then the Cipher block will be generated. Using the synchronization key, The Decryption system can update itself to the initial conditions of the Encryption system before generating the Cipher block.
3 LORENZ CIPHER SYSTEM

In this work Lorenz dynamical system was used as Encryption/Decryption system (Figures 3 and 4). The original Lorenz dynamical system (Lorenz, 1963) is a continuous dynamical system with state equations:

\[
\begin{align*}
\dot{X} &= -\sigma \cdot X - \sigma \cdot Y \\
\dot{Y} &= -X \cdot Z - r \cdot X - Y \\
\dot{Z} &= X \cdot Y - b \cdot Z
\end{align*}
\]

(2) (3) (4)

\[\sigma = 10 \quad b = 8/3 \quad r = 28\]

A modified discrete version of Lorenz system is defined here with a difference equation of the form:

\[
\begin{align*}
X(n+1) &= X(n) + h \cdot (-\sigma \cdot X(n) - \sigma \cdot Y(n)) \\
Y(n+1) &= Y(n) + h \cdot (-X(n) \cdot Z(n) - r \cdot X(n) - Y(n)) \\
Z(n+1) &= Z(n) + h \cdot (X(n) \cdot Y(n) - b \cdot Z(n))
\end{align*}
\]

(5) (6) (7)

\[h = 0.01\]

A new parameter \(h\) is introduced above which is the length of time step. This parameter should be taken carefully not to destabilize the system. While taking \(h\) smaller than 0.02 observed to work well, a precise discussion of stability with respect to \(h\) is beyond the scope of our work. The discretized Lorenz system allows faster computations in cipher system.

The result for running these equations (without taking a private key in to account) for 10000 iterations is plotted in Figure 5. \(X, Y, Z\) are plotted against discrete time \((1000 < n < 3000)\) in Figures 6, 7 and 8.

In this work state variable \(Y\) was chosen for filling the Cipher block matrix and transform \(T\) fits the range and quantizes the generated numbers. \(T(Y) - Z\) is plotted in Figure 9. (No key was used here).
For testing the synchronization condition on this system we break it into two subsystems:

\[
\begin{align*}
\dot{Y} &= -X + Z - r \cdot X - Y \\
\text{And} \\
\dot{X} &= -\sigma \cdot X - \sigma \cdot Y \\
\dot{Z} &= X + Y - b \cdot Z
\end{align*}
\]

Assuming two Lorenz systems with different initial conditions:

\[
\begin{align*}
\begin{bmatrix} w_{11} \\ w_{12} \end{bmatrix} &= \begin{bmatrix} -\sigma & 0 \\ Y & -b \end{bmatrix} \begin{bmatrix} w_{21} \\ w_{22} \end{bmatrix} \\
\text{and} \\
w_0 &= \begin{bmatrix} w_{11} \\ w_{12} \end{bmatrix} = \begin{bmatrix} x - x' \\ z - z' \end{bmatrix}.
\end{align*}
\]

The Eigen values of the Jacobian are also the transverse lyapunov exponents (Stavroulakis, 2006) and are:

\[
\lambda_1 = -\sigma, \lambda_2 = -b.
\]

Which are negative and therefore the two systems synchronize as \( t \to \infty \) for almost every initial condition. In the next section it is experimentally shown that two coupled modified Lorenz systems synchronize within a few time steps (a short length synchronization key).

4 EXPERIMENTS

Based on what was derived in the above sections, we evaluate our system which is based on our modified
Lorenz dynamical system. The value of $h$ in equations (5), (6) and (7) was taken to be 0.02. The initial conditions for the Encryption system were chosen as $X(0) = -10, Y(0) = -7, Z(0) = 35$; these values were chosen because they are about the center of the Lorenz attractor Figure 5.

For generating the Cipher block, this form of equation (1) was used:

$$\text{Cipher block} = T([Y(N)_{p,q}, 50])$$  \hspace{1cm} (9)

The autocorrelation of a Cipher block of size 100*100 is calculated and depicted in Figure 10. (No key was used).

![Autocorrelation of a Cipher block](image10)

Figure 10: The autocorrelation of a Cipher block of size 100*100.

Figure 11: Original image (which was taken from the math work increments, "Matlab R2007A").

Figures 11 and 12 show the original image (which is a satellite picture of Boston that was taken from Math work increments, Matlab R2007A) and the encrypted image. The 2D-FFT of original and encrypted images is plotted in figures 13 and 14. The histograms of the plain text and Cipher text can be observed in figures 15 and 16.

![Original image](image11)

![Encrypted image](image12)

![FFT of original image](image13)

![FFT of encrypted image](image14)
The results of our experiments (Figure 17 and Table 1) ensure us about the rapid synchronization of two coupled modified Lorenz systems even when they are started from very different initial conditions. In Figure 17 the Encryption system initial conditions are \((x_1, y_1, z_1) = (-10, -7, 35)\) and the Decryption system initial conditions are \((x_2, y_2, z_2) = (27, 70, 0)\). \(n\) is the length of synchronization key.

A sum of square error is calculated to compare the original and decrypted images.

\[
SE = \sum_{i=1}^{N}(x_i - d_i)^2 \tag{10}
\]

Where \(N\) is the number of pixels; \(x_i\) and \(d_i\) are the original and decrypted image pixel intensity values. Table 1 shows the mean square error values for different initial conditions after synchronization process with a synchronization key of length 300.

Table 1: Square Error of decryption after synchronization (with different initial conditions).

<table>
<thead>
<tr>
<th>(SE)</th>
<th>Encryption initial conditions ((x,y,z))</th>
<th>Decryption initial conditions ((x,y,z))</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>0.00000</td>
<td>(-10, -7, 35)</td>
</tr>
<tr>
<td>2</td>
<td>0.00000</td>
<td>(-10, -7, 35)</td>
</tr>
<tr>
<td>3</td>
<td>0.00000</td>
<td>(-10, -7, 35)</td>
</tr>
</tbody>
</table>

The above results make us sure that for almost every practical initial condition for the decryption and encryption system, a synchronization key of length 300 will enforce the decryption system toward the encryption system’s initial condition. For a better insight to the geometry of the system another \(SE\) is calculated but without any synchronization taking in to account and the initial condition of the decryption system is slightly changed (Table 2). This Observation briefly shows the dependence of the system to the initial conditions.

Table 2: Square Error of decryption without synchronization.

<table>
<thead>
<tr>
<th>(SE)</th>
<th>Encryption initial conditions ((x,y,z))</th>
<th>Decryption initial conditions ((x,y,z))</th>
</tr>
</thead>
<tbody>
<tr>
<td>4</td>
<td>17234526</td>
<td>(-10, -7, 35)</td>
</tr>
</tbody>
</table>

5 CONCLUSIONS

Benefited from the complexity and unpredictability, chaotic pseudorandom sequences generated by the nonlinear dynamical systems with strange attractors show excellent capabilities for cryptography. The Lorenz attractor used in this work was chosen because it is simple, and a large body of research is available about its dynamics. It is possible to use higher dimensional chaotic systems and higher
number of keys.

As shown in this paper, two dynamical systems that have the same strange attractor can be synchronized and used as Cipher system. The spatial and spectral features of the system that were obtained experimentally, ensures us that the system is truly applicable. The dependence of the system on the initial conditions increases the system independence from the plain text.

Unpredictability, complexity and dependence of the systems output on the initial condition make this system desired for applications such as military image cryptography.

ACKNOWLEDGEMENTS

The author wishes to thank Prof. Moddares Hashemi, Isfahan University of Technology, for his help and support.

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